

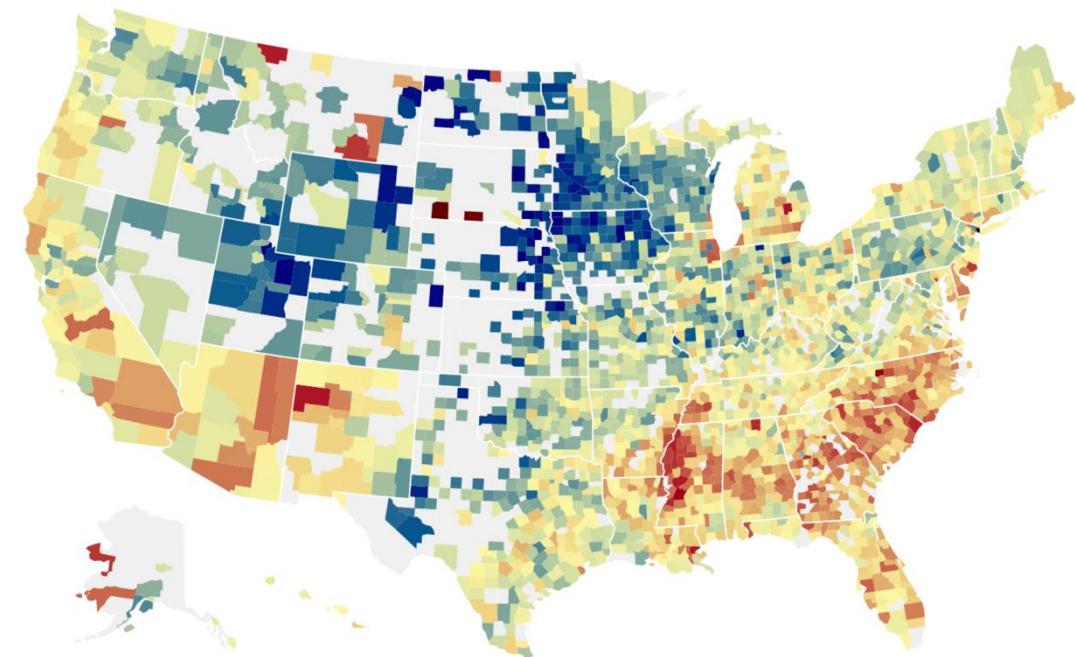
Measuring Income Mobility Under Differential Privacy

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Motivation

- ❖ Understanding economic mobility is essential for policy evaluation
- ❖ Analysts require access to administrative datasets containing sensitive information about individuals
- ❖ **Challenge:** how do we publish useful mobility statistics while preserving individual privacy?



Income Data

Data Sources

- ❖ Tax returns (IRS 1040)
- ❖ UI Wage Records (ES-202)
- ❖ Program Records (SNAP/TANF)

Structure

- ❖ Longitudinal tabular data

ID	2017	2018	...	2022
1	\$52,000	\$44,000	...	\$53,000
2	\$0	\$30,000	...	\$0
3	\$87,000	\$93,000	...	\$110,000
4	\$20,000	\$20,000	...	\$20,000

