

Stochastic Modelling of Measles in a Disease-Eliminated Setting in Europe

Student

10 September, 2017

Abstract

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1 Acknowledgements

I would like to thank Dr. Sebastian Funk, to whom I owe a great deal for his patience and guidance during this project.

I would also like to thank my family and partner, Annie, who all provided tremendous support throughout the process.

2 Introduction

Measles is one of 25 vaccine preventable illnesses identified by the WHO as a global eradication target in their Global Vaccine Action Plan. While elimination efforts in some areas of the globe have seen great success, Europe still bears a disproportionate burden of the disease. This is due, at least in part, to low vaccination coverage in several nations[1].

While data on effective vaccination rates vary based on national surveillance capacity, regional efforts, like the European Sero-Epidemiology Network (ESEN), have provided more robust measurements ranging over a decade. Their findings reveal that all nations with an endemic spread of the disease fall short of the herd immunity threshold (around 96%)[2]. This shortfall reflects the recent trend of hesitancy on the part of parents to immunize their child with both doses of the MMR vaccine required for full coverage.

Beyond the immediate effects of endemic measles transmission within a country, it is reasonable to question whether these nations also put the elimination efforts of their neighbors at risk. It is this question that this project seeks to answer, particularly as more nations start to reach their elimination targets and are declared “measles eliminated” by the European division of the WHO[3].

3 Aims and Objectives

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4 Materials and Methods

4.1 Coding

All model functions were coded in R[4] with C++ supplement. The utilized packages were as follows:

- adaptivetau[5]
- ggplot2[6]
- data.table[7]
- Rcpp[8]
- Foreach[9]
- microbenchmark[10]
- profvis[11]

To increase modelling performance, the Foreach package parallelized the modelling function to utilize all available processor threads. The data.table package provided the “data.table” R object that is capable of much faster data sorting and subsetting methods than the standard packages. Rcpp served as a linker package between R and C++, allowing for computationally intensive portions of the R code to be offloaded to C++ and called within the R environment. Finally, the microbenchmark and profvis packages were essential for code optimization and profiling.

In addition to the model functional code, this document was created in L^AT_EX and compiled to PDF using the X_YL^AT_EX compiler.

4.2 SEIR Compartmental Model

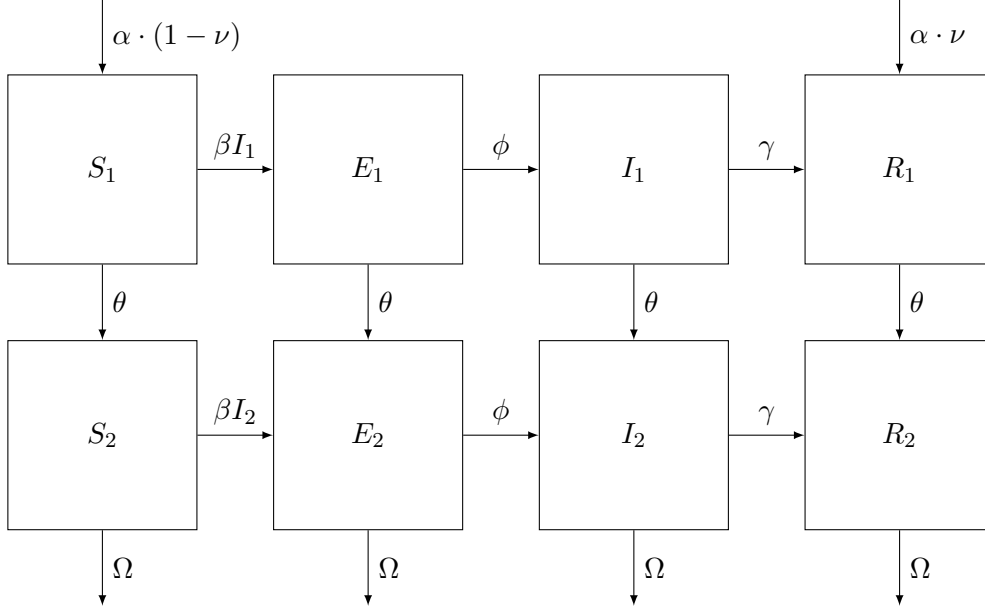


Figure 1: Age stratified SEIR Model with vital dyanmics

Where:

