Time Series

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ARMA models

Autoregressive Moving-Average Models

 $\{\varepsilon_t\}$ is a white noise

• ARMA(1, 1)

$$Y_t = \theta Y_{t-1} + \varepsilon_t + \varphi \varepsilon_{t-1}$$

ARMA(p, q)

$$Y_t = \theta_1 Y_{t-1} + \theta_2 Y_{t-2} + \cdots + \theta_p Y_{t-p} + \varepsilon_t + \varphi_1 \varepsilon_{t-1} + \varphi_2 \varepsilon_{t-2} + \cdots + \varphi_q \varepsilon_{t-q}$$

More general ARMA(p, q)

$$Y_t = c + \theta_1 Y_{t-1} + \theta_2 Y_{t-2} + \cdots + \theta_p Y_{t-p} + \varepsilon_t + \varphi_1 \varepsilon_{t-1} + \varphi_2 \varepsilon_{t-2} + \cdots + \varphi_q \varepsilon_{t-q}$$

Properties of ARMA(p,q) models

White Noise

Stationarity

- $\rightarrow E[\varepsilon_t] = 0$ for all t
- $\rightarrow Var(\varepsilon_t) = \sigma^2 \text{ for all } t$
- $\rightarrow Cov(\varepsilon_t, \varepsilon_{t+j}) = 0$ for all t and $j \neq 0$

Autocovariances

$$\gamma(0) = \sigma^2$$

$$\checkmark$$
 $\gamma(k) = 0$ for all $k \neq 0$

Autocorrelation

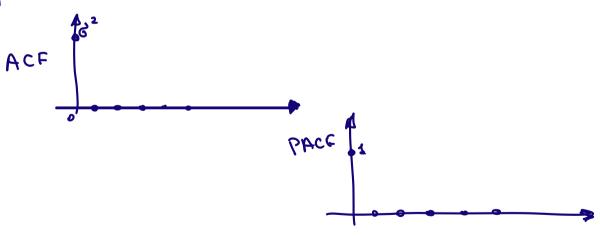
$$\rho(0) = 1$$

$$\rho(k) = 0 \text{ for all } k \neq 0$$

PACF

$$\alpha(0) = 1$$

$$\rightarrow \alpha(k) = 0 \text{ for all } k > 0$$



$MA(1): Y_t = \varepsilon_t + \varphi \varepsilon_{t-1}$

(25:0)N(0;32)

Autocovariances

$$\gamma(\mathbf{0}) = Var(Y_t) = \sigma^2(\mathbf{1} + \boldsymbol{\varphi}^2), \gamma(\mathbf{1}) = Cov(Y_t, Y_{t+1}) = \boldsymbol{\varphi}\sigma^2$$

$$\gamma(k) = 0$$
 for all $|k| > 1$

ACF

$$\rho(0) = 1, \rho(1) = \frac{\varphi}{1 + \varphi^2}$$

$$\rho(k) = 0$$
 for all $|k| > 1$

PACF

> complicated, but does not become 0 at some lag

$MA(q): Y_t = \varepsilon_t + \varphi_1 \varepsilon_{t-1} + ... + \varphi_q \varepsilon_{t-q}$

Stationarity

 \rightarrow automatically follows from stationarity of $\{\varepsilon_t\}$

Autocovariances

$$\gamma(0) = Var(Y_t) = \sigma^2(1 + \varphi_1^2 + ... + \varphi_q^2),$$

$$\gamma(k) = \sigma^2(\varphi_k + \varphi_{k+1}\varphi_1 + \varphi_{k+2}\varphi_2 + ... + \varphi_q\varphi_{q-k}) \text{ for } k = 1, ..., q$$

$$\rightarrow \gamma(k) = 0 \text{ for } |k| > q$$

AR(1): $Y_t = \theta Y_{t-1} + \varepsilon_t$

• Plug in the expression for Y_{t-1} , Y_{t-2} , and so on:

