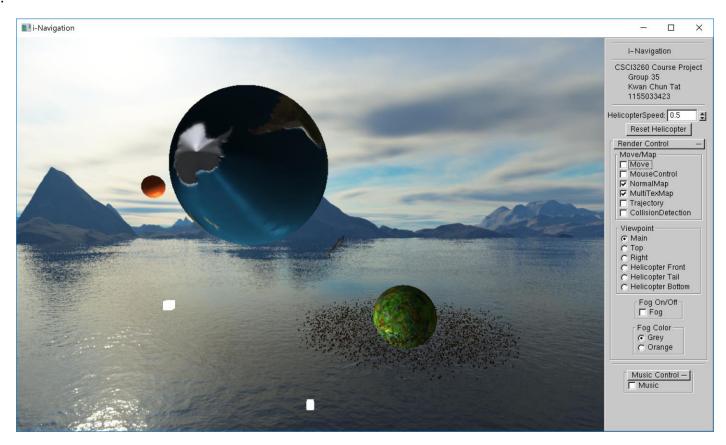
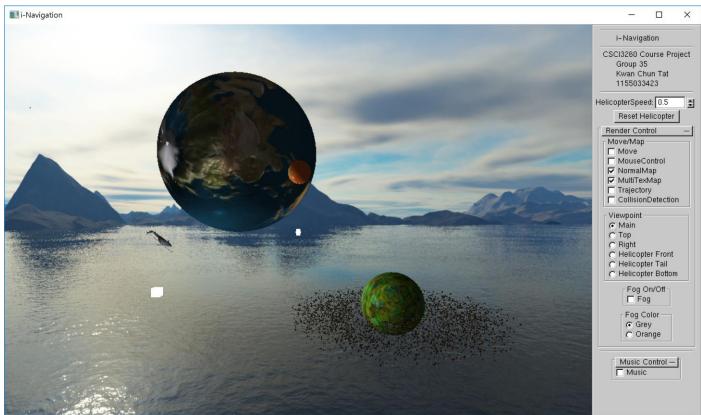
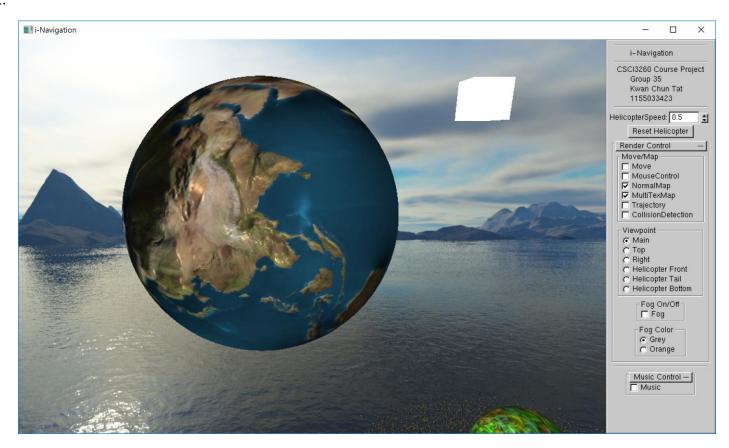
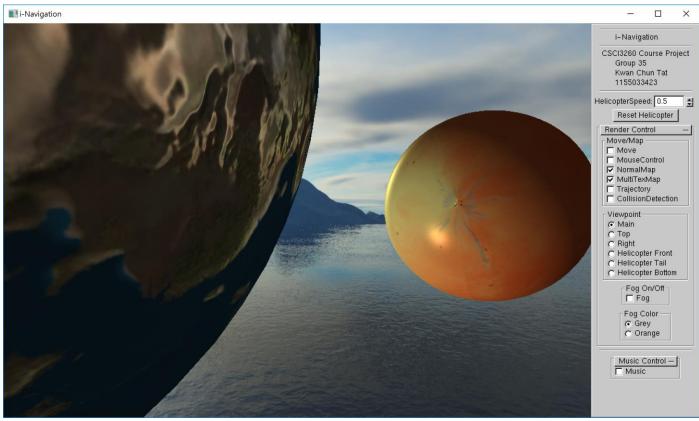
# CSCI3260 Course Project Report Group 35 Kwan Chun Tat 1155033423

