# **BASSEM DAHROUG**

#### PhD, Mechatronics Engineer

https://bdahroug.github.io/

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Besançon, France

#### **EXPERIENCE**

#### Mechatronics Engineer

**AMAROB Technologies** 

**i** 06/2021 - 11/2022

Besançon, France

Participation in different innovative projects

- design, simulation, manufacturing, and programming of mechatronic devices, in particular, the micro-robotic systems dedicated to intracorporeal laser surgery that AMAROB proposes;
- validation of the devices developed with AMAROB's collaborators, including partner hospitals and AMAROB's customers.

#### Researcher, Post-doctoral

Institute FEMTO-ST, Dept. AS2M (Automatique et Systèmes Micro-Mécatroniques)

**1** 09/2018 - 12/2020

Besançon, France

Participation in the INSERM project "ROBOT" (Robotics and Optical coherence tomography for optical BiOpsy in the digestive Tract)

- design and development of a prototype in order to validate and integrate the distinct technological and methodological proposed by the different project's teams,
- implement a visual servoing scheme based on the 3D imaging (C-scan) obtained from the OCT for guiding a robot during the intra-operative phase in order to perform a repeatable optical biopsy.

## **EDUCATION**

#### Ph.D. in Engineering Sciences

**UBFC (Université Bourgange Franche-Comté)** 

**1**1/2014 - 02/2018

Besançon, France

Dissertation: Minimally Invasive Surgery in the Middle Ear: a guided micro-robotic system to efficiently remove cholesteatoma.

# Joint M.Sc. in Mechatronics and Micro-Mechatronics Systems

ENSMM (Ecole National Supérieur de Mécanique et des Microtechnique) and EPI (Escuela Politécnica de Ingeniería de Gíjon)

**=** 09/2012 - 09/2014

Besançon, France and Gíjon, Spain

Total score 15 out of 20 at ENSMM, and 7 out of 10 at EPI Master thesis: Design, modelling and control of a contactless modular conveyor.

#### B.Sc. in Mechanical Engineering

AAST, College of Engineering Studies and Technology, Mechantronics Depart.

**=** 09/2011 - 09/2006

Alexandria, Egypt

Graduation project: Mobile robot control for parking manoeuvre.

### **SKILLS & KNOW-HOW**

Mechatronic design
Robotics
Automatic control
Scientific programming
Mechanics
Electronics

Robotic experimentation
Analysis, synthesis and solving problems

Oral and writing communication Organization, rigor and autonomy Project Collaboration

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# COMPUTER SKILLS

FreeCAD Solidworks CATIA V5 G-code C/C++ ViSP, OpenCV PCL, VTK Python, Java JS, HTML, CSS micro-controller Ladder Matlab/Simulink Octave **KiCAD** Egale **Proteus** CMSOL Multiphysics Blender Windows Linux

## **LANGUAGES**





