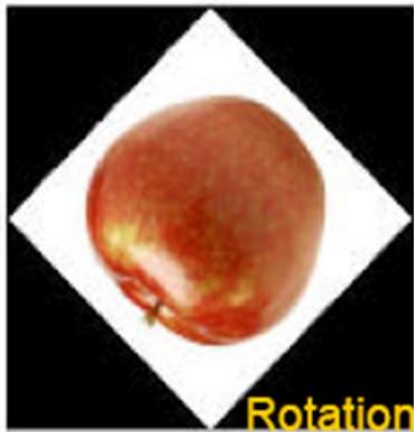


If an image is not aligned  
the same way we want it to be,

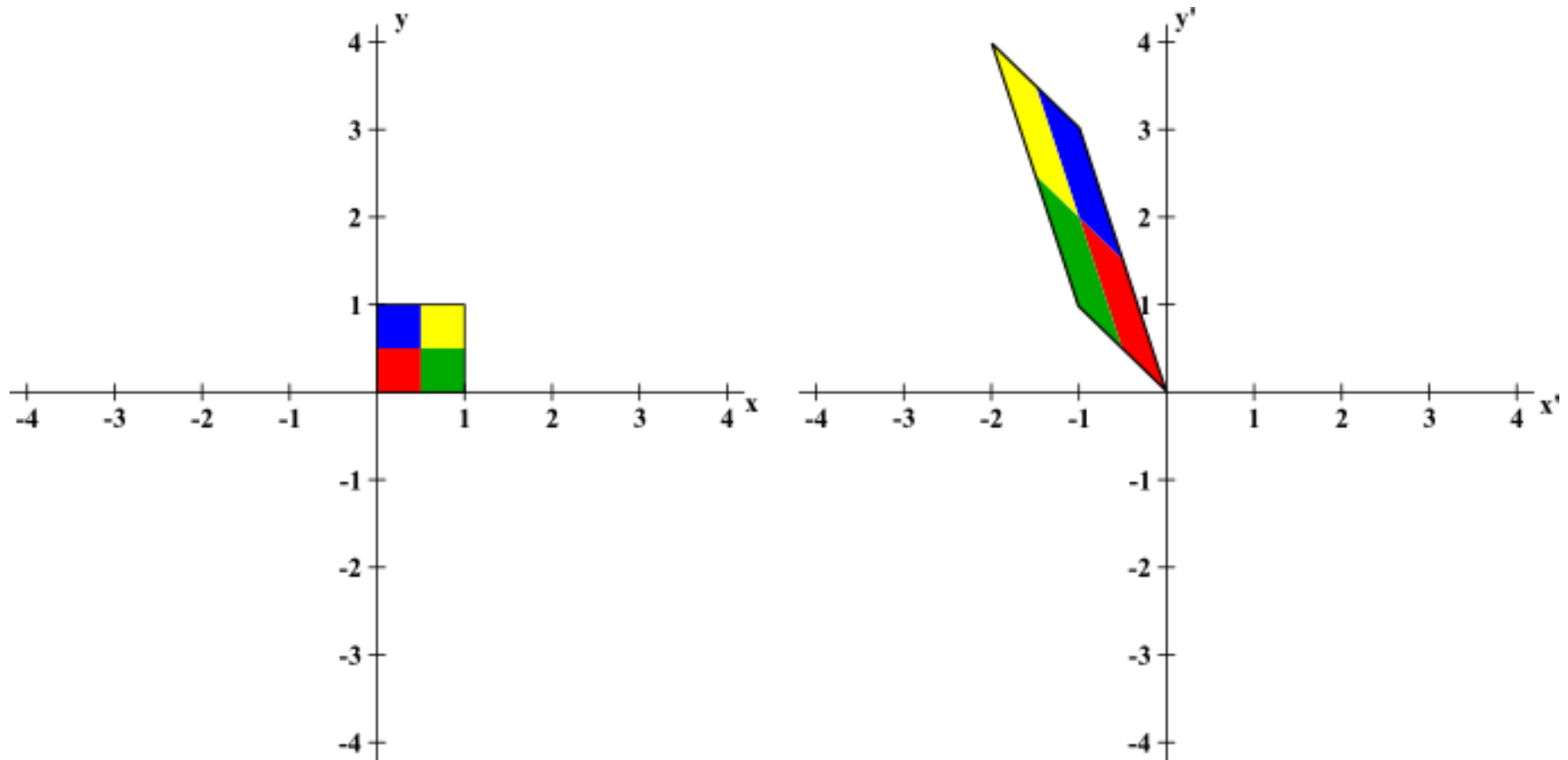
*How should it be processed  
to adjust its alignment*