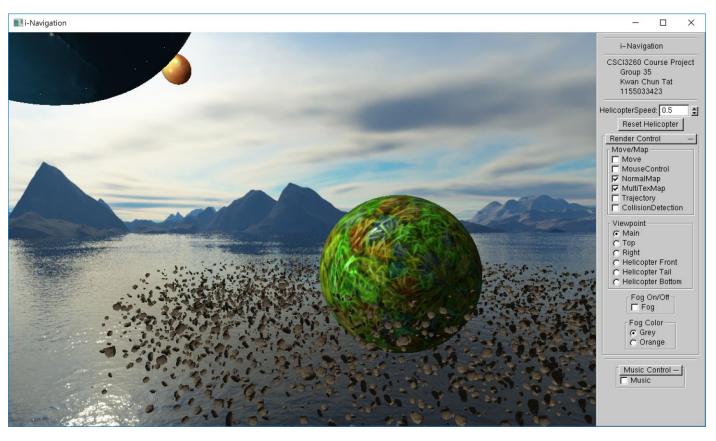
1.

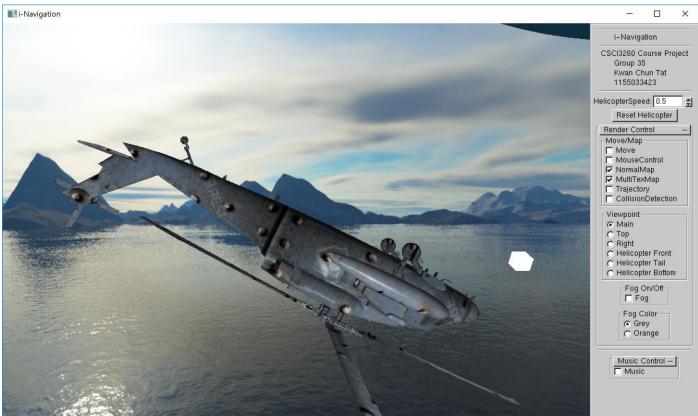


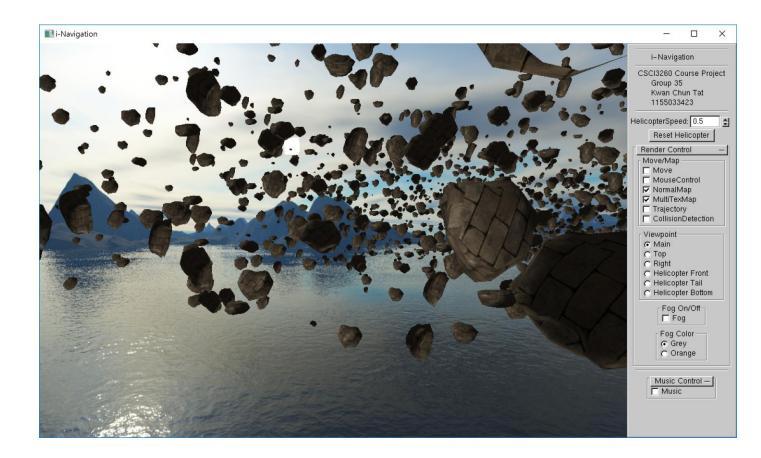






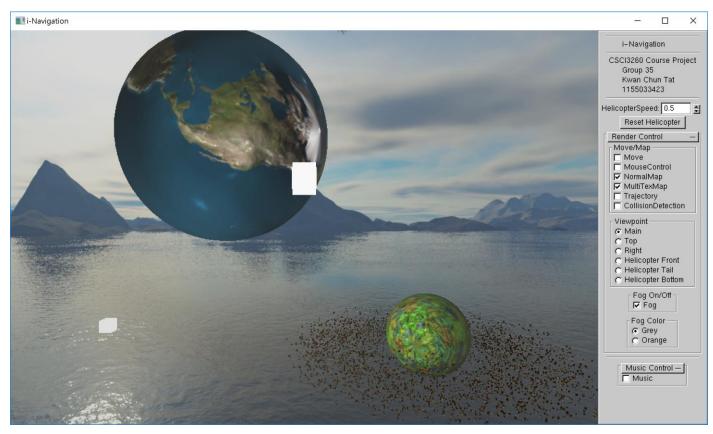


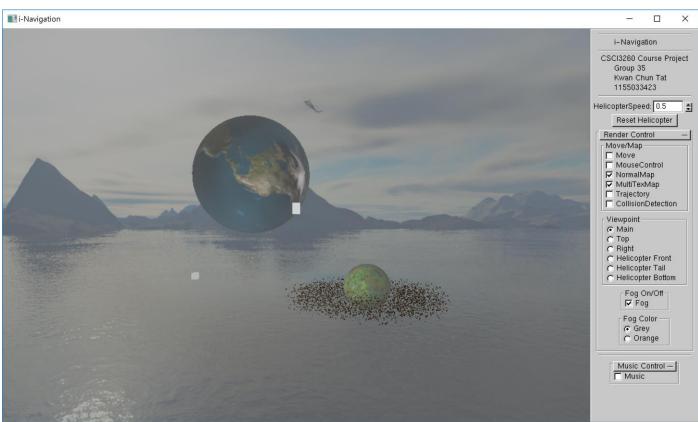




3.

