

Math 基础: 矩阵求导, y : scalar/m-vec, x : scalar/n-vec

$$\frac{\partial y}{\partial x} = \left(\frac{\partial y_1}{\partial x} \right) \frac{\partial y}{\partial x} = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} & \dots & \frac{\partial y_1}{\partial x_n} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} & \dots & \frac{\partial y_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial y_m}{\partial x_1} & \frac{\partial y_m}{\partial x_2} & \dots & \frac{\partial y_m}{\partial x_n} \end{pmatrix}$$

$$\left(\frac{\partial Y}{\partial x_{ij}} \right) = \left[\frac{\partial y_{i,j}}{\partial x} \right] \quad \left(\frac{\partial y}{\partial x} \right)_{ij} = \frac{\partial y}{\partial x_{ij}}$$

$$\textcircled{1} \frac{\partial a^T x}{\partial x} = \frac{\partial x^T \cdot a}{\partial x} = a \quad \star \text{重要求导!}$$

$$\textcircled{2} \frac{\partial x^T A x}{\partial x} = (A + A^T) x$$

Lagrange: 对于优化问题: $f(x) \leq 0, i=1, \dots, m$
 $h_i(x) = 0, i=1, \dots, n$
 则: $\mathcal{L}(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{j=1}^n \nu_j h_j(x)$
 其中 λ 和 ν 是拉格朗日乘子, $\lambda_i \geq 0, \nu_i$ 无约束

KKT条件: $\begin{cases} f_i(x) \leq 0, i=1, \dots, m \\ h_i(x) = 0, i=1, \dots, n \\ \lambda_i \geq 0 \end{cases}$

且 $\lambda_i f_i(x) = 0, i=1, \dots, m, \nabla_x \mathcal{L}(x, \lambda, \nu) = 0$

奇异值分解: $A = U \Sigma V^T, U \in \mathbb{R}^{m \times m}, V \in \mathbb{R}^{n \times n}, U^T U = I, V^T V = I; \Sigma \in \mathbb{R}^{m \times n}, (\Sigma)_{ii} = \sigma_i$, 且 σ_i 为非负数且满足: $\sigma_1 \geq \sigma_2 \geq \dots \geq 0$

由求: $A^T A x = \lambda x, |A^T A - \lambda I| = 0$

$\sigma_i = \sqrt{\lambda_i}$, 而 U 中每个列向量为 $A A^T$ 中 eigen

V 中每个列向量为 $A^T A$ 中 eigenvector

MAP: $\hat{\theta} = \underset{\theta}{\operatorname{argmax}} P(\theta|D) \propto P(\theta) \cdot P(D|\theta)$

MLE: $\hat{\theta} = \underset{\theta}{\operatorname{argmax}} P(D|\theta)$

GD: $x^{k+1} \leftarrow x^k - \alpha_k \nabla f(x^k) \rightarrow \rightarrow \geq 0$

$\log P(X) = \int q(z) \log \frac{P(X, z)}{q(z)} dz + K_L(q(z) \| P(z|X))$

ELBO

$$H(X) = -\sum_{x \in X} p(x) \log p(x) = \mathbb{E}[\log \frac{1}{p(x)}]$$

$$H(Y|X) = -\sum_{x \in X} p(x) \sum_{y \in Y} p(y|x) \log p(y|x)$$

$$= \sum_{x \in X} \sum_{y \in Y} p(x, y) \log \frac{1}{p(y|x)}$$

$$I(X; Y) = \sum_{x, y} p(x, y) \log \frac{p(x, y)}{p(x)p(y)} = \text{or: } H(X) - H(X|Y)$$

$$I(X; Y) = \sum_{x, y} p(x, y) \log \frac{p(x, y)}{p(x)p(y)} = \text{or: } H(X) - H(X|Y)$$

$$H(X) = H(X|Y) + I(X; Y)$$

$$H(X|Y) = H(X) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

$$H(X, Y) = H(X) + H(Y) - I(X; Y)$$

Kernel: 将样本映射至高维以 solve 线性不可分问题。但也希望在高维中算内积, 可用原始数据在低维中的操作得到! 与计算大!! 即:

