Bryan Ngo

Vector Differential Equations

Change of Basis

Inductors (Preview)

EECS 16B CSM

Bryan Ngo

Computer Science Mentors

2020-09-21

1 Vector Differential Equations

2 Change of Basis

Who am I?

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Vector Differentia Equations

Change of Basis



- 2nd year majoring in EECS
- first time in CSM!
- took EECS 16B Spring 2020
- Pertinent fact: what I ate for lunch

Who are you?

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- Name
- Pronouns
- Year/Major
- Pertinent fact

Logistics

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- unexcused absences in first 3 weeks → auto-dropped & NP
- excused absences
 - email bryanngo@berkeley.edu & cc mentors@berkeley.edu with subject line [Request for Absence] <course>
- Slides available at https://github.com/bdngo/16b-csm

Expectations

Me to You

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- Be skeptical
- Constant feedback
- Become passionate about 16B

Expectations

You to Me

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Vector Differential Equations

General Form

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Vector Differential Equations

Change of Basis

$$\frac{d}{dt}x(t) = Ax(t) + Bu(t)$$
(1)

- lacksquare if $m{A}$ is diagonal, simply a bunch of exponential differential Equations
- if not, we can try to diagonalize

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Motivation

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Vector Differentia Equations

Change of Basis

- conversion from one linear coordinate system to another
- 3Blue1Brown video

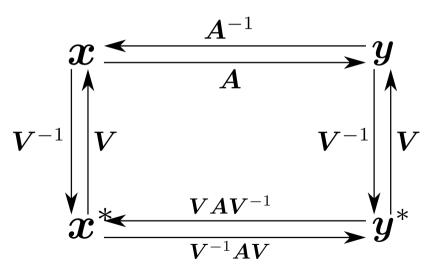
A Visualization

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Diagonalization

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- want the eigenvectors to be the basis for a vector space
- makes math way easier

Diagonalization

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- want the eigenvectors to be the basis for a vector space
- makes math way easier

$$V = \begin{bmatrix} v_1 & v_2 & \cdots & v_n \end{bmatrix}$$
 (2)

$$AV = \begin{bmatrix} \lambda_1 v_1 & \lambda_2 v_2 & \cdots & \lambda_n v_n \end{bmatrix}$$
 (3)

$$= \begin{bmatrix} \boldsymbol{v}_1 & \boldsymbol{v}_2 & \cdots & \boldsymbol{v}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix}$$
(4)

$$= V\Lambda \implies \Lambda = V^{-1}AV \tag{5}$$



Diagonalizing DEs

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Change of Basis

$$\frac{d}{dt}x(t) = Ax(t) + Bu(t)$$
(6)

$$\frac{d}{dt}\mathbf{x}(t) = \mathbf{A}\mathbf{x}(t) + \mathbf{B}\mathbf{u}(t)$$

$$\frac{d}{dt}\mathbf{V}\mathbf{z}(t) = \mathbf{A}\mathbf{V}\mathbf{z}(t) + \mathbf{B}\mathbf{u}(t)$$

$$\Rightarrow \frac{d}{dt}\mathbf{z}(t) = \mathbf{V}^{-1}\mathbf{A}\mathbf{V}\mathbf{z}(t) + \mathbf{V}^{-1}\mathbf{B}\mathbf{u}(t)$$
(8)

$$\Rightarrow \frac{d}{dt} \mathbf{z}(t) = \mathbf{V}^{-1} \mathbf{A} \mathbf{V} \mathbf{z}(t) + \mathbf{V}^{-1} \mathbf{B} \mathbf{u}(t)$$
 (8)

$$= \mathbf{\Lambda} \mathbf{z}(t) + \mathbf{V}^{-1} \mathbf{B} \mathbf{u}(t) \tag{9}$$

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Basic Properties

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Vector Differential Equations

Change of Basis

$$V_{L} = L \frac{d}{dt} I_{L}$$

$$(10)$$

- like a capacitor but for magnetic fields
- resists instantaneous change in current

Basic Properties

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Vector Differential Equations

Change of Basis

$$V_{L} = L \frac{d}{dt} I_{L}$$

$$(10)$$

- like a capacitor but for magnetic fields
- resists instantaneous change in current
- what happens when $\omega = 0$? $\omega = \infty$?