

ESIEE PARIS

ARTIFICIAL INTELLIGENCE AND CYBERSECURITY

Artificial Intelligence

Lab 3 Report

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1 Introduction

In this report, we will present the results of the third project of the Artificial Intelligence course. The project consists of implementing

2 Tests

To run the program, we use the following command:

```
python3 pacman_AIC.py -p ReflexAgent [-l testClassic]
```

Running the command without the flag *-l testClassic*, renders a version of the maze without any walls.

The first two tests ran as expected, the Pacman tries to eat all the food in the field while avoiding all the ghosts. The main problem with both tests is that, while avoiding the ghosts, it'll stay in place most of the time, and not go after the food.

This can be improved by implementing an evaluation function, which will be developed in the next section.

3 Reflex Agent

In this part, we were purposed to improve the **ReflexAgent** function in the **multiAgents.py** file in the project by proposing an evaluation function.

3.1 ReflexAgent improvement

In order to improve the **ReflexAgent**, we need a good evaluation function to help the AI decide what to do next. A great evaluation function should be able to tell the agent what is the best action to take in a given state, rewarding good actions and punishing bad ones.

For our problem, we decided that a good action should be eating a food pellet, and a bad action should be getting eaten by a ghost. So, our evaluation function calculates the distance of Pacman to the food pellets and the ghosts. It then returns a score like the following:

```
return score + closestFoodScore - closestGhostScore
```

We also decided on using the Manhattan distance to calculate the distance between Pacman, the ghosts and the food pellets, because it is a less computationally expensive solution to this problem, and don't really affect the final score.

Finally, the result we got is the following:

```
def evaluationFunction(self, currentGameState, action):  
  
    """ VARIABLES """  
  
    foodList = newFood.asList()  
  
    # manhattan distance  
    foodDistances = \  
        [manhattanDistance(newPos, food) for food in foodList]  
    ghostDistances = \  
        [manhattanDistance(newPos, ghost) for ghost in newGhostsPos]  
  
    # closest food and ghost  
    closestFood = min(foodDistances) if len(foodDistances) > 0 else 0  
    closestGhost = min(ghostDistances) if len(ghostDistances) > 0 else 0  
  
    # score calculation for food and ghost  
    closestFoodScore = 0 if closestFood == 0 else 1.0/closestFood  
    closestGhostScore = 0 if closestGhost == 0 else 1.0/closestGhost  
  
    score = closestFoodScore - closestGhostScore  
  
    return successorGameState.getScore() + score
```

3.2 Tests

In order to test our new evaluation function, we executed the following tests:

3.2.1 testClassic

Command:

```
python3 pacman.AIC.py -p ReflexAgent -l testClassic
```

Output:

```
Pacman emerges victorious! Score: 562
Average Score: 562.0
Scores:      562.0
Win Rate:    1/1 (1.00)
Record:      Win
```

3.2.2 mediumClassic

- One ghost test run

Command:

```
python3 pacman.AIC.py -p ReflexAgent -k 1
```

Output:

```
Pacman emerges victorious! Score: 1485
Average Score: 1485.0
Scores:      1485.0
Win Rate:    1/1 (1.00)
Record:      Win
```

- Two ghosts test run

Command:

```
python3 pacman.AIC.py -p ReflexAgent -k 2
```

Output:

```
Pacman emerges victorious! Score: 1407
Average Score: 1407.0
Scores:      1407.0
Win Rate:    1/1 (1.00)
Record:      Win
```

3.2.3 No layout 20 runs average

During this part of the testing, we ran the **ReflexAgent** 20 times on each of the 6 combinations of the settings listed below, and calculated the average score and the win rate. The possible settings are as listed (identified with the letters a-e):

- Possible settings:
 - (a) One ghost
 - (b) Two ghosts
 - (c) Random ghosts
 - (d) Random ghosts with fixed seed
 - (e) Non random ghost

The results obtained are shown in Table 1.

Configuration	(a, c)	(a, d)	(a, e)	(b, c)	(b, d)	(b, e)
Average Score	671.65	785.2	449.9	464.7	228.7	-14.25
Win Rate	14/20 (0.70)	18/20 (0.90)	10/20 (0.50)	10/20 (0.50)	6/20 (0.30)	1/20 (0.05)

Table 1: ReflexAgent test results

3.2.4 Results

The **ReflexAgent** was successful in clearing most of the purposed tests. Especially the the ran in sections 3.2.1 and 3.2.2 (**testClassic** and **mediumClassic**), were no problem for the agent.

Things start to fall short when it comes to test in section 3.2.3. The agent obtained decent success in the test with a single ghost, but performance declined on tests with two ghost. The agent only cleared 6 out of 20 tests with random ghosts, and was only able to clear a single test with non random ghosts.