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle = \phi(x_i)^T \phi(x_j)$$

target \rightarrow Loss (random)

$\rightarrow x^{t-1} \rightarrow x^t \rightarrow x^{t+1}$

$\frac{dL}{dw^t} = \frac{\partial L}{\partial x^t} \cdot \frac{\partial x^t}{\partial w^t} \cdot \frac{\partial w^t}{\partial L}$ 链式法则

Recom Sys & Matrix Factorization

Unconstrained: $R \in \mathbb{R}^{m \times n}$, $R \leq \text{rank } k < \min(m, n)$

$U \in \mathbb{R}^{m \times k}$, $V \in \mathbb{R}^{n \times k}$, s.t., $R = UV^T$

$\nabla (U, V) = \frac{1}{2} \|R - UV^T\|_F^2 = \frac{1}{2} \sum_{i,j=1}^n (R_{ij} - U_{i \cdot} \cdot V_{\cdot j}^T)^2$

where R_{ij} is known. 可加 $\frac{1}{2} \|U\|_F^2 + \frac{1}{2} \|V\|_F^2$ 正则化

$\nabla U_j: \nabla_j (U, V) = -E_{ij} V_{\cdot j}^T + \lambda U_j$

$\nabla V_{\cdot i}: \nabla_i (U, V) = -E_{ij} U_j + \lambda V_{\cdot i}$ (SGD)

$U_j \leftarrow U_j - \eta \nabla U_j$; $V_{\cdot i} \leftarrow V_{\cdot i} - \eta \nabla V_{\cdot i}$

Or: Fix V , 解 U ; Fix U , 解 V ; 循环

若已知 SVD $R = Q \Sigma P^T$, 则可 truncate $\rightarrow k$

$U \triangleq Q_k \Sigma_k$, $V \triangleq P_k$, 开始优化

Constrained: $U, V = \text{argmin}_{U, V} \frac{1}{2} \|R - UV^T\|_F^2$ s.t.

$U_j \geq 0, V_{ij} \geq 0$

集成: Boosting: Goal: $\hat{h}(x) = \text{sign}(\sum_{t=1}^T \alpha_t h_t(x))$

AdaBoost: Boosting: $h_t(x)$ 间有依赖关系

for $t = 1, \dots, T$ do $\leftarrow T$ 机器学习个数

choose h_t (一般: weak) (and train)

weight rate $\in (0, 1)$

if $\epsilon > 0.5$, break (太差!)

$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right)$

$D_{t+1}(x) = \frac{D_t(x)}{Z_t} \times \begin{cases} \exp(-\alpha_t), & \text{if 预测对} \\ \exp(\alpha_t), & \text{if 错} \end{cases}$

$= \frac{D_{\text{train}}}{Z_t} \exp(-\alpha_t h_t(x))$

end for T

$h(x) = \text{sign}(\sum_{t=1}^T \alpha_t h_t(x)) \Rightarrow$ 只能作二分类

*: $Z_t = e^{\alpha_t \epsilon_t} + e^{-\alpha_t (1 - \epsilon_t)}$, $\alpha_t = \frac{1}{2} \ln \frac{1 - \epsilon_t}{\epsilon_t}$

