

(Weak) Stationarity.

struct. \rightarrow ETS(AAA) model
non-struct. \rightarrow solutions of ARMA $p-q$.

Forecasting Principles and Practice

ETS(AAA)

ETS seasonality (-|-)
trend (-|-)
error (A - additive)

y_t (observed) TS

$\beta = 0 \Leftrightarrow$
stable slope
of trend

unicorns

u_t - source of randomness

l_t - level (smooth. y_t) (deseasoned y_t)

b_t - trend growth rate [slope of trend]

s_t - seasonal component

(ETS(AAA))

$u_t \sim N(0; \sigma^2)$ independent.

$$s_t = s_{t-12} + \gamma \cdot u_t$$

same month
of past year

$$b_t = b_{t-1} + \beta \cdot u_t$$

$$l_t = l_{t-1} + b_{t-1} + \alpha \cdot u_t$$

$$y_t = l_{t-1} + b_{t-1} + s_{t-12} + u_t$$

(ETS(AAA))

$[s_0, s_{-1}, s_{-2}, \dots, s_{-11}]$

$$s_0 + s_{-1} + s_{-2} + \dots + s_{-11} = 0$$

$\leftarrow b_0$

$\leftarrow l_0$

init. cond

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(ETS(AAA))

$$S_0, S_{-1}, S_{-2}, \dots, S_{-11}$$

$$S_0 + S_{-1} + S_{-2} + \dots + S_{-11} = 0$$

$$\leftarrow b_0$$

$$\leftarrow l_0$$

(ETS(AAN))

init. cond

Ex.

18 par + 1 constraint on them

17 free param

a) How many param. s are there

$$b) E(y_1), E(y_2), E(y_t)$$

$$d) I > (y_t) \text{ stationary?}$$

$$c) \text{Var}(y_1), \text{Var}(y_2)$$

$$\sigma^2, S_0, \dots, S_{-11}, b_0, l_0$$

$$\alpha, \beta, \gamma$$

const: $l_0, b_0, S_0, S_{-1}, \dots, S_{-11}$

$$b_1 = b_0 + \beta \cdot u_1 \leftarrow \text{random var. } b$$

$$l_1 = \underbrace{l_0 + b_0}_{\text{const}} + \underbrace{\alpha \cdot u_1}_{\text{random}}$$

$$E(y_1) = E(l_0 + b_0 + S_{-11} + u_1) = l_0 + b_0 + S_{-11} + 0$$

$$\text{Var}(y_1) = \text{Var}(l_0 + b_0 + S_{-11} + u_1) = \sigma^2$$

$$E(y_2) = E(l_1 + b_1 + S_{-10} + u_2) =$$

$$= E((l_0 + b_0 + \alpha \cdot u_1) + (b_0 + \beta \cdot u_1) + S_{-10} + u_2) =$$

$$= l_0 + b_0 + 0 + b_0 + S_{-10} + 0 =$$

$$= l_0 + 2b_0 + S_{-10}$$

exp trend exp seas

$$E(y_{100}) = l_0 + 100b_0 + S_{-8}$$

$S_{99} = 2v$

$S_0, S_{-1}, \dots, S_{-11}$

const

$$y_{100} \rightarrow S_{98} \rightarrow S_{96} \rightarrow \dots \rightarrow S_{-8}$$

def

(y_t) is stationary

$$E(y_t) = \mu$$

$$\text{Var}(y_t) = \gamma_0$$

$$\text{Cov}(y_t, y_{t-1}) = \gamma_1$$

$$\text{Cov}(y_t, y_{t-2}) = \gamma_2$$

$$\text{Cov}(y_t, y_{t-k}) = \gamma_k$$

$$d) y_t \sim \text{ETS}(AAA)$$

$$E(y_t) \neq \text{const}$$

$$\text{Var}(y_t) \neq \text{const}$$

not stationary

$$e) l_{100} = 10 \quad b_{100} = 3 \quad S_{89} = -2 \quad S_{90} = 4 \quad \sigma^2 = 9$$

$$L = \beta = \gamma = \frac{1}{2}$$

$$F_{100} = \mathcal{F}(y_{100}, y_{99}, \dots)$$

95% PI for y_{101} given F_{100}

95% PI for y_{102} given F_{100}

indep

$$E(y_{101} | F_{100}) = E(l_{100} + b_{100} + S_{89} + u_{101} | F_{100}) =$$

$$= \underbrace{l_{100}}_{\text{EV}} + \underbrace{b_{100}}_{\text{EV}} + \underbrace{S_{89}}_{\text{EV}} + \underbrace{E(u_{101})}_{0} =$$