$$Y_{t} = \theta Y_{t-1} + \varepsilon_{t}$$

$$Y_{t-1} = \theta Y_{t-2} + \varepsilon_{t-1}$$

$$Y_{t-2} = \theta Y_{t-2} + \varepsilon_{t-1}$$

$$Y_{t} = \theta (\theta Y_{t-2} + \varepsilon_{t-1}) + \varepsilon_{t} = \theta^{2} Y_{t-2} + \theta \varepsilon_{t-1} + \varepsilon_{t}$$

$$Y_{t} = \theta^{n} Y_{t-n} + \sum_{j=0}^{n-1} \theta^{j} \varepsilon_{t-j}$$
if $y_{t} = 0$, $y_{t} = 0$,

- If $|\theta| \ge 1$, as $n \to \infty$, $\theta^n \to \infty$, and Y_t explodes.
- So we need $|\theta|$ < 1 for stationarity.

$$\frac{\theta|<1 \text{ for stationarity.}}{\Box } = \frac{E[y_{1}]}{E[y_{1}]} = \frac{E[\theta, y_{2}]}{E[y_{1}]} = \frac{E[\theta, y_{2}]}{E[y_{1}]} = \frac{E[\theta, y_{2}]}{E[y_{2}]} = \frac{e[\theta, y_{2}]$$

$AR(1): Y_t = \theta Y_{t-1} + \varepsilon_t$

• **Stationarity:** stationary if $|\theta| < 1$. Then

$$\rightarrow E[Y_t] = 0$$
 for all t

$$Var(Y_t) = \theta^2 Var(Y_{t-1}) + Var(\varepsilon_t) = \frac{\sigma^2}{1-\theta^2}$$
 for all t

$$\rightarrow Cov(Y_t, Y_{t-k}) = \theta^k \frac{\sigma^2}{1-\theta^2}$$
 for all t , for all k

Autocovariances

$$\gamma(k) = \theta^k \frac{\sigma^2}{1-\theta^2}$$
 for all k

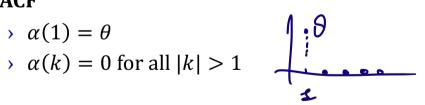


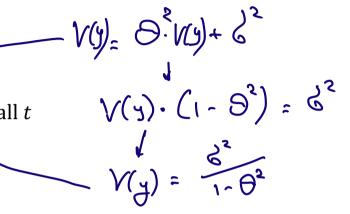
$$\rho(k) = \theta^k$$
 for all k

PACF

$$\alpha(1) = \theta$$

$$\alpha(k) = 0 \text{ for all } |k| > 1$$





$AR(1): Y_t = \theta Y_{t-1} + \varepsilon_t$

9+-1 = L. 9+=> 9+=9.L. 9++ E+

4+.(1-8.4)= 8+ • Can be derived in a different way: $(1 - \theta L)Y_t = \varepsilon_t$, so if $(1 - \theta L)$ has an inverse, Y_t can be written as

written as
$$Y_t = (1 - \theta L)^{-1} \varepsilon_t = \sum_{j=0}^{\infty} \theta^j L^j \varepsilon_t (-1)^{\frac{1}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} (-1)^{\frac{2}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} (-1)^{\frac{2}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} (-1)^{\frac{2}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} (-1)^{\frac{2}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} (-1)^{\frac{2}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} (-1)^{\frac{2}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} (-1)^{\frac{2}{2}} = 1 + \theta L + (\theta L)^{\frac{2}{2}} = 1 + \theta L +$$

- Now, $Cov(\varepsilon_t, Y_{t-1}) = \sum_{j=0}^{\infty} \theta^j Cov(\varepsilon_t, \varepsilon_{t-j}) = 0$, if $Cov(\varepsilon_t, \varepsilon_{t-j}) = 0$ for all j > 0. So, if $\{\varepsilon_t\}$ is a white noise, it holds.
- Also, $E[\varepsilon_t|Y_{t-1}] = E[\varepsilon_t|\varepsilon_{t-1}, \varepsilon_{t-2}, ...]$, so if $\{\varepsilon_t\}$ is an MDS, the regression assumption is satisfied.

