aab Release a

В

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AABB

1.1 package_aab.src package

1.1.1 Submodules

1.1.2 package_aab.src.Automata module

```
class package_aab.src.Automata.Automata(alphabet: str, pattern: str)
    Bases: object
```

Class implemented for the search of patterns in nucleotide sequences. This pattern search method processes a sequence in a linear way, reading from left to right. The search started at the first state of the "machine" and at the first character of the text, at each step of the search the next character of the sequence is considered, the next state is searched state and moves to a new state. The number of states is equal to the length of the pattern plus one. The pattern is found when the pattern being searched for is equal to the length of the pattern entered.

applyNextState (seq: str) \rightarrow list

Method that returns a list of all next states. :param seq: sequence entered :return: list of next states

buildTransitionTable (pattern: str)

Method that constructs the transition table. The transition table returns the next state of the automata machine from the current state and previous states. :param pattern: pattern to search in the sequence

```
nextState ( current: int, char: str ) \rightarrow int
```

Method that returns the next state. :param current: current state :param char: character of the pattern to search for :return: the next state

```
patternSeqPosition (seq: str) \rightarrow list
```

Method that returns the list of positions where an occurrence of the pattern in the sequence starts. :param: sequence entered :return: list of the positions where an occurrence of the pattern in the sequence starts.

printAutomata()

```
package_aab.src.Automata.overlap (seq1: str, seq2: str) \rightarrow int
```

Method that overlaps two sequences and checks for matching :param seq1: first string :param seq2: second string :return: last position of the smallest string that matches

1.1.3 package_aab.src.BWT module

```
class package_aab.src.BWT.BWT ( seq='', buildsufarray=False, sa=None )
    Bases: object
```

Class for implementing the Burrows-Hweeler algorithm. The algorithm is useful for compressing large sequences, thus reducing their space. Moreover, it is possible to find patterns in the compression format efficiently.

```
build_bwt ( text, buildsufarray=False ) → str
```

Method that generates rotations of the text and sorts them to construct the BWT string. :param text: :param buildsufarray: :return:

```
bw_matching ( pattern=<class 'str'> ) → List[int]
```

Method for searching for patterns from BWT sequence :param pattern: pattern to search :return: list of matches found

```
bw_matching_pos ( patt ) \rightarrow List
```

Method that searches for matching patterns :param patt: pattern to search :return: list of matches found

```
check_seqs()
```

Method that checks if the sequence introduced is a string :return:

```
static findithocc ( le, elem, index )
```

Method that allows the discovered of the i-ésima occurence of an symbol in the list :param le: :param elem: :param index: :return: -1 in the cases where doesn't occur

```
get_first_col() → List[str]
```

Method that recovers the first column of BWT sequence. The first column correspond the BWT sequence sorted. :return: first column of Matrix M

```
{\tt inverse\_bwt}\;(\;\;) \to str
```

Method recovers the original sequence from its BWT. :return: string of the original sequence

```
last_to_first ( ) → List
```

Creates a list mapping each character in the BWT sequence to its corresponding index in the first column. :return: list of indices

```
set bwt (bw)
```

Method that sets the BWT string directly for a BTW instance. It is useful in scenarios where we have a precomputed BWT string and want to assign it to the bwt attribute of the BWT instance without recomputing it using the build_bwt method. :param bw: :return:

1.1.4 package aab.src.BoyerMoore module

```
class package_aab.src.BoyerMoore.BoyerMoore(alphabet=<class'str'>, pattern=<class'str'>)
Bases: object
```

```
process_bcr()
```

Bad Character rule implementation. This rule is used to skip over characters in the text that do not match the corresponding character in the pattern. It precomputes the last occurrence of each character in the pattern and uses this information to determine the number of positions to shift the pattern relative to the text when there is a mismatch. Method where a dictionary is created with all possible symbols (occ) as keys, and the values define the rightmost position at which the symbol appears in the pattern (-1 means it does not occur). This allows you to quickly calculate the number of positions to follow to search according to the mismatch in the pattern (value for the symbol in the dictionary). Note that

this value can be negative, meaning that the rule in this case is not useful and is ignored in the next iteration.

```
process_gsr()
```

