Bassem DAHROUG

PhD, Mechatronics Engineer

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Field of Interest

Mechatronics - Mechatronics Design - Robotics - Automatic control - Visual servoing - Programming - Mechanics - Fluid mechanics - (micro)Manufacturing - Materials - Electronics

Skills and Know-how

Mechatronic design ●●●●●
Robotics ●●●●○
Automatic control ●●●●○
Scientific programming ●●●●○
Mechanics ●●●◐○
Electronics ●●●◐○

Robotic experimentation ●●●●●
Analysis, synthesis and solving problems ●●●●○
Oral and writing communication ●●●●○
Organization, rigor and autonomy ●●●●○
Project Collaboration ●●●◐○

Education

11/2014 – 02/2018 **Doctor of philosophy in Engineering Sciences**, ***UBFC*** [1], Besançon, France.
Dissertation: Minimally Invasive Surgery in the Middle Ear: a guided micro-robotic system to efficiently remove cholesteatoma.

09/2012 – 09/2014 **Masters degree in Mechatronics and Micro-Mechatronics Systems**, joint masters degree from **ENSMM** [2], Besançon, France and **EPI** [3], Gíjon, Spain.
Master thesis: Design, modelling and control of a contactless modular conveyor.

09/2006 – 09/2011 **Bachelor degree in Mechanical Engineering**, ***AAST*** [4], *College of Engineering Studies and Technology, Department of Mechatronics*, Alexandrie, Egypt.
Graduation project titre: Mobile robot control for parking manoeuvre.

Professional and Academic Experiences

03/2023 – present **Robotics Engineer - Control & Mechatronics**, ***ROVIAL Space*** [5], Toulouse, France.

- participate in the research and development of innovative robotic solutions for space applications;
  - design and develop mechatronic systems by using different robotic structures (e.g., manipulator arm, legged robot) for performing assembly and repair tasks;
  - develop a low-level controller for actuating the robotic system;
  - develop a high-level controller for computing forward and inverse kinematics controllers, as well as dynamics ones;
  - develop a perception controller to guide the robotic system throughout its various tasks;
  - develop a scientific simulation for robotic systems and their digital twin;
  - create experimental proof-of-concept to validate the developed robotic system;
  - integrate and test the various components of the developed robotics system;
- collaborates with other departments, such as Structure and Space, to gather requirements and specifications.

[1] UBFC: https://www.ubfc.fr/
[3] ENSMM: https://www.ens2m.fr/
[3] EPI: http://www.epigijon.uniovi.es/
[4] AAST: http://www.aast.edu/en/index.php
[5] ROVIAL: https://rovial.eu/

09/2021 – 01/2022 **Temporary teaching**, ***ENSMM***, Besançon, France.
- 20 hours of practical work of JAVA programming for students in the 1^{st} year of bachelor.

06/2021 – 11/2022 **Mechatronics engineer**, ***AMAROB Technologies*** [6], Besançon, France.
- participate in the research and development of the main product of the company which is a micro-robotic systems dedicated to intracorporeal laser surgery;
  - design of a mechatronics device to actuate a blendable micro-robot;
  - manufacturing some parts of the micro-robot;
- take part in the company activities with its collaborators and client;
  - design and fabricate a medical prototype for detecting the breast cancer;
  - manufacturing using milling and electrical discharge machines.

09/2019 – 01/2020 **Temporary teaching**, ***UFC*** [7], Besançon, France.
- 28 hours of practical work of robotics for the **ISIFC** [8] students in the 3^{rd} year of bachelor;
- 12 hours of practical work of 3D computer vision for the students in the 2^{nd} year of master;
- 9 hours of practical work of automatic control of continuous system for the students in the 3^{rd} year of bachelor.

09/2018 – 12/2020 **Researcher, Post-doctoral**, *Institute* ***FEMTO-ST*** [9]*, Department AS2M (Automatique et Systèmes Micro-Mécatroniques)*, Besançon, France.
- participate to the INSERM project "*ROBOT*" (Robotics and Optical coherence tomography for optical BiOpsy in the digestive Tract) [2017 – 2021] which proposes an innovative approach to detect the cancer cells at the digestive tract;
- implement a visual servoing scheme based on the 3D imaging (C-scan) obtained from the OCT (Optical Coherence Tomography) for guiding a robot during the intra-operative phase in order to perform a repeatable optical biopsy;
- design and development of a prototype in order to validate and integrate the distinct technological and methodological approaches proposed by the different projects teams;
- supervision of two undergraduate trainees;
- valorization of the dissertation work.

