Trust in Vehicle-to-Vehicle Communication

Boakye Dankwa, Rajeev R. Raje, Raghavendran Vijayan, Darsh Sanghavi Department of Computer and Information Science Indiana University Purdue University Indianapolis, Indiana, USA

Abstract—In traditional Pedestrian Automatic Emergency Braking (PAEB) system, vehicles equipped with onboard sensors such as (rader, camera, and infrared) detects pedestrians, alerts the driver and/ or automatically take action to prevent vehicle-pedestrian collision. In some situations, a vehicle may not be able to detect a pedestrian due to blind spots. Such a vehicle could benefit from the sensor data from neighboring vehicles in making such safety critical decisions. We propose a trust model for ensuring shared data are valid and trustworthy for use in making safety critical decisions. Simulation results of the proposed trust model show promise.

Index Terms—TODO; TODO; TODO;

I. Introduction

TODO

II. RELATED WORK

TODO

III. PROPOSED TRUST MANAGEMENT SYSTEM FOR V2V-PAEB

TODO

1) Measured Trust: TODO

IV. RESULTS AND DISCUSSIONS

TODO

V. CONCLUSIONS AND FUTURE EXTENSIONS

TODO

ACKNOWLEDGMENT