Good Suffix rule implementation. Calculates the value of the f list (the length of the longest proper suffix that matches the suffix of the pattern), and s list (the length of the longest proper suffix that matches the prefix of the pattern).

```
search_pattern ( text=<class 'str'> ) → List[int]
```

This method allows to find a pattern in a given text, based on the object of the class that contains the pattern and its alphabet. :param text: string of the text where we want to look for our pattern :return: list with the indexes where the pattern starts

1.1.5 package_aab.src.EAMotifs module

1.1.6 package_aab.src.EvolAlgorithm module

1.1.7 package_aab.src.Indiv module

```
class package_aab.src.Indiv.Indiv(size, genes=[], lb=0, ub=1)
    Bases: object
    # The Indiv class represents an individual in a genetic algorithm. It contains methods for initial-
    ization, mutation, crossover, and fitness evaluation.
    crossover ( indiv2 ) \rightarrow tuple
    getFitness() → Union[int, float]
    getGenes ( ) \rightarrow list
    initRandom (size: int) \rightarrow None
    mutation ( ) \rightarrow None
    one_pt_crossover(indiv2) → tuple
    setFitness (fit) \rightarrow None
class package_aab.src.Indiv.IndivInt(size: int, genes: list = [], lb: int = 0, ub: int = 1)
    Bases: Indiv
    initRandom (size: int) \rightarrow None
         Method that generates a list of genes of the individual (random int numbers between upper
         and lower bounds):param size: number of genes to generate:return:
    mutation()
class package_aab.src.Indiv.IndivReal ( size: int, genes: list = [], lb: float = 0.0, ub: float =
1.0)
    Bases: Indiv
    initRandom (size: int) \rightarrow None
         Method that generates a list of genes of the individual with random values in the interval [lb,
         ub]. :param size: :return:
    mutation ( ) \rightarrow None
```

Method for real representations that alters a single gene (mutation) The mutation method performs a mutation operation on one randomly selected gene in the individual. :return:

1.1.8 package_aab.src.MetabolicNetwork module

1.1.9 package_aab.src.MotifFinding module

```
class package_aab.src.MotifFinding.MotifFinding(size: int = 8, seqs=None)
```

Bases: object

Class implemented for searching for recurrent patterns in a biological sequence, which can be DNA or proteins. The pattern to look for can be an exact sequence or a degenerate consensus in which there are ambiguous characters.

branchAndBound () → Optional[Union[list, List[int]]]

Method that implements to iterate over the initial position of the list of solutions to find the best solution motif. :return: the vector of starting positions s (representative of the best motif found)

bypass (s: list) \rightarrow list

Method implemented to bypass the condition explained above. :param s: index list of the motifs in the entered sequences. :return: list of indexes with zeros in the non-corresponding positions.

createMotifFromIndexes (indexes: list)

Method that implements probabilistic motifs of type MyMotif. :param indexes: list of the indexes of the initial positions of the motif of the sub-sequences used to create the motif. :return:

exhaustiveSearch () $\rightarrow list$

Method implemented to find the motif with the vector of best scores. This method allows to derive the profile and the consensus sequence. :return: vector of best scores

gibbs ($num_iterations: int) \rightarrow list$

Method that implements the Gibbs Sampling algorithm, by choosing new segments at random (increasing the possibilities of converging to a correct solution). The algorithm starts with a set of randomly selected motif positions, and then in each iteration, it chooses one sequence at random, removes it from consideration, and recomputes the motif position based on the remaining sequences. This process continues for a fixed number of iterations, after which the algorithm returns the best set of motif positions found so far. :param num_iterations: number of iterations :return: list of best scores

${\tt heuristicConsensus}\;(\) \to list$

 $^{\prime\prime\prime}$ Method that computes the heuristic consensus algorithm: - Considering only the first two sequences, choose the initial positions s1 and s2 that give a better score. - For each of the following sequences, iteratively, choose the best starting position in the sequence, in order

to maximize the score.

