

Exact and Soft Successive Refinement of the Information Bottleneck

Hippolyte Charvin, Nicola Catenacci Volpi, Daniel Polani

University of
Hertfordshire **UH**

Adaptive Systems Research Group, Department of Computer Science
University of Hertfordshire
Work funded by the Pazy Foundation, Grant ID. 195

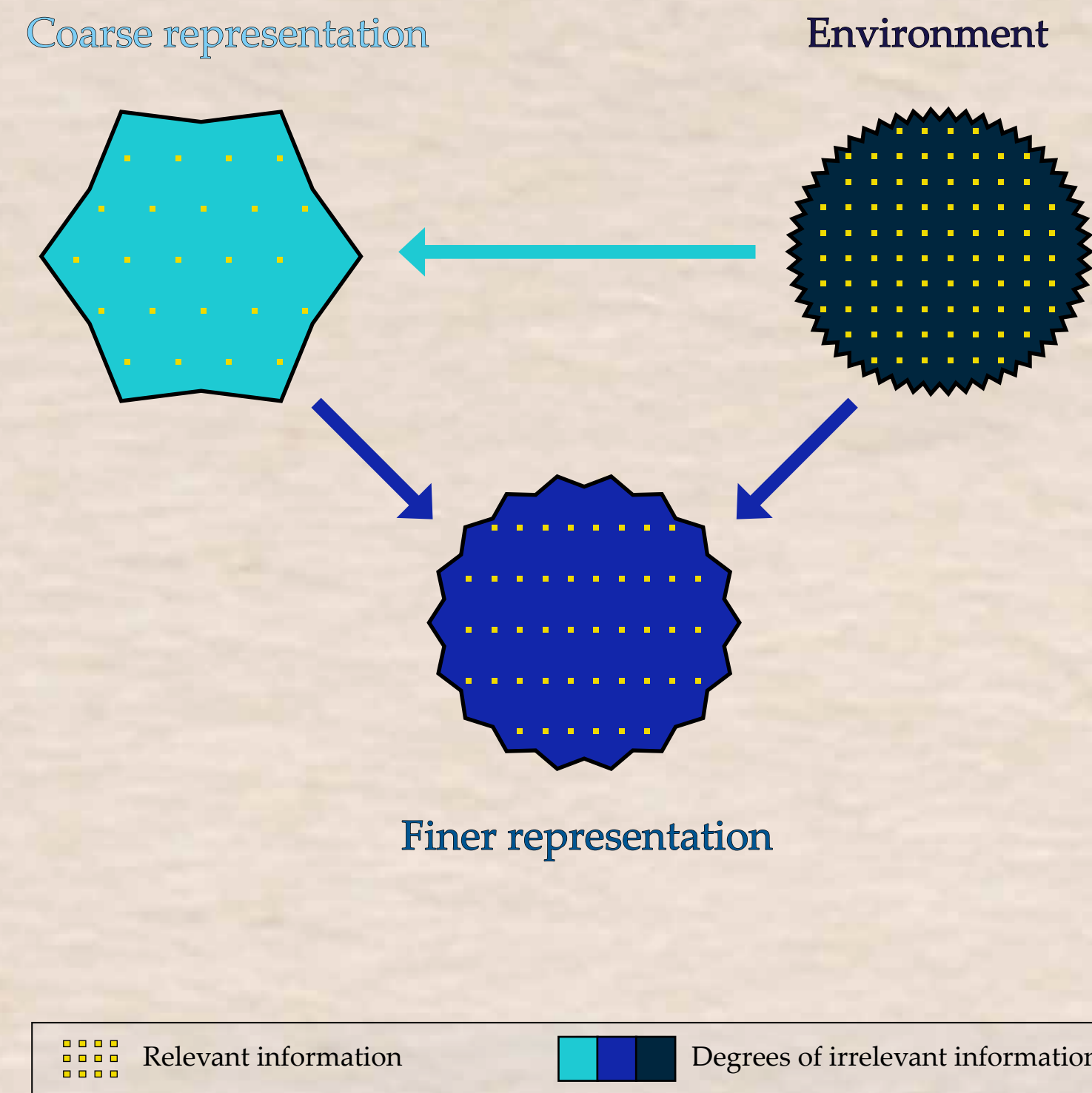


Motivation

Embodied agents must **balance** their representations' **behavioral relevancy** with the **cognitive cost** of their production and use.
But the right **trade-off varies along time** (e.g. along development), and updating representations comes with a cognitive cost as well.
→ What are the **informationally optimal limits** on the **refinement** and **coarsening** of already existing representations?