# How can we obtain this look of image?



**Answer is through Geometric (point) Transformation**

# Transforming points in 2D to a new axis

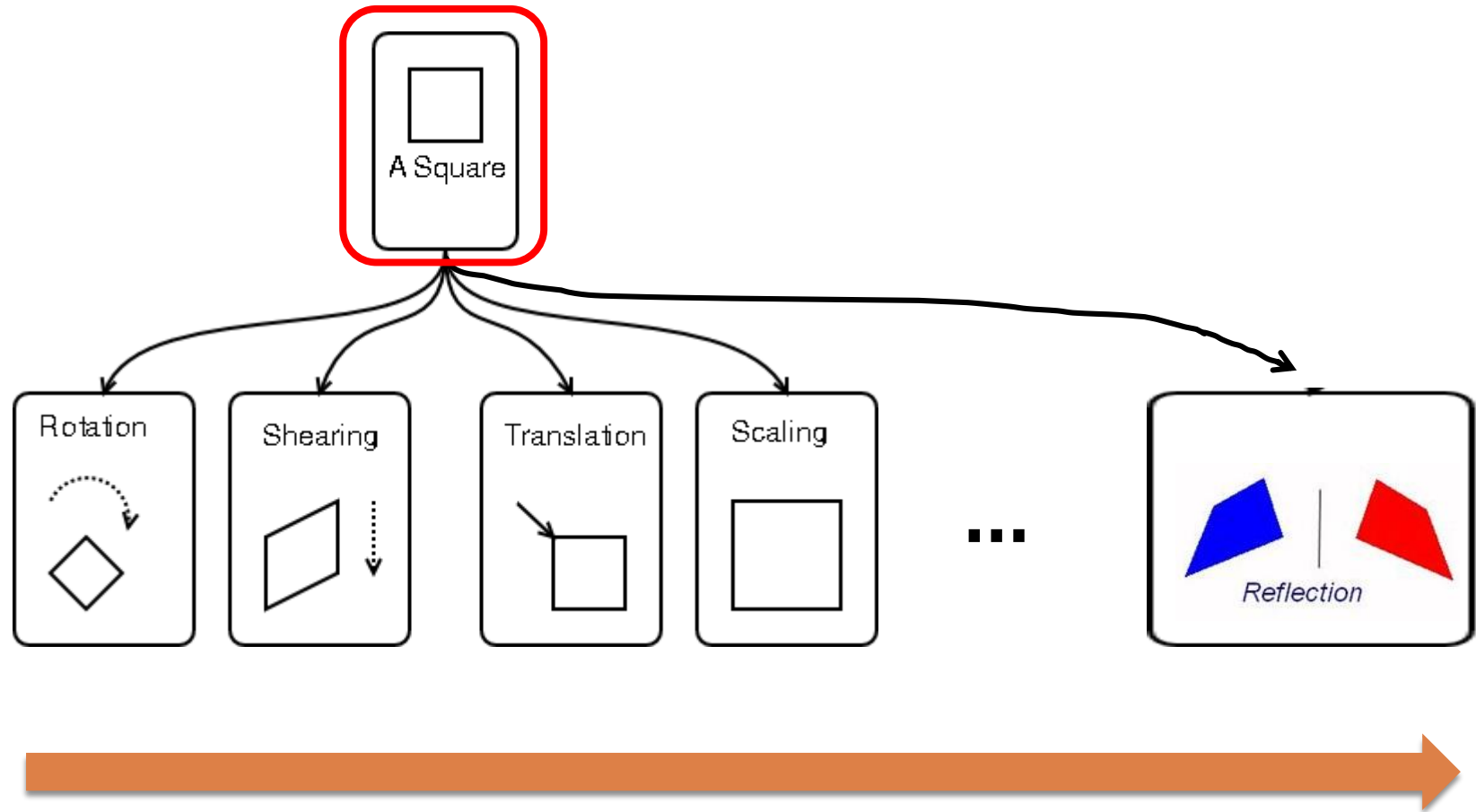


From current axis (x,y)

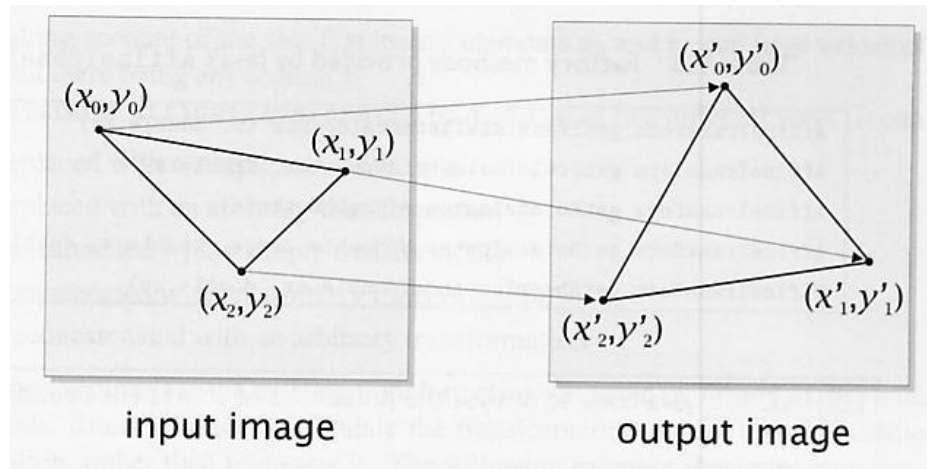


To new axis (x',y')

