

Optimization. Hi!! (W03)

W02: (KT theorem)

W03 cookbook procedure.

We have opt-n problem with inequalities.

Step 1

Avoid as much as poss.
solving opt-n problems with
inequalities.

Ex.

$$\max [5 - x_1^2 - x_2^2 + x_1 x_2 + 5x_1]$$

$$\text{s.t. } (x_1 + x_2 \geq 100)$$

↳ stand way: KT

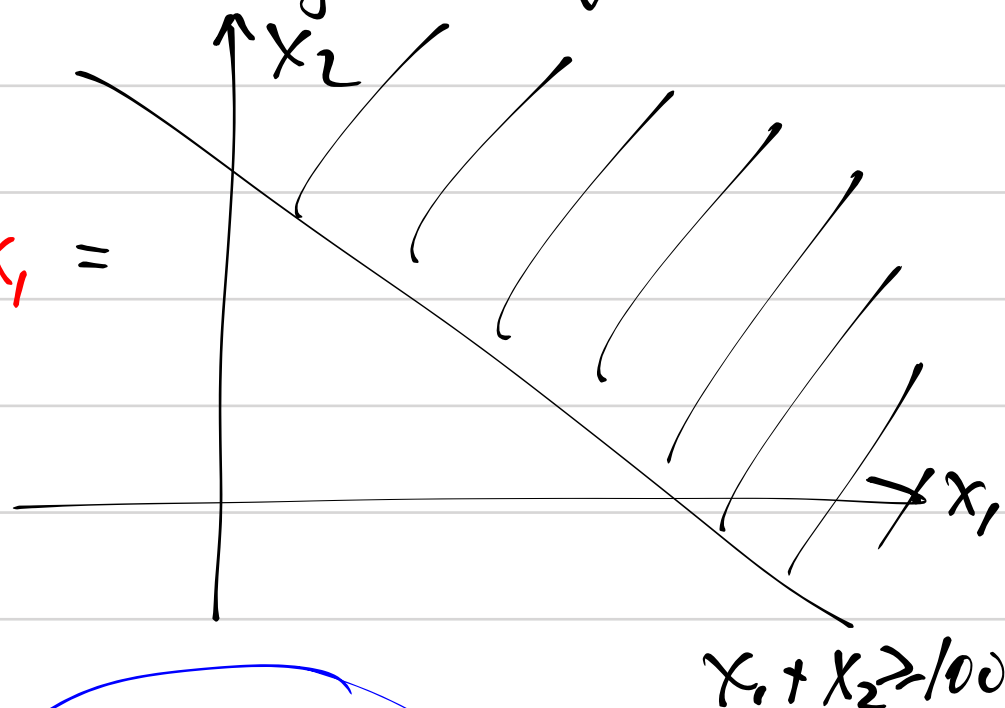
advice: stop and think whether you
can simplify it.

main quest: is it possible to transform
inequality into equality?

* monotonicity

* graphical analysis

*



$$f(x_1, x_2) = 5 - x_1^2 - x_2^2 + x_1 x_2 + 5x_1 =$$

$$-x_2^2 + 2 \cdot \frac{1}{2} x_1 x_2 - \frac{1}{4} x_1^2$$

$$= a^2 + 2ab - b^2$$

$$= 5 - x_2^2 + 2 \cdot \frac{1}{2} x_1 x_2 - \frac{1}{4} x_1^2 - \frac{3}{4} x_1^2 + 5x_1$$

$$= 5 - \left[x_2^2 + 2 \cdot \frac{1}{2} x_1 x_2 - \frac{1}{4} x_1^2 \right] - \frac{3}{4} x_1^2 + 5x_1 =$$

$$= 5 - \left(x_2 - \frac{1}{2} x_1 \right)^2 = \left(\sqrt{\frac{3}{4}} x_1 \right)^2 + 2 \cdot \left(\frac{1}{2} \cdot \sqrt{\frac{3}{4}} x_1 \cdot \sqrt{\frac{4}{3}} \cdot 5 \right) =$$