AR(1)

• Can be derived in a different way: $(1 - \theta L)Y_t = \varepsilon_t$, so if $(1 - \theta L)$ has an inverse, Y_t can be written as

$$Y_t = (1 - \theta L)^{-1} \varepsilon_t = \sum_{j=0}^{\infty} \theta^j L^j \varepsilon_t$$

- So it is covariance-stationary and ergodic, if $\sum_{j=0}^{\infty} |\theta^j| < \infty$, i.e., whenever $|\theta| < 1$.
- Now, $Cov(\varepsilon_t, Y_{t-1}) = \sum_{j=1}^{\infty} \theta^j Cov(\varepsilon_t, \varepsilon_{t-j}) = 0$, if $Cov(\varepsilon_t, \varepsilon_{t-j}) = 0$ for all j > 0. So, if $\{\varepsilon_t\}$ is a white noise, it holds.
- Also, $E[\varepsilon_t | Y_{t-1}] = E[\varepsilon_t | \varepsilon_{t-1}, \varepsilon_{t-2}, ...]$, so if $\{\varepsilon_t\}$ is an MDS, the regression assumption is satisfied.

AR(p)

Stationarity:
$$y_{4} \cdot \theta_{1} \cdot y_{4-1} \cdot \theta_{2} \cdot y_{4-2} + \dots + \theta_{p} \cdot y_{4-p} + \xi_{4}$$

$$y_{4} \cdot \xi_{1} - \theta_{1} \cdot \xi_{1} - \theta_{2} \cdot \xi_{2} - \dots + \theta_{p} \cdot y_{4-p} + \xi_{4}$$

$$\xi_{4} \cdot \xi_{1} - \theta_{1} \cdot \xi_{1} - \theta_{2} \cdot \xi_{2} - \dots + \theta_{p} \cdot y_{4-p} + \xi_{4}$$

- AR(p) process is stationary, if $\Theta(L) = 1 \theta_1 L ... \theta_p L^p$ can be inverted.
- Holds, if the roots of the (characteristic) polynomial $1 \theta_1 x \theta_2 x^2 \dots \theta_p x^p$ lie *outside* the unit circle.
- AR(1): $1 \theta x = 0 \Rightarrow |x| = 1/|\theta| > 1$, if $|\theta| < 1$.
- Equivalent formulation: the process is stationary if the roots of the inverse characteristic polynomial $\lambda^p \theta_1 \lambda^{p-1} ... \theta_{p-1} \lambda \theta_p$ lie inside the unit circle
- AR(1): $\lambda \theta = 0 \Rightarrow |\lambda| = |\theta| < 1$.
- Necessary condition: the coefficients of $\Theta(L)$ should add up to less than 1, i.e. $\sum_{j=1}^{p} \theta_p < 1$. $A^{(2)}: \mathcal{Y}_{+} = 1.3 \cdot \mathcal{Y}_{+} = 0.4 \cdot \mathcal{Y}_{+-2} \cdot \mathcal{Y}_{+}$
- **Sufficient condition**: the absolute values of coefficients of $\Theta(L)$ should add up to less than 1, i.e. $\sum_{i=1}^{p} |\theta_{p}| < 1$.

AR(p)

Stationarity:

- AR(p) process is stationary, if the roots of the (characteristic) polynomial $1 \theta_1 x \theta_2 x^2 \dots \theta_p x^p$ lie *outside* the unit circle.
- ACF: can be computed recursively (*Yule-Walker equations*): for k = 1, 2, ...

$$\rho(k) = \theta_1 \rho(k-1) + \dots + \theta_p \rho(k-p)$$

• **PACF**: First $p \alpha(k)$ are (in general) nonzero, and $\alpha(k) = 0$, for |k| > p.