The fundamental trade-off

- Trade-off for embodied agents: **Behavioral relevancy** of representations vs. **cognitive cost** of their use.
- Postulate:
Evolution poises representations close to **optimality**.
- Thus crucial to understand the optimal limit on feasible trade-offs.
- These are described in information-theoretic terms by the **Information Bottleneck (IB) method** [1].
- However:
The method *a priori* disregards the **relationship between representations**, which might crucially affect the informationally optimal limits.



Successive incorporation of information

Assume the agent

- First** needs a **coarse** IB optimal representation of its environment,
- Then at a **later** stage, builds on it and on new information from the environment, to design a **finer** IB optimal representation.

To which extent can the finer optimal representation **leverage the information already extracted** in the coarser one?

If **all** the information can be leveraged - i.e., if **no cognitive work is wasted** along the refinement process - there is “**Successive Refinement**” [2,3].

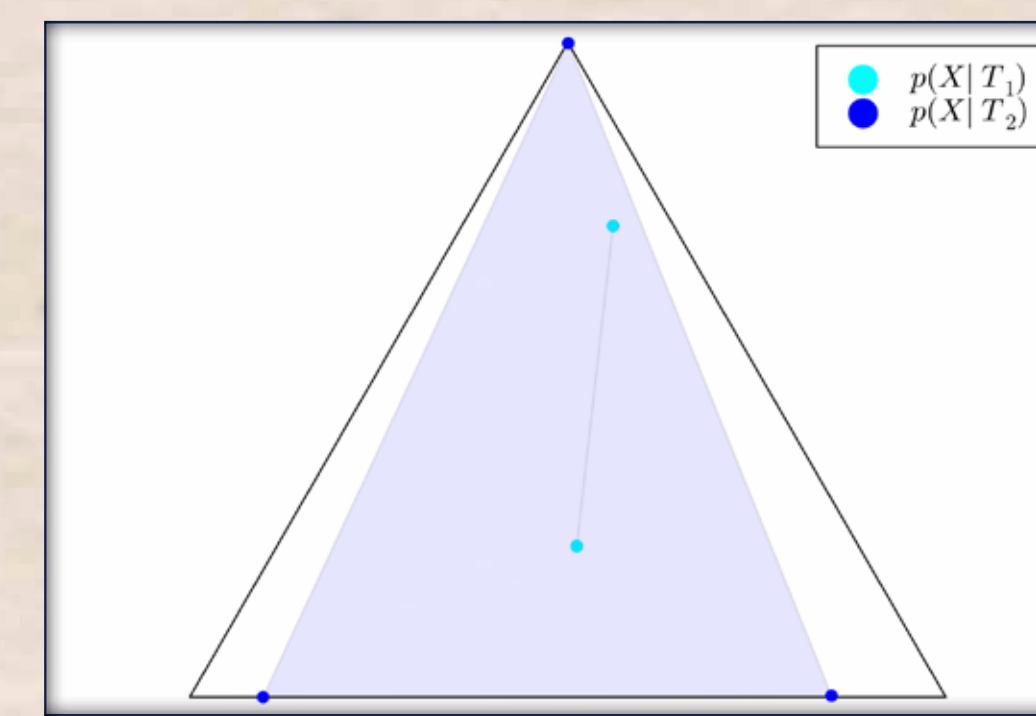
Exact SR: theoretical results

Convex hull characterisation

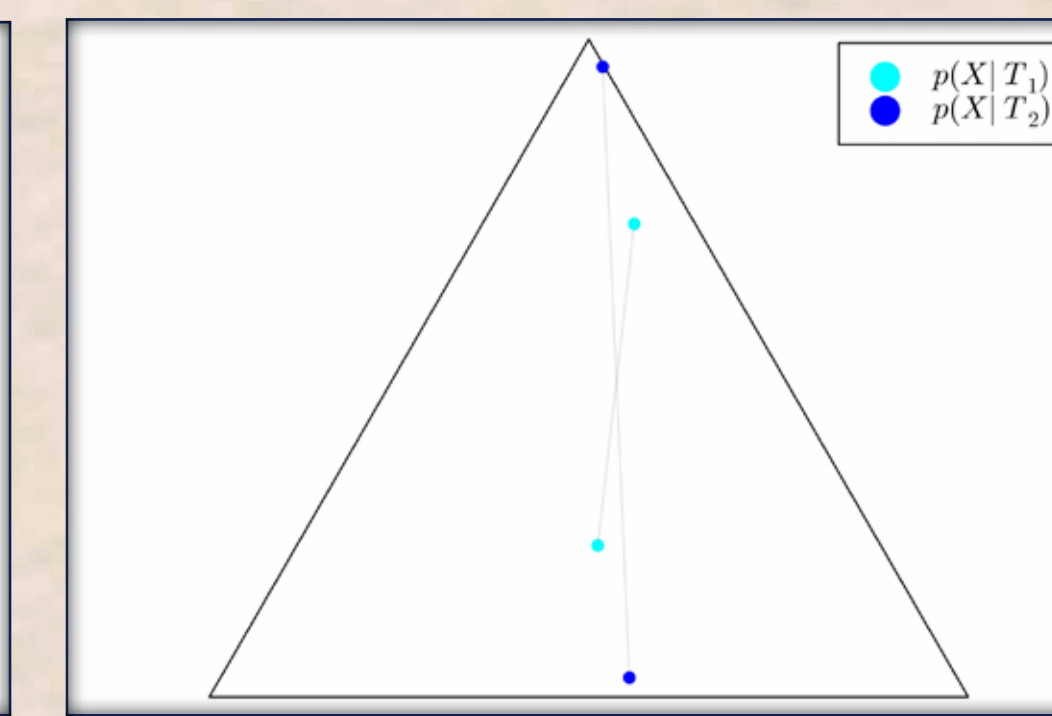
Successive Refinement: if and only if we can find

- a coarse IB optimal representation T_1 ,
- a finer representation T_2 which is **also IB optimal**,

such that the coarse decoder's conditional probabilities $p(X|T_1)$ are in the **convex hull** of the finer one's $p(X|T_2)$, where X is the environment.



Condition satisfied



Condition not satisfied

Some IB problems are always successively refinable: if

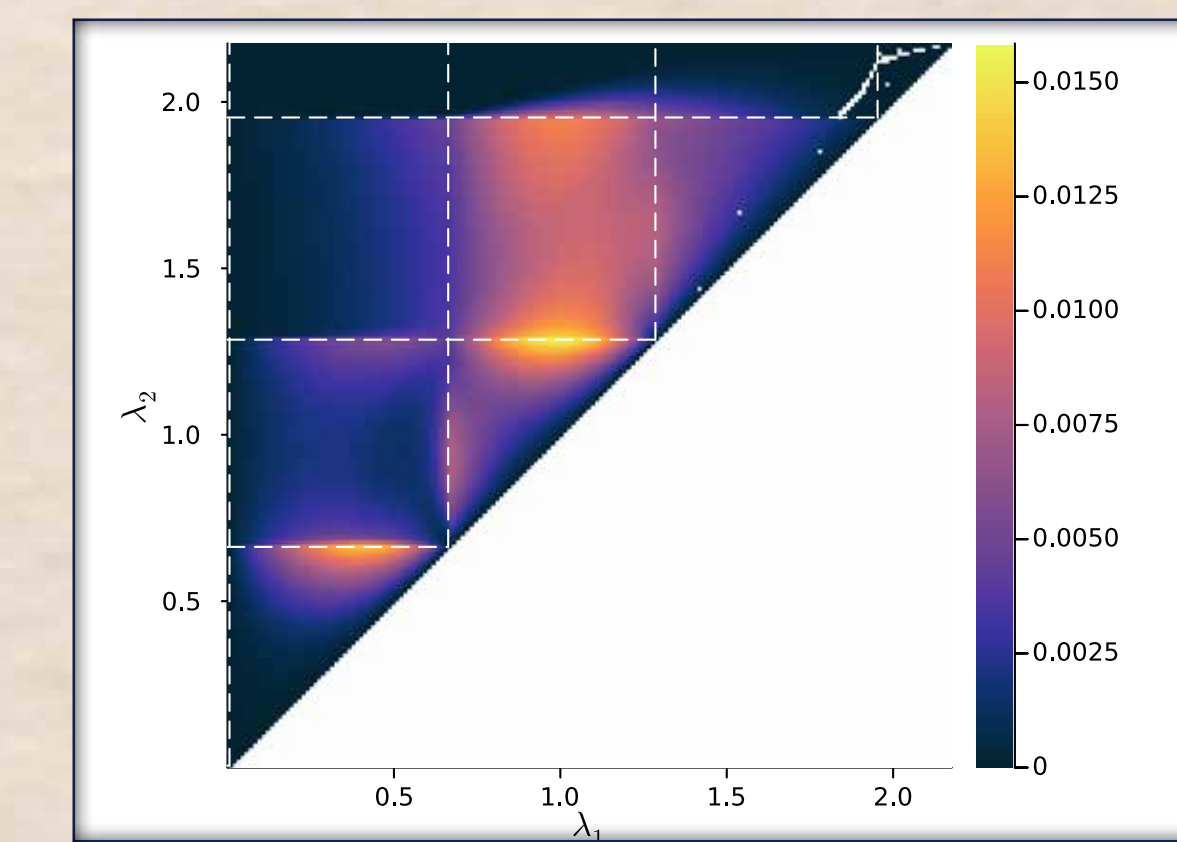
- X and Y are jointly Gaussian vectors, or
 - Y is a deterministic function of X , or
 - X and Y are binary,
- where X : environment and Y : relevant features.