Returns list of starting positions s (representative of the best motif found)

$\textbf{heuristicStochastic} \; (\;) \to list$

Method that computes the heuristic stochastic consensus algorithm, using the most likely segments to adjust starting positions to achieve the best profile (motif) :return: the vector of starting positions s (representative of the best motif found)

```
nextSol ( s: list ) \rightarrow list
```

Auxiliary method (to exhaustiveSearch) that gives the next vector of starting positions. Method implemented to iterate over all the possible values of the motif position in the entered sequence. :param s: list of the motif indexes in the entered sequence. :return: list of all the possible values of the position of the motif in the entered sequence.

```
nextVertex ( s: list ) \rightarrow list
```

Method implemented to find the next vertex. :param s: list of indices of the motifs in the entered sequences. :return: list of next vertices

```
readFile ( file: str, type: str ) \rightarrow None
```

Method that reads the sequence file. param file: sequence file. param type: type of the sequences.

```
roulette ( f: list ) \rightarrow int
```

Method implemented to simulate examples of a roulette wheel. The probability of choosing a certain position is proportional to your score. :param f: list of positions :return: chosen value

```
score (s: list) \rightarrow int
```

Method implemented for the scoring function. The scoring function iterates over all motif positions and determines the maximum value of the motif score. :param s: list of motif indices in the entered sequences. :return: maximum score of the motif score.

```
scoreMult(s)
```

Method implemented for the multiplication of the maximum motif scores. The scoreMult() method provides a way to quantify the importance of each occurrence of a motif by calculating the maximum score for each position in the motif, and then multiplying these scores together to get an overall score. :param s: list of the motif indexes in the introduced sequences. :return: multiplication of maximum scores.

```
seqSize ( i: int ) \rightarrow int
```

Method that returns the length of the sequence. :param i: index of the sequence in the sequence list. :return: length of the sequence with index i from the sequence list.

```
package_aab.src.MotifFinding.random() → x in the interval [0, 1).
package_aab.src.MotifFinding.test1_1()
package_aab.src.MotifFinding.test1_2()
package_aab.src.MotifFinding.test1_3()
package_aab.src.MotifFinding.test1_4()
package_aab.src.MotifFinding.test1_5()
package_aab.src.MotifFinding.test2()
```

1.1.10 package aab.src.MyGraph module

```
class package_aab.src.MyGraph.MyGraph(g: dict = {})
Bases: object
```

Class for implementation of graphs. Class MyGraph is a parent class of different ones such as: MetabolicNetwork, OverlapGraph and DeBruijnGraph. This class essentially builds graphs with a given dictionary of values or strings.

```
add_edge ( o: str, d: str )
```

Method that add edge to the graph; if vertices do not exist, they are added to the graph :param o: vertice do arco :param d: vertice do arco :return:

```
add_vertex ( v: str )
```

Method that adds a vertex to the graph and tests if vertex exists or not, adding if True :param v: element to add in the graph

all_clustering_coefs() \rightarrow dict

Method that calculates all coefficients :return: dictionary of coefficients of each node where the key corresponds to each node and each coefficient

all_degrees ($deg_type='inout'$) \rightarrow dict

Method that computes the degree (of a given type) for all nodes.

"Deg_type" can be "in", "out", or "inout"

Parameters deg_type - tipo de grau (entrada, saída ou ambos)

Returns returns the degrees

betweenness_centrality (node) \rightarrow float

$check_balanced_graph() \rightarrow bool$

Checking method if the graph is balanced return:value of "False" or "True", if the graph is unbalanced or balanced, respectively

$check_balanced_node (node) \rightarrow bool$

Method to check if a node is balanced :param node: node :return: value of "False" or "True", if the node's input degree is not equal/or is equal to the node's output degree, respectively

$check_if_hamiltonian_path(p: list) \rightarrow bool$

Method checking if path is Hamiltonian :param p: path :return: value of "False" or "True" if the Hamiltonian path is invalid or valid, respectively.

$check_if_valid_path(p: list) \rightarrow bool$

Method of checking if path is correct :param p:path :return: value of "False" or "True" if path is invalid or valid, respectively.

check_nearly_balanced_graph()

Method to check if the graph is semi-balanced :return: returns none (if the graph is not semi-balanced) or the tuples

closeness_centrality (node: str)

Method of averaging approach to distances travelled between affected nodes :param node: node :return: returns the average distance between affected nodes

clustering_coef (v) \rightarrow float

Clustering coefficient calculation method, to measure the extent to which each node is embedded in a cohesive group :param v: node :return: clustering coefficient

degree (v: str) \rightarrow int

Method that obtains the number of degree. Represents the number adjacentes nodes of the given one :param v: node :return: returns degree of node v

distance(s,d)

