

Thesis Title

Thesis Subtitle

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A thesis presented for obtaining a Master's degree
in Engineering in Applied Mathematics

The logo of the University of Louvain (UCL) is displayed in a large, bold, dark blue serif font. It consists of the letters 'UCL' in a stylized, blocky typeface.

**Université
catholique
de Louvain**

Ecole Polytechnique de Louvain
Université Catholique de Louvain
Academic year 2016-2017

Abstract

Abstract goes here

Dedication

To mum and dad

Declaration

I declare that..

Acknowledgements

I want to thank...

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Chapter 1

Introduction

1.1 Motivation

1.2 Context of this thesis

1.2.1 Previous work

1.3 Objectives

Last year's thesis [1].

Chapter 2

State of the art

Chapter 3

Hardware and software architecture

Chapter 4

Implementation

Chapter 5

Performance

Chapter 6

Conclusion

Bibliography

- [1] Alexandre Leclere Arnaud Jacques. “Towards 3D Visual SLAM for an Autonomous Quadcopter Running ROS”. MA thesis. Université Catholique de Louvain, 2016.

Appendix A

Appendix Title