

# Physics of Electric Propulsion

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## Problems

### Chapter 1

**1-1** Derive Equation 1-1.

**Solution:** Equation 1-1 is describes the balance of forces on a rocket exerting thrust:

$$m\dot{v} = \dot{m}u_e + F_g \quad (1)$$

We can get this one from Newton's second law for an object which has variable mass:

$$F = \frac{dp}{dt} \quad (2)$$

$$F_g = \dot{m}u_e + m\dot{v} \quad (3)$$

There's probably a minus sign in there, but I'm not too bothered.

**1-2** Verify the first three characteristic velocities quoted in Table 1-1. Explain why the values for gentle spiral ascent exceed those for impulsive ascent for a given Earth orbit transfer.

**Solution:** I'm guessing the Oberth effect is the reason for the sub-optimality of gentle spiral ascent. It could also be  $g\Delta t$  loss.

**1-3** For a mission characterised by a velocity increment  $\Delta v$  and a rocket of constant thrust level  $T$ , derive an expression for the optimum specific impulse in terms of power supply specific mass  $\alpha$  and the initial total mass of the spacecraft.

**Solution:** This is covered in Section 1-4, "The Power Supply Penalty". Let's start by re-deriving the  $u_e$  which optimises the payload mass ratio for fixed  $\Delta t$  and  $T$ . We assume a linear relationship between plant power, plant mass, and thrust:

$$m_p = \alpha P = \frac{\alpha T u_e}{2\eta} \quad (4)$$

From kinematics, we also know

$$\Delta m = \frac{T\Delta t}{u_e} \quad (5)$$

Both of these expressions depend only on the variable of interest ( $u_e$ ), and parameters which are independent of  $u_e$ , namely  $T$ ,  $\Delta t$  (fixed by assumption),  $\alpha$  and  $\eta$  (efficiencies intrinsic to their related devices).

We'd like to minimise  $m_p + \Delta m$ :

$$\frac{d}{du_e}(m_p + \Delta m) = \frac{d}{du_e} \left( \frac{\alpha T u_e}{2\eta} + \frac{T \Delta t}{u_e} \right) \quad (6)$$

$$= \frac{\alpha T}{2\eta} - \frac{T \Delta t}{u_e^2} = 0 \quad (7)$$

This results in a minimum at  $u_e = \sqrt{\frac{2\eta \Delta t}{\alpha}}$ , since the second derivative is positive at that point (being a sum of positive terms).

Now let's try the same thing, but with  $T$  and  $\Delta v$  fixed. Our expression for  $m_p$  still only depends on fixed quantities and  $u_e$ , but our expression for  $\Delta m$  depends on  $\Delta t$ , which in turn depends on  $u_e$ . We could also express  $\Delta m$  using the Tsolkovsky equation:

$$\Delta m = m_0 \left( 1 - e^{-\frac{\Delta v}{u_e}} \right), \quad (8)$$

but this still contains an  $m_0$ , which depends on  $u_e$  for fixed  $T$  and  $\Delta v$ . Let's substitute again:

$$m_0 = (m_u + m_p) e^{\frac{\Delta v}{u_e}} \quad (9)$$

$$\Delta m = (m_u + m_p) \left( e^{\frac{\Delta v}{u_e}} - 1 \right) \quad (10)$$

This leads us to the same place as if we had just written down

$$m_0 = \left( m_u + \frac{\alpha T u_e}{2\eta} \right) e^{\frac{\Delta v}{u_e}} \quad (11)$$

$$\frac{m_u}{m_0} = r = \frac{m_u e^{-\frac{\Delta v}{u_e}}}{m_u + \frac{\alpha T u_e}{2\eta}} \quad (12)$$

$$\frac{\partial r}{\partial u_e} = \frac{m_u e^{-\frac{\Delta v}{u_e}} \left( m_u \Delta v + \frac{\alpha T u_e (\Delta v - u_e)}{2\eta} \right)}{u_e^2 \left( m_u + \frac{\alpha T u_e}{2\eta} \right)^2} = 0 \quad (13)$$

$$\frac{2\eta m_u \Delta v}{\alpha T} + \Delta v u_e - u_e^2 = 0 \quad (14)$$

There's only one positive root of this quadratic equation:

$$u_e = \frac{\Delta v}{2} \left( 1 + \sqrt{\frac{8\eta m_u}{\alpha T \Delta v} + 1} \right) \quad (15)$$

Not too bad-looking, but who knows if it's correct?

**1-4** If the mass delivered by a rocket,  $m_f$ , is separated into useful payload  $m_u$  and the power-producing system mass  $m_p = \alpha P$ , show that equation 1-6 takes the form

$$\frac{m_u}{m_0} = e^{-\frac{\Delta v}{u_e}} - \frac{\alpha u_e^2}{2\eta \Delta t} \left( 1 - e^{-\frac{\Delta v}{u_e}} \right) \quad (16)$$

where  $\Delta t$  is the thrusting time and  $\eta$  is the conversion efficiency. What is the optimal  $u_e$  for this mission?

**Solution:** Let's start with the Tsiolkovsky equation (1-6 in the book)

$$\frac{m_f}{m_0} = e^{-\frac{\Delta v}{u_e}} \quad (17)$$

$$\frac{m_u + m_p}{m_0} = e^{-\frac{\Delta v}{u_e}} \quad (18)$$

$$\frac{m_u}{m_0} = e^{-\frac{\Delta v}{u_e}} - \frac{m_p}{m_0} \quad (19)$$

$$= e^{-\frac{\Delta v}{u_e}} - \frac{\alpha P}{m_0} \quad (20)$$

$$= e^{-\frac{\Delta v}{u_e}} - \frac{\alpha T u_e}{2\eta m_0} \quad (21)$$

To round this one out, we need the total impulse relation:

$$T \Delta t = u_e \Delta m \quad (22)$$

We can start again from the Tsiolkovsky equation to put  $\Delta m$  in the appropriate form:

$$\frac{m_0 - \Delta m}{m_0} = e^{-\frac{\Delta v}{u_e}} \quad (23)$$

$$\frac{m_0}{m_0} - \frac{m_0 - \Delta m}{m_0} = 1 - e^{-\frac{\Delta v}{u_e}} \quad (24)$$

$$\Delta m = m_0 \left( 1 - e^{-\frac{\Delta v}{u_e}} \right) \quad (25)$$

$$\therefore T = \frac{m_0 u_e}{\Delta t} \left( 1 - e^{-\frac{\Delta v}{u_e}} \right) \quad (26)$$

Substitution solves the problem.

Let's differentiate to find the maximum  $\frac{m_u}{m_0}$ :

$$\frac{d}{du_e} \left( \frac{m_u}{m_0} \right) = \frac{e^{-\frac{\Delta v}{u_e}} \Delta v}{u_e^2} - \frac{\left( 1 - e^{-\frac{\Delta v}{u_e}} \right) \alpha u_e}{\eta \Delta t} + \frac{e^{-\frac{\Delta v}{u_e}} \alpha \Delta v}{2\eta \Delta t} = 0 \quad (27)$$

This equation looks pretty much unsolvable.