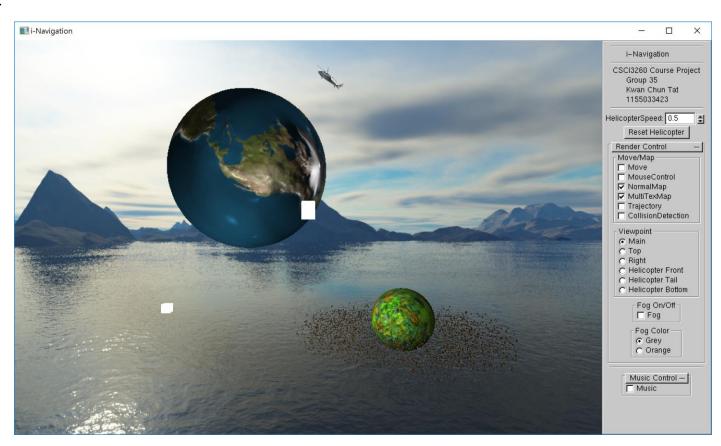


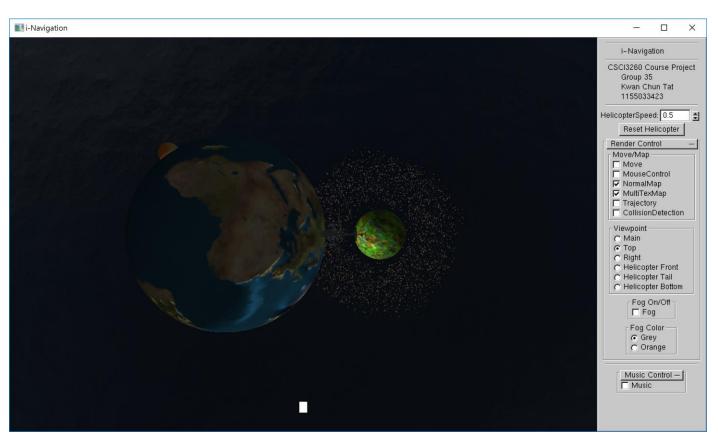


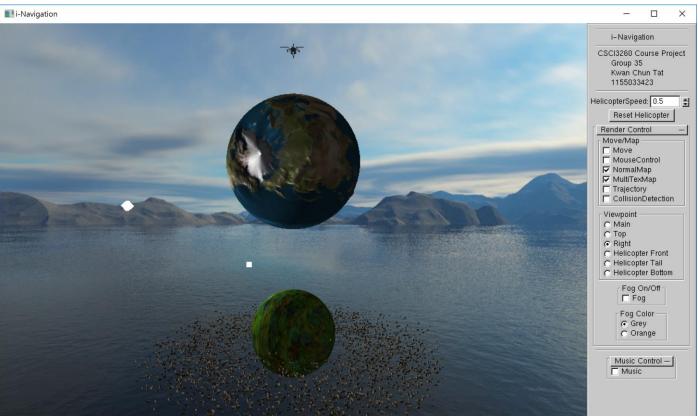




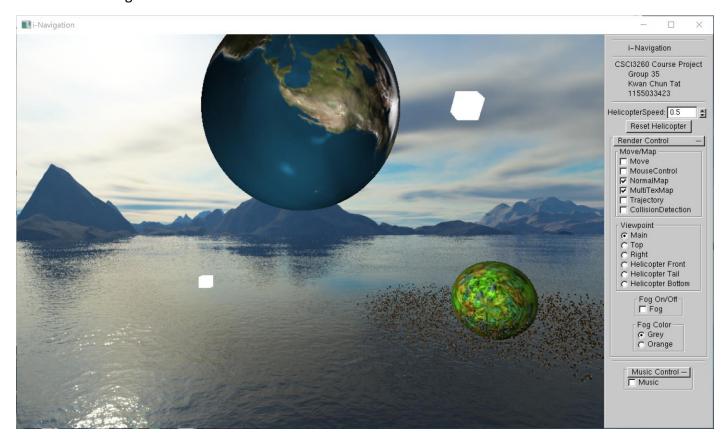
5.