# What would point transform effect an image?



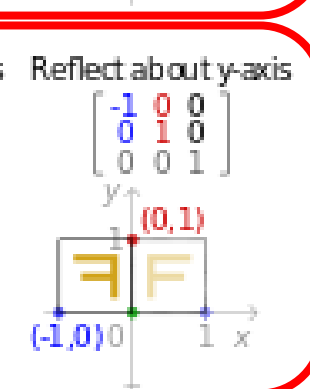
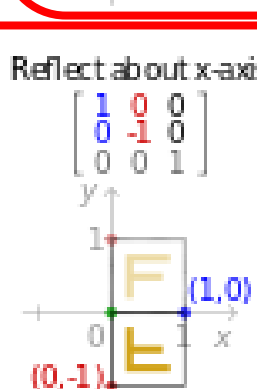
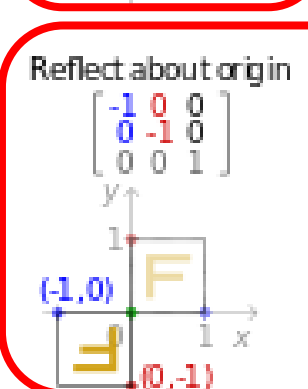
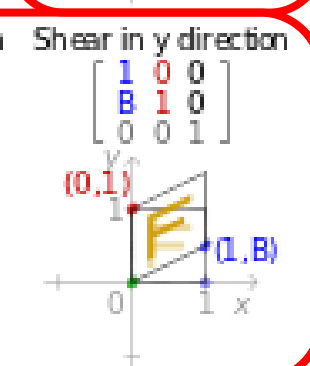
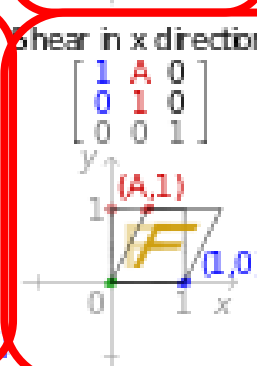
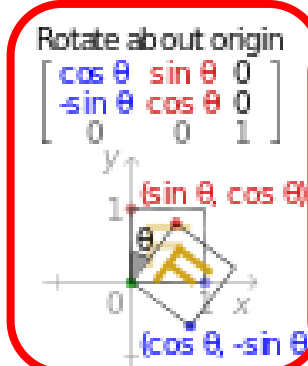
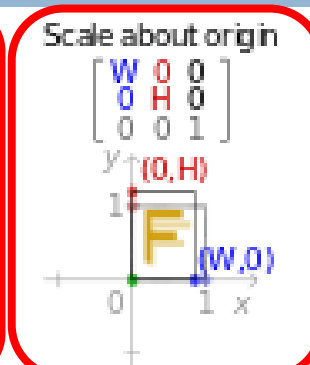
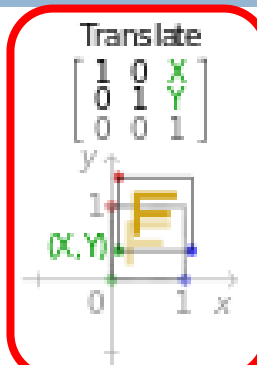
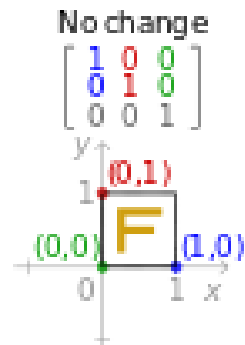
# Geometric Transformation (point transform)



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} a_0 & a_1 \\ b_0 & b_1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} a_2 \\ b_2 \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} a_0 & a_1 & a_2 \\ b_0 & b_1 & b_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

# Relation between transform action and transfer function



$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Translation

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Scaling

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Rotation

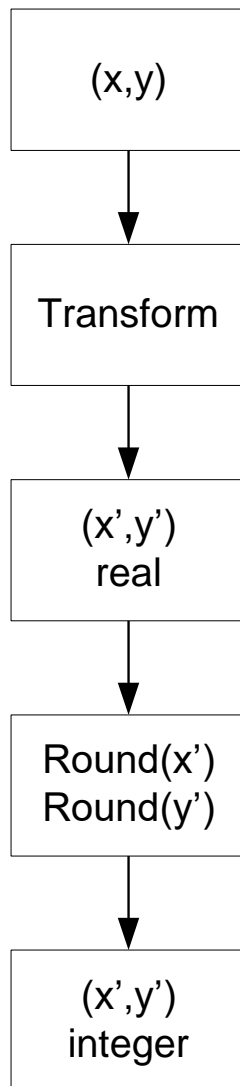
$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & sh_x & 0 \\ sh_y & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Shearing

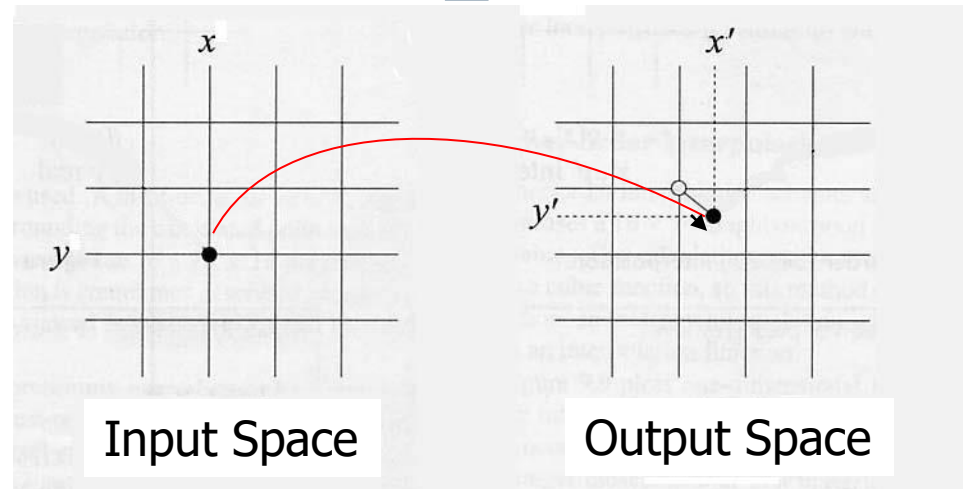
# How would point transform

Apply to an image?