β_n = Rate of contact between infectious and susceptible persons

ϕ = Rate of onset of infectiousness subsequent to being infected

γ = Rate of recovery from measles from infectious period

α = Crude birth rate

ν = Effective vaccination rate at birth

Ω = Crude death rate

θ = Rate of aging from young to old compartments

To explore the infection dynamics of measles, a SEIR model was selected with two age compartments, subdividing younger and older populations. This was chosen for a few reasons. Firstly, it allows for the modelling of heterogeneous mixing within these age groups. Additionally, it allows for the model to more closely align with the age strata reported in seroprevalence data, thereby reducing the number of assumptions which would need to be made to fit incoming data. Finally, the selection of two compartments over some higher dimension limits the mathematical complexity of both modeling the data as well as mapping the parameter space while also allowing for some variation in age demographics.

4.3 Model Dynamics as Deterministic ODEs

The dynamics which describe the compartmental model can be written deterministically as ordinary differential equations :

$$\frac{dS_1}{dt} = N\alpha(1 - \nu) - S_1(\beta I_1 + \theta) \quad (1)$$

$$\frac{dE_1}{dt} = S_1\beta I_1 - E_1(\phi + \theta) \quad (2)$$

$$\frac{dI_1}{dt} = E_1\phi - I_1(\gamma + \theta) \quad (3)$$

$$\frac{dR_1}{dt} = N\alpha\nu + I_1\gamma - R_1\theta \quad (4)$$

$$\frac{dS_2}{dt} = S_1\theta - S_2(\beta I_2 + \Omega) \quad (5)$$

$$\frac{dE_2}{dt} = E_1\theta + S_2\beta I_2 - E_2(\phi + \Omega) \quad (6)$$

$$\frac{dI_2}{dt} = I_1\theta + E_2\phi - I_2(\gamma + \Omega) \quad (7)$$

$$\frac{dR_2}{dt} = R_1\theta + I_2\gamma - R_2\Omega \quad (8)$$

4.4 The Model as a Stochastic System

Model stochasticity was accomplished through the R package, `adaptivetau`. The deterministic differential equations are supplied as a rate function and evaluated by `adaptivetau`. Transitions are supplied as a vector and their rates defined by a rate function. The model is then stepped using a process called “explicit tau-leaping”[12].

This process provides an approximation of the output expected from Gillespie algorithm by maximizing the time step (called τ) between data points while minimizing the rate of change of the transition. The resulting output supplies many data points where the rate of change in a transition is high and sparse data points where the rate of change is low. This serves a dual purpose:

- To provide vastly superior performance to the Gillespie algorithm
- To introduce model stochasticity by using a random walk variable to define transition advancement

In making the model stochastic, we can now represent the standard compartmental model as a markov chain process.

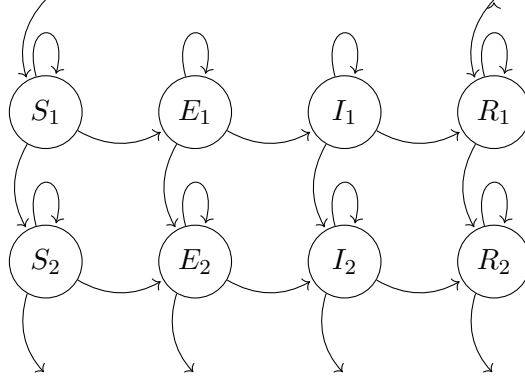


Figure 2: Markov-chain representation of the SEIR Model

This serves to highlight the possible transitions between each state per time step. The “force” of the transitions can still be described in the same way as the compartmental SEIR Model in Figure 1. However, the probability of any transition per time step is now a function of a poisson-distributed random walk variable defined in the `adaptivetau` modelling function.