ARMA(p,q)

Can be written as

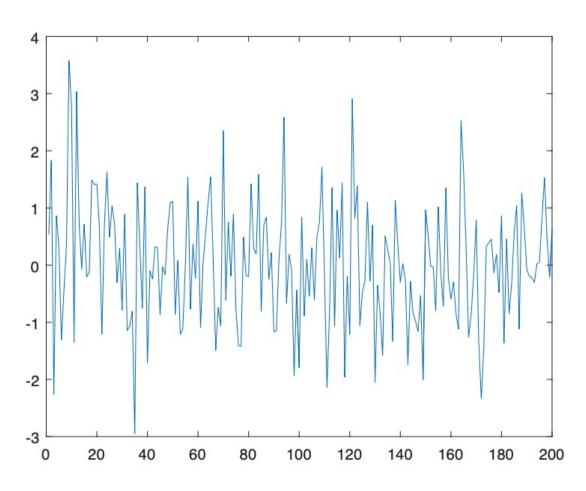
$$Y_t = \Psi(L) \varepsilon_t$$

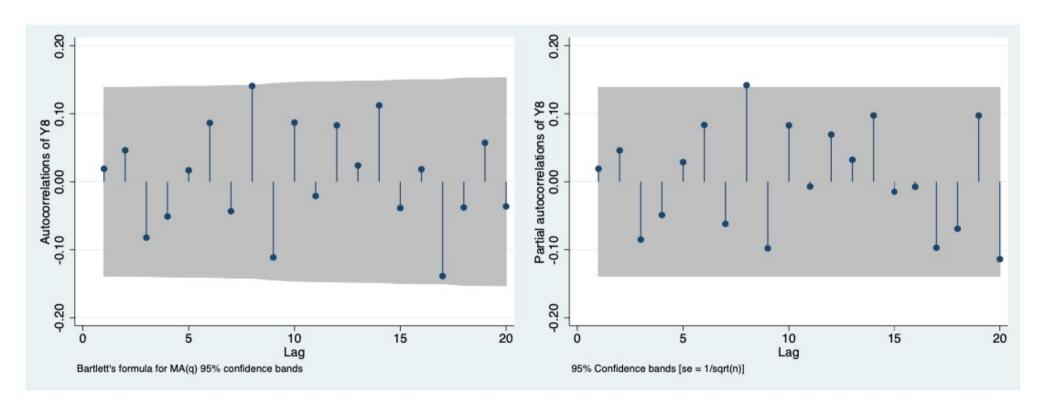
if $\Theta(L)$ is invertible (i.e., has inverse), where $\Psi(L) = \Theta(L)^{-1}\Phi(L)$, $\Theta(L) = 1 - \theta_1 L - \dots - \theta_p L^p$ and $\Phi(L) = 1 + \varphi_1 L - \dots + \varphi_q L^q$.

- ARMA(p,q) process is stationary, if and only if the lag polynomial corresponding to the AR part is invertible.
- Stationary ARMA(p,q) can be written as $MA(\infty)$.
- ACF and PACF: combination of ACFs and PACFs for AR(p) and MA(q)
 (none is zero after a certain lag, but decays exponentially fast)

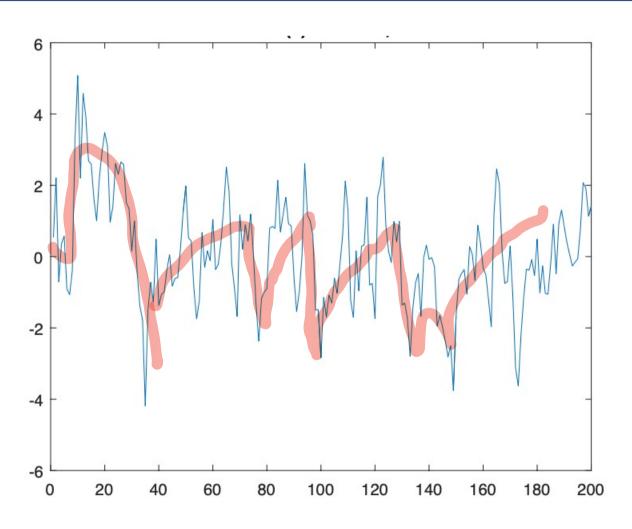
ARMA(p,q)