Transition Matrices

Represent mobility between two years

- ❖ Discretize income columns and compute a normalized two-way histogram

Discretization may be data-dependent

- ❖ Tax brackets vs. quantiles

Note: Divide rows by row sums to obtain a stochastic matrix

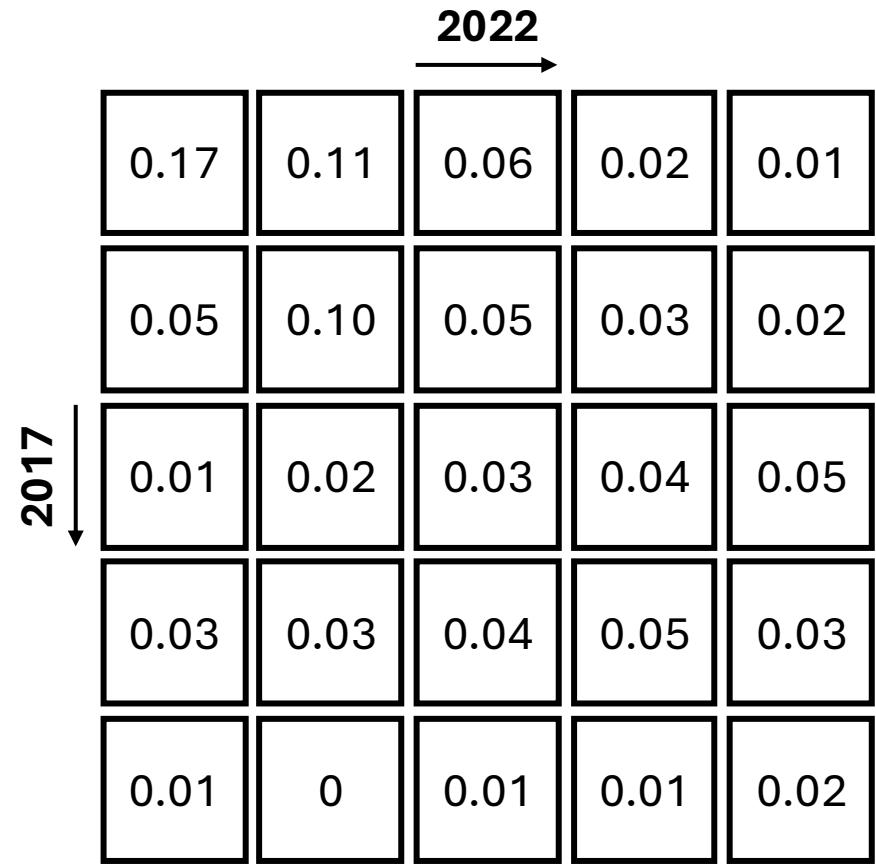
2022					
2017	0.17	0.11	0.06	0.02	0.01
	0.05	0.10	0.05	0.03	0.02
	0.01	0.02	0.03	0.04	0.05
	0.03	0.03	0.04	0.05	0.03
	0.01	0	0.01	0.01	0.02