$$-a^2 + 2 \cdot a b - b^2$$

$$a = \sqrt{\frac{3}{4}} x_1$$

$$b = \frac{1}{2} \cdot \sqrt{\frac{4}{3}} \cdot 5 = \frac{5}{\sqrt{3}}$$

$$= 5 - \left(x_2 - \frac{1}{2} x_1 \right)^2 - \left(\sqrt{\frac{3}{4}} x_1 - \frac{5}{\sqrt{3}} \right)^2 + \frac{25}{3}$$

opt. without
constraints

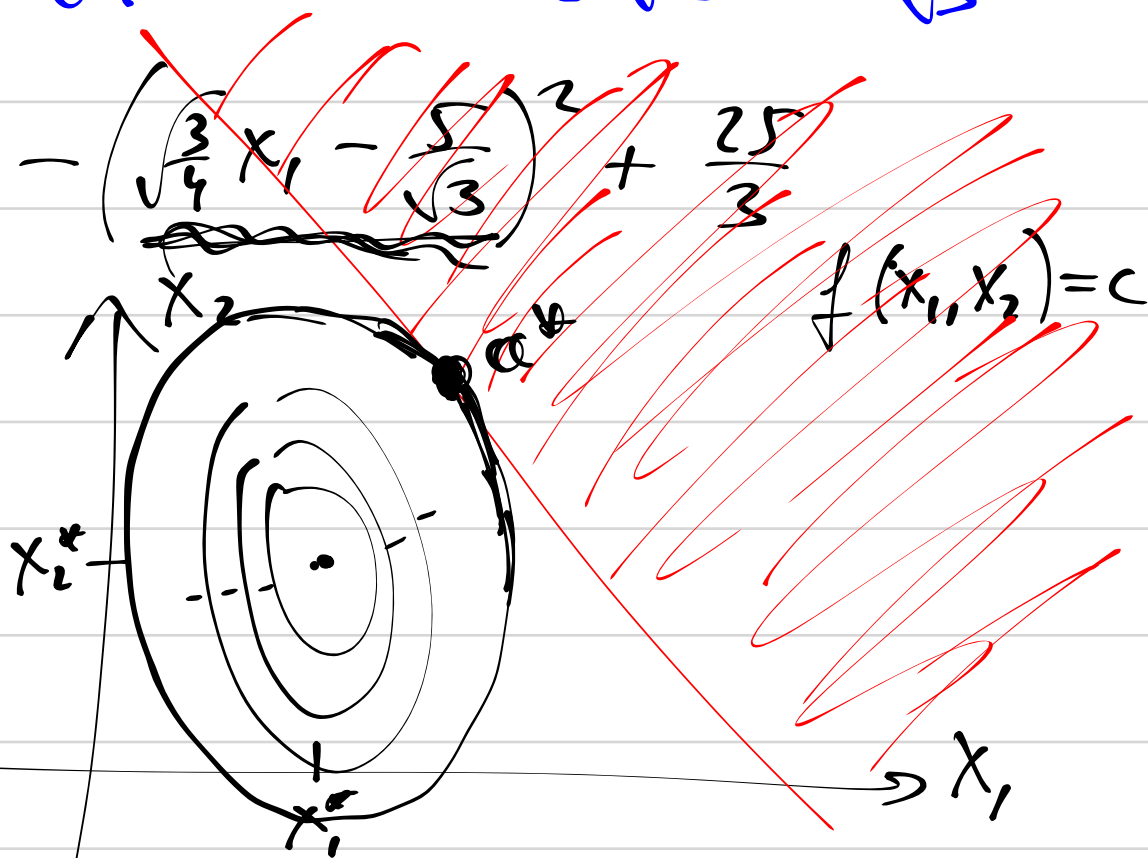
is located

$$\text{at: } x_2^* = \frac{1}{2} x_1^*$$

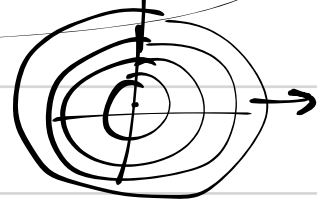
$$\sqrt{\frac{3}{4}} x_1^* = \frac{5}{\sqrt{3}}$$

$$x_1^* = \frac{5 \cdot 2}{3}$$

$$x_2^* = \frac{5}{3}$$



$$x_1^2 + x_2^2 = \text{const}$$



a^* is the constr. extremum.