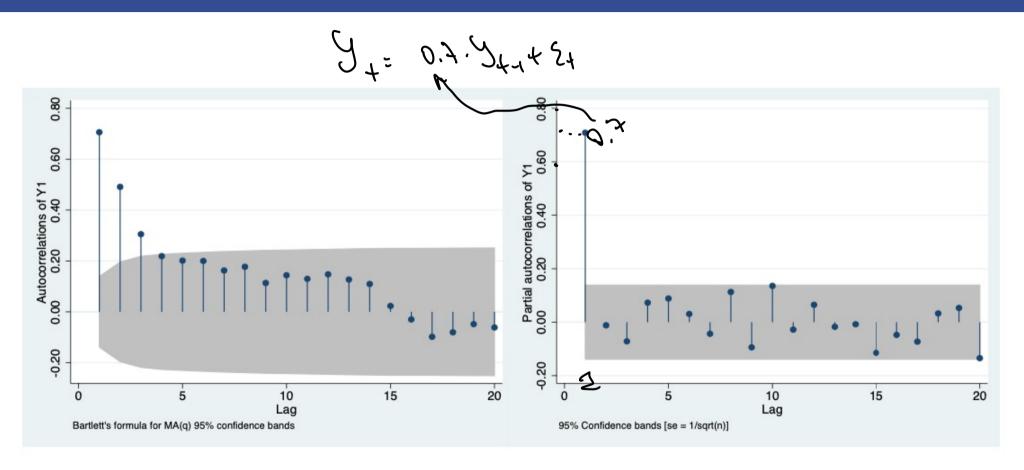
Process	ACF	PACF
WN	$ \rho(k) = 0 $	$\alpha(k)=0$
AR(1)	$\rho(k) = \theta^k$	$\alpha(1) = \theta, \alpha(k) = 0 \text{ for } k > 1$
AR(p)	Exponentially decays to 0,	First p are non-zero; $\alpha(k) =$
	may oscillate	0, for $k > p$
MA(1)	$\rho(1) = \varphi, \rho(k) = 0 \text{ for } k > 1$	Exp. decays to 0, may oscil-
		late; $sign(\alpha(1)) = sign(\varphi)$
MA(q)	First $q \rho(k)$ are non-zero,	Exp. decays to 0, may oscil-
	$\rho(k) = 0$, for $k > q$	late
ARMA(1,1)	$sign(\rho(1)) = sign(\theta + \varphi)$; exp.	$\alpha(1) = \rho(1)$; exp. decays (os-
	decays (oscillating if θ < 0)	cillating if $\theta > 0$)
ARMA(p,q)	Starts exp. decaying (may	Starts exp. decaying (may
	oscillate) at lag q	oscillate) at lag p



