hw4-task2

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1. 习题4.8-4.14

2. 习题4.16,4.19-4.22

```
dec = 6 # 设置每一步计算保留小数点后位数 (精度,可以自己调整)
import numpy as np
np.set_printoptions(formatter={'float': ('{: 0.' + str(dec) + 'f}').format})
import matplotlib.pyplot as plt
import matplotlib as mpl
mpl.rcParams['text.usetex'] = True
import sympy as sp
```

1 习题4.8

对于一般的 Lagrange 插值而言有如下关系:

$$f(x)=L(x)+\frac{f^{(n+1)}(\xi)}{(n+1)!}\omega(x)$$

当 f(x) 是小于等于 n 次的多项式函数时,有 $f^{(n+1)}(\xi) = 0$,因此有 f(x) = L(x) 。

2 class LagrangeInterpolation 编写

```
1
    class LagrangeInterpolation:
 2
 3
        def __init__(self, x_in: np.ndarray, y_in: np.ndarray) -> None:
 4
            self.x_in = x_in
 5
            self.y_in = y_in
 6
            self.N = len(self.x_in)
 7
            self.getInterpolationCoeff()
 8
 9
10
        def getInterpolationCoeff(self) -> None:
11
            X = np.zeros([self.N, self.N])
12
            for i in range(self.N):
13
                X[i] = self.x_in ** i
14
                pass
15
            self.coeff = np.linalg.inv(X.T) @ self.y_in
16
            pass
17
18
        def value(self, x: float) -> float:
19
            x_ = x ** np.arange(0, self.N, 1)
20
            return self.coeff @ x_
21
            pass
22
23
        def values(self, x: np.ndarray) -> np.ndarray:
24
            n = len(x)
25
            y = np.zeros(n)
26
            for i in range(n):
27
                y[i] = self.value(x[i])
28
                pass
29
            return y
30
            pass
31
32
        def expr(self) -> str:
33
            s = ""
```

```
34
            for i in range(self.N):
35
                if i == 0:
36
                    s += str(self.coeff[i]) + " + "
37
                    pass
38
                else:
39
                    s += str(self.coeff[i]) + "x^" + str(i) + " + "
40
                    pass
41
                pass
42
            return s[:-2]
43
            pass
44
45
        pass
    习题4.9
3
3.1 线性插值
1 \times = \text{np.array}([45, 60]) \times \text{np.pi} / 180
2 | y = np.sin(x)
 3 i = LagrangeInterpolation(x, y)
4 i.expr()
1 '0.23035091339287384 + 0.6070244240594347x^1 '
1 | print("插值值为: ", i.value(50 * np.pi / 180))
   print("精确值为: ", np.sin(50 * np.pi / 180))
   print("error = ", np.abs(i.value(50 * np.pi / 180) - np.sin(50*np.pi/180)))
1 插值值为: 0.7600796553858448
   精确值为: 0.766044443118978
   error = 0.005964787733133248
3.2 二次插值
1 | x = np.array([30, 45, 60]) * np.pi / 180
y = np.sin(x)
3 i = LagrangeInterpolation(x, y)
4 i.expr()
1 '-0.05877803813906546 + 1.251252649641426x^1 + -0.35153865113380967x^2 '
1 | print("插值值为: ", i.value(50 * np.pi / 180))
    print("精确值为: ", np.sin(50 * np.pi / 180))
   print("error = ", np.abs(i.value(50 * np.pi / 180) - np.sin(50*np.pi/180)))
1 插值值为: 0.7654338952290286
   精确值为: 0.766044443118978
 3 error = 0.0006105478899494088
```

5 function AitkenInterpolation 编写

```
1
    def AitkenInterpolation(x: float, x_in: np.ndarray, y_in: np.ndarray) ->float:
 2
        for i in range(len(x_in) - 1):
 3
            for j in range(len(x_in) - i - 1):
 4
                y_{in}[j] = (y_{in}[j+1] - y_{in}[j]) / (x_{in}[j+i+1] - x_{in}[j]) * (x - x_{in}[j]) +
    y_in[j]
 5
                pass
 6
            pass
 7
        return y_in[0]
 8
        pass
 1 | x = np.arange(-2, 3, 1)
   y = np.power(3, x+2) / np.power(3, 2)
 3 y
 1 array([ 0.111111, 0.333333, 1.000000, 3.000000, 9.000000])
 1 | print("0.5处插值值为: ", AitkenInterpolation(0.5, x, y))
 1 0.5处插值值为: 1.70833333333333333
6 习题4.11
   x = np.array([
       0.46, 0.47, 0.48, 0.49
 3
    ])
 4
   y = np.array([
        0.4846555, 0.4937452, 0.5027498, 0.5116683
 6
 7 | i = LagrangeInterpolation(x[0:-1], y[0:-1])
   i.expr()
 1 \quad \texttt{'-0.02546380000035242} \ + \ 1.3046850000009727x^1 \ + \ -0.42549999999937427x^2 \ \texttt{'}
 1 print("x = 0.472时, 插值值为: ", i.value(0.472))
 1 x = 0.472时,插值值为: 0.495552928000246
 1 | i = LagrangeInterpolation(y[1:], x[1:])
 2 | i.expr()
 1 '0.07016152590608726 + 0.5144575226386223x^1 + 0.5981826073884804x^2 '
```

```
1 | print("f(x)=0.5 时值为 (反插值): ", i.value(0.5))
```