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \rightarrow \begin{pmatrix} x_2 - \frac{1}{2} x_1 \\ \sqrt{\frac{3}{4}} x_1 - \frac{5}{\sqrt{3}} \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} & 1 \\ \sqrt{\frac{3}{4}} & 0 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ -\frac{5}{\sqrt{3}} \end{pmatrix}$$

Now:

max

$$5 - x_1^2 - x_2^2 + x_1 x_2 + 5x_1$$

s.t.

$$x_1 + x_2 = 100$$

$$x_2 = 100 - x_1$$

$$\max_{x_1} 5 - x_1^2 + x_1(100 - x_1) - (100 - x_1)^2 + 1x_1$$

hope you can finish from here //

ex 2.

Monotonicity.

global

max

$$x_1^2 \cdot x_2^3 \cdot x_3^5 \cdot x_4^6$$

$f(x_1, x_2, x_3, x_4)$

s.t.

$$x_1 \geq 0$$

$$x_2 \geq 0$$

$$x_3 \geq 0$$

$$x_4 \geq 0$$

$$x_1 + x_2 + x_3 + x_4 \leq 600$$

Idea 1: $x_1 = 0$ or $x_2 = 0$ or $x_3 = 0$ or $x_4 = 0$
are not optimal!

conclusion: $x_1 > 0$ $x_2 > 0$
 $x_3 > 0$ $x_4 > 0$

Idea 2. a point (x_1, x_2, x_3, x_4)
with $x_1 + x_2 + x_3 + x_4 < 600$
can't be optimal.

in such a point one can increase
 x_4 (or x_2 or x_1 or x_3) a little bit
and f will increase

conclusion:

$$x_1 + x_2 + x_3 + x_4 = 600$$

$$\max \quad (5 - x_1^2 - x_2^2 + x_1 x_2 + 5x_1)$$

$$\text{s.t.} \quad (x_1 + x_2 \geq 100)$$

cook book procedure

Step 1. Check NDCQ

Step 2. write Lagrangian function

Step 3. take (and solve) F.O.C

Step 4. check sufficiency conditions

Step 1.

we need to check NDCQ for all possible combinations of active constraints.

active constraint LHS = RHS

$$x_1 + x_2 \geq 100$$

act

non act

$$x_1 + x_2 = 100$$

$$x_1 + x_2 > 100$$

$$J = \left(\frac{\partial h}{\partial x_1}, \frac{\partial h}{\partial x_2} \right) = (1, 1)$$

$$\text{rank}(1, 1) = 1$$

$$\text{number of act} = 1$$

||

$$\text{rank} = 0$$

$$\text{number of act} = 0$$

||

NDCQ :

rank of the Jacobian matrix of active constraints is equal to the number of active constraints.

$$\begin{cases} h_1 \geq 0 \\ h_2 \geq 0 \\ h_3 \geq 0 \end{cases}$$

case 1

$$\begin{aligned} h_1 &= 0 \\ h_2 &= 0 \\ h_3 &= 0 \end{aligned}$$

case 2

$$\begin{aligned} h_1 &> 0 \\ h_2 &= 0 \\ h_3 &= 0 \end{aligned}$$

case 3

boundary !!

$$\text{max} \quad (5 - x_1^2 - x_2^2 + x_1 x_2 + 5x_1)$$

$$\text{s.t.} \quad (x_1 + x_2 \geq 100) \rightarrow x_1 + x_2 - 100 \geq 0$$

Step 2

$$\begin{cases} \text{max} f(x_1, \dots, x_n) \\ h_i(x_1, \dots, x_n) \geq 0 \end{cases}$$

$$L(x_1, x_2, \lambda) = f \pm \lambda \cdot h$$

$$L = 5 - x_1^2 - x_2^2 + x_1 x_2 + 5x_1 + \lambda(x_1 + x_2 - 100)$$

$$\text{min } 5 - x_1^2 - x_2^2 \dots$$

$$\text{max } -5 + x_1^2 + x_2^2 \dots$$

Step 3

F.O.C.

