




# BASSEM DAHROUG


## PhD, Mechatronics Engineer

 <https://bdahroug.github.io/>     bdahroug@gmx.com     Toulouse, France

## EXPERIENCE

### Robotics Engineer - Control & Mechatronics

#### ROVIAL Space

 03/2023 – present     Toulouse, France

- Participation in the development of unprecedented Robotics and AI solutions for Space Applications
- contribute to the design and development of ROVIAL's robots hardware and control;
  - contribute in the printing, integration, assembly and manufacturing of the robotic module and components, and in the experimental proof of concept prototype.

### Mechatronics Engineer

#### AMAROB Technologies

 06/2021 – 11/2022     Besançon, France

- Participation in different innovative projects
- design, simulation, manufacturing, and programming of mechatronic devices, in particular, the micro-robotic systems dedicated to intracorporeal laser surgery that AMAROB proposes;
  - validation of the devices developed with AMAROB's collaborators, including partner hospitals and AMAROB's customers.

## EDUCATION

### Ph.D. in Engineering Sciences

#### UBFC (Université Bourgogne Franche-Comté)

 11/2014 – 02/2018     Besançon, France

Dissertation: *Minimally Invasive Surgery in the Middle Ear: a guided micro-robotic system to efficiently remove cholesteatoma.*

### Joint M.Sc. in Mechatronics and Micro-Mechatronics Systems

#### ENSMM (Ecole National Supérieur de Mécanique et des Microtechnique) and EPI (Escuela Politécnica de Ingeniería de Gijón)

 09/2012 – 09/2014     Besançon, France and Gijón, Spain

Total score 15 out of 20 at ENSMM, and 7 out of 10 at EPI Master thesis: *Design, modelling and control of a contactless modular conveyor.*

### B.Sc. in Mechanical Engineering

#### AAST, College of Engineering Studies and Technology, Mechantronics Depart.

 09/2011 – 09/2006     Alexandria, Egypt

Graduation project: *Mobile robot control for parking manoeuvre.*

## SKILLS & KNOW-HOW

Mechatronic design	● ● ● ● ●
Robotics	● ● ● ● ○
Automatic control	● ● ● ● ○
Scientific programming	● ● ● ● ○
Mechanics	● ● ● ● ○
Electronics	● ● ● ● ○
Robotic experimentation	● ● ● ● ●
Analysis, synthesis and solving problems	● ● ● ● ○
Oral and writing communication	● ● ● ● ○
Organization, rigor and autonomy	● ● ● ● ○
Project Collaboration	● ● ● ● ○

## COMPUTER SKILLS

3DExperience

Solidworks

CATIA V5

FreeCAD

G-code

C/C++

ViSP, OpenCV

PCL, VTK

Python, Java

JS, HTML, CSS

micro-controller

Ladder

Matlab/Simulink

Octave

KiCAD

Egale

Proteus

Webots

CMSOL Multiphysics

Blender

Linux

Windows

## LANGUAGES

 English	 French
 Arabic	 Spanish