# Forward Mapping



Integer grid  $(x, y)$   Real number grid  $(x', y')$



$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} a_0 & a_1 & a_2 \\ b_0 & b_1 & b_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

**An Image uses integer grid**

$$g(\text{round}(x'), \text{round}(y'))$$



# Point Transform Example

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Rotation

$$\theta = 90$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos(90) & -\sin(90) & 0 \\ \sin(90) & \cos(90) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

	y=0	y=1
x=0	1	2
x=1	3	4

x	y	x'	y'
0	0		
0	1		
1	0		
1	1		

# Point Transform Example

	$y=0$	$y=1$
$x=0$	1	2
$x=1$	3	4

i/p image  
 $f(x,y)$

$\theta = 90$



	$y'=0$	$y'=1$
$x'=-1$	2	4
$x'=0$	1	3

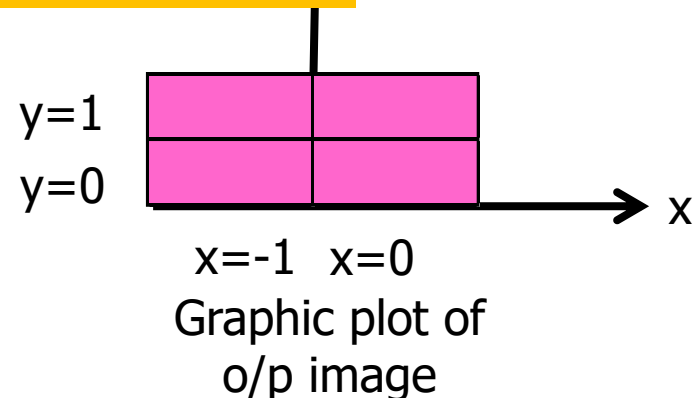
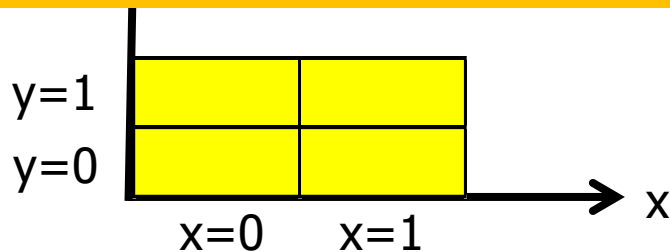
o/p image  
 $g(x,y)$

จุดหมุนที่ pixel ตำแหน่ง (0,0)

Image world

Graphic world

**Can the rotation results be kept in realworld image array?**



# Shifting Back to **Unsigned Integer Grid**

	$y'=0$	$y'=1$
$x'=-1$	2	4
$x'=0$	1	3

o/p image  
 $g(x,y)$

Actual rotation result



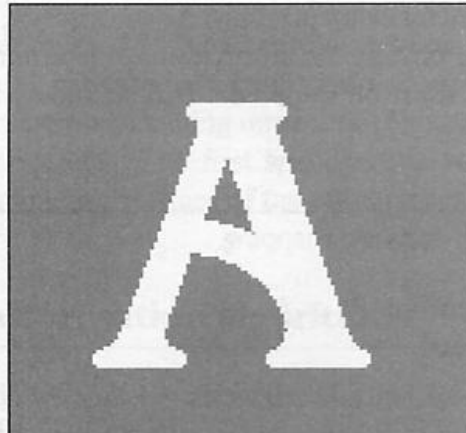
	$y'=0$	$y'=1$
$x'=0$	2	4
$x'=1$	1	3

Mapping result onto  
unsigned integer grid

# Forward Mapping Problem

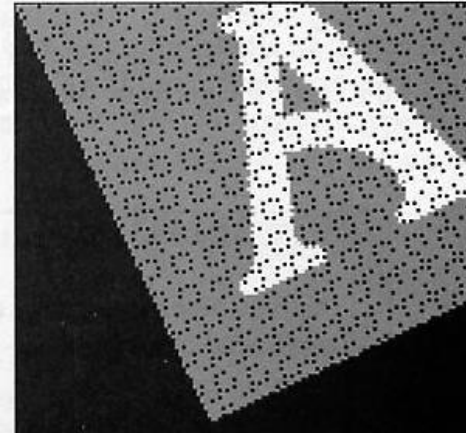
Why does the o/p image can not hold all the area of the result?

