

- Order condition and rank condition for IV.

ex) $y_i = \beta_1 + \beta_2 X_{2i} + \beta_3 X_{3i} + u_i$

$E(u_i) = 0$, $E(X_{3i} u_i) = 0$ but $E(X_{2i} u_i) \neq 0$

It says "∃ correlation b/w X_{2i} and u_i "

↓

→ It is possible that Endogeneity problems occur.

Assume $\exists Z_{1i}, Z_{2i}$ s.t. $E(Z_{1i} u_i) = 0$ and $E(Z_{2i} u_i) = 0$.

Then, in this case, 1 is an IV candidate.

X_{3i} is an IV candidate

Z_{1i}
& Z_{2i} are IV candidates.

$$E \begin{bmatrix} 1 \\ X_{3i} \\ Z_{1i} \\ Z_{2i} \end{bmatrix} (1 \ X_{2i} \ X_{3i}) = E \begin{bmatrix} 1 & X_{2i} & X_{3i} \\ X_{3i} & X_{3i} X_{2i} & X_{3i}^2 \\ Z_{1i} & Z_{1i} X_{2i} & Z_{1i} X_{3i} \\ Z_{2i} & Z_{2i} X_{2i} & Z_{2i} X_{3i} \end{bmatrix} \Rightarrow \text{The rank of this matrix needs to be at least 3.}$$

* Counting the number of IVs and that being greater than or equal to the number of regressors is called order condition. (Necessary condition).

* But the condition that the above (*) matrix has the rank equal to or exceeding the number of regressors is called the rank condition.

(Necessary and sufficient condition for uniquely recovering β by IV moment conditions).

Note

of IVs \geq # of regressors : order condition.

rank of (*) \geq # of regressors : rank condition.

• 2SLS in this context.

1st stage : getting fitted values.

regress 1 on 1, X_{3i} , Z_{1i} , Z_{2i} and obtain fitted values.

$$1 = \pi_1' \cdot 1 + \pi_2' X_{3i} + \pi_3' Z_{1i} + \pi_4' Z_{2i} + V_{1i}$$

$$\Rightarrow \hat{\pi}_1 = 1, \hat{\pi}_2 = 0, \hat{\pi}_3 = 0, \hat{\pi}_4 = 0 : \text{yields perfect fit!}$$

$$\text{The fitted values are all 1. } \hat{1} = \hat{\pi}_1' \cdot 1 + 0 \cdot X_{3i} + 0 \cdot Z_{1i} + 0 \cdot Z_{2i}$$

$$\hat{1} = 1 \cdot 1$$

regress X_{2i} on 1, X_{3i} , Z_{1i} , Z_{2i} and obtain fitted values.

$$X_{2i} = \pi_1^2 \cdot 1 + \pi_2^2 \cdot X_{3i} + \pi_3^2 \cdot Z_{1i} + \pi_4^2 \cdot Z_{2i} + V_{2i}$$

$$\Rightarrow \hat{X}_{2i} = \hat{\pi}_1^2 \cdot 1 + \hat{\pi}_2^2 \cdot X_{3i} + \hat{\pi}_3^2 \cdot Z_{1i} + \hat{\pi}_4^2 \cdot Z_{2i}$$

regress X_{3i} on 1, X_{3i} , Z_{1i} , Z_{2i}

$$X_{3i} = \pi_1^3 \cdot 1 + \pi_2^3 \cdot X_{3i} + \pi_3^3 \cdot Z_{1i} + \pi_4^3 \cdot Z_{2i} + V_{3i}$$

$$\Rightarrow \hat{X}_{3i} = \hat{\pi}_1^3 \cdot 1 + \hat{\pi}_2^3 \cdot X_{3i} + \hat{\pi}_3^3 \cdot Z_{1i} + \hat{\pi}_4^3 \cdot Z_{2i}$$

$$= 0 \cdot 1 + 1 \cdot X_{3i} + 0 \cdot Z_{1i} + 0 \cdot Z_{2i} : \text{yield perfect fit!}$$

$$\hat{X}_{3i} = X_{3i}$$

↓

2nd stage : regress y_i on fitted values (1, \hat{X}_{2i} , X_{3i})

: In 2SLS, if we have a regressor which is not correlated with the error terms, then at the 2nd stage the variable itself can be used as a regressor.

Note

$$E(1 \cdot u_i) = 0$$

$$E(X_{3i} \cdot u_i) = 0$$

] 1, X_{3i} can be used as themselves.

$E(X_{2i} \cdot u_i) \neq 0$: X_{2i} should be changed by IVs.

For 2SLS, \hat{X}_{2i} can be used at the 2nd stage.