Mobility Indices

Scalar summaries capturing various facets of mobility

- ❖ Analysts typically report a suite of indices

Examples



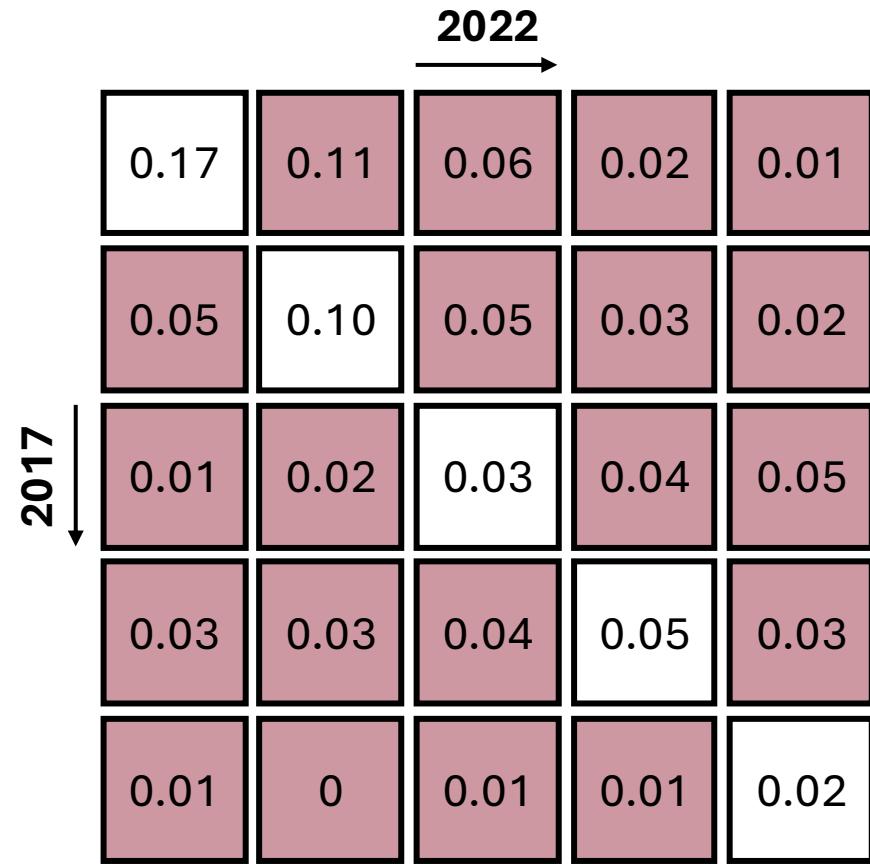
Mobility Indices

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Examples

- ❖ Prais-Bibby index measures the proportion of sample that changed bins



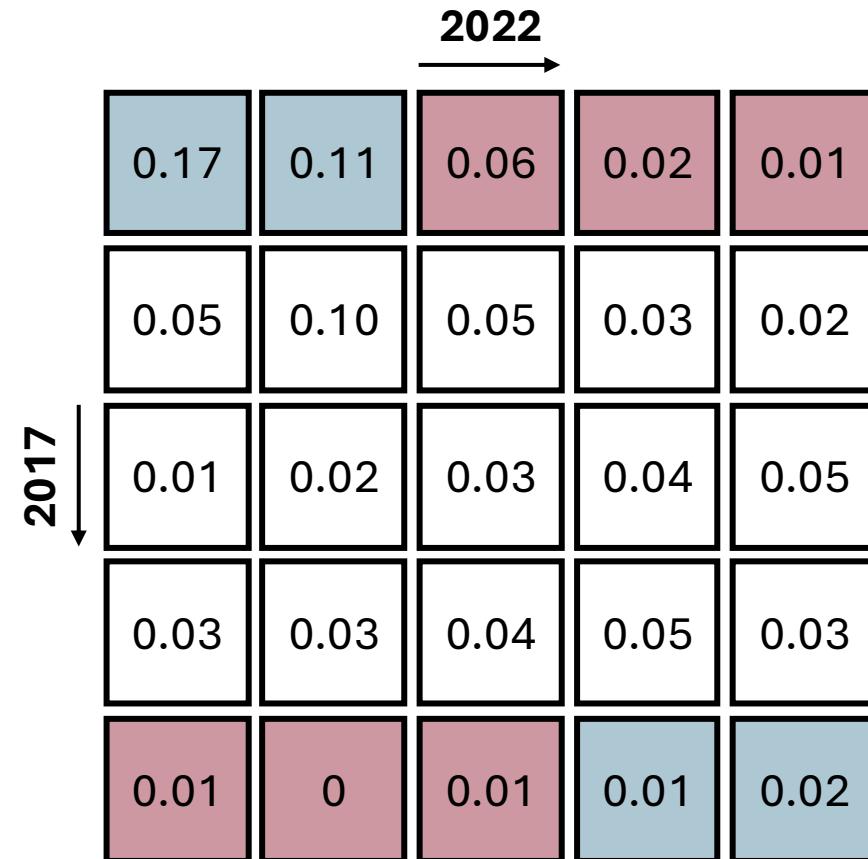
Mobility Indices

Scalar summaries capturing various facets of mobility

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Examples

- ❖ Prais-Bibby index measures the proportion of sample that changed bins
- ❖ Origin-specific indices measure the proportions that "escaped the bottom" and "fell from the top"



Differential Privacy

Informal Definition

- ❖ An algorithm is *differentially private* if its distribution over outputs does not change much when swapping the values of a single data record

