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- $(\Omega, \mathcal{F}, \mathbb{P})$  a probability space
- X, Z two random variables
- elementary conditional probability :

$$\mathbb{P}[X=x \mid Z=z] = \mathbb{P}[X=x,Z=z]/\mathbb{P}[Z=z]$$

elementary conditional expectation :

$$\mathbb{E}[X \mid Z = z] = \sum_{X} x \mathbb{P}[X = X \mid Z = z]$$

- $Y = \mathbb{E}[X \mid \sigma(Z)]$ ?
  - Y is measurable with respect to  $\sigma(Z)$
  - $\bullet \ \mathbb{E}[Y1_{Z=z}] = \mathbb{E}[X1_{Z=z}]$

- $(\Omega, \mathcal{F}, \mathbb{P})$  is a probability space
- X is a random variable on the probability space with  $\mathbb{E}[|X|] < \infty$
- $A \subset \mathcal{F}$  is a sub  $\sigma$ -algebra

Then there exists a random variable Y such that

- Y is  $\mathcal{A}$ -measurable with  $\mathbb{E}[|Y|] < \infty$
- for any  $A \in \mathcal{A}$ , we have  $\mathbb{E}[Y1_A] = \mathbb{E}[X1_A]$ .

Moreover, if  $\tilde{Y}$  also satisfies the above two properties, then  $\tilde{Y} = Y$  a.s. A random variable Y with the above two properties is called the **conditional expectation** of X given A, and we denote it by  $\mathbb{E}[X \mid A]$ .

#### Remark:

- If  $A = \{\emptyset, \Omega\}$ , then  $\mathbb{E}[X | A] = \mathbb{E}[X]$ .
- If X is A-measurable, then  $\mathbb{E}[X \mid A] = X$ .
  - If  $Y = \mathbb{E}[X \mid A]$ , then  $\mathbb{E}[Y] = \mathbb{E}[X]$   $A = \begin{cases} \begin{cases} k \text{ of } -10-20-21 \end{cases}, \begin{cases} k \text{ of } -10-20-21 \end{cases}, \begin{cases} k \text{ of } -10-20-21 \end{cases} \end{cases}$   $\chi_{8} 5^{k} \cdot p^{k} \in \mathcal{Q} \quad \text{ell} \quad \text{ell} \quad \chi_{8}$

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- ▶ **Probability space** is triple  $(\Omega, \mathcal{F}, P)$  where  $\Omega$  is sample space,  $\mathcal{F}$  is set of events (the  $\sigma$ -algebra) and  $P : \mathcal{F} \to [0, 1]$  is the probability function.
- $\sigma$ -algebra is collection of subsets closed under complementation and countable unions. Call  $(\Omega, \mathcal{F})$  a measure space.
- ▶ **Measure** is function  $\mu : \mathcal{F} \to \mathbb{R}$  satisfying  $\mu(A) \ge \mu(\emptyset) = 0$  for all  $A \in \mathcal{F}$  and countable additivity:  $\mu(\cup_i A_i) = \sum_i \mu(A_i)$  for disjoint  $A_i$ .
- ▶ Measure  $\mu$  is **probability measure** if  $\mu(\Omega) = 1$ .

4

- ▶ monotonicity:  $A \subset B$  implies  $\mu(A) \leq \mu(B)$
- ▶ subadditivity:  $A \subset \bigcup_{m=1}^{\infty} A_m$  implies  $\mu(A) \leq \sum_{m=1}^{\infty} \mu(A_m)$ .
- ▶ continuity from below: measures of sets  $A_i$  in increasing sequence converge to measure of limit  $\bigcup_i A_i$
- **continuity from above:** measures of sets  $A_i$  in decreasing sequence converge to measure of intersection  $\bigcap_i A_i$

#### Why not all Subsets are Sigma-Algebra?

- ▶ Uniform probability measure on [0,1) should satisfy **translation invariance:** If B and a horizontal translation of B are both subsets [0,1), their probabilities should be equal.
- ▶ Consider wrap-around translations  $\tau_r(x) = (x + r) \mod 1$ .
- ▶ By translation invariance,  $\tau_r(B)$  has same probability as B.
- ▶ Call x, y "equivalent modulo rationals" if x y is rational (e.g.,  $x = \pi 3$  and  $y = \pi 9/4$ ). An **equivalence class** is the set of points in [0,1) equivalent to some given point.
- ▶ There are uncountably many of these classes.
- Let  $A \subset [0,1)$  contain **one** point from each class. For each  $x \in [0,1)$ , there is **one**  $a \in A$  such that r = x a is rational.
- ▶ Then each x in [0,1) lies in  $\tau_r(A)$  for **one** rational  $r \in [0,1)$ .
- ▶ Thus  $[0,1) = \cup \tau_r(A)$  as r ranges over rationals in [0,1).
- ▶ If P(A) = 0, then  $P(S) = \sum_r P(\tau_r(A)) = 0$ . If P(A) > 0 then  $P(S) = \sum_r P(\tau_r(A)) = \infty$ . Contradicts P(S) = 1 axiom.