• Intuitive Motivation for 2SLS.

$$y_i = \beta_1 + \beta_2 X_{2i} + \beta_3 X_{3i} + u_i$$

When $E(X_{2i} u_i) \neq 0$, $E(X_{3i} u_i) = 0$ and $E(u_i) = 0$,

Regress X_{2i} on $1, X_{3i}, Z_{1i}, Z_{2i}$

$$X_{2i} = \underbrace{\hat{\pi}_1 + \hat{\pi}_2 X_{3i} + \hat{\pi}_3 Z_{1i} + \hat{\pi}_4 Z_{2i}}_{\hat{X}_{2i}} + \underbrace{\hat{v}_{2i}}_{\text{OLS residual of this regression.}}$$

↓

$$X_{2i} = \hat{X}_{2i} + \hat{v}_{2i}$$

Thus, $y_i = \beta_1 + \beta_2 (\hat{X}_{2i} + \hat{v}_{2i}) + \beta_3 X_{3i} + u_i$

$$= \beta_1 \underbrace{1 + \beta_2 \hat{X}_{2i} + \beta_3 X_{3i}}_{\text{orthogonal to } \hat{v}_{2i}} + (u_i + \beta_2 \hat{v}_{2i})$$

\hat{v}_{2i} and $(1, \hat{X}_{2i}, X_{3i})$ are orthogonal by construction.

$$\sum_{i=1}^N \hat{v}_{2i} = 0, \quad \sum_{i=1}^N \hat{v}_{2i} X_{3i} = 0, \quad \sum_{i=1}^N \hat{v}_{2i} Z_{1i} = 0, \quad \sum_{i=1}^N \hat{v}_{2i} Z_{2i} = 0.$$

* The 2SLS exploits the variation in regressors that are not correlated with the residual term u_i .

* When # of IVs = # of regressors, $\hat{\beta}_{2SLS} = \hat{\beta}_{IV}$.

: This result allows to study 2SLS and use the result to understand $\hat{\beta}_{IV}$.
(But, 2SLS are not useful under Heteroskedasticity).

• Generalized Method of Moment.

To motivate the objective function used in GMM, Need to know WLS.

$$Y = X\beta + u \quad E(uu'|X) = \sigma^2 I_N \quad \text{Under Homoskedasticity} \\ + \text{No correlation across observations.}$$

$$Y = X\beta + u \quad E(uu'|X) = \begin{pmatrix} \sigma^2(x_1) & 0 & \dots & 0 \\ 0 & \sigma^2(x_2) & & \vdots \\ \vdots & & \ddots & 0 \\ 0 & \dots & 0 & \sigma^2(x_N) \end{pmatrix} \quad \text{Under Heteroskedasticity.} \\ + \text{No correlation across observations.}$$

↓

Now, we allow there exists correlation across observations.

$$E(uu'|X) = \Omega_{N \times N} = \begin{pmatrix} \sigma^2(x_1) & \text{cov}(x_1, x_2) & \dots & \text{cov}(x_1, x_N) \\ \text{cov}(x_2, x_1) & & & \vdots \\ \vdots & & \ddots & \text{cov}(x_{N-1}, x_N) \\ \text{cov}(x_N, x_1) & \dots & \text{cov}(x_N, x_{N-1}) & \sigma^2(x_N) \end{pmatrix}$$

$$\text{Then, } \underbrace{\Omega^{-\frac{1}{2}} Y}_{\tilde{Y}} = \underbrace{\Omega^{-\frac{1}{2}} X}_{\tilde{X}} \beta + \underbrace{\Omega^{-\frac{1}{2}} u}_{\tilde{u}}$$

$$\tilde{Y} = \tilde{X} \beta + \tilde{u} \quad \dots \quad (**)$$

$$E(\tilde{u}\tilde{u}'|X) = E(\Omega^{-\frac{1}{2}} u u' (\Omega^{-\frac{1}{2}})' | X) = \Omega^{-\frac{1}{2}} E(uu'|X) (\Omega^{-\frac{1}{2}})' \\ = \Omega^{-\frac{1}{2}} \Omega (\Omega^{-\frac{1}{2}})' = I_N.$$

⇒ (**) satisfies condition for the OLS estimator to be BLUE

$$\hat{\beta}_{GLS} = (\tilde{X}'\tilde{X})^{-1} \tilde{X}'\tilde{Y} = (X'(\Omega^{-\frac{1}{2}})' \Omega^{-\frac{1}{2}} X)^{-1} X'(\Omega^{-\frac{1}{2}})' \Omega^{-\frac{1}{2}} Y \\ = (X' \Omega^{-1} X)^{-1} X' \Omega^{-1} Y \quad (\because (\Omega^{-\frac{1}{2}})' (\Omega^{-\frac{1}{2}}) = (\Omega^{-\frac{1}{2}} (\Omega^{-\frac{1}{2}})')^{-1} = \Omega^{-1})$$

↓ Let's check a simple case.

