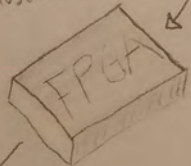
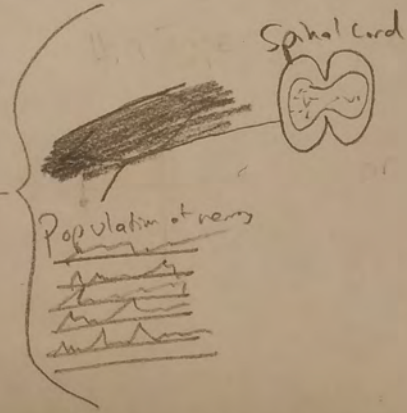


Controller

- Inputs:
- joint angles
 - endpoint position
 - tendon forces
 - desired position
 - muscle model state



- Outputs:
- voltage commands to amplifier → motors
 - update to muscle model state



Muscle Model