$$\frac{\partial L}{\partial x_1} = 0$$

$$\lambda \geq 0$$

$$\frac{\partial L}{\partial x_2} = 0$$

$$\frac{\partial L}{\partial \lambda} = x_1 + x_2 - 100 \geq 0$$

$$\text{compl. slack: } \lambda \cdot \frac{\partial L}{\partial \lambda} = 0$$

start solving from here

Case 1

$$\lambda = 0$$

$$\frac{\partial L}{\partial x_1} = -2x_1 + x_2 + 5 + \lambda = 0$$

$$\frac{\partial L}{\partial x_2} = -2x_2 + x_1 + \lambda = 0$$

$$\begin{cases} \lambda = 0 \\ x_1 = 2x_2 \\ -2(2x_2) + x_2 + 5 = 0 \end{cases}$$

$$x_2 = \frac{5}{3}$$

$$x_1 = \frac{10}{3}$$

$$\lambda = 0$$

$$\frac{5}{3} + \frac{10}{3} - 100 \geq 0 \quad [\text{FALSE}]$$

no points in case 1

Case 2

$$\lambda > 0$$

$$\frac{\partial L}{\partial \lambda} = 0$$

$$\frac{\partial L}{\partial x_1} = -2x_1 + x_2 + 5 + \lambda = 0$$

$$\frac{\partial L}{\partial x_2} = -2x_2 + x_1 + \lambda = 0$$

$$\frac{\partial L}{\partial \lambda} = x_1 + x_2 - 100 = 0$$

$$\begin{cases} -3x_1 + 3x_2 + 5 = 0 \\ x_1 + x_2 = 100 \quad (\times 3) \end{cases}$$

$$6x_2 + 5 = 300$$

$$x_2 = 295/6$$

$$x_1 = 100 - x_2 =$$

$$= \frac{600}{6} - \frac{295}{6} =$$

$$\lambda = 2x_2 - x_1 = \frac{590 - 305}{6} = \frac{285}{6}$$

one susp point:

$$x_1 = \frac{295}{6} \quad x_2 = \frac{305}{6}$$
$$\lambda = \frac{285}{6}$$

Step 4

- * graphical analysis
- * [soon] bordered Hessians
- * Weierstrass theorem
- *

we have already done it

Example

Step 1 only

check NDCQ

$$\begin{cases} x_1^2 + 2x_2^2 \leq 100 \\ x_1^3 \leq 1000 \end{cases}$$

case ①

$$\begin{cases} x_1^2 + 2x_2^2 < 100 \\ x_1^3 < 1000 \end{cases}$$

0 constraints
NDCQ holds

case ②

$$\begin{cases} x_1^2 + 2x_2^2 = 100 \\ x_1^3 < 1000 \end{cases}$$

$$J = (2x_1; 4x_2)$$

rank $J = 1$

number of active const = 1
NDCQ holds.

case ③

$$\begin{cases} x_1^2 + 2x_2^2 < 100 \\ x_1^3 = 1000 \end{cases}$$

$$x_1 = 10$$

$$J = (3x_1^2; 0) = (300; 0) \quad \text{rank } J = 1$$

number of active const = 1
NDCQ holds.

case ④

number of active const = 2

$$\begin{cases} x_1^2 + 2x_2^2 = 100 \\ x_1^3 = 1000 \end{cases}$$

$$J = \begin{pmatrix} 2x_1 & 4x_2 \\ 3x_1^2 & 0 \end{pmatrix}$$

$$J = \begin{pmatrix} 20 & 0 \\ 300 & 0 \end{pmatrix} \quad \text{rank} = 1$$

NDCQ fails

at $(x_1=10, x_2=0)$

$$x_1 = 10$$

we need to check it!