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#### DEPARTMENT OF COMPUTER SCIENCE

**Sub: Mathematics** 

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**Demonstrator's** 

Signature

Date:- / /20

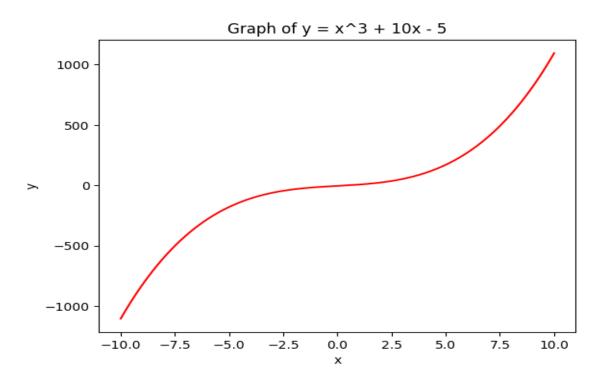
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## Q1. Attempt any Two of the following

# A ) Write a python program to plot the graph of $y=x^3+10x-5$ for $x \in [-10,10]$ in red color.

import matplotlib.pyplot as plt import numpy as np def f(x): return x\*\*3 + 10\*x - 5 x\_values = np.linspace(-10, 10, 100 y\_values = f(x\_values) plt plot(x\_values x\_values color='

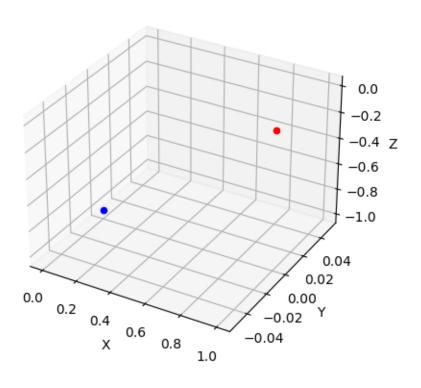
x\_values = np.linspace(-10, 10, 1000) y\_values = f(x\_values) plt.plot(x\_values, y\_values, color='red') plt.xlabel('x') plt.ylabel('y') plt.title('Graph of y = x^3 + 10x - 5') plt.show()



# B) Write a python program in 3D to rotate the point (1,0,0) through XZ –plane in clockwise direction (rotation through Y-axis by an angle of $90^\circ$ )



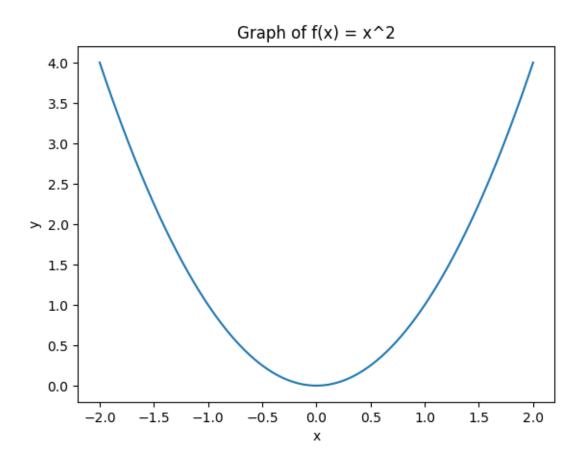
```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
point = np.array([[1], [0], [0]])
theta = np.radians(90)
cos\_theta = np.cos(theta)
sin\_theta = np.sin(theta)
rotation_matrix = np.array([[cos_theta, 0, sin_theta],
                  [0, 1, 0],
                  [-sin_theta, 0, cos_theta]])
rotated_point = rotation_matrix @ point
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
ax.scatter(point[0], point[1], point[2], c='r', marker='o')
ax.scatter(rotated_point[0], rotated_point[1], rotated_point[2], c='b', marker='o')
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
plt.show()
```



# C ) Using python plot the graph of function $f(x)=x^2$ on the interval [-2,2]

## ->

```
import matplotlib.pyplot as plt
import numpy as np
def f(x):
  return x^**2
x_values = np.linspace(-2, 2, 1000)
y_values = f(x_values)
plt.plot(x_values, y_values)
plt.xlabel('x')
plt.ylabel('y')
plt.title('Graph of f(x) = x^2')
plt.show()
```

