Lecture 5 Conditional Expectation

Peter Lukianchenko

7 October 2024

- ▶ It all starts with the definition of conditional probability: P(A|B) = P(AB)/P(B).
- If X and Y are jointly discrete random variables, we can use this to define a probability mass function for X given Y = y.
- ▶ That is, we write $p_{X|Y}(x|y) = P\{X = x | Y = y\} = \frac{p(x,y)}{p_Y(y)}$.
- In words: first restrict sample space to pairs (x, y) with given y value. Then divide the original mass function by $p_Y(y)$ to obtain a probability mass function on the restricted space.
- ▶ We do something similar when X and Y are continuous random variables. In that case we write $f_{X|Y}(x|y) = \frac{f(x,y)}{f_Y(y)}$.
- ▶ Often useful to think of sampling (X, Y) as a two-stage process. First sample Y from its marginal distribution, obtain Y = y for some particular y. Then sample X from its probability distribution given Y = y.
- Marginal law of X is weighted average of conditional laws.

- Let X be value on one die roll, Y value on second die roll, and write Z = X + Y.
- ▶ What is the probability distribution for X given that Y = 5?
- ► Answer: uniform on {1, 2, 3, 4, 5, 6}.
- ▶ What is the probability distribution for Z given that Y = 5?
- ► Answer: uniform on {6, 7, 8, 9, 10, 11}.
- ▶ What is the probability distribution for Y given that Z = 5?
- \triangleright Answer: uniform on $\{1, 2, 3, 4\}$.

- Now, what do we mean by E[X|Y = y]? This should just be the expectation of X in the conditional probability measure for X given that Y = y.
- Can write this as $E[X|Y=y] = \sum_{x} xP\{X=x|Y=y\} = \sum_{x} xp_{X|Y}(x|y).$
- Can make sense of this in the continuum setting as well.
- In continuum setting we had $f_{X|Y}(x|y) = \frac{f(x,y)}{f_Y(y)}$. So $E[X|Y=y] = \int_{-\infty}^{\infty} x \frac{f(x,y)}{f_Y(y)} dx$

4

- Let X be value on one die roll, Y value on second die roll, and write Z = X + Y.
- ▶ What is E[X|Y=5]?
- ▶ What is E[Z|Y=5]?
- ▶ What is E[Y|Z=5]?

- ▶ Can think of E[X|Y] as a function of the random variable Y. When Y = y it takes the value E[X|Y = y].
- ▶ So E[X|Y] is itself a random variable. It happens to depend only on the value of Y.
- Thinking of E[X|Y] as a random variable, we can ask what its expectation is. What is E[E[X|Y]]?
- ▶ Very useful fact: E[E[X|Y]] = E[X].
- ▶ In words: what you expect to expect X to be after learning Y is same as what you now expect X to be.
- Proof in discrete case: $E[X|Y=y] = \sum_{x} xP\{X=x|Y=y\} = \sum_{x} x\frac{p(x,y)}{p_Y(y)}$.
- ▶ Recall that, in general, $E[g(Y)] = \sum_{y} p_{Y}(y)g(y)$.
- ► $E[E[X|Y = y]] = \sum_{y} p_Y(y) \sum_{x} x \frac{p(x,y)}{p_Y(y)} = \sum_{x} \sum_{y} p(x,y)x = E[X].$

- Definition: $Var(X|Y) = E[(X E[X|Y])^2|Y] = E[X^2 E[X|Y]^2|Y].$
- Var(X|Y) is a random variable that depends on Y. It is the variance of X in the conditional distribution for X given Y.
- Note $E[Var(X|Y)] = E[E[X^2|Y]] E[E[X|Y]^2|Y] = E[X^2] E[E[X|Y]^2].$
- If we subtract E[X]² from first term and add equivalent value E[E[X|Y]]² to the second, RHS becomes Var[X] − Var[E[X|Y]], which implies following:
- ▶ Useful fact: Var(X) = Var(E[X|Y]) + E[Var(X|Y)].
- One can discover X in two stages: first sample Y from marginal and compute E[X|Y], then sample X from distribution given Y value.
- Above fact breaks variance into two parts, corresponding to these two stages.

- Let X be a random variable of variance σ_X^2 and Y an independent random variable of variance σ_Y^2 and write Z = X + Y. Assume E[X] = E[Y] = 0.
- ▶ What are the covariances Cov(X, Y) and Cov(X, Z)?
- ▶ How about the correlation coefficients $\rho(X, Y)$ and $\rho(X, Z)$?
- ▶ What is E[Z|X]? And how about Var(Z|X)?
- ▶ Both of these values are functions of X. Former is just X. Latter happens to be a constant-valued function of X, i.e., happens not to actually depend on X. We have $Var(Z|X) = \sigma_Y^2$.
- ► Can we check the formula Var(Z) = Var(E[Z|X]) + E[Var(Z|X)] in this case?

- Sometimes think of the expectation E[Y] as a "best guess" or "best predictor" of the value of Y.
- It is best in the sense that at among all constants m, the expectation $E[(Y m)^2]$ is minimized when m = E[Y].
- But what if we allow non-constant predictors? What if the predictor is allowed to depend on the value of a random variable X that we can observe directly?
- Let g(x) be such a function. Then $E[(y g(X))^2]$ is minimized when g(X) = E[Y|X].

- Toss 100 coins. What's the conditional expectation of the number of heads given the number of heads among the first fifty tosses?
- What's the conditional expectation of the number of aces in a five-card poker hand given that the first two cards in the hand are aces?

Conditional expectation, $\mathbb{E}(X | Y)$, is a random variable with randomness inherited from Y, not X.

Example: Suppose
$$Y = \begin{cases} 1 & \text{with probability } 1/8, \\ 2 & \text{with probability } 7/8, \end{cases}$$

and
$$X \mid Y = \begin{cases} 2Y & \text{with probability } 3/4, \\ 3Y & \text{with probability } 1/4. \end{cases}$$

Conditional variance

The conditional variance is similar to the conditional expectation.

- Var(X | Y = y) is the variance of X, when Y is fixed at the value Y = y.
- Var(X | Y) is a random variable, giving the variance of X when Y is fixed at a value to be selected randomly.

Definition: Let X and Y be random variables. The conditional variance of X, given Y, is given by

$$\mathit{Var}(X \,|\, Y) = \mathbb{E}(X^2 \,|\, Y) - \Big\{ \mathbb{E}(X \,|\, Y) \Big\}^2 = \mathbb{E}\Big\{ (X - \mu_{X \,|\, Y})^2 \,|\, Y \Big\}$$

If all the expectations below are finite, then for ANY random variables X and Y, we have:

i)
$$\mathbb{E}(X) = \mathbb{E}_Y \Big(\mathbb{E}(X \mid Y) \Big)$$
 Law of Total Expectation.

Note that we can pick any r.v. Y, to make the expectation as easy as we can.

ii)
$$\mathbb{E}(g(X)) = \mathbb{E}_Y \Big(\mathbb{E}(g(X) | Y) \Big)$$
 for any function g .

iii)
$$Var(X) = \mathbb{E}_Y \Big(Var(X \mid Y) \Big) + Var_Y \Big(\mathbb{E}(X \mid Y) \Big)$$

Law of Total Variance.