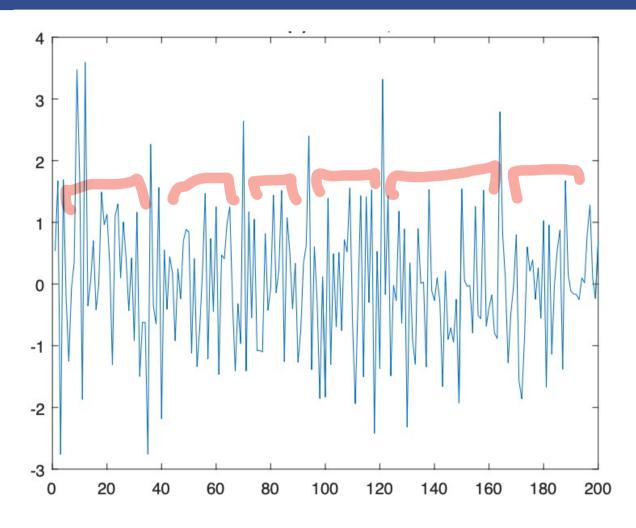


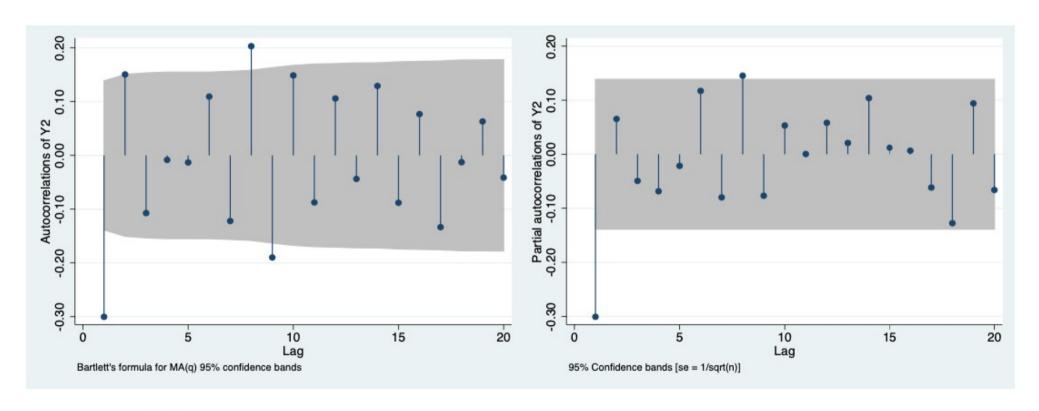
White noise



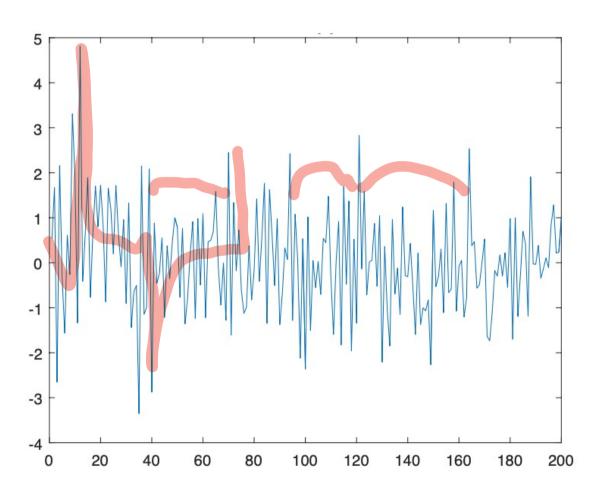


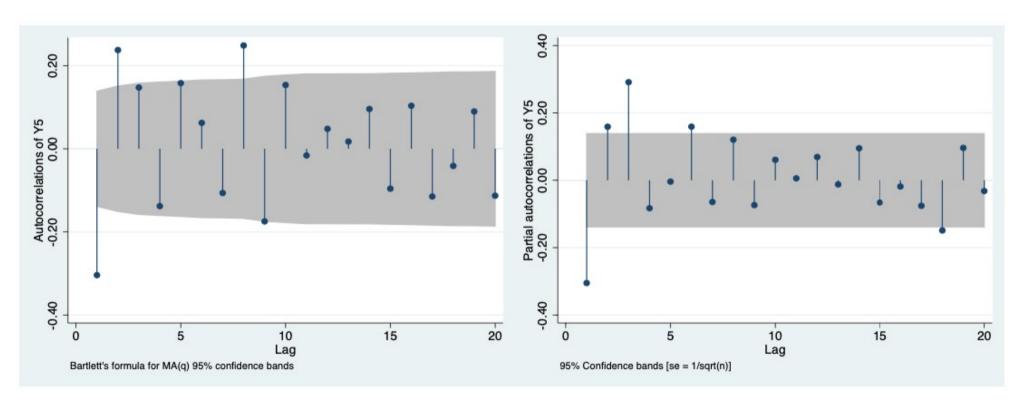
AR(1) with $\theta_1 = 0.7$



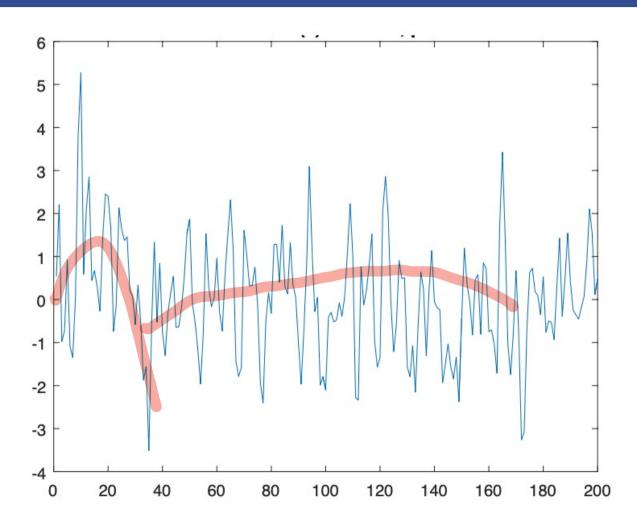