Achieved by injecting carefully calibrated randomness

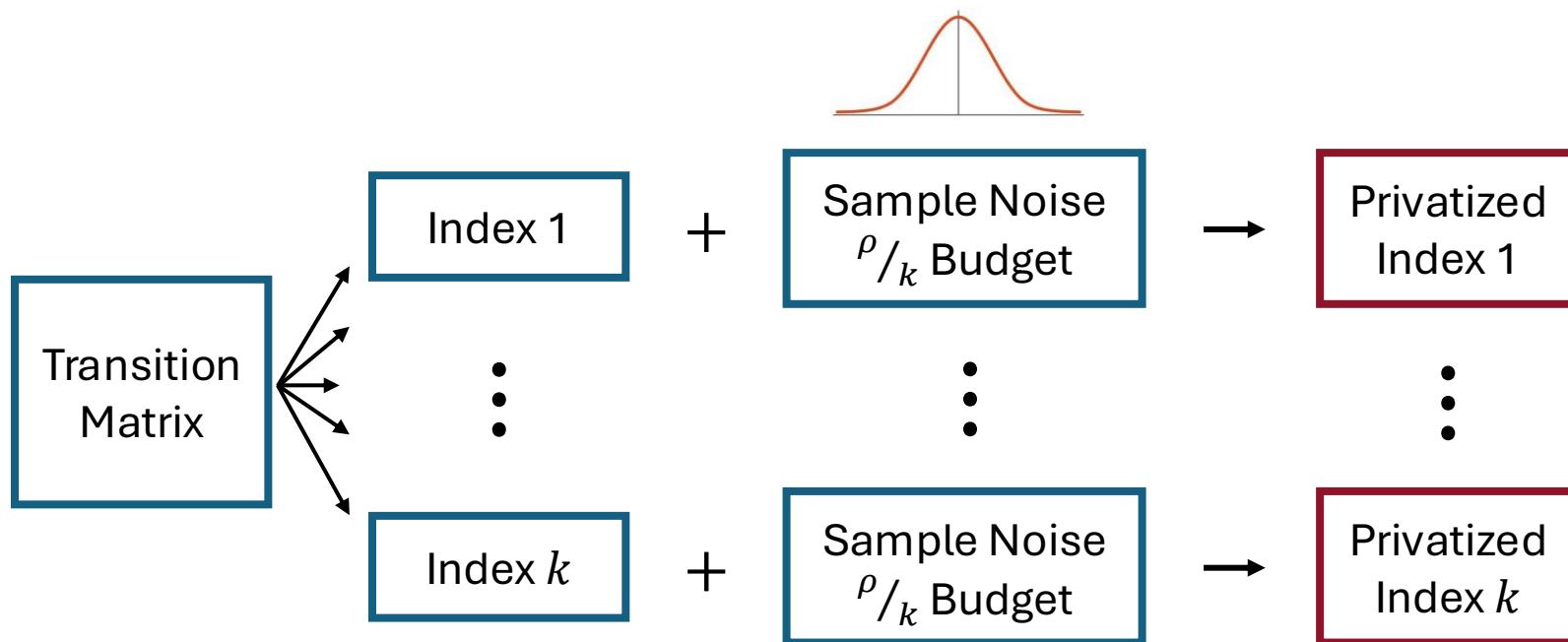
- ❖ Adding Gaussian noise (Gaussian mechanism)
- ❖ Privacy budget ρ controls the privacy-accuracy tradeoff
- ❖ Lower ρ implies stronger privacy (more noise)

