## Wiener process and martingales

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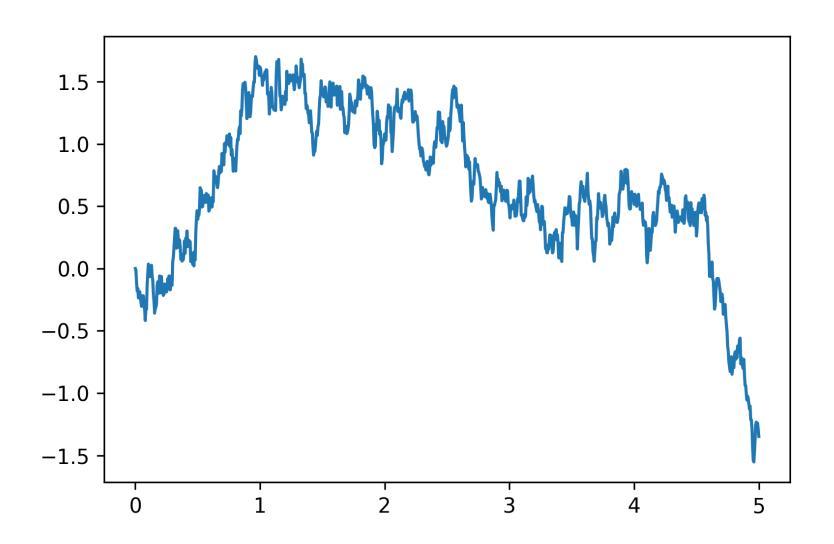
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- Problem solving and computer simulations.



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- $X_t$  one particular random variable.

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Tradition: when we consider two arbitrary moments of time, s and t, we usually assume  $s \leq t$ .

## **Divide and conquer**

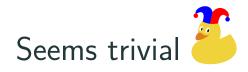
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$$W_t = W_s + (W_t - W_s)$$

Exercise 
$$\ref{eq:width}$$
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$$= \mathbb{P}(Z > -0.5) = \mathbb{P}(Z < 0.5) = F(0.5) \approx 0.69.$$

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- $(W_t)$  denotes a Wiener process.
- Z denotes a standard normal random variable,  $Z \sim \mathcal{N}(0; 1)$ .
- F(u) denotes the standard normal distribution function,  $F(u) = \mathbb{P}(Z \le u)$ .

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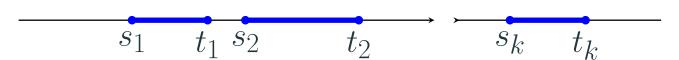
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The increments  $W_6-W_4$ ,  $W_4-W_3$ ,  $W_{2.5}-W_1$  are independent.

#### Independence of increments: full glory

If the time intervals  $[s_1,t_1]$ ,  $[s_2,t_2]$ , ...,  $[s_k,t_k]$  are non overlapping,



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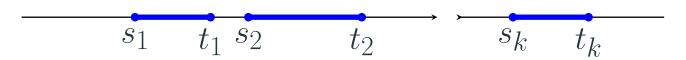
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Remark: the right border of an interval may touch the left border of the next one, but may not exceed it,  $t_j \leq s_{j+1}$ .

Exercise  $\bullet$ . Find  $\mathbb{E}(W_t)$ ,  $Var(W_t)$ ,  $Cov(W_s, W_t)$ .

$$\mathbb{E}(W_t) = \mathbb{E}(W_t - W_0) = 0$$

Exercise  $\ref{eq:lemma:eq:lem$ 

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Exercise  $\ref{eq:lemma:eq:lem$ 