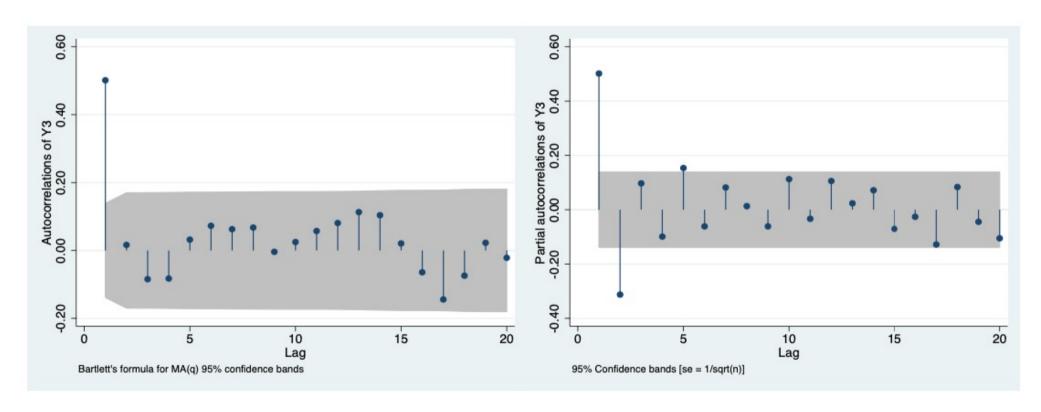
AR(1) with
$$\theta_1 = -0.3$$



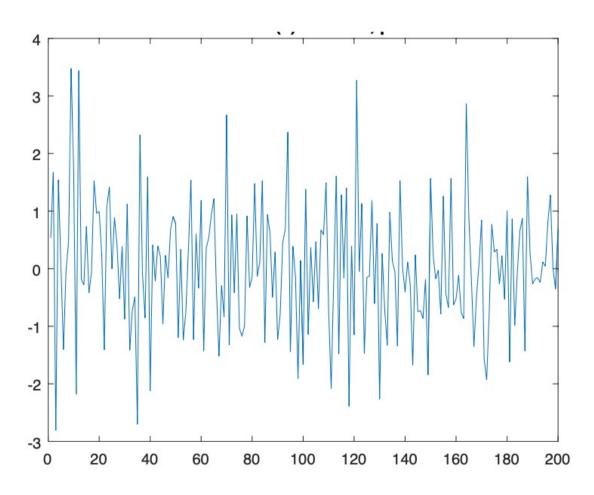


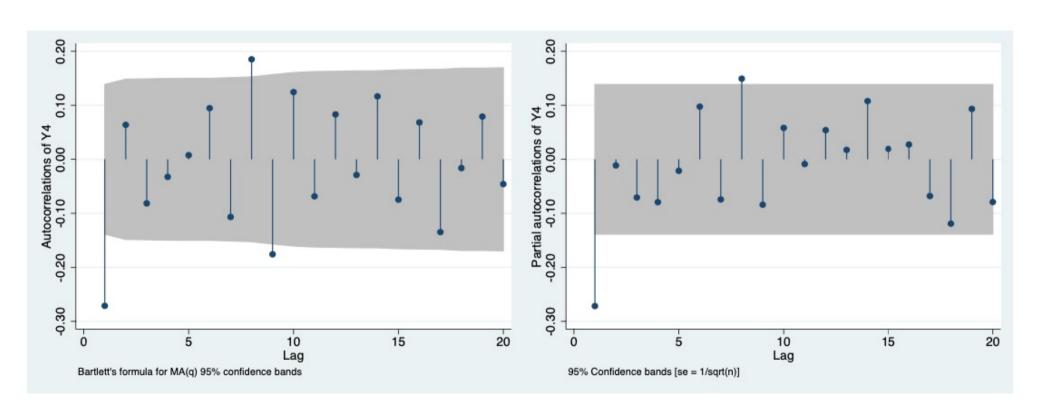
AR(3):
$$Y_t = -0.3Y_{t-1} + 0.2Y_{t-2} + 0.3Y_{t-3} + \varepsilon_t$$



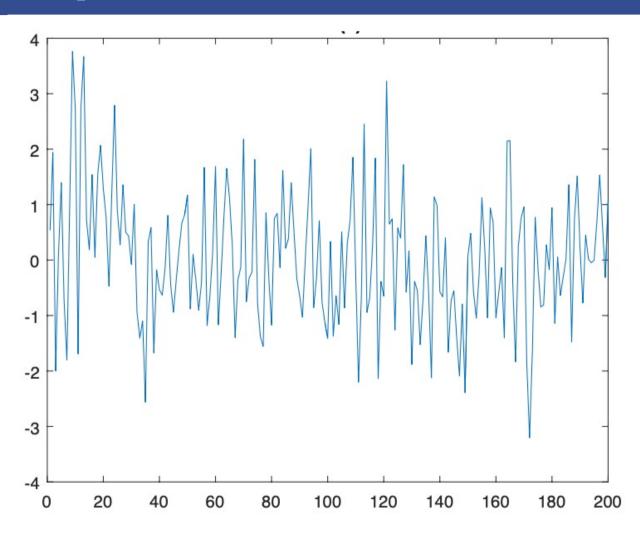