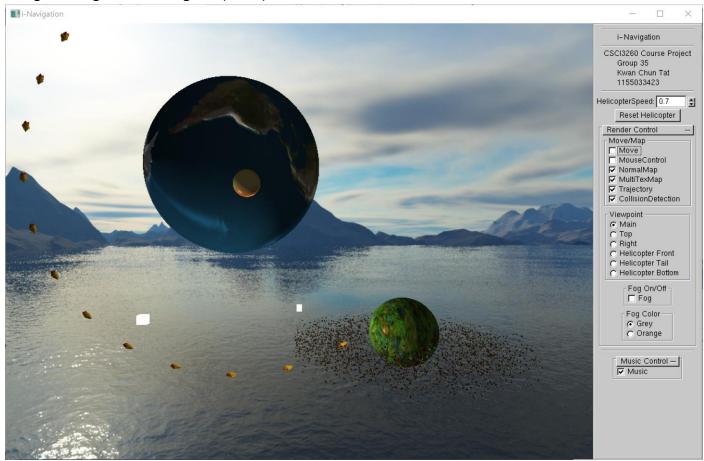


## 6. Another visible light source:

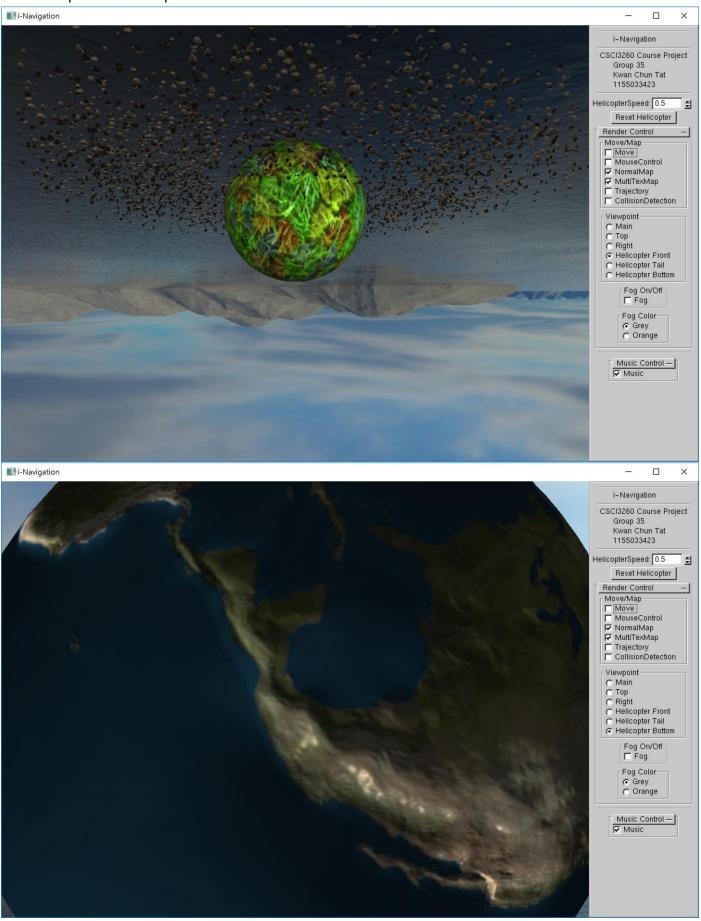


### **Collision Detection:**

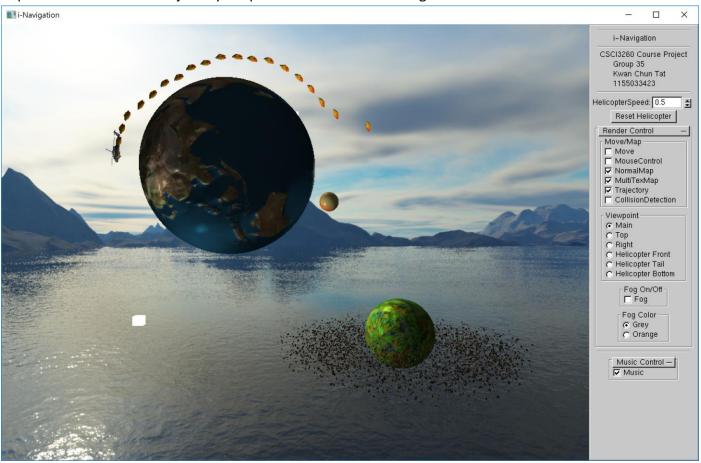
Using Axis-Aligned Bounding Box (AABB).



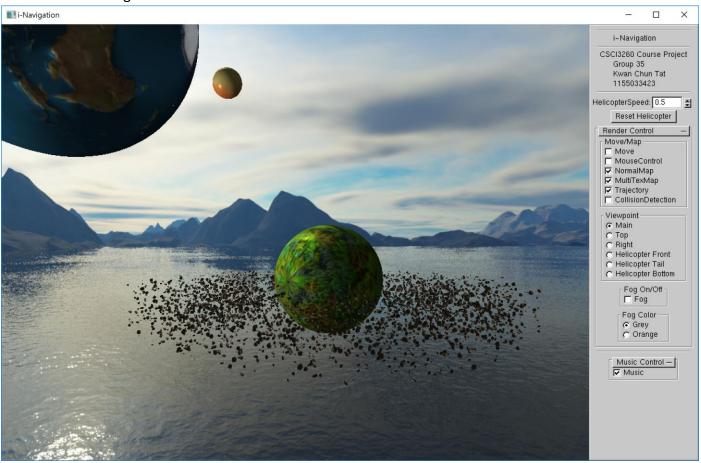
## Extra viewpoints on the space vehicle:



## Represent the real-time trajectory of space vehicle D with a string of star:



## Instanced rendering:



Play background music with IrrKlang Library.

Prefect correct Normal Mapping for Earth.

Followed "Tutorial 13 : Normal Mapping" on "opengl-tutorial.org" (<a href="http://www.opengl-tutorial.org/intermediate-tutorials/tutorial-13-normal-mapping/">http://www.opengl-tutorial.org/intermediate-tutorials/tutorial-13-normal-mapping/</a>). Source code in

"Normal\_mapping.cpp", "Normal\_mapping.h" and some code in "Bind\_Data.cpp" obtained from the GitHub of the website, under the WTFPL Public License.