i/p image  
 $f(x, y)$



$f(x, y)$

o/p image  
 $g(x, y)$

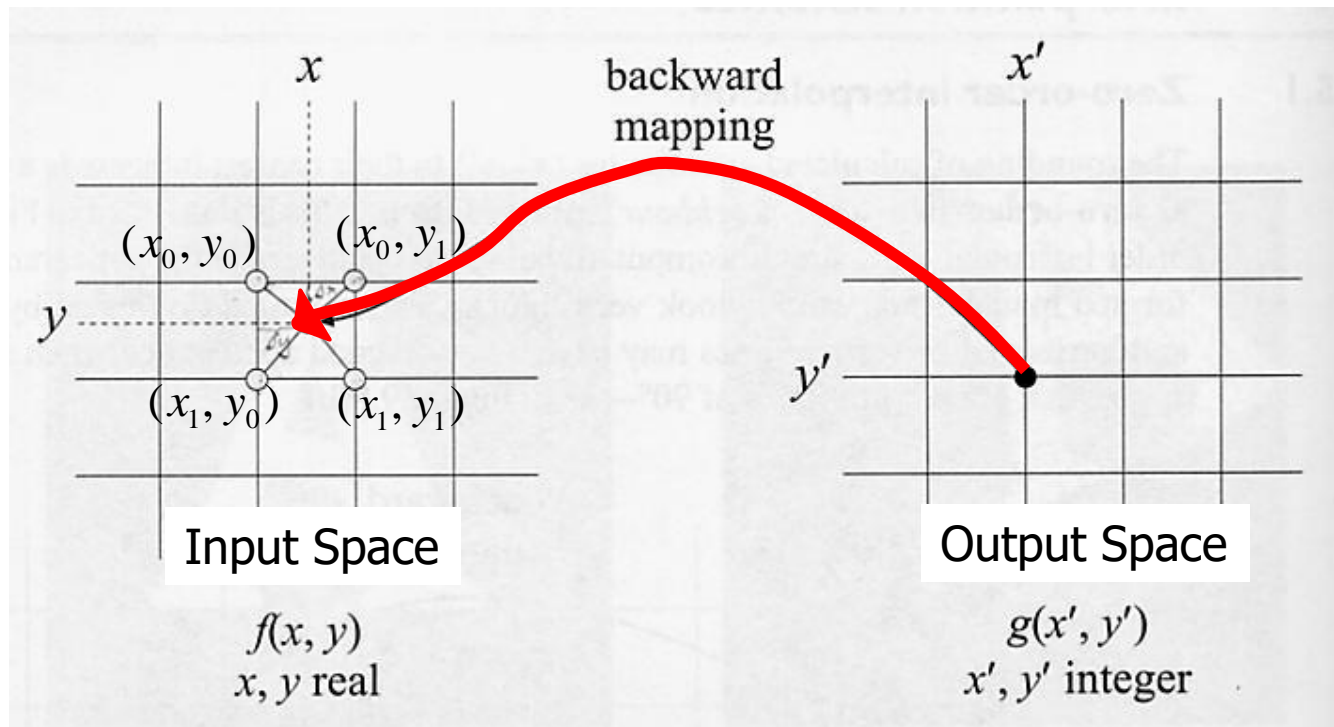


$g(x', y')$

How can the o/p image get all the black dots?

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(25^\circ) & -\sin(25^\circ) \\ \sin(25^\circ) & \cos(25^\circ) \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

# Backward Mapping



$$g(x', y') = \text{interpolation}[f(x, y)]$$

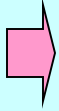
ค่าเฉลี่ยจากตำแหน่งพิกเซลเพื่อนบ้านรอบจุด  $(x, y)$

# Geometric Transform Parameters


## (Backward Mapping)

Backward


Forward

1) Rotation  
$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x' \\ y' \end{bmatrix}$$


$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

2) Translation (Shift)  
$$\begin{aligned} x &= x' - \Delta x \\ y &= y' - \Delta y \end{aligned}$$

$$\begin{aligned} x' &= x + \Delta x \\ y' &= y + \Delta y \end{aligned}$$

3) Enlarge or reduce by scaling factor (S)  
$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \frac{1}{S_x} & 0 \\ 0 & \frac{1}{S_y} \end{bmatrix} \begin{bmatrix} x' \\ y' \end{bmatrix}$$

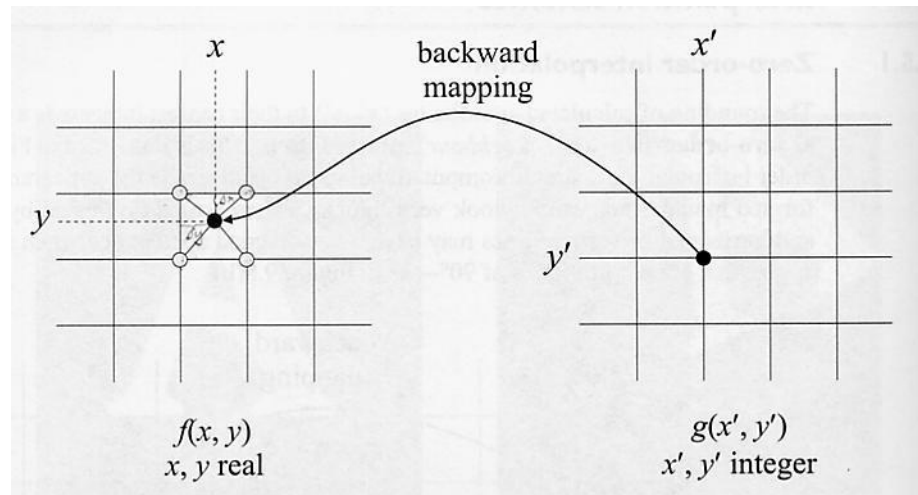
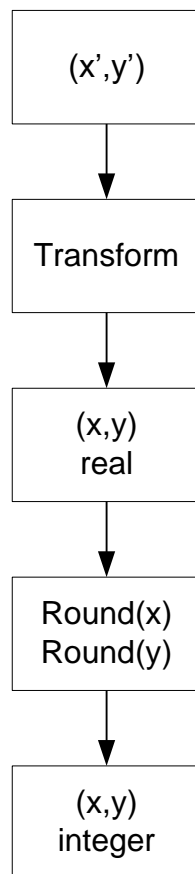
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} S_x & 0 \\ 0 & S_y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