$Z_t = 2 \sqrt{\epsilon_t (1 - \epsilon_t)}$

Δ : 对于无法接受带权样本的基本算法, 可重复采样

Bagging: for $t = 1, \dots, T$ do

for $s = 1, \dots, S$ do \leftarrow 每个 h_t 用自己的

$is \sim \text{Uniform}(1, \dots, N)$ S_t

$S_t = \{(x^{(is)}, y^{(is)})\}_{s=1}^S$

$h_t = \text{train}(S_t)$

return $\hat{h}(x) = \text{aggregate}^*(h_1, \dots, h_T)$

*: 如分类中, 为 majority vote; 回归中, average

Feature Bagging: 随机选 S 个 feature, 每个样本只

关注这 S 个, 每个 h_t . D_t 重新做一个新的

Random Forest: 抽 n 个 sample \rightarrow 基决策树每个

结点的属性集合子集, 在于集上选最优属性。

*: $k = \log_2 d$; $k = 1$: 随机; $k = d$: 原决策树 learn

Δ : Bootstrapping: 抽 n 个样本 (有放回), 36.8% 的 sample 集

表现不错, 且收敛性与 Bagging 相同 $\lim_{m \rightarrow \infty} (1 - \frac{1}{m})^m = \frac{1}{e}$

K-means: Initialize $c = \{c_1, \dots, c_k\}$

Repeat for i in $\{1, \dots, N\}$

until: $z^{(i)} \leftarrow \text{argmin}_j \|x^{(i)} - c_j\|_2$

Converge for j in $\{1, \dots, k\}$

$c_j \leftarrow \text{argmin}_i \sum_{i: z^{(i)}=j} \|x^{(i)} - c_j\|_2^2$

$\Rightarrow C_j = \frac{1}{|C_j|} \sum_{x \in C_j} x$ (平均)

*: 可随机, 也可 Furthest Point Heuristic, 也可:

++: 先选 C_1 , pick C_j from 分布: picked

$P(C_j = x^{(i)}) \propto \min_j \|x^{(i)} - c_j\|_2^2$, $x^{(i)}$ are not

posterior prior $P(x, z | \theta)$

EM: $E: Q(\theta | \theta^t) = \sum_z P(z | x, \theta^t) \log P(x, z | \theta)$

M: $\theta^{t+1} = \text{argmax}_{\theta} [Q(\theta | \theta^t) + \log p(\theta)]$ 加 MAP

GMM: 假设点生成: K 个高斯以 π_k 概率率随机

选一个, 然后点生成服从分布 $N(x | \mu_k, \Sigma_k)$

则 $\log p(x, z | \theta) = \sum_{i=1}^N \log \pi_{z_i} + \log N(x_i | \mu_{z_i}, \Sigma_{z_i})$

$r_k = P(z_i = k | x_i, \theta^{\text{old}})$

$= \frac{P(x_i | z_i = k, \theta^{\text{old}}) P(z_i = k | \theta^{\text{old}})}{\sum_{k=1}^K P(x_i | z_i = k, \theta^{\text{old}}) P(z_i = k | \theta^{\text{old}})}$

$= \frac{P(x_i | \theta^{\text{old}})}{\sum_{j=1}^K \pi_j^{\text{old}} N(x_i | \mu_j^{\text{old}}, \Sigma_j^{\text{old}})}$

$\sum_{j=1}^K \pi_j^{\text{old}} N(x_i | \mu_j^{\text{old}}, \Sigma_j^{\text{old}})$

$M: Q(\theta, \theta^{\text{old}}) = \sum_{i=1}^N \sum_{k=1}^K r_{ik} [\log \pi_k + \log N(x_i | \mu_k, \Sigma_k)]$

且: $\sum_k \pi_k = 1$, $\Sigma = Q(\theta, \theta^{\text{old}}) + \lambda (I - \sum_{k=1}^K \pi_k)$

$\Rightarrow \pi_k^{\text{new}} = \frac{1}{N} \sum_{i=1}^N r_{ik}$

$\mu_k^{\text{new}} = \frac{\sum_{i=1}^N r_{ik} x_i}{\sum_{i=1}^N r_{ik}}$

$\Sigma_k^{\text{new}} = \frac{\sum_{i=1}^N r_{ik} (x_i - \mu_k^{\text{new}})(x_i - \mu_k^{\text{new}})^T}{\sum_{i=1}^N r_{ik}}$

$\sum_{i=1}^N r_{ik}$

PAC: 主成分分析:

① $x_i \leftarrow x_i - \frac{1}{m} \sum_{i=1}^m x_i$: X ② XX^T (协方差)

③ 特征值分解 ④ 取最大 d' 个 eigenvalue 对应的

eigenvector, 组成 $w^* \in \mathbb{R}^{d \times d'}$

则 $w^* x$ 后进入低维

CNN: 注重于 local connectivity; parameter

sharing; pooling/subsampling hidden units

卷积中: kernel 数之和为 1; 卷积中: 还有 bias!!