$$= 10 + 3 - 2 = 11$$

we know only param of the model

difference

$$E(y_{101}) - E(y_{101} | F_{100})$$

$$\text{Var}(y_{101} | F_{100}) = l_0 + 10/b_0 + S_{-7}$$

$$\begin{aligned} \text{Var}(l_{100} + b_{100} + S_{89} + u_{101} | F_{100}) &= l_{100} + b_{100} + S_{89} \\ &= \text{Var}(u_{101} | F_{100}) = \text{Var}(u_{101}) = 9 \end{aligned}$$

we know y_1, \dots, y_{100} + param of the model

$$\text{PI} \quad [11 - 1.96\sqrt{9}; 11 + 1.96\sqrt{9}]$$

! Warning !

! Achtung !

Equations can have many solutions

Ex.

$u_t \sim N(0, 9)$ indep.

$$y_t = 0.5 y_{t-1} + u_t + u_{t-1}$$

ARMA [equation]

[!] equation can have ∞ [!] solutions

11
a)

$$y_0 = 10$$

$E(y_1), E(y_2), E(y_t)?$
 $\text{Var}(y_1), \text{Var}(y_2)?$

is (y_t) stat-ry?

b)

$$y_0 = u_0$$

$E(y_t)?$ $\text{Var}(y_1)?$ $\text{Var}(y_2)$

is (y_t) stat-ry?

c*)

find y_0 such that (y_t) is stat-nary.

$$y_0 \neq 10$$

$$y_1 = 5 + u_1 + u_0$$

$$E(y_1) = 5$$

$$y_2 = 0.5(5 + u_1 + u_0) + u_2 + u_1$$

$$E(y_2) = 2.5$$

$$y_3 = 0.5(= [y_2] =) + u_3 + u_2$$

$$E(y_t) = 0.5 E(y_{t+1}) + 0 + 0$$

$$E(y_t) = \frac{10}{2^t}$$

(y_t) is not stat-ry

$$\text{Var}(y_1) = \text{Var}(5 + u_1 + u_0) = 9 + 9 = 18$$

$$\text{Var}(y_2) = \text{Var}(0.5 u_1 + 0.5 u_0 + u_2 + u_1) = \text{Var}\left(\frac{1}{2} u_0 + 1.5 u_1 + u_2\right)$$

$$= \left(\frac{1}{2}\right)^2 \cdot 9 + (1.5)^2 \cdot 9 + 1^2 \cdot 9$$

$$b) E(y_0) = E(u_0) = 0 \Rightarrow E(y_1) = 0 \Rightarrow E(y_2) = 0 \dots$$

$$\begin{aligned}\text{Var}(y_1) &= \text{Var}(0.5 \cdot u_0 + u_1 + u_0) = \\ &= \text{Var}(u_1 + 1.5u_0) = 9 + 1.5^2 \cdot 9\end{aligned}$$

$$\text{Var}(y_2) = \text{Var}(0.5(y_1) + u_2 + u_1) = \dots \neq \text{Var}(y_1)$$

(y_t) is not stationary.

c) $y_0 = ?$ to make (y_t) stationary?

Strategy 1.

sd

$$y_t = u_t + \alpha_1 \cdot u_{t-1} + \alpha_2 \cdot u_{t-2} + \dots$$

$\nearrow \text{MA}(\infty)$

$$(y_1) = u_1 + \alpha_1 \cdot u_0 + \alpha_2 \cdot u_{-1} + \dots$$

$$y_2 = u_2 + \alpha_1 \cdot u_1 + \alpha_2 \cdot u_0 + \dots$$

$$\text{Var}(y_1) = 1^2 \cdot 9 + \alpha_1^2 \cdot 9 + \alpha_2^2 \cdot 9 + \dots$$

$$\text{Var}(y_2) = 1^2 \cdot 9 + \alpha_1^2 \cdot 9 + \dots$$

$$y_t = 0.5 y_{t-1} + u_t + u_{t-1} \quad \text{orig. equat.}$$

$$\underline{u_t} + \underline{\alpha_1 u_{t-1}} + \alpha_2 u_{t-2} + \alpha_3 u_{t-3} = 0.5 \left(\underline{u_{t-1}} + \underline{\alpha_1 u_{t-2}} + \alpha_2 u_{t-3} + \dots \right) + \underline{u_t} + \underline{u_{t-1}}$$