$$y_1 = X_1\beta_1 + u_1 \\ y_2 = X_2\beta_2 + u_2 \Rightarrow \Omega = \begin{pmatrix} \sigma^2 & \rho\sigma^2 \\ \rho\sigma^2 & \sigma^2 \end{pmatrix}$$

Under Homoskedasticity,
but \exists correlation across regressors

$$\Omega = \sigma^2 \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} = \begin{pmatrix} a & 0 \\ 0 & c \end{pmatrix} \begin{pmatrix} a & b \\ b & c \end{pmatrix} = \sigma^2 \begin{pmatrix} a^2 & ab \\ ab & b^2 + c^2 \end{pmatrix}$$

$$a^2 = 1 \quad ab = \rho$$

$$b^2 + c^2 = 1$$

\Downarrow

$$a = 1, b = \rho, c = \sqrt{1 - \rho^2}$$

$$\Omega = \sigma^2 T T' = \sigma^2 \begin{pmatrix} a & 0 \\ 0 & c \end{pmatrix} \begin{pmatrix} a & b \\ b & c \end{pmatrix} = \sigma^2 \begin{pmatrix} 1 & 0 \\ \rho & \sqrt{1 - \rho^2} \end{pmatrix} \begin{pmatrix} 1 & \rho \\ 0 & \sqrt{1 - \rho^2} \end{pmatrix}$$

$$\text{Then, } T^{-1} = \begin{pmatrix} 1 & 0 \\ \rho & \sqrt{1 - \rho^2} \end{pmatrix}^{-1} = \frac{1}{\sqrt{1 - \rho^2}} \begin{pmatrix} \sqrt{1 - \rho^2} & 0 \\ -\rho & 1 \end{pmatrix}$$

Assume $\sigma^2 = 1$, and then $\Omega^{-\frac{1}{2}} = T^{-1}$.

$$\Omega^{-\frac{1}{2}} Y = \frac{1}{\sqrt{1 - \rho^2}} \begin{pmatrix} \sqrt{1 - \rho^2} & 0 \\ -\rho & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} y_1 \\ \frac{1}{\sqrt{1 - \rho^2}} (y_2 - \rho y_1) \end{pmatrix}$$

$$\begin{aligned} y_1 &= X_1\beta_1 + u_1 \\ y_2 &= X_2\beta_2 + u_2 \end{aligned} \Rightarrow Y = X\beta + u$$

$$\Omega^{-\frac{1}{2}} X = \frac{1}{\sqrt{1 - \rho^2}} \begin{pmatrix} \sqrt{1 - \rho^2} & 0 \\ -\rho & 1 \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} = \begin{pmatrix} X_1 \\ \frac{1}{\sqrt{1 - \rho^2}} (X_2 - \rho X_1) \end{pmatrix}$$

\Rightarrow We regress $\begin{pmatrix} y_1 \\ \frac{1}{\sqrt{1 - \rho^2}} (y_2 - \rho y_1) \end{pmatrix}$ on $\begin{pmatrix} X_1 \\ \frac{1}{\sqrt{1 - \rho^2}} (X_2 - \rho X_1) \end{pmatrix}$

↳ Weighted by $\Omega^{-\frac{1}{2}}$, we can eliminate correlation across regressors,
and then taking OLS regression is the idea of GLS

• The idea of GMM

: the same as the method of moments allowing for the possibility that there are more than enough moment conditions to recover unknown parameters.

⇒ In our context, the moment conditions can be written as

$$\hat{g}(b) \equiv E \left\{ \underbrace{Z_i}_{J \times 1} \underbrace{(y_i - X_i' \hat{\beta})}_{1 \times 1} \right\} = 0$$

↓
General form for Non-linear cases.

$$E \left\{ \underbrace{g(w_i; \theta)}_{r \times 1} \right\} = 0$$

Note A sample analog of the moment conditions is

$$\frac{1}{N} \sum_{i=1}^N \underbrace{Z_i (T_i - X_i' b)}_{J \times 1} = 0 \quad \leftarrow K \times 1$$

• If $J < K$, impossible.

• In general, Moment of Method would solve for the solution to be fine the estimator, but that approach fail if $J > K$.
(overidentification).

⇒ For MoM, we need the condition $J = K$.

⇒ Define the metric between vectors by the norm;

$$\|V\|_A = \sqrt{V'AV} \text{ for a given positive definite matrix } A.$$

✕ The GMM estimator of β is defined as the minimizer of

$$\min_{b \in \mathbb{R}^K} \hat{g}(b)' A \hat{g}(b) \text{ for a given } A. \quad (\hat{\beta}_{GMM} = \operatorname{argmin} \hat{g}(b)' A \hat{g}(b))$$

How to choose A ? ⇒ "Optimal of $(\hat{g})^{-1}$ "