4 Minimax

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4.1 Minimax implementation

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```
def MAX_VALUE(self, gameState, d):
    if d == 0 or gameState.isWin() or gameState.isLose():
        # base case: return evaluation function
        return self.evaluationFunction(gameState), Directions.STOP

    bestScore, bestAction = -math.inf, Directions.STOP

    for action in gameState.getLegalActions(0):
        successors = gameState.generateSuccessor(0, action)

        # call minimaxer agent (ghosts)
        value, _ = self.MIN_VALUE(successors, d, 1)

        # update best score and action
        if value > bestScore:
            bestScore, bestAction = value, action

    return bestScore, bestAction
```

Table 2: Maximizer function

```
def MIN_VALUE(self, gameState, d, indexAgent):
    if d == 0 or gameState.isWin() or gameState.isLose():
        # base case: return evaluation function
        return self.evaluationFunction(gameState), Directions.STOP

    bestScore, bestAction = math.inf, Directions.STOP

    for action in gameState.getLegalActions(indexAgent):
        successors = gameState.generateSuccessor(indexAgent, action)
        if indexAgent == gameState.getNumAgents() - 1:
            # call pacman
            value, _ = self.MAX_VALUE(successors, d - 1)
        else:
            # call next ghost
            value, _ = self.MIN_VALUE(successors, d, indexAgent + 1)

        # update best score and action
        if value < bestScore:
            bestScore, bestAction = value, action

    return bestScore, bestAction
```

Table 3: Minimizer function

4.2 Tests

In order to test the Minimax algorithm implemented, we ran it 20 times, using different depths, and the results are shown in the table below:

Depth	2	3	4
Average	-173	546	701
Best	1249	1531	1732
Win Rate	1/20 (0.05)	11/20 (0.55)	11/20 (0.55)

Table 4: Minimax test results

5 AlphaBeta algorithm

The Alpha Beta implementation for the Minimax algorithm consists of two main changes: the addition of two parameters, alpha and beta, and the pruning of the search tree.

The parameters alpha and beta helps the algorithm identify if it is possible to continue searching the tree, or if a optimal value was already reached. In this case, we proceed with the pruning of the search tree, and return the value of the node.

This pruning is done in both the minimizer and maximizer functions, and help us reduce the number of nodes that are evaluated, and therefore, the time it takes to find the optimal move. This translates into a considerable performance improvement, as we will see in the next section.

5.1 AlphaBeta implementation

In order to implement the AlphaBeta algorithm, we used the same functions as the Minimax algorithm, but added two parameters to the functions, alpha and beta. The alpha and beta parameters are used to prune the search tree, and are initialized as **-math.inf** and **math.inf** respectively. The alpha and beta parameters are updated in the minimizer function, and the maximizer function, as shown in the code below:

```
""" CODE """

if value > beta:
    return value, action

alpha = max(alpha, value)

""" CODE """
```

Table 5: Maximizer function with beta pruning

```
""" CODE """

if value < alpha:
    return value, action

""" CODE """
```

Table 6: Minimizer function with alpha pruning

5.2 Tests

In order to test the performance of the Alpha Beta algorithm, we used the same tests as the Minimax algorithm, and compared the results. The results are shown in the table below:

Depth	2	3	4
Average	-121.5	413.6	635.85
Best	1001	1604	1701
Win Rate	1/20 (0.05)	9/20 (0.45)	11/20 (0.55)

Table 7: AlphaBeta test results

5.2.1 Performance comparison with Minimax

After running the tests, we compared the performance of the Minimax (Table 4) and Alpha Beta (Table 7) algorithms.

As expected, the performance between the two algorithms is practically the same. That's expected, as the main functionality of both algorithms is the same, the only difference between the two being the pruning in the Alpha Beta version.

Where the difference is definitely noticeable is in the runtime of both algorithms. To test this, we ran the same tests as before, but with a depth of 3, and compared the results. The results are shown in Table 8. As we can see, the Alpha Beta algorithm is 15.6% faster than the Minimax algorithm.

Algorithm	Minimax	AlphaBeta
Time	167.78s	145.10s
Speedup	-	15.6%

Table 8: Minimax VS AlphaBeta (Depth=3)

The speedup obtained in this test is not that significant, but it is still a considerable improvement. This shy performance improvement is most likely due to the fact that the main bottleneck of the algorithm is not the search. In our tests, we noticed that, due to the depth limit, when the Pacman eventually gets isolated in a area of the maze with no food, the algorithm doesn't really know what to do, and this leads to games that take a long time to finish.

To verify this, we ran the same test with the DirectionalGhost option. This forces the Pacman to move more frequently (as it is now being more effectively chased by the ghosts), but due to the exploration depth limitation, it loses games more oftenly. The results are shown in Table 9.

Now the speedup is much more significant, as the Alpha Beta algorithm is 83.5% faster than the Minimax algorithm. There is still more room to improvement though, but the performance gain is already considerable.

Algorithm	Minimax	AlphaBeta
Time	38.58s	21.03s
Speedup	-	83.5%

Table 9: Minimax VS AlphaBeta (Depth=3, DirectionalGhost)