

Prüfer

li



3 ha = 3 months x 3 hrs

4/9

Exer (\*)  $y_t = 0.5y_{t-1} - 0.06y_{t-2} + u_t$   $u_t \sim \text{white noise}$

- One stat. soln  
MA( $\infty$ ) wrt ( $u_t$ )
- lag polynomial, characteristic polynomial.
  - Are there any stationary sol-s of (\*)
  - can stationary solution (if it exists) be written as MA( $\infty$ ) wrt ( $u_t$ )?

$$(1 - 0.5L + 0.06L^2)y_t = u_t \rightarrow \text{roots } l_1 = \frac{1}{0.2} \quad l_2 = \frac{1}{0.3}$$

$$P(l) = 1 - 0.5l + 0.06l^2$$

lag polynomial of AR part

characteristic polynomial

$$y_t - 0.5y_{t-1} + 0.06y_{t-2} = 0 \quad (\text{no } u_t) \quad (\text{const})$$

let's find simple solutions  $y_t = \lambda^t$

$$\lambda^t - 0.5\lambda^{t-1} + 0.06\lambda^{t-2} = 0 \quad \text{roots}$$

$$\text{char}(\lambda) = \lambda^2 - 0.5\lambda + 0.06 \quad \lambda_1 = 0.2 \quad \lambda_2 = 0.3$$

characteristic polynomial of AR part

[Th] equation  $P(L) \cdot y_t = c + Q(L) \cdot u_t$ ,  
 $u_t$  is a white noise.

If lag polynomials of AR and MA part have no common roots then there 3 cases:

- No stationary solutions  $\left\{ \begin{array}{l} \text{There is a root of lag poly } |l|=1 \\ \text{there is a root of char poly } |l|=1 \end{array} \right.$

- Unique stationary solution of the form

$$y_t = \mu + u_t + c_1 u_{t-1} + c_2 u_{t-2} + \dots \quad \text{MA}(\infty) \text{ wrt } (u_t)$$

- Unique stationary solution of the form

$$y_t = \mu + v_t + c_1 v_{t-1} + c_2 v_{t-2} + \dots \quad \text{MA}(\infty) \text{ wrt } (v_t) \text{ where } v_t \text{ is a white noise different from } u_t$$

ALL roots  $|l| > 1$   
ALL roots  $|l| < 1$

No  $|l|=1$ ,  $\exists |l| > 1$

No  $|l|=1$ ,  $\exists |l| < 1$

Ex.  $y_t = 6y_{t-1} - 10y_{t-2} + u_t + u_{t-1}$   $u_t \sim \text{white noise}$

One

No

a) how many stationary solutions are there?

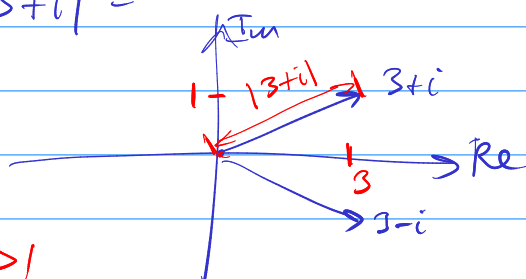
b) can the stationary solution be written as  $MA(\infty)$  w.r.t  $(u_t)$ ?

char-c poly of AR part:  $\lambda^2 - 6\lambda + 10 = 0$   
 MA part:  $\lambda + 1 = 0$

roots AR part:  $\lambda^2 - 6\lambda + 9 + 1 = 0$   $(\lambda - 3)^2 = -1$   
 MA part:  $\lambda_1 = -1$   $\lambda - 3 = \pm i$   
 $\lambda_1 = 3 - i$   
 $\lambda_2 = 3 + i$

no common roots of AR and MA part.

$|3 - i| = |3 + i| =$



$\text{Re}(3+i) = 3$

$|3+i| = \sqrt{3^2 + 1^2} = \sqrt{10} > 1$

$|3-i| = \dots = \sqrt{10} > 1$

Ex

non-causal  $y_t$

$y_t = u_t + \frac{1}{2}u_{t+1} + \left(\frac{1}{2}\right)^2 u_{t+2} + \left(\frac{1}{2}\right)^3 u_{t+3} \dots$   $u_t \sim \text{white noise}$

Yes

No

a) is this a stationary process?

b) is it  $MA(\infty)$  w.r.t  $(u_t)$ ?

c)  $\text{Cov}(y_t, y_{t-1})$ ?

causal  $y_t$

$MA(\infty)$  w.r.t to  $(u_t)$  :  $y_t = \mu + u_t + c_1 u_{t-1} + c_2 u_{t-2} + c_3 u_{t-3} + \dots$

a)  $E(y_t) = 0 + \frac{1}{2}0 + \dots = 0$

$\text{Var}(y_t) = \sigma_u^2 + \left(\frac{1}{2}\right)^2 \sigma_u^2 + \left(\frac{1}{2}\right)^4 \sigma_u^2 + \left(\frac{1}{2}\right)^6 \sigma_u^2 + \dots = \text{const} = \frac{\sigma_u^2}{1 - \left(\frac{1}{2}\right)^2} = \frac{\sigma_u^2}{1 - \frac{1}{4}}$

b) NO

d)  $\text{Cov}(u_t + \frac{1}{2}u_{t+1} + (\frac{1}{2})^2 u_{t+2} + (\frac{1}{2})^3 u_{t+3} + \dots,$