Method that calculates the distance between two nodes, s and d, in a graph represented as an adjacency list :param s: node s where the path begins :param d: node d where the path ends :return: returns the distance between the nodes s and d

eulerian_cycle()

Eulerian cycle passes through all arcs of the examining graph once, returning to the starting node :return: value of "None" (if not an Eulerian cycle) or the list res (cycle list)

eulerian_path()

Eulerian path method, if existent :return: returns the path

get_adjacents (v: str) \rightarrow list

Method that obtains adjacents of the given element :param v: node :return: returns the list of nodes adjacent to node v

$\texttt{get_edges} () \rightarrow list$

Method that gets the edges in the graph as a list of tuples (origin, destination) v represent the origin d represent the destination

$get_nodes() \rightarrow list$

Method that obtain list of nodes in the graph

get_predecessors (v: str) \rightarrow list

Method that obtains predecessors of the given element :param v: node :return: returns a list of predecessor nodes of node v

get_successors (v: str)

Method that obtains the successors of the given element :param v: node :return: returns a list of successor nodes of node v

$has_cycle() \rightarrow bool$

Method that checks if the graph has a loop, that is if the path is closed :return: value of "False" or "True" if the path is not closed or closed, respectively.

$$highest_closeness(top=10) \rightarrow list$$

$highest_degrees$ ($all_deg=None$, $deg_type='inout'$, top=10) \rightarrow list

Method that calculates higher degrees param all_deg: input and output grades, or both param deg_type: degree type (input, output or both) :return: list of the highest degrees

in degree (v: str) \rightarrow int

Method that obtains number of in degree. Represents the number of predecessors this node of the graph possesses :param v: nodo :return: returns degree of entry from node

$is_connected() \rightarrow bool$

Method for checking whether it is connected or not :return: value of "False" or "True", if not connected or connected, respectively

mean_clustering_coef() → float

Method of the global average of coefficients :return: the value of the average of all coefficients

mean_clustering_perdegree (deg_type='inout') → dict

Method that calculates values for the average of coefficients for all nodes :param deg_type: type of degree (input, output or both) :return: returns the dictionary of nodes and their coefficient

mean_degree ($deg_type='inout'$) \rightarrow dict

Method to calculate the average degrees :param deg_type: type of degree (input, output or both) :return: returns the average degrees

mean_distances()

Method that calculates the cverage distance dethod for Each Node :return: returns the average distance and the proportion of nodes reachable

$node_has_cycle(v)$

Method to check if the node has a cycle, that is if it begins and ends in the same node :param v: node :return: value of "False" or "True" if the node has no cycle or has a cycle, respectively

```
out_degree ( v: str ) \rightarrow int
```

Method that obtains the number of out degree. Represents the number of successors/ramifications this node of the graph possesses :param v: node :return: returns degree of exit from node

print_graph()

Method that prints the content of the graph as adjacency list

```
prob_degree ( deg\_type='inout' ) \rightarrow dict
```

Method for calculating degree probability :param deg_type: type of degree (input, output or both) :return: returns the probability of degrees

```
reachable\_bfs(v)
```

Method of nodes reachable from v starts with the source node, then visits all its successors, followed by its successors until all possible nodes are visited :param v: starting node :return: returns list of nodes reachable from v

```
reachable_dfs(v)
```

Method of nodes reachable from v, from left to right (in depth) starts with the source node, explores its first successor, then its first successor until no further exploration is possible, then returns to explore more alternatives. :param v: node :return: returns list of nodes reachable from v

```
reachable_with_dist(s: str)
```

Method that returns a list of the reachable nodes from the given "s" and respective distance needed :param s: node s :return: list of tuples of the reachable nodes and distance: (Node, Distance)

```
search_hamiltonian_path()
```

 $^{\prime\prime}$ Hamiltonian pathfinding method :return: if p is different from None returns p otherwise returns None

```
search_hamiltonian_path_from_node ( start: int )
```

Hamiltonian pathfinding method on the graph :param start: initial node :return: Hamiltonian path in list

```
shortest_path(s,d)
```