4) Shear (บีบ)  
$$\begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{|\det()|} \begin{bmatrix} -1 & sh_x \\ sh_y & -1 \end{bmatrix} \begin{bmatrix} x' \\ y' \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & sh_x \\ sh_y & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

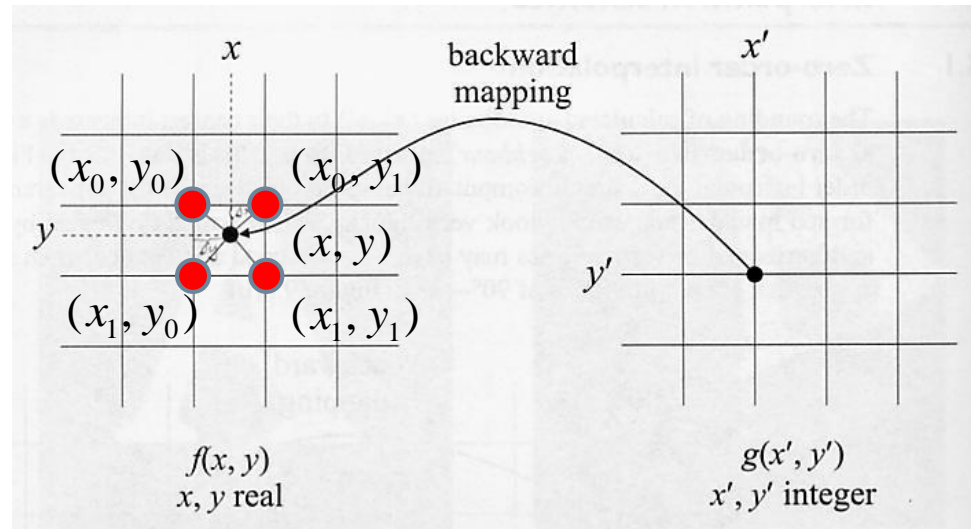
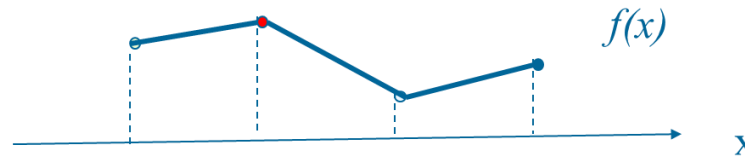
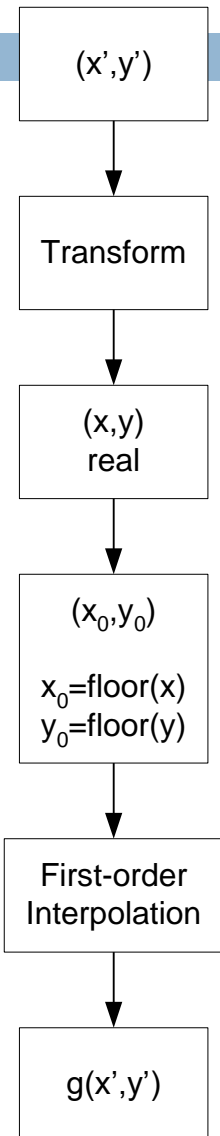
# Zero-order Interpolation

(nearest neighbor)



$$g(x', y') = f[\text{round}(x), \text{round}(y)]$$

# First-order interpolation (bilinear interpolation)



$$\Delta x = x - x_0$$

$$\Delta y = y - y_0$$

$$\begin{aligned}
 g(x', y') = & f(x_0, y_0) + [f(x_1, y_0) - f(x_0, y_0)]\Delta x \\
 & + [f(x_0, y_1) - f(x_0, y_0)]\Delta y \\
 & + [f(x_1, y_1) + f(x_0, y_0) - f(x_0, y_1) - f(x_1, y_0)]\Delta x\Delta y
 \end{aligned}$$



# Rotation using Bilinear Interpolation

	y=0	y=1
x=0	1	2
x=1	3	4

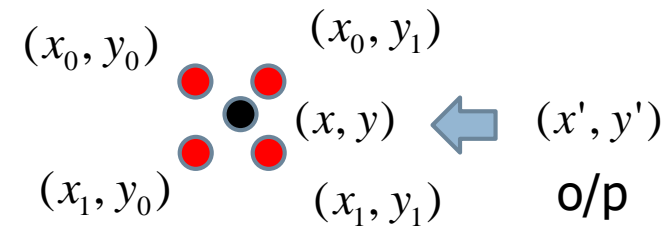
	y=-1	y=0	y=1	y=2
x=-2	0	0	0	0
x=-1	0	0	2	0
x=0	0	1	4	0
x=1	0	0	3	0
x=2	0	0	0	0

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x' \\ y' \end{bmatrix}$$

Rotate	30
cos()	0.866025
sin()	0.5

Forward mapping						
x	y	f(x,y)	x'=xcos-ysin	y'=xsin+ycos	round(x')	round(y')
0	0	1	0	0	0	0
0	1	2	-0.5	0.866025	-1	1
1	0	3	0.866025	0.5	1	1
1	1	4	0.366025	1.366025	0	1
	min		-0.5	0	-1	0
	max		0.866025	1.366025	1	1

# Backward Mapping (Bilinear Interpolation)



$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos 30^\circ & \sin 30^\circ \\ -\sin 30^\circ & \cos 30^\circ \end{bmatrix} \begin{bmatrix} x' \\ y' \end{bmatrix}$$