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 $Cov(W_7, W_3) = 3.$ 

#### **Two friends**

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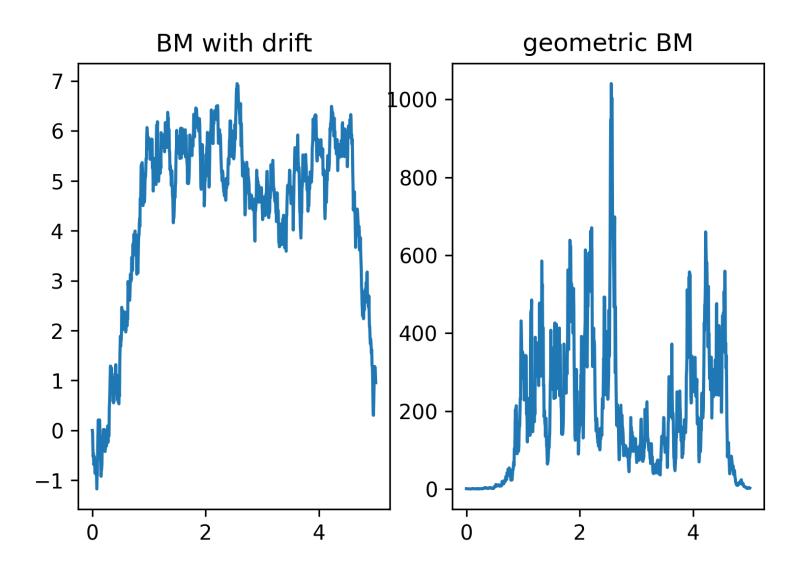


Stochastic process  $(S_t, t \ge 0)$  that may be written as

$$S_t = S_0 \exp(aW_t + bt),$$

is called geometric brownian motion.

## **Two plots**



## BM with drift and scaling

Exercise  $\clubsuit$ . Find  $\mathbb{E}(5W_t + 6t)$  and  $\operatorname{Var}(5W_t + 6t)$ .

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$$\mathbb{E}(5W_t + 6t) = 0 + 6t = 6t$$

$$Var(5W_t + 6t) = Var(5W_t) = 25t$$

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$$\mathbb{E}(\exp(aZ)) = \int_{-\infty}^{+\infty} \exp(az)f(z) dz =$$

$$= \int_{-\infty}^{+\infty} \exp(az) \frac{1}{\sqrt{2\pi}} \exp(-z^2/2) dz$$

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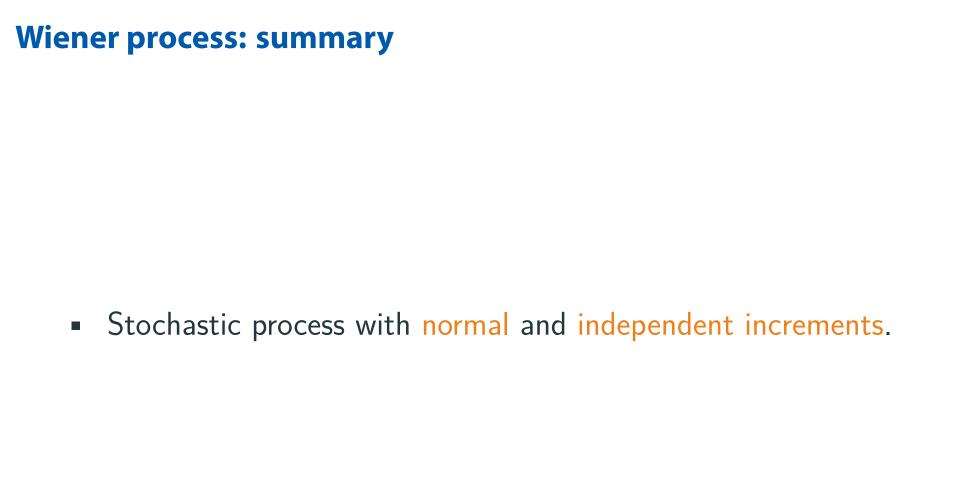
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$$M^{(k)}(0) = \mathbb{E}(X^k)$$



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- Modeling information using sigma-algebras;
- Properties of conditional expected value;
- Conditional variance.



John knows the value of X.

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Maria knows the value of X and Y.

John knows the value of X.

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Maria knows more!

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How to model this mathematically?

#### Informal definition



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### **Example**

The sigma-algebra  $\sigma(X,Y)$  contains the events  $\{X<5\}$ ,  $\{X>2Y\}$ ,  $\{\sin Y>\cos X\}$ , ...