- ▶ The **Borel**  $\sigma$ -algebra  $\mathcal{B}$  is the smallest  $\sigma$ -algebra containing all open intervals.
- Say that B is "generated" by the collection of open intervals.
- ▶ Why does this notion make sense? If  $\mathcal{F}_i$  are  $\sigma$ -fields (for i in possibly uncountable index set I) does this imply that  $\bigcap_{i \in I} \mathcal{F}_i$  is a  $\sigma$ -field?

A filtration is a non-decreasing family of sub  $\sigma$ -algebras of  $\mathcal{F}$  indexed by time, i.e. a family  $\mathbb{F} := (\mathcal{F}_t)_{t \in \mathbb{T}}$  such that

$$\mathcal{F}_s \subseteq \mathcal{F}_t$$
,

for  $s \leq t$ , where  $t, s \in \mathbb{T}$ .

Let  $\mathbb{F}$  be a (continuous time) filtration. We say that  $\mathbb{F}$  is the **right-continuous filtration** if for any  $t \in \mathbb{T}$  we get

$$\mathcal{F}_t = \mathcal{F}_{t_+}$$
,

where 
$$\mathcal{F}_{t_+} := \bigcap_{s>t,s\in\mathbb{T}} \mathcal{F}_s$$
.

$$\mathcal{F}_1$$
  $\mathcal{F}_2$   $\mathcal{F}_3$  ...  $\mathcal{F}_4$ 

$$\mathcal{F}_2$$
  $\mathcal{F}_3$  ...  $\mathcal{F}_4$  ...  $\mathcal{F}_{14,04}$  ....

process X is said to be **adapted** to filtration  $\mathbb{F}$  (or  $\mathbb{F}$ -adapted) if  $X_t$  is  $\mathcal{F}_t$ -measurable for any  $t \in \mathbb{T}$ .

Let X be a stochastic process. We say that  $\mathbb{F}^X := (\mathcal{F}^X_t)_{t \in \mathbb{T}}$ , where

$$\mathcal{F}_t^X = \sigma(X_s, s \le t, s \in \mathbb{T})$$

is a filtration **generated** by stochastic process X.

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a standard probability space with  $\Omega = [0, 1]$ . Let

$$\mathcal{A} := \sigma(N \subset [0,1] : \#N < \infty)$$

denote the  $\sigma$ -algebra of countable sets (and their complements). For time horizon  $\mathbb{T} = [0, +\infty)$  we define filtration  $\mathbb{F} = (\mathcal{F}_t)_{t \in \mathbb{T}}$  by setting

$$\mathcal{F}_t := \begin{cases} \mathcal{A} & \text{for } t \in [0, 1); \\ \mathcal{F} & \text{for } t \in [1, \infty). \end{cases}$$

Next, we define a stochastic process  $X = (X_t)_{t \in \mathbb{T}}$  by setting

$$X_t(\omega) := \mathbbm{1}_{\Delta}(t,\omega) = \begin{cases} 1 & \text{if } t = \omega \text{ and } t \leq 1/2 \\ 0 & \text{otherwise} \end{cases}, \qquad t \in \mathbb{T}, \omega \in \Omega.$$

where  $\Delta := \{(t,t) : t \in [0,\frac{1}{2}]\}$  is a subset of  $\mathbb{T} \times \Omega$ .

#### Definition (Moments)

Let X be a discrete random variable, and let  $n\geqslant 1$  be an integer. The number

$$E(X^n) = \sum_x x^n p_X(x)$$

is called the n-th moment of X. Notice that the first moment is the mean.

#### Definition

Let X be a discrete random variable. The function

$$M_X(t) = E(e^{tX})$$

is called the moment generating function (MGF) of X.

#### Problem (Geometric)

Let X be geometric with parameter p. Show that

$$M_X(t) = rac{pe^t}{1 - qe^t}.$$

#### Problem (Binomial)

Let X be binomial with parameters n and p. Show that

$$M_X(t) = (pe^t + q)^n.$$

#### Problem (Poisson)

Let X be Poisson with parameter  $\lambda$ . Show that

$$M_{X}(t) = e^{\lambda(e^{t}-1)}.$$

$$P(\chi = \alpha) = \frac{\chi^{2} e^{\lambda}}{\chi^{1}}$$

$$P(\chi = \alpha) = \frac{\chi^{2} e^{\lambda}}{\chi^{2}}$$

$$P(\chi = \alpha) = \frac{\chi^{2} e$$

#### Theorem

Let X be a discrete random variable. Then

$$M_X'(0)=E(X).$$
 In general, for each  $n\geqslant 1$ , 
$$\bigvee_{x\in C}(x):=\bigvee_{x}(o)-\left(\bigvee_{x}(o)\right)^2$$
  $M_X^{(n)}(0)=E(X^n).$ 

#### Theorem

1. Let X be geometric with parameter p. Then

$$E(X) = 1/p$$
 and  $var(X) = q/p^2$ .

2. Let X be binomial with parameters n and p. Then

$$E(X) = np$$
 and  $var(X) = npq$ .

#### Theorem (Change of Scale Theorem)

Let Y = aX + b, where a and b are real numbers and X is a random variable. Then  $M_Y(t) = e^{tb}M_X(at)$ .

#### Theorem (Uniqueness Theorem)

Let X and Y be random variables. If  $M_X(t) = M_Y(t)$  for all  $t \in [-a, a]$  for some positive real number a, then X and Y have the same distribution, that is,  $F_X = F_Y$ .