$(x, y)_{i/p}$

$$g(x', y') = f(x_0, y_0) + [f(x_1, y_0) - f(x_0, y_0)]\Delta x$$

$$+ [f(x_0, y_1) - f(x_0, y_0)]\Delta y$$

$$+ [f(x_1, y_1) + f(x_0, y_0) - f(x_0, y_1) - f(x_1, y_0)]\Delta x\Delta y$$

x'	y'	x=x'cos+y'sin	y=-x'sin+y'cos	x0	y0	f(x0,y0)	f(x0,y1)	f(x1,y0)	f(x1,y1)	dx	dy
-2	-1	-2.2321	0.1340	-3	0	0	0	0	0	0.7680	0.1340
-2	0	-1.7321	1.0000	-2	1	0	0	0	0	0.2680	0.0000
-2	1	-1.2321	1.8660	-2	1	0	0	0	0	0.7680	0.8660
-2	2	-0.7321	2.7321	-1	2	0	0	0	0	0.2680	0.7321
-1	-1	-1.3660	-0.3660	-2	-1	0	0	0	0	0.6340	0.6340
-1	0	-0.8660	0.5000	-1	0	0	0	1	2	0.1340	0.5000
-1	1	-0.3660	1.3660	-1	1	0	0	2	0	0.6340	0.3660
-1	2	0.1340	2.2321	0	2	0	0	0	0	0.1340	0.2321
0	-1	-0.5000	-0.8660	-1	-1	0	0	0	1	0.5000	0.1340
0	0	0.0000	0.0000	0	0	1	2	3	4	0.0000	0.0000
0	1	0.5000	0.8660	0	0	1	2	3	4	0.5000	0.8660
0	2	1.0000	1.7321	1	1	4	0	0	0	0.0000	0.7321
1	-1	0.3660	-1.3660	0	-2	0	0	0	0	0.3660	0.6340
1	0	0.8660	-0.5000	0	-1	0	1	0	3	0.8660	0.5000
1	1	1.3660	0.3660	1	0	3	4	0	0	0.3660	0.3660
1	2	1.8660	1.2321	1	1	4	0	0	0	0.8660	0.2321
2	-1	1.2321	-1.8660	1	-2	0	0	0	0	0.2321	0.1340
2	0	1.7321	-1.0000	1	-1	0	0	0	0	0.7321	0.0000
2	1	2.2321	-0.1340	2	-1	0	0	0	0	0.2321	0.8660
2	2	2.7321	0.7321	2	0	0	0	0	0	0.7321	0.7321

# Backward Mapping

## (Bilinear Interpolation)

$$\begin{aligned}
 g(x', y') = & f(x_0, y_0) + [f(x_1, y_0) - f(x_0, y_0)]\Delta x \\
 & + [f(x_0, y_1) - f(x_0, y_0)]\Delta y \\
 & + [f(x_1, y_1) + f(x_0, y_0) - f(x_0, y_1) - f(x_1, y_0)]\Delta x\Delta y
 \end{aligned}$$

f(x0,y0)	f(x0,y1)	f(x1,y0)	f(x1,y1)	dx	dy	[f(x1,y0)-f(x0,y0)]*dx	[f(x0,y1)-f(x0,y0)]*dy	[...]*dx*dy	g(x',y')
0	0	0	0	0.7680	0.1340	0.0000	0.0000	0.0000	0.0000
0	0	0	0	0.2680	0.0000	0.0000	0.0000	0.0000	0.0000
0	0	0	0	0.7680	0.8660	0.0000	0.0000	0.0000	0.0000
0	0	0	0	0.2680	0.7321	0.0000	0.0000	0.0000	0.0000
0	0	0	0	0.6340	0.6340	0.0000	0.0000	0.0000	0.0000
0	0	1	2	0.1340	0.5000	0.1340	0.0000	0.0670	0.2010
0	0	2	0	0.6340	0.3660	1.2680	0.0000	-0.4641	0.8038
0	0	0	0	0.1340	0.2321	0.0000	0.0000	0.0000	0.0000
0	0	0	1	0.5000	0.1340	0.0000	0.0000	0.0670	0.0670
1	2	3	4	0.0000	0.0000	0.0000	0.0000	0.0000	1.0000
1	2	3	4	0.5000	0.8660	1.0000	0.8660	0.0000	2.8660
4	0	0	0	0.0000	0.7321	0.0000	-2.9282	0.0000	1.0718
0	0	0	0	0.3660	0.6340	0.0000	0.0000	0.0000	0.0000
0	1	0	3	0.8660	0.5000	0.0000	0.5000	0.8660	1.3660
3	4	0	0	0.3660	0.3660	-1.0981	0.3660	-0.1340	2.1340
4	0	0	0	0.8660	0.2321	-3.4641	-0.9282	0.8038	0.4115
0	0	0	0	0.2321	0.1340	0.0000	0.0000	0.0000	0.0000
0	0	0	0	0.7321	0.0000	0.0000	0.0000	0.0000	0.0000
0	0	0	0	0.2321	0.8660	0.0000	0.0000	0.0000	0.0000
0	0	0	0	0.7321	0.7321	0.0000	0.0000	0.0000	0.0000