Input: $(H_{\text{in}}, W_{\text{in}}, C_{\text{in}})$, 卷积: (K, K, C_{in}) , 填充 P

stride S , 则输出 $(H_{\text{out}}, W_{\text{out}}, C_{\text{out}})$:

$H_{\text{out}} = \left\lfloor \frac{H_{\text{in}} + 2P - K}{S} \right\rfloor + 1$ (卷积)

$W_{\text{out}} = \left\lfloor \frac{W_{\text{in}} + 2P - K}{S} \right\rfloor + 1$ (不是个通道)

$C_{\text{out}} = C_{\text{in}} - K + 1$ (bias of bias = C_{out})

每个 channel 的卷积结果是相加而非平均

Pooling layers: e.g., Max pooling (no learnable parameters)

CNN 的两个关键性质: Equivariance, 输入经过变换后,

输出也经历某种变换; Invariance, 输出不变! (平移)

\rightarrow 卷积 (e.g. conv with shift) \rightarrow 池化 (e.g. conv + pooling)

SVM 符号: 约束 $W^T x + b = -1, W^T x + b = 1$

$\gamma = \frac{1}{\|w\|}, d = \frac{2}{\|w\|}$, 则构造问题

$\min \frac{1}{2} \|w\|^2, s.t. y_i (w^T x_i + b) \geq 1$

$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 + \sum_{i=1}^m \alpha_i (1 - y_i (w^T x_i + b))$

$\alpha = (\alpha_1, \alpha_2, \dots, \alpha_m)$. 则 KKT 条件:

① Primal: $y_i (w^T x_i + b) \geq 1$ ② dual: $\alpha_i \geq 0$

③ Complementary: $\alpha_i (y_i (w^T x_i + b) - 1) = 0$

④ Stationary: $\nabla_w L = 0$

对 w 偏导: $w = \sum_{i=1}^m \alpha_i y_i x_i$ 代入:

$b: \sum_{i=1}^m \alpha_i y_i = 0$

$\max_{\alpha} \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^m \alpha_i \alpha_j y_i y_j x_i^T x_j$

s.t. $\sum_{i=1}^m \alpha_i y_i = 0, \alpha_i \geq 0$, 解出 α 后:

$f(w) = w^T x + b = \sum_{i=1}^m \alpha_i y_i x_i^T x + b$

Why biased? $E(\hat{\sigma}_{MLE}) = E[\frac{1}{n} \sum_{i=1}^n (x_i - \hat{x}_{MLE})]$

则 $E[\hat{\sigma}_{MLE}] = \frac{n-1}{n} \sigma^2$, bias = $-\frac{\sigma^2}{n}$

Probably Approximate Correct learning:

$P(|\hat{\theta} - \theta^*| \geq \epsilon) \leq 2e^{-2n\epsilon^2} \leq \delta, n \geq \frac{\ln(2/\delta)}{2\epsilon^2}$

K-mean++ achieves a $O(\log k)$ approximation to optimal clustering: 这种思路对初始化的方法有益

ELBO: $\log p(X) = \log \frac{p(X, Z)}{p(Z|X)} \cdot p(X)$

$= \int \log \frac{p(X, z)}{q(z)} \frac{q(z)}{p(z|X)} \cdot p(X) dz$

$= \int q(z) \log \frac{p(X, z)}{q(z)} dz + \int q(z) \log \frac{q(z)}{p(z|X)} dz$