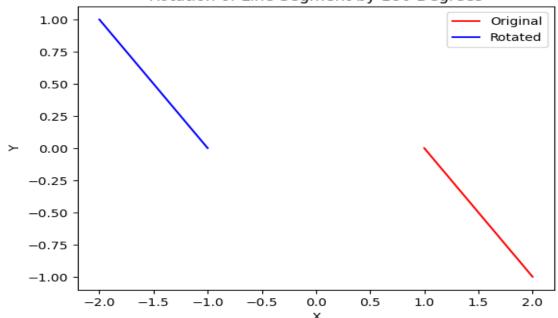


## Q2) Attempt any TWO of the following

# A) Write a python program to rotate the segment by 180° having end points (1,0) and (2,-1) →

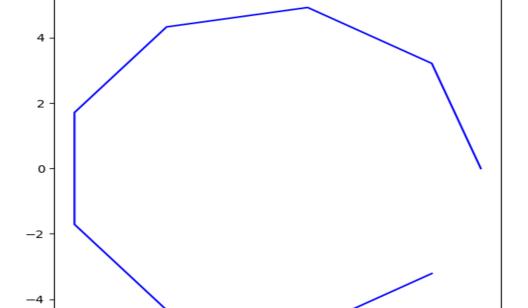
```
->
import numpy as np
import matplotlib.pyplot as plt
point1 = np.array([1, 0])
point2 = np.array([2, -1])
theta = np.radians(180)
cos\_theta = np.cos(theta)
sin\_theta = np.sin(theta)
rotation_matrix = np.array([[cos_theta, -sin_theta],
                 [sin_theta, cos_theta]])
rotated_point1 = rotation_matrix @ point1
rotated_point2 = rotation_matrix @ point2
plt.plot([point1[0], point2[0]], [point1[1], point2[1]], 'r', label='Original')
plt.plot([rotated_point1[0], rotated_point2[0]], [rotated_point1[1], rotated_point2[1]], 'b',
label='Rotated')
plt.xlabel('X')
plt.ylabel('Y')
plt.title('Rotation of Line Segment by 180 Degrees')
plt.legend()
plt.show()
```





# $\boldsymbol{B}$ ) Write a python program to draw a polygon with 8 sides having radius 5 centered at origin and find its area and perimeter

```
->
   import matplotlib.pyplot as plt
   import numpy as np
   num sides = 8
   radius = 5
   angles = np.linspace(0, 2 * np.pi, num_sides + 1)[:-1]
   x_coords = radius * np.cos(angles)
   y_coords = radius * np.sin(angles)
   plt.figure(figsize=(6, 6))
   plt.plot(x_coords, y_coords, 'b')
   plt.axis('equal')
   plt.title('Regular Polygon with 8 Sides and Radius 5')
   side_length = 2 * radius * np.sin(np.pi / num_sides)
   perimeter = num_sides * side_length
   area = (num_sides * radius ** 2 * np.sin(2 * np.pi / num_sides)) / 2
   print("Area:", area)
   print("Perimeter:", perimeter)
   plt.show()
```



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Regular Polygon with 8 Sides and Radius 5

```
C) Write a python program to find the area and perimeter of the \triangle XYZ, where X(1,2),
Y(2,-2),Z(-1,2)
->
import math
X = (1, 2)
Y = (2, -2)
Z = (-1, 2)
XY = \text{math.sqrt}((Y[0] - X[0]) ** 2 + (Y[1] - X[1]) ** 2)
XZ = \text{math.sqrt}((Z[0] - X[0]) ** 2 + (Z[1] - X[1]) ** 2)
YZ = \text{math.sqrt}((Z[0] - Y[0]) ** 2 + (Z[1] - Y[1]) ** 2)
perimeter = XY + XZ + YZ
s = (XY + XZ + YZ) / 2
area = math.sqrt(s * (s - XY) * (s - XZ) * (s - YZ))
print("Area:", area)
print("Perimeter:", perimeter)
output:
         Area: 4.0000000000000003
         Perimeter: 11.123105625617661
Q3) Attempt the following
A) Attempt any ONE of the following
        I) Write a program to solve the following LPP:
              Min Z=3.5x+2y
              Subject to x+y \ge 5
                          x≥4
                          y≤2
                          x,y \ge 0
```