# Forward vs Backward Mapping

## (Bilinear Interpolation)

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos 30^\circ & \sin 30^\circ \\ -\sin 30^\circ & \cos 30^\circ \end{bmatrix} \begin{bmatrix} x' \\ y' \end{bmatrix}$$


	y=0	y=1
x=0	1	2
x=1	3	4

Forward Mapping



	y=-1	y=0	y=1	y=2
x=-2	0	0	0	0
x=-1	0	0	2	0
x=0	0	1	4	0
x=1	0	0	3	0
x=2	0	0	0	0

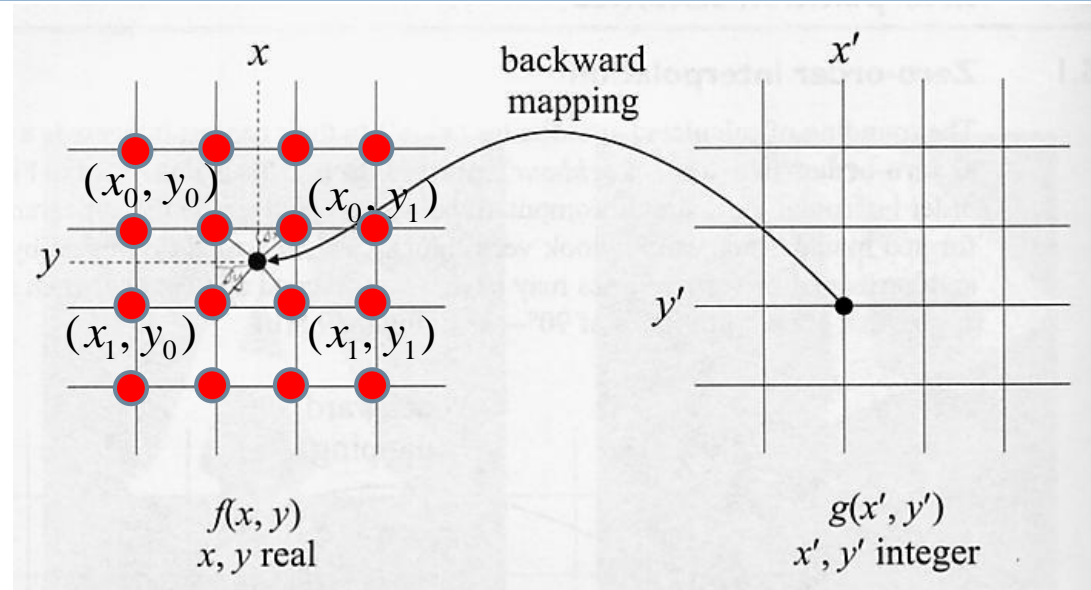
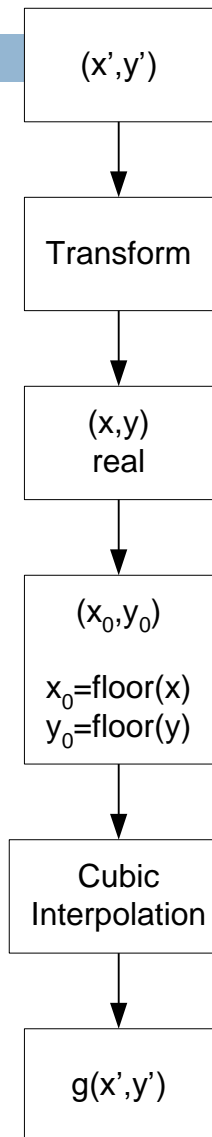
Backward Mapping



	y=-1	y=0	y=1	y=2
x=-2	0	0	0	0
x=-1	0	0.2010	0.8038	0
x=0	0.0670	1	2.8660	1.0718
x=1	0	1.3660	2.1340	0
x=2	0	0	0	0

	y=-1	y=0	y=1	y=2
x=-2	0	0	0	0
x=-1	0	0	1	0
x=0	0	1	3	1
x=1	0	1	2	0
x=2	0	0	0	0

# High-order interpolation (cubic interpolation)



$$\Delta x = x - x_0$$

$$\Delta y = y - y_0$$

$$g(x', y') = \sum_{m=-1}^2 \sum_{n=-1}^2 f(x_0 + m, y_0 + n) R(m - \Delta x) R(\Delta y - n)$$

$$R(k) = \frac{1}{6} [P(k+2)^3 - 4P(k+1)^3 - 4P(k-1)^3 + 6P(k)^3]$$

$$P(z) = \begin{cases} z & z > 0 \\ 0 & z \leq 0 \end{cases}$$



**Zero-Order Interpolation**



**First-Order (Bilinear) Interpolation**



**Cubic Interpolation**



# Homework

- ให้ห้ศ.สร้างภาพขนาด 2x2 พิกเซล ในรูปของ 2D-array
- กำหนดค่าใน 2D-array ด้วยการ random ค่าระหว่าง 3-7
- ทำการหมุนภาพด้วยเทคนิค Backward mapping และใช้การกำหนดค่าระดับความเข้มแสงผลลัพธ์ด้วยเทคนิคการเฉลี่ยค่าแบบ bilinear interpolation
  - ▣ มุมที่หมุนขึ้นกับเลขท้ายของรหัสสนศ. Mod 4
    - $[\text{zeta}(0) \text{ zeta}(1) \text{ zeta}(2) \text{ zeta}(3)] = [30, 60, 120, 150]$
- แสดงขั้นตอนการคำนวณการหมุนภาพโดยละเอียดลงในกระดาษ A4