Soft Successive Refinement

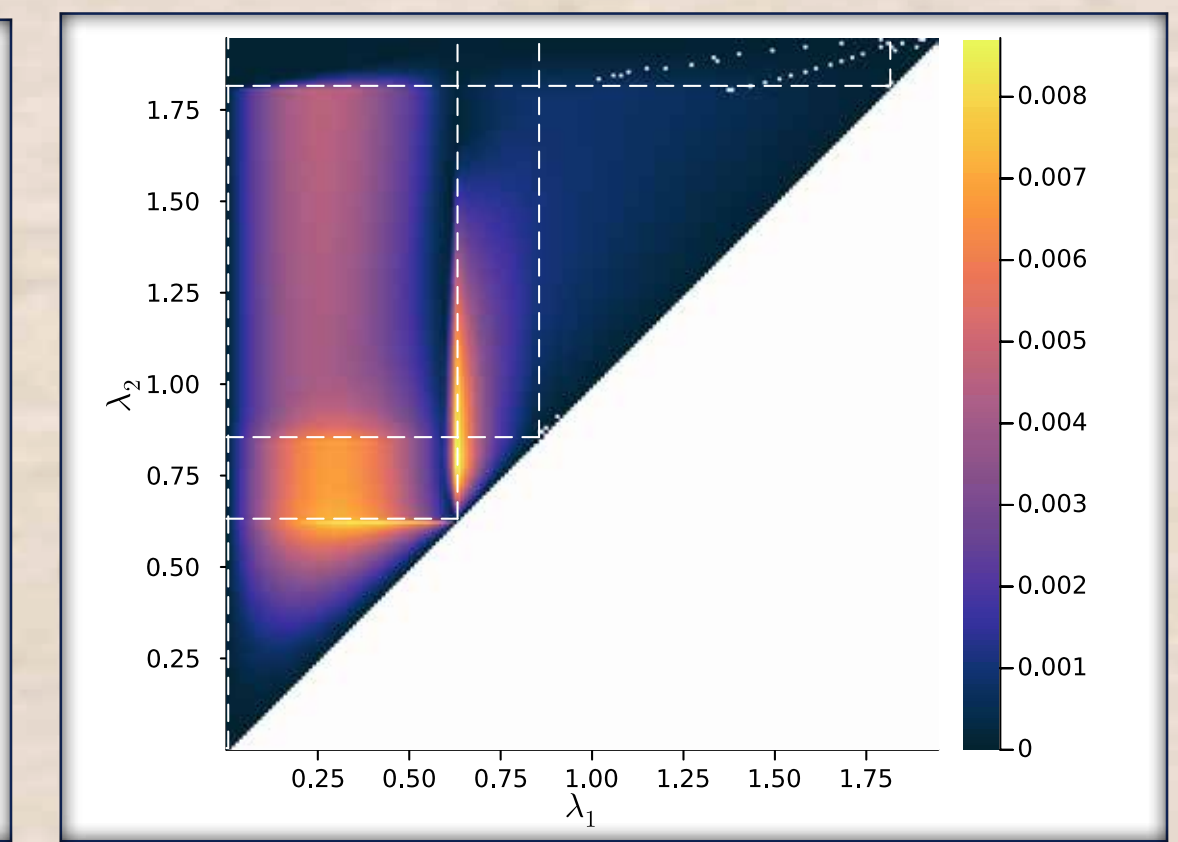
Information discarded along representation's refinement can be quantified [4] with the **unique information** [5]:

$$\min I_r(X; T_1 | T_2)$$

over all $r(X, T_1, T_2)$ such that $r(X, T_1) = p(X, T_1)$ and $r(X, T_2) = p(X, T_2)$.