$= \int q(z) \log \frac{p(X, z)}{q(z)} dz + KL(q(z) || p(z|X))$

ELBO ≥ 0

ELBO = $\int q(z) \log p(X, z) dz - \int q(z) \log q(z) dz$

$= E_{q(z)} [\log p(X, z)] + H(q(z))$

Perceptron mistake bound: $(R/r)^2$

Proof: 设 θ^* 为完美超平面参数, 且 $\|\theta^*\| = 1$

且 $\forall i, y^{(i)} \cdot (\theta^* \cdot x^{(i)}) \geq r, \|\theta^{(k+1)}\| \geq kr$

则 $\theta^{(k+1)} = \theta^{(k)} + y^{(i)} x^{(i)}$

$\theta^{(k+1)} \cdot \theta^* \geq \theta^{(k)} \cdot \theta^* + r$, 又 $\theta^{(k+1)}$ 空初值

同时 $\|\theta^{(k+1)}\|^2 = \|\theta^{(k)} + y^{(i)} x^{(i)}\|^2 < 0$, 矛盾!

$\leq \|\theta^{(k)}\|^2 + \|x^{(i)}\|^2 \leq kR^2, k \leq \frac{R^2}{r^2}$

Logistics: $p(y_i | x_i; w, b) = y_i p_1(x_i; \beta) + (1 - y_i) p_0(x_i; \beta)$

$\mathcal{L}(\beta) = \sum_{i=1}^m (-y_i \beta^T x_i + \ln(1 + e^{\beta^T x_i}))$

$\frac{\partial \mathcal{L}(\beta)}{\partial \beta} = -\sum_{i=1}^m \hat{x}_i (y_i - p_1(x_i; \beta))$

AdaBoost: $\epsilon = \frac{1}{n} \sum_{i=1}^n \mathbb{I}(y_i \neq H_{final}(x_i))$

$\leq \frac{1}{n} \sum_{i=1}^n \exp(-y_i (\sum_{t=1}^T \alpha_t h_t(x_i)))$

$D_{H_1}(i) = \frac{Z_T(i)}{Z_{T-1}(i)} \exp(-\alpha_T y_i h_T(x_i))$

$D_T(i) = \frac{D_{H_1}(i)}{Z_{T-1}(i)} \exp(-\alpha_T y_i h_T(x_i))$

$D_1(i) = \frac{1}{n}$

$\epsilon \leq \frac{1}{n} \sum_{i=1}^n \exp(-y_i \sum_{t=1}^T \alpha_t h_t(x_i)) = \frac{1}{n} \sum_{i=1}^n \prod_{t=1}^T D_t(i)$

$\epsilon \leq \frac{1}{n} \sum_{i=1}^n \exp(-y_i \sum_{t=1}^T \alpha_t h_t(x_i)) = \frac{1}{n} \sum_{i=1}^n \prod_{t=1}^T D_t(i)$

$\therefore \epsilon \leq \prod_{t=1}^T Z_t, \text{ 又 } Z_t = e^{\alpha_t^T \epsilon_t} e^{-\alpha_t^T \epsilon_t}$

$\frac{\partial Z_t}{\partial \alpha_t} = \epsilon_t e^{\alpha_t^T \epsilon_t} - (1 - \epsilon_t) e^{-\alpha_t^T \epsilon_t} \Rightarrow \alpha_t = \frac{1}{2} \log \frac{1 - \epsilon_t}{\epsilon_t}$

$\frac{\partial^2 Z_t}{\partial \alpha_t^2} = \epsilon_t e^{\alpha_t^T \epsilon_t} + (1 - \epsilon_t) e^{-\alpha_t^T \epsilon_t} \geq 2\sqrt{\epsilon_t(1 - \epsilon_t)}$

或: $\mathcal{L}(\exp(H/D)) = E_{x \sim D} [e^{-f(x)H(x)}]$

$\frac{\partial}{\partial H(x)} = e^{-H(x)} p(f(x) = 1|x) + e^{H(x)} p(f(x) = -1|x)$

$H(x) = \frac{1}{2} \ln \frac{p(f(x) = 1|x)}{p(f(x) = -1|x)}$

$H(x) = \frac{1}{2} \ln \frac{p(f(x) = 1|x)}{p(f(x) = -1|x)}$