09/2015 – 01/2016 **Temporary teaching**, ***ENSMM***, Besançon, France.
- 64 hours of practical work of automatic control and programming for students in the 1^{st} year of bachelor.

11/2014 – 02/2018 **Research assistant,PhD student**, *Institute* ***FEMTO-ST****, Department AS2M*, Besançon, France.
- early research stage of the project "μ*RMES*" (Micro-Robot for Middle Ear Surgery)
  - analysis of the clinical need for middle ear surgery to treat the disease known as cholesteatoma;
  - development of an image-guided micro-robotic system to perform this procedure.
- collaboration with **ARTOG** Center [10], Bern, Switzerland, by conducting experimental tests to evaluate the proposed controller in a clinical environment;
- supervision of six undergraduate trainees.

02/2014 – 08/2014 **Master graduation project**, *Institute* ***FEMTO-ST****, Department AS2M*, Besançon, France.
- participate to the project "*Smart Block*" [2011 – 2015] which innovates the transportation of fragile objects by designing a modular and reconfigurable conveyor;
  - propose new designs for a modular block which builds an aerodynamic conveyor for transporting photovoltaic cells;
  - model the air jets below an object;
  - propose control law to control the opening of the ports of each block independently so that the object can maintain a fixed position or follow a desired trajectory;
  - numerical and experimental validation of the proposed controller.

[6] AMAROB: https://amarob.com/
[8] UFC: http://www.univ-fcomte.fr/
[8] ISIFC: http://isifc.univ-fcomte.fr/pages/en/index.html
[9] FEMTO-ST: http://www.femto-st.fr/en/
[10] ARTOG: http://www.artorg.unibe.ch/research/igt/index_eng.html

02/2012 – 07/2012 **Temporary teaching**, ***AAST***, *Department of Mechanics*, Alexandria, Egypt.
- practical work of robotics and CAD (Computer Aided Design);
- tutor of a university team participating in the 11^{th} MATE (Marine Advanced Technology Education Centre) International ROV Competition.

02/2012 – 07/2012 **Bachelor graduation project**, ***AAST***, *Department of Mechanics*, Alexandria, Egypt.
- model and control of a mobile robot (car-like vehicle) for performing an automated parking maneuver.

Scholarship and Awards

2016 International mobility grant for doctoral students, funded by **UBFC**

2015 Best Automation Paper Award [11], **ICRA**'2015 (IEEE Internaltional Conference on Robotics and Automation)

2012 European Scholarship, Master **EU4M** (Mechatronics and Micro-Mechatronics Systems [12]) funded by the Erasmus Mundus programme

2008 Participation in competition **Robocon** (Egypt) with AAST team, 4th place in Egypt

Computer skills

Computer Aided Design (CAD): FreeCAD, Solidworks, CATIA, 3DExperience, Creo
Computer Aided Manufacturing (CAM): G-Code, FreeCAD-Path, Vericut, GO2Cam
Electronic Design Automation (EAD): KiCAD, Egale, Proteus, Quartus
Mathematics: Matlab/Simulink, Octave
Numerical Modeling: COMSOL Multiphysics
Programming: C/C++, ViSP, OpenCV, PCL, VTK, CMake, Python, Java, JS, HTML, CSS, micro-controller, Ladder, TCP/IP, I2C, Android
Robotics libraries: RBDyn, DART, Bullet
Simulation: Webots, Blender
Version Control: SVN, GIT
Operating Systems: Linux, Windows
Planning: Gantt
Office Tools: LaTeX, MS-office, Sozi

Linguistics

English French Arabic Spanish

[11] ICRA'2015: https://www.ieee-ras.org/about-ras/latest-news/635-icra-2015-award-recipients-announced
[12] EU4M: http://www.eu4m.eu/