1 f(x)=0.5 时值为 (反插值): 0.4769359390725185

7 习题4.12

$$f[x_0,x_0] = \lim_{x o x_0} rac{f(x)-f(x_0)}{x-x_0} = f'(x_0)$$

8 习题4.13

这里比较好的证明方法是数学归纳法,因为比较显然,就不再说明了。

9 习题4.14

同样比较显然,这里就不在多说明。

10 习题4.16

```
1
    def DifferenceQuotient(x_in: np.ndarray, y_in: np.ndarray) -> float:
 2
        x_ = x_{in.copy}()
 3
        y_ = y_{in.copy}()
 4
        for i in range(len(x_in) - 1):
 5
             for j in range(len(x_in) - i - 1):
 6
                 y_{j} = (y_{j+1} - y_{j}) / (x_{j+i+1} - x_{j})
 7
 8
             pass
 9
        return y_[0]
10
        pass
1
  f = lambda x: x**5 - 3*x**3 + x - 1
2
   for i in range(1, 7):
3
       x = 3 ** np.arange(0, i+1, 1)
4
       y = f(x)
5
       print("f[3^0,...3^"+str(i)+"] = ", DifferenceQuotient(x, y))
6
1 | f[3^0, \dots 3^1] = 83
2 \mid f[3^0, \dots 3^2] = 1171
3 \mid f[3^0, \dots 3^3] = 1207
4 | f[3^0, \dots 3^4] = 121
  f[3^0, \dots 3^5] = 1
6 | f[3^0, \dots 3^6] = 0
```

11 习题4.18

$$f[x_0, x_1, \cdots, x_p] = egin{cases} 0 & p < n+1 \ 1 & p = n+1 \end{cases}$$

12 习题4.19

```
class NewtonInterpolation:

def __init__(self, x_in: np.ndarray, y_in: np.ndarray) -> None:
    self.x_in = x_in
    self.y_in = y_in
    self.N = len(self.x_in)
```

```
7
             self.getNewtonInterpolationCoeff()
 8
             pass
 9
10
        def differenceQuotient(self, x: np.ndarray, y: np.ndarray) -> float:
11
             N = len(x)
12
             sum = 0
13
             for k in range(N):
14
                 prod = 1
15
                 for i in range(N):
16
                     if i != k:
17
                         prod *= (x[k] - x[i])
18
                         pass
19
                     pass
20
                 sum += y[k] / prod
21
                 pass
22
             return sum
23
             pass
24
25
        def getNewtonInterpolationCoeff(self) -> None:
26
             self.coeff = np.zeros(self.N)
27
             for i in range(0, self.N):
28
                 self.coeff[i] = self.differenceQuotient(self.x_in[0:i+1],
    self.y_in[0:i+1])
29
                 pass
30
             pass
31
32
        def value(self, x: float) -> float:
33
             sum = 0
34
             for i in range(self.N):
35
                 prod = 1
36
                 for j in range(i):
37
                     prod *= (x - self.x in[j])
38
                     pass
39
                 sum += self.coeff[i] * prod
40
                 pass
41
             return sum
42
             pass
43
44
        def expr(self, n = 100000) -> str:
45
             s = ""
46
             s += str(self.coeff[0]) + " + "
47
             for i in range(1, min(n, self.N)):
48
                 prod = ""
49
                 for j in range(i):
50
                     prod += "(x - " + str(self.x_in[j]) + ")"
51
52
                 s += str(self.coeff[i]) + prod + " + "
53
                 pass
54
             return s[:-2]
55
             pass
56
57
        pass
```

13 习题4.20

```
i = NewtonInterpolation(y, x)
print("y = 0.5时, x插值值为: ", i.value(0.5))
```

1 y = 0.5时, x插值值为: 2.9107142857142856

14 习题4.21

$$l_0(x_0) = 1$$
 $l_0(x_i) = 0 (i \neq 0)$

运用牛顿插值,可以直接导出:

$$l_0[x_0,x_1,\cdots,x_n] = \sum_{k=0}^n rac{l_0(x_k)}{\prod_{i=0,i
eq k}^n (x_k-x_i)} = rac{1}{\prod_{i=1}^n (x_0-x_i)}$$

因此显然有:

$$l_0(x) = \sum_{j=0}^{n-1} \prod_{k=0}^j rac{x-x_k}{x_0-x_{k+1}}$$

证毕。

15 习题4.22

1