$$P(\text{transition}) \sim \text{Poisson}(R_{\text{trans}} \cdot \tau) \quad (9)$$

As a consequence, for sufficiently large transition rates (R_{trans}) or time steps (τ), Equation 9 can be simplified using the normal distribution:

$$P(\text{transition}) \sim N\left(R_{\text{trans}} \cdot \tau, \sqrt{R_{\text{trans}} \cdot \tau}\right) \quad (10)$$

4.5 Estimating Model Parameters

Population demographic data for the project was acquired from the United Nations Department of Economic and Social Affairs, Population Division (UN DESA). Measles seroprevalence data was made available by findings from ESEN2 presented to the World Health Organization.

As previously mentioned, the model will have two age compartments in an effort to reduce the number of dimensions. However, the WHO report provides seroprevalence data in several age categories, and the appropriate proportion of measles seronegativity in each age group must be extrapolated. Additionally, the data in the seroepidemiology report were not all collected in the same year. Several countries, such as Sweden, have not submitted updated data in over 20 years, therefore some liberty was taken in best estimating these population values. Where possible, sensitivity analyses of the parameters were conducted to quantify the impact on model results.

To extrapolate values for in the model, seroprevalence values were direct standardized using the most recent population age demographics for each country. Two summary measures were created by summing the weighted rates for each age range contained in the model compartments. This is described here by the following equation:

$$P_{[i,n]} = \sum_i^n W_i \cdot \hat{p}_i \quad (11)$$

where:

$P_{[i,n]}$ = measles seroprevalence from ages i to n ,

W_i = weight of age group i , calculated as the quotient of the population of age group i divided by the population in groups i to n , and

\hat{p}_i = measles seroprevalence in group i

The resulting seroprevalence values are then multiplied by their respective populations to generate the proportion susceptible and immune in the two age compartments.

4.6 Calculating R_0

We can calculate R_0 by taking the leading eigenvalue of the Next Generation Matrix. Probably not important

4.7 Defining Model Steady-State Conditions

This section may not need to exist

4.8 Visualizing Parameter Space

To determine the smallest inputs into the model which would result in an epidemic, I analyzed the hyperparameter space of two model parameters. I employed whole grid search to avoid the possibility of missing the global optimum, which approximation methods such as random search may do without appropriate parameter weighting.

Let the two parameter inputs be defined as:

$$x \in \{1, 2, \dots, n\} \quad (12)$$

and,

$$y \in \{1, 2, \dots, n\} \quad (13)$$

where:

x = number of new cases of measles added to the model, and

y = number of “insertion events” which occur during one model simulation.

The cost function, $f(x, y)$, provides scalar output of the largest outbreak length when evaluating the model with x and y as inputs.

The three dimensional surface of the hyperparameter space is found by evaluating $f(x, y)$ with all reasonable combinations of x and y . The three values can then be expressed as cartesian coordinates and plotted. Importantly, this will help to reveal local maxima, minimizing for the input values.

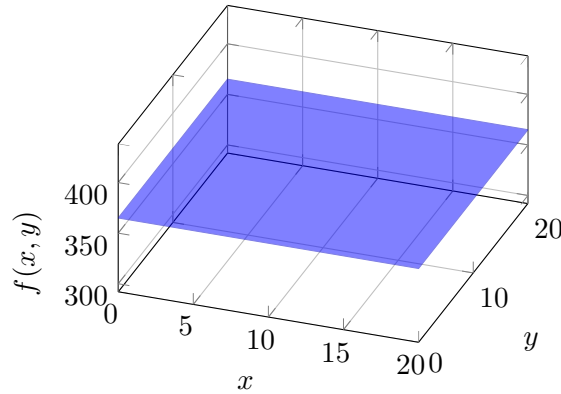


Figure 3: Example surface plot; maxima threshold shown at $f(x, y) = 365$

5 Results

There will be some results here

6 Discussion

There will be discussion of results here.

7 Recommendations

There will be some conclusions drawn here from the data. Hopefully they will be useful.

References

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