$u_{t-1} + \frac{1}{2}u_t + (\frac{1}{2})^2 u_{t+1} + (\frac{1}{2})^3 u_{t+2} + (\frac{1}{2})^4 u_{t+3} + \dots) =$

$= \frac{1}{2}\sigma_u^2 + \frac{1}{2}(\frac{1}{2})^2 \cdot \sigma_u^2 + (\frac{1}{2})^2 \cdot (\frac{1}{2})^3 \cdot \sigma_u^2 + (\frac{1}{2})^3 \cdot (\frac{1}{2})^4 \sigma_u^2 + \dots =$

$= \frac{\frac{1}{2}\sigma_u^2}{1 - (\frac{1}{2})^2} = \frac{2\sigma_u^2}{3}$

ARMA(2,1) model/process

$y_t = ?y_{t-1} + ?y_{t-2} + c + u_t + ?u_{t-1}$

$y_t = ? + u_t + ?u_{t-1} + ?u_{t-2} + \dots$

- ⊕  $(y_t)$  is stationary
- ⊕  $MA(\infty)$  w.r.t  $(u_t)$
- ⊕  $PL(y_t) = \alpha(L) \cdot u_t + c$
- $PL()$  and  $Q(L)$  have no common roots.

$y_t$  is  $MA(\infty)$  w.r.t  $(u_t) \Rightarrow y_t$  is stationary.

Ex.

ARMA(2,0) model = AR(2) model

with equation  $y_t = 5 + 0.3y_{t-1} + u_t, u_t \sim \text{noise.}$   
 $u_t \sim N(0, 16)$

- a) autocov function  $\gamma_k$ ? partial autocov-n  $\psi_{kk}$ ?
- b)  $y_{100} = 10$  PI 95% for  $y_{101}$ ?
- c)  $y_{100} = 10$  PI 95% for  $y_{100000}$ ?

d) represent  $y_t$  as  $MA(\infty)$  w.r.t  $(u_t)$ .

a)  $\text{Cov}(y_t, y_{t+k}) = \frac{\text{Cov}(y_t, y_{t+k})}{\sqrt{\text{Var}(y_t) \text{Var}(y_{t+k})}} = \frac{\text{Cov}(y_t, y_{t+k})}{\text{Var}(y_t)} = \frac{\gamma_k}{\gamma_0}$

$$y_t = 5 + 0.3 y_{t-1} + u_t$$

$$\mu + u_{t-1} + ? u_{t-2} + ? u_{t-3} \dots$$

$y_0$ :

$$\text{Var}(y_t) = 0.3^2 \text{Var}(y_{t-1}) + \text{Var}(u_t) + 2 \cdot 0.3 \text{Cov}(y_{t-1}, u_t)$$

$\uparrow \qquad \qquad \qquad \uparrow \qquad \qquad \qquad 16 \qquad \qquad \qquad \downarrow 0$

$$y_0 = 0.09 \cdot y_0 + 16 \qquad y_0 = \frac{16}{0.91}$$

$$\text{Cov}(y_{t-1}, y_t) = \text{Cov}(y_{t-1}, 5 + 0.3 y_{t-1} + u_t)$$

$$y_1 = 0.3 y_0 + 0$$

$$\text{Cov}(y_{t-2}, y_t) = \text{Cov}(y_{t-2}, 5 + 0.3 y_{t-1} + u_t)$$

$$y_2 = 0.3 \cdot y_1 + 0$$

$$y_3 = 0.3 \cdot y_2$$

$$\rho_1 = \text{Cov}(y_t, y_{t-1}) = \frac{y_1}{y_0} = 0.3$$

$$\rho_2 = \text{Cov}(y_t, y_{t-2}) = \frac{y_2}{y_0} = 0.3^2$$

$$\vdots$$

$$\rho_k = 0.3^k$$

$$\text{Cov} = 0.3^k$$

$$y_t \quad y_{t+1} \quad y_{t+2} \quad \dots \quad y_{t+k}$$

$$\varphi_{kk} = \rho \text{Cov}(y_t, y_{t+k} ; y_{t+1}, y_{t+2}, \dots, y_{t+k-1})$$

$$\varphi_{11} = \rho \text{Cov}(y_t, y_{t+1} ; \emptyset) = \text{Cov}(y_t, y_{t+1}) = 0.3 = \rho_1$$

$$\varphi_{22} = \rho \text{Cov}(y_t, y_{t+2} ; y_{t+1})$$

$$y_t = 5 + 0.3 y_{t-1} + u_t$$

decomposition

$$y_t = \alpha + \varphi_{21} \cdot y_{t-1} + \varphi_{22} \cdot y_{t-2} + w_t$$

$$\begin{cases} \text{Cov}(y_{t-1}, w_t) = 0 \\ \text{Cov}(y_{t-2}, w_t) = 0 \end{cases} \Rightarrow \varphi_{22} ?$$

$$\begin{aligned} \alpha &= 5 \\ \varphi_{21} &= 0.3 \\ \varphi_{22} &= 0 \end{aligned}$$

$$y_t = 5 + 0.3 y_{t-1} + 0 \cdot y_{t-2} + u_t$$

$$\begin{cases} \text{Cov}(y_{t-1}, u_t) = 0 \\ \text{Cov}(y_{t-2}, u_t) = 0 \end{cases}$$