Use zCDP version of differential privacy

Output Perturbation

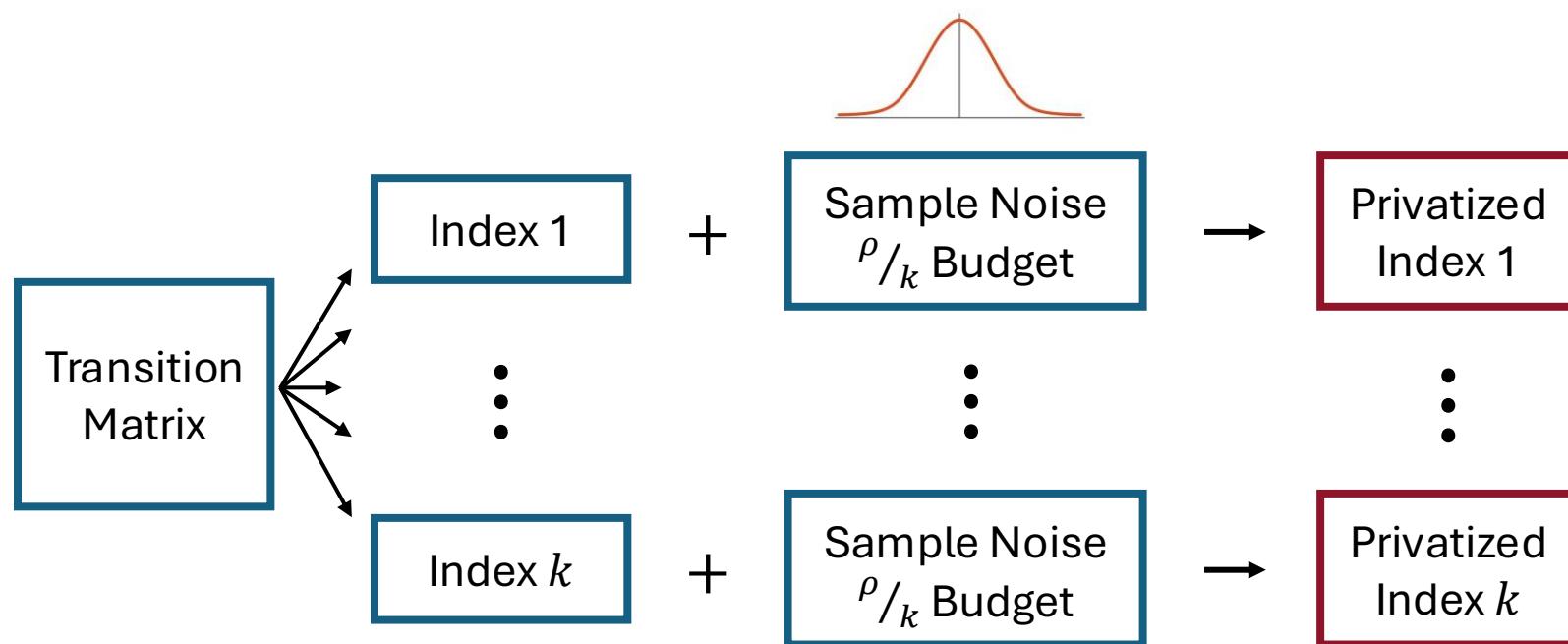
Approach

- ❖ Compute each of k indices from the raw data
- ❖ Add Gaussian noise calibrated to privacy budget ρ/k to each index



Limitations

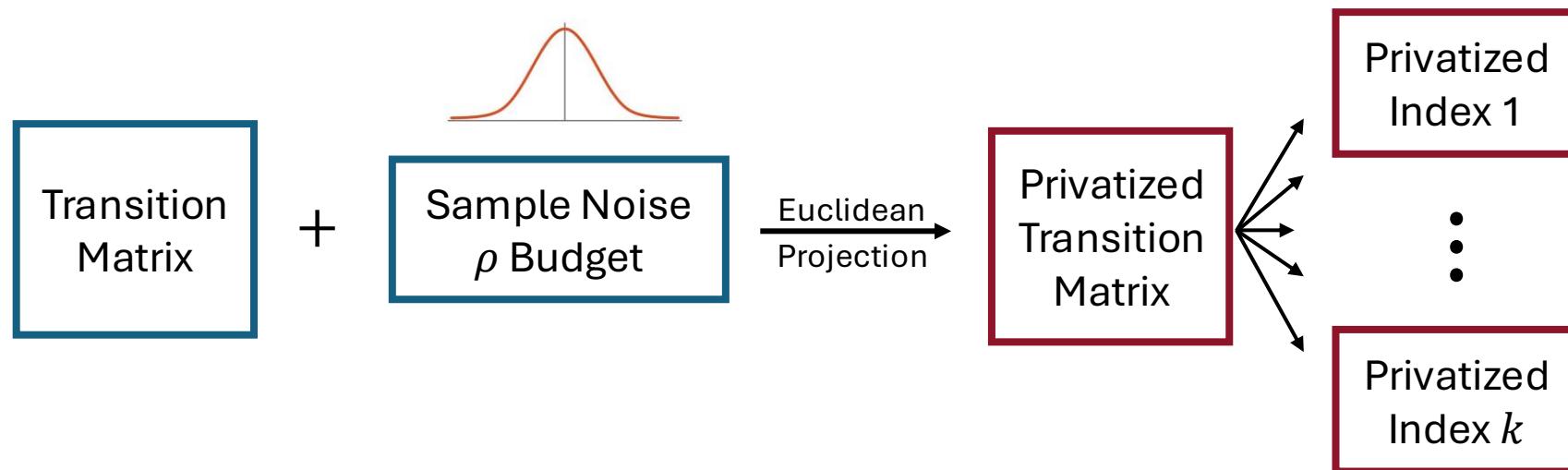
- ❖ Released indices may be **mutually inconsistent**
- ❖ Must **commit to indices** before accessing data
- ❖ **Budget fragments** as more indices are measured
- ❖ **Limited** to well-behaved indices



Perturb and Project

Approach

- ❖ Add Gaussian noise calibrated to privacy budget ρ to transition matrix
- ❖ Project noisy transition matrix to a valid probability distribution (Euclidean projection)
- ❖ Compute indices from privatized transition matrix