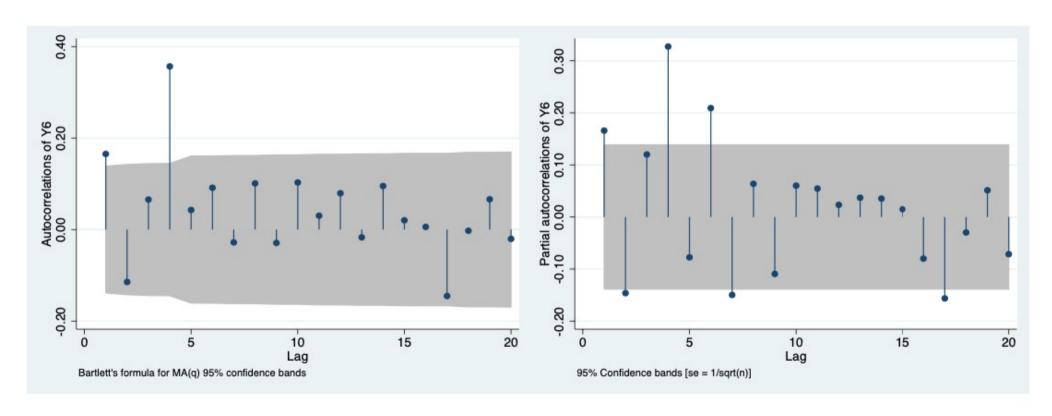
MA(1) with $\varphi_1 = 0.7$





MA(1) with $\varphi_1 = -0.3$





MA(4): $Y_t = \varepsilon_t + 0.2 \varepsilon_{t-1} - 0.2 \varepsilon_{t-2} + 0.1 \varepsilon_{t-3} + 0.5 \varepsilon_{t-4}$

