EECS 16B CSM

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Computer Science Mentors

2021-09-20

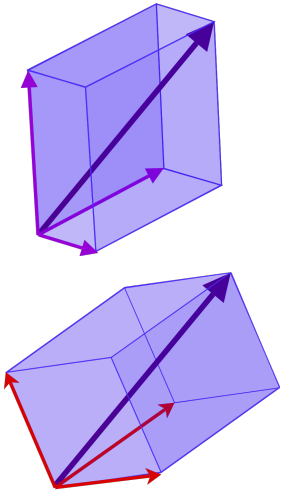
Logistics

- unexcused absences in first 3 weeks $\rightarrow$ **auto-dropped & NP**
- excused absences: email bryanngo@berkeley.edu & cc mentors@berkeley.edu with subject line `[Request for Absence] <course>`
- Slides available at `https://github.com/bdngo/16b-csm`

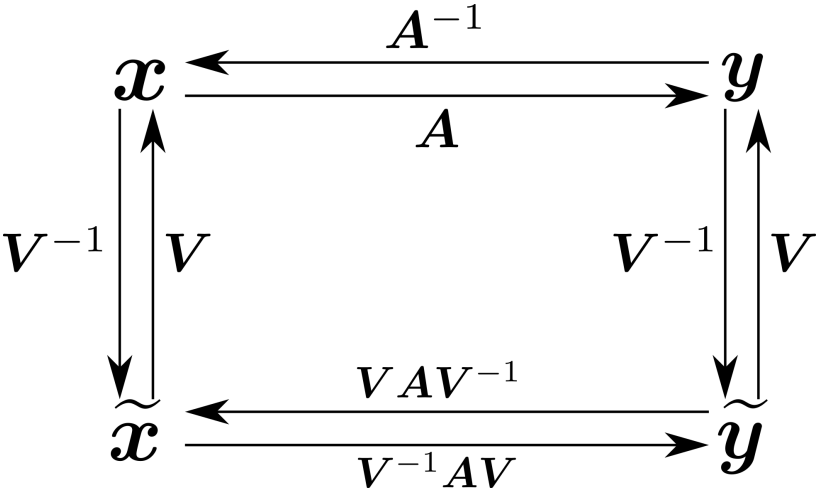
Change of Basis

Motivation

- conversion from one linear coordinate system to another
- 3Blue1Brown video



A Visualization



Diagonalization

- want the eigenvectors to be the basis for a vector space
- makes math *way* easier

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$$\boldsymbol{V} = \begin{bmatrix} \boldsymbol{v}_1 & \boldsymbol{v}_2 & \cdots & \boldsymbol{v}_n \end{bmatrix} \tag{1}$$

$$\boldsymbol{AV} = \begin{bmatrix} \lambda_1 \boldsymbol{v}_1 & \lambda_2 \boldsymbol{v}_2 & \cdots & \lambda_n \boldsymbol{v}_n \end{bmatrix} \tag{2}$$

$$= \begin{bmatrix} \boldsymbol{v}_1 & \boldsymbol{v}_2 & \cdots & \boldsymbol{v}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix} \tag{3}$$

$$= \boldsymbol{V\Lambda} \implies \boldsymbol{\Lambda} = \boldsymbol{V}^{-1}\boldsymbol{AV} \tag{4}$$

Vector Differential Equations

General Form

$$\frac{d}{dt}\boldsymbol{x}(t) = \boldsymbol{A}\boldsymbol{x}(t) + \boldsymbol{B}\boldsymbol{u}(t) \tag{5}$$

- if $\boldsymbol{A}$ is diagonal, simply a bunch of exponential differential Equations
- if not, we can try to diagonalize

Diagonalizing DEs

$$\frac{d}{dt}\boldsymbol{x}(t) = \boldsymbol{A}\boldsymbol{x}(t) + \boldsymbol{B}\boldsymbol{u}(t) \tag{6}$$

$$\frac{d}{dt}\boldsymbol{V}\boldsymbol{z}(t) = \boldsymbol{A}\boldsymbol{V}\boldsymbol{z}(t) + \boldsymbol{B}\boldsymbol{u}(t) \tag{7}$$

$$\Rightarrow \frac{d}{dt}\boldsymbol{z}(t) = \boldsymbol{V}^{-1}\boldsymbol{A}\boldsymbol{V}\boldsymbol{z}(t) + \boldsymbol{V}^{-1}\boldsymbol{B}\boldsymbol{u}(t) \tag{8}$$

$$= \boldsymbol{\Lambda}\boldsymbol{z}(t) + \boldsymbol{V}^{-1}\boldsymbol{B}\boldsymbol{u}(t) \tag{9}$$