->

c = [3.5, 2] A = [[1, 1], [-1, 0], [0, 1]] b = [5, -4, 2]

x\_bounds = (0, None) y bounds = (0, None)

from scipy.optimize import linprog

result = linprog(c, A\_ub=A, b\_ub=b, bounds=[x\_bounds, y\_bounds])

```
print("Optimal value:", round(result.fun, 2))
print("Optimal point:", tuple(round(x, 2) for x in result.x))
output:
         Optimal value: 14.0
         Optimal point: (4.0, 0.0)
II ) Write a python program to solve the LPP and find optimal solution if exist
      Max Z=3x+5y+4z
       Subject to 2x+3y \le 8
                      2y+5z≤10
                      3x+2y+4z \le 15
                      X,y,z \ge 0
->
       from scipy.optimize import linprog
       c = [-3, -5, -4]
       A = [[2, 3, 0],
          [0, 2, 5],
          [3, 2, 4]]
       b = [8, 10, 15]
       x_bounds = (0, None)
       y_bounds = (0, None)
       z_bounds = (0, None)
       result = linprog(c, A_ub=A, b_ub=b, bounds=[x_bounds, y_bounds, z_bounds])
       if result.success:
         print("Optimal value:", round(-result.fun, 2))
         print("Optimal point:", tuple(round(x, 2) for x in result.x))
       else:
         print("Optimization failed. The problem may be infeasible or unbounded.")
output:
Optimal value: 18.66
Optimal point: (2.17, 1.22, 1.51)
```

## B) Attempt any ONE of the following

- I) Write a python program to apply the following transformation on the point [-2,4]
- A) Reflection through Reflection through -axis
- B) Scaling in X-coordinate by factor 6
- C) Scaling in Y-coordinate by factor 4.1
- **D**) Shering in X-direction by  $\frac{7}{2}$

```
import numpy as np
point = np.array([-2, 4])
reflection_x = np.array([[1, 0], [0, -1]])
reflected_point_x = np.dot(reflection_x, point)

scaling_x = np.array([[6, 0], [0, 1]])
scaled_point_x = np.dot(scaling_x, point)
scaling_y = np.array([[1, 0], [0, 4.1]])
scaled_point_y = np.dot(scaling_y, point)

shearing_x = np.array([[1, 7/2], [0, 1]])
sheared_point_x = np.dot(shearing_x, point)

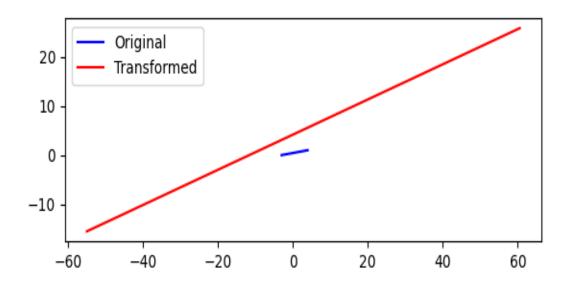
print("Original point: ", point)
print("Reflection through x-axis: ", reflected_point_x)
print("Scaling in x-coordinate by factor 6: ", scaled_point_y)
print("Scaling in x-direction by 7/2: ", sheared_point_x)
```

#### output:

Original point: [-2 4]
Reflection through x-axis: [-2 -4]
Scaling in x-coordinate by factor 6: [-12 4]
Scaling in y-coordinate by factor 4.1: [-2. 16.4]
Shearing in x-direction by 7/2: [12. 4.]

- II ) Write a python program to find the combined transformation on the line segment between the points A[4,1] & B[-3,0] for the following sequence of transformation
- A ) Rotation about origin through an angle  $\frac{\pi}{4}$
- B) Uniform scaling by 7.3 units
- C) Scaling in X-coordinate by 3 units
- **D**) Shering in X direction by  $\frac{1}{2}$  units

```
->
  import numpy as np
  import matplotlib.pyplot as plt
  from matplotlib.transforms import Affine2D
  A = np.array([4, 1])
  B = np.array([-3, 0])
  AB = np.vstack((A, B))
  T1 = Affine2D().rotate(np.pi/4) # Rotation about origin through an angle \pi/4
  T2 = Affine 2D().scale(7.3, 7.3) # Uniform scaling by 7.3 units
  T3 = Affine 2D().scale(3, 1) # Scaling in X-coordinate by 3 units
  T4 = Affine 2D().skew(0.5, 0) # Shering in X direction by 1/2 units
  T_{combined} = T1 + T2 + T3 + T4
  AB_transformed = T_combined.transform(AB)
  fig, ax = plt.subplots()
  ax.plot(AB[:, 0], AB[:, 1], 'b', label='Original')
  ax.plot(AB_transformed[:, 0], AB_transformed[:, 1], 'r', label='Transformed')
```



ax.legend()

plt.show()

ax.set\_aspect('equal')