Unique information, example 1



Unique information, example 2

- Rich structure which is not accessible with the binary notion of exact successive refinement
- Unique information rises then sharply drops close to IB bifurcations
- Sharp transition due to that of bottlenecks' trajectories on the probability simplex
- Unique information always significantly low, as compared to system's global information

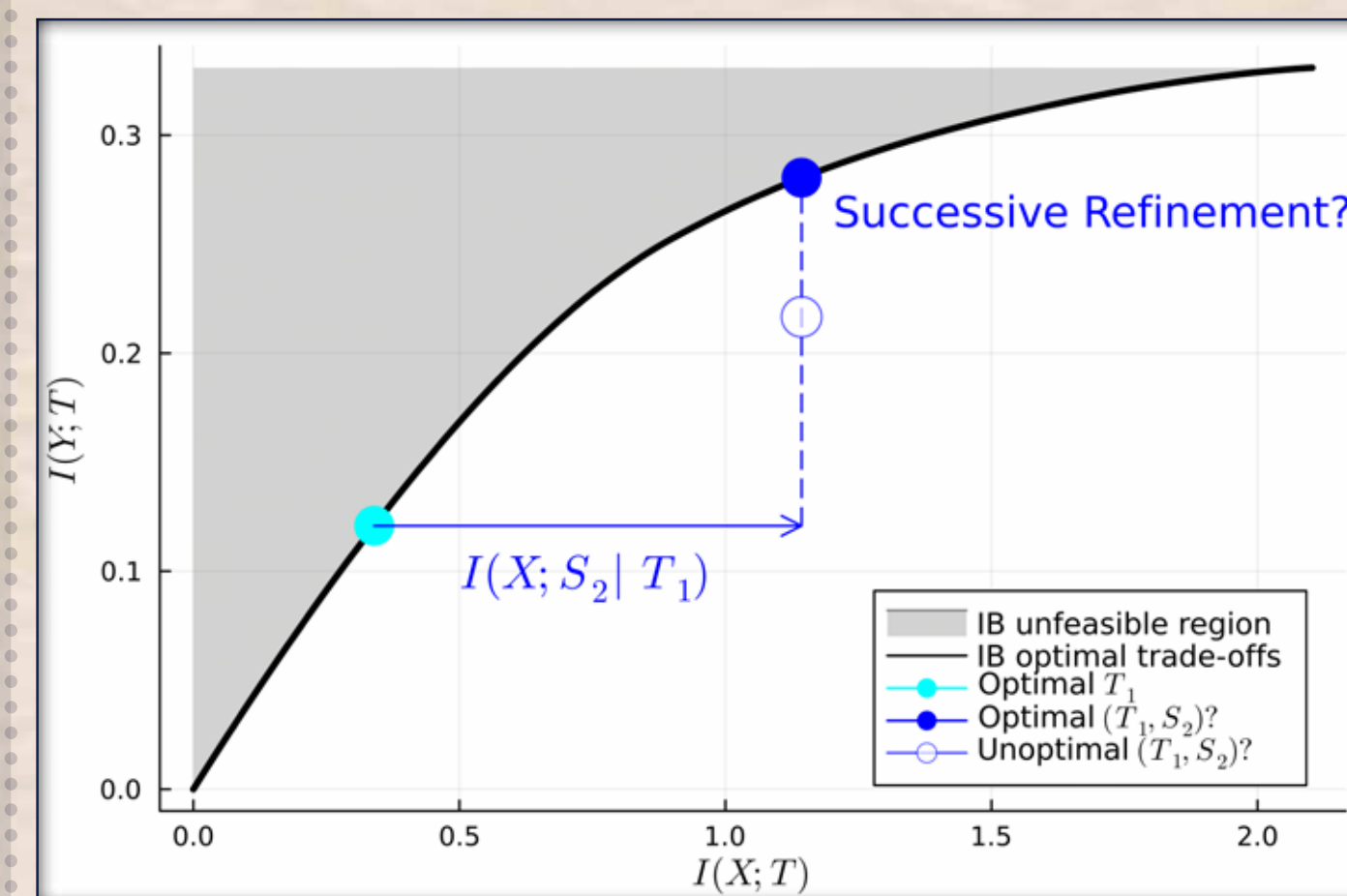
All our results on representations' refinement apply equally well to their coarsening.