Perturb and Project

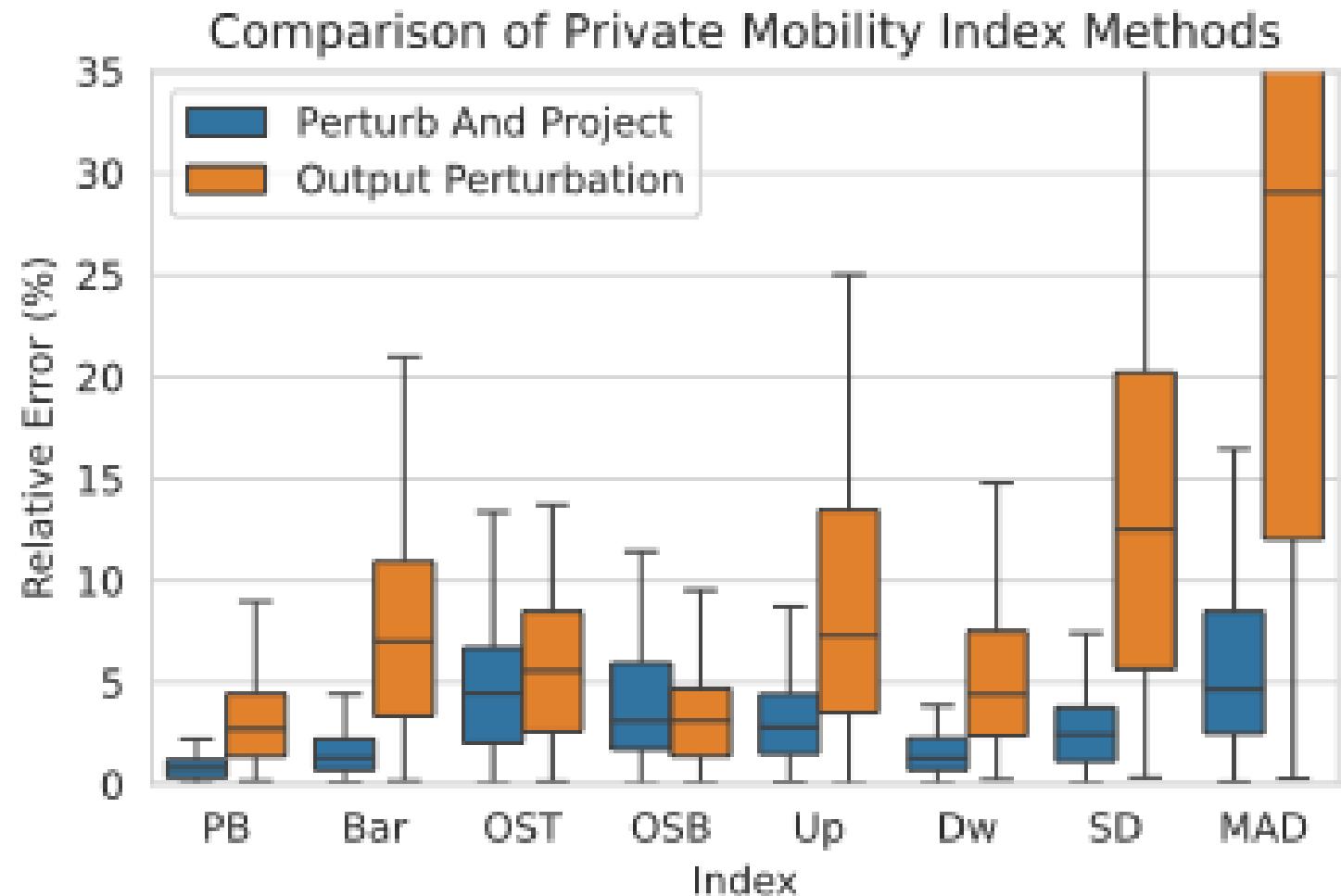
Addresses limitations of Output Perturbation

- ❖ **Consistency:** all indices released are mutually consistent
- ❖ **Flexibility:** new indices can be released without incurring additional privacy cost
- ❖ **Robustness:** supports all indices, e.g., indices with unbounded sensitivity

Additional Benefits

- ❖ **Transparency:** privatized transition matrix can be released

Empirical Evaluation



Extensions

Transition matrices using quantiles

- ❖ Allocate part of privacy budget to estimate quantiles (e.g. JointExp)
- ❖ Preliminary experiments suggest allocating ~10% of budget to quantile estimation

Multi-period mobility

- ❖ Track indices over time (2017-2018, 2017-2019, ...)
- ❖ Sliding window (2017-2020, 2018-2021, ...)
- ❖ Adapting Perturb and Project requires sophisticated query answering techniques
 - e.g. ResidualPlanner, GReM-LNN
- ❖ Preliminary results suggest even greater improvement over Output Perturbation

Takeaways

- ❖ Practitioners can publish mobility indices with a formal privacy guarantee
- ❖ Perturb and Project offers a compelling combination of accuracy, transparency, and flexibility
- ❖ Provides a practical strategy for statistical agencies working with sensitive administrative records



Thank You

Questions?

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