coef	LHS	RHS
u_t	1	1
u_{t-1}	α_1	$0.5 + 1$
u_{t-2}	α_2	$0.5 \cdot \alpha_1$
u_{t-3}	α_3	$0.5 \cdot \alpha_2$
\vdots	\vdots	\vdots

$$\alpha_1 = 1.5$$

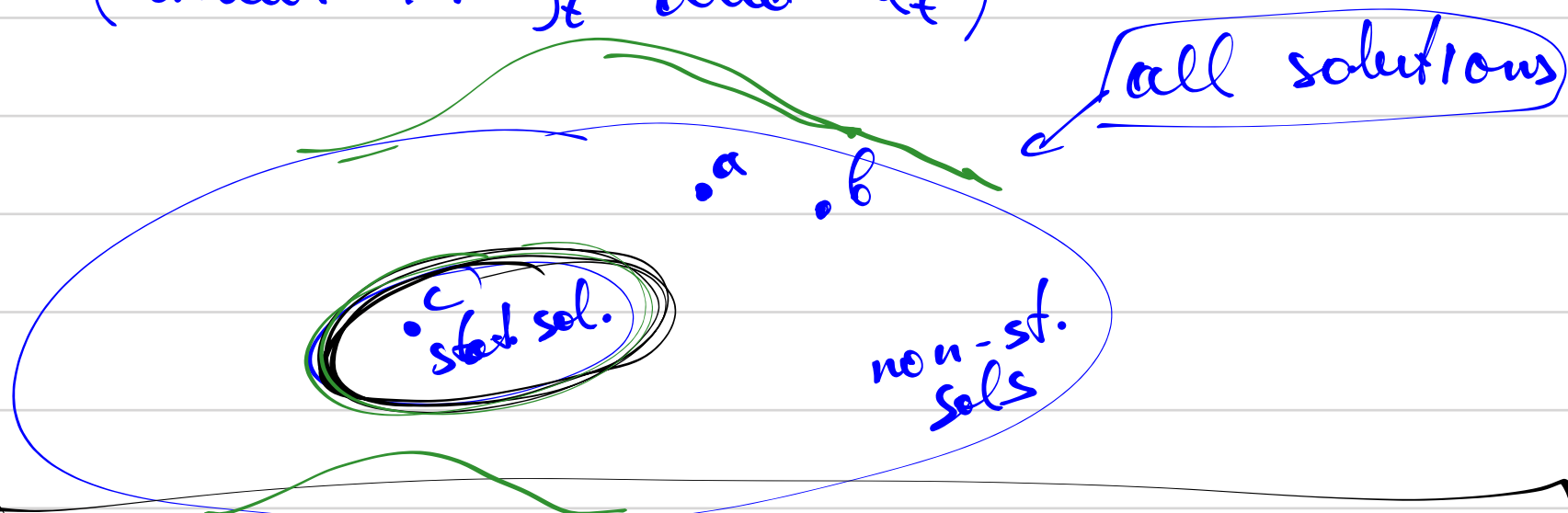
$$\alpha_2 = 0.75$$

\vdots

ARMA-type equation

$$y_t = 0.5y_{t-1} + u_t + u_{t-1}$$

(linear in y_t and u_t)



th: If we multiply or divide an ARMA-type eq-n by $P(L)$ with no unit roots then the set of stationary solutions will not change.

$$(1 - 0.5L) \cdot y_t = (1 + L) \cdot u_t$$

$$(*) \quad y_t = \frac{1+L}{1-0.5L} u_t = (1+L) \cdot \frac{1}{1-0.5L} \cdot u_t \quad \ominus$$

$$\frac{1}{1-q} = 1 + q + q^2 + q^3 + q^4 + \dots$$

$$\ominus (1+L) \cdot (1 + 0.5L + (0.5L)^2 + (0.5L)^3 + \dots) \cdot u_t$$

$$= (1 + L \cdot (1 + 0.5) + L^2 \cdot (0.5 + 0.5^2) + L^3 (0.5^2 + 0.5^3) + \dots) u_t$$

$$y_t = u_t + 1.5u_{t-1} + (0.5 + 0.5^2)u_{t-2} + (0.5^2 + 0.5^3)u_{t-3} + \dots$$

$$(*) \quad y_0 = u_0 + 1.5u_{-1} + (0.5 + 0.5^2)u_{-2} + \dots$$

↑ limit cond

$$\Rightarrow y_1 = u_1 + 1.5u_0 + \dots$$

$$y_2 = u_2 + 1.5u_1 + \dots$$