Formalism

The Information Bottleneck

- The representation T extracts, within the environment X , information about relevant features Y (e.g., future, perceptions, homeostatic variables, ...)
- Cognitive cost is $I(X; T)$
- Behavioral relevancy is $I(Y; T)$
- “IB” optimal representations solve, for some λ ,

$$\arg \max_{Y-X-T, I(X;T) \leq \lambda} I(Y;T)$$



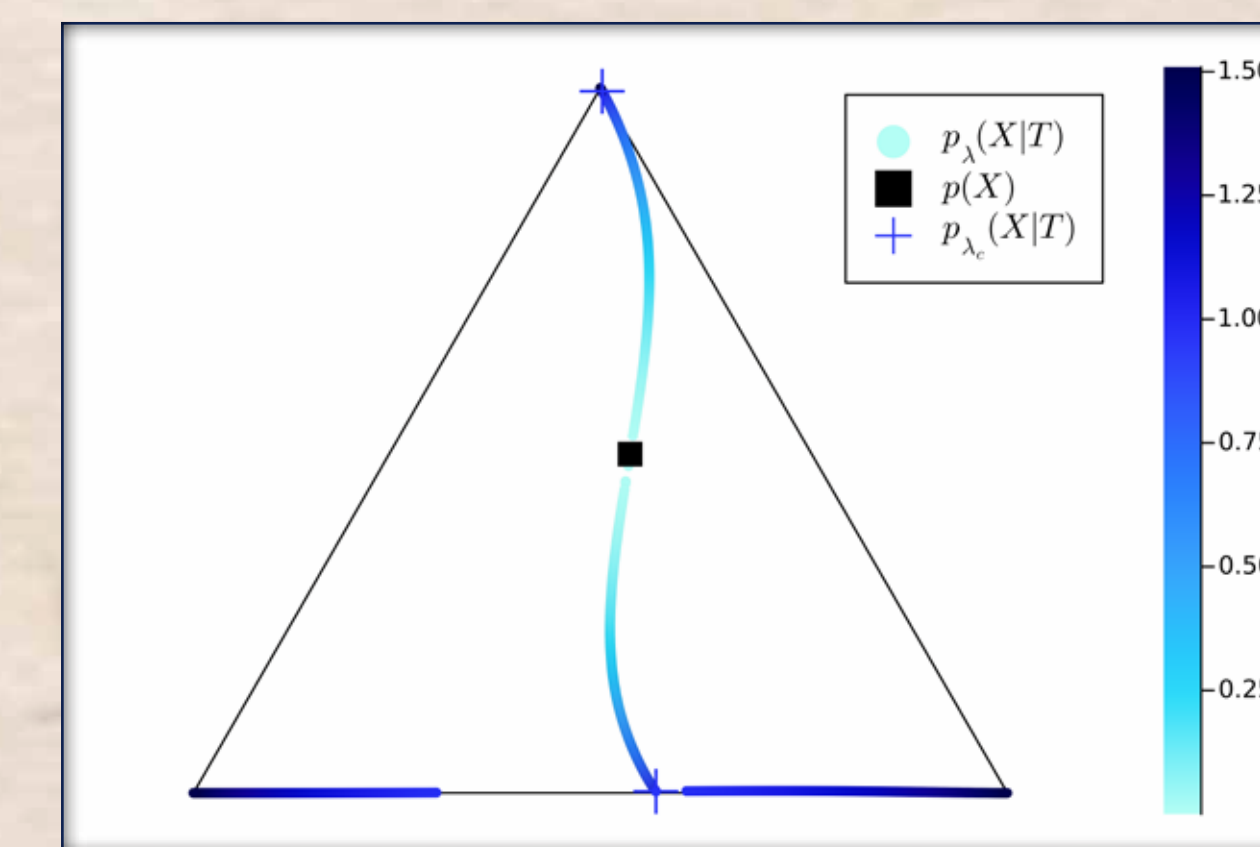
Exact Successive Refinement (SR)

- Create IB optimal coarse representation T_1
- Create finer representation (T_1, S_2) where supplement of information S_2 solves, for some λ_2 ,

$$\arg \max_{Y-X-(T_1, S_2), I(X; S_2 | T_1) \leq \lambda_2} I(Y; S_2 | T_1)$$

- Successive refinement: (T_1, S_2) fulfills IB optimality

Exact SR: minimal numerical experiments



- In general, exact successive refinement does not always hold
 - But visually, convex hull condition often “close” to being satisfied
- Almost no information discarded along refinement?

References

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