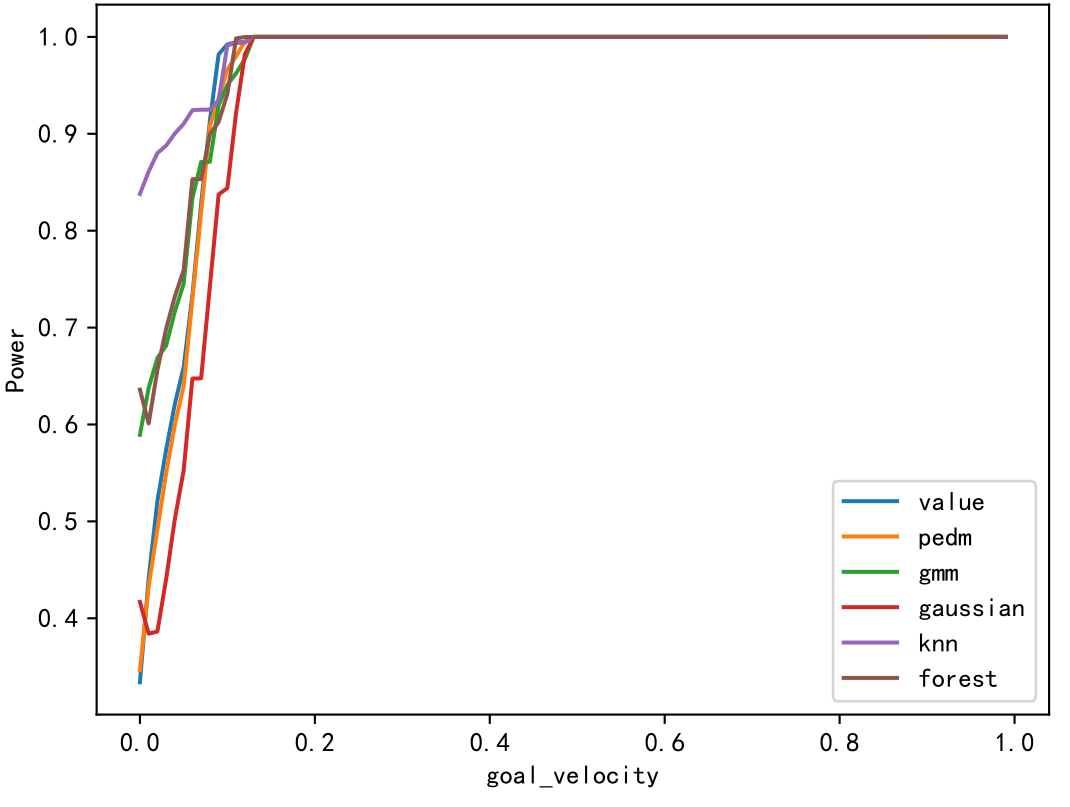
1.0
0.9
0.8
0.7
0.6
0.5
0.4
Power
0.0
0.2
0.4
0.6
0.8
1.0
goal_velocity
value
pedm
gmm
gaussian
knn
forest