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Maria knows more:  $\mathcal{F}_J \subset \mathcal{F}_M$ .

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#### Informal theorem



The random variable R is measurable with respect to  $\sigma(X,Y)$  if and only if R is a deterministic function of X and Y.

### **Best prediction**

### Informal definition



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# Difference of $\mathbb{E}(R \mid \mathcal{F})$ and $\mathbb{E}(R)$

If I know X and Y then my best prediction of R may depend on X and Y.

In general:  $\mathbb{E}(R \mid \mathcal{F})$  is a random variable.

#### **Notation**

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- $\mathbb{E}(R \mid \mathcal{F})$ : for a general  $\sigma$ -algebra  $\mathcal{F}$ ;
- $\mathbb{E}(R \mid \sigma(X, Y))$  or  $\mathbb{E}(R \mid X, Y)$ : for  $\sigma$ -algebra generated by X and Y.

### When we may omit conditioning?

• If R is independend of X and Y then  $\mathbb{E}(R \mid X, Y) = \mathbb{E}(R)$ : If I know nothing useful about R then I can drop my information.

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- If R is independend of X and Y then  $\mathbb{E}(R \mid X, Y) = \mathbb{E}(R)$ : If I know nothing useful about R then I can drop my information.
- $\mathbb{E}(\mathbb{E}(R\mid\mathcal{F}))=\mathbb{E}(R)$ : The average of best guess is the average of predicted variable.

$$\mathbb{E}(R \mid \mathcal{F}) = R;$$

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$$\mathbb{E}(2RS + R^2 \mid \mathcal{F}) = 2R\mathbb{E}(S \mid \mathcal{F}) + R^2.$$

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# Definition 4



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#### **Theorem**



$$\operatorname{Var}(R \mid \mathcal{F}) = \mathbb{E}(R^2 \mid \mathcal{F}) - (\mathbb{E}(R \mid \mathcal{F}))^2.$$

• Irrelevant information may be omitted:

If R is independent of  $\mathcal{F}$  then  $\mathbb{E}(R \mid \mathcal{F}) = \mathbb{E}(R)$  and  $\operatorname{Var}(R \mid \mathcal{F}) = \operatorname{Var}(R)$ .

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$$Var(2\exp(5W_t) \mid W_t) = 0;$$

- Irrelevant information may be omitted: If R is independent of  $\mathcal{F}$  then  $\mathbb{E}(R \mid \mathcal{F}) = \mathbb{E}(R)$  and  $\operatorname{Var}(R \mid \mathcal{F}) = \operatorname{Var}(R)$ .
- If R is known (measurable with respect to  $\mathcal{F}$ ), then we may treat R like a constant:

$$Var(2\exp(5W_t) \mid W_t) = 0;$$

$$Var(2RS + R^2 \mid \mathcal{F}) = (2R)^2 Var(S \mid \mathcal{F}) + 0.$$

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- Conditional variance  ${\rm Var}(R\mid X,Y)$  is the conditional expected value of the squared error of the best prediction.

# Martingales

# Martingales: short plan

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Reminder: Sigma-algebra  $\mathcal{F}_t$  is the collection of events.

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The filtration  $(\mathcal{F}_t, t \geq 0)$  is called a natural filtration of a process  $(X_t, t \geq 0)$  if at time t you have only the information about past values of the process,

$$\mathcal{F}_t = \sigma(X_u, u \in [0; t]).$$

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# Martingale

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Consider a filtration  $(\mathcal{F}_t, t \geq 0)$  and a process  $(M_t, t \geq 0)$ .

If the best prediction of the future value  $M_t$  of a process is its current value  $M_s$  for  $s \leq t$ ,

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Usually we consider natural filtration  $(\mathcal{F}_t)$  of the process  $(M_t)$ .

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This martingale is very useful in Black and Scholes model.

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Consider a filtration  $(\mathcal{F}_t, t \in \{0, 1, 2, ...\})$  and a process  $(M_t, t \in \{0, 1, 2, ...\})$ .

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is completely equivalent to

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