Method that returns the shortest path between s and d (list of nodes it passes through) :param s: node s, node where the path begins :param d: node d, node where the path ends :return: return the shortest path, list of nodes it passes through

```
size()
```

Method that obtains the size of the graph: number of nodes and number of edges

```
package_aab.src.MyGraph.is_in_tuple_list (tl, val) \rightarrow bool
```

1.1.11 package aab.src.MyGraph1 module

```
class package_aab.src.MyGraph1.MyGraph ( g: dict = {})
    Bases: object
```

```
add_edge ( o: Union[str, int, float], d: Union[str, int, float] )
```

Add edge to the graph; if vertices do not exist, they are added to the graph :param o: represents the origin (starting) vertex :param d: represents the destination (ending) vertex of the edge

```
add_vertex ( v: Union[str, int, float] )
```

Add a vertex to the graph; tests if vertex exists not adding if it does

degree (v: Union[str, int, float]) \rightarrow int

Method that calculates degree of node v (all adjacent nodes either forerunners or successors)

distance (s: Union[str, int, float], d: Union[str, int, float])

Method that calculates the distance between two nodes, s and d, in a graph represented as an adjacency list :param s: node s where the path begins :param d: node d where the path ends :return: returns the distance between the nodes s and d

 $get_adjacents(v: Union[str, int, float]) \rightarrow list$

Method to obtain adjacents of the given element

 $get_edges() \rightarrow list$

Method returning the list of arcs v represent the origin node d represent the destination node

 $get_nodes() \rightarrow list$

Method that returns the list of nodes in the graph

 $\texttt{get_predecessors}$ (v: Union[str, int, float]) $\rightarrow list$

Method to obtain predecessors of the given element

 $\texttt{get_successors}$ (v: Union[str, int, float]) \rightarrow list

Method for obtain successors of the given element

has_cycle()

 $in_degree(v: Union[str, int, float]) \rightarrow int$

Method to obtain the number of in degree. Represents the number of predecessors this node of the graph possesses

 $node_has_cycle(v: Union[str, int, float]) \rightarrow bool$

Method that verifies if a node has a cycle, i.e. if it starts and ends at the same node

 $\mathtt{out_degree}$ (v: Union[str, int, float]) \rightarrow int

Method to obtain the number of out degree. Represents the number of successors/ramifications this node of the graph possesses

print_graph()

Prints the content of the graph as adjacency list

reachable_bfs (v: Union[str, int, float]) \rightarrow list

Method of nodes reachable from v starts with the source node, then visits all its successors, followed by its successors until all possible nodes are visited :param v: starting node :return: returns list of nodes reachable from v

 $reachable_dfs(v: Union[str, int, float]) \rightarrow list$

Method of nodes reachable from v, from left to right (in depth) starts with the source node, explores its first successor, then its first successor until no further exploration is possible, then returns to explore more alternatives. :param v: node :return: returns list of nodes reachable from v

reachable_with_dist (s: Union[str, int, float]) \rightarrow list

Method that returns a list of the reachable nodes from the given "s" and respective distance needed :param s: node s :return: list of tuples of the reachable nodes and distance: (Node, Distance)

shortest_path (s: Union[str, int, float], d: Union[str, int, float])

Method that returns the shortest path between s and d (list of nodes it passes through)

:param s: node s, node where the path begins :param d: node d, node where the path ends :return: return the shortest path, list of nodes it passes through

```
size() \rightarrow tuple
```

Method that returns the size of the graph: number of nodes, number of edges

```
package_aab.src.MyGraph1.is_in_tuple_list(tl,val)
package_aab.src.MyGraph1.test1()
package_aab.src.MyGraph1.test2()
package_aab.src.MyGraph1.test3()
package_aab.src.MyGraph1.test4()
package_aab.src.MyGraph1.test5()
```

1.1.12 package_aab.src.MyMotifs module

```
class package_aab.src.MyMotifs.MyMotifs ( lseqs: list = [], pwm: list = [], alphabet: Optional[str] = None )
```

Bases: object

Class that presents the methods that allow the manipulation and search of recurring patterns (motifs) in biology sequences and also do PWM.

```
consensus () \rightarrow str
```

Method that generates a consensus sequence. Consensus sequences store the most conserved characters in each position of the pattern, that is, the highest value of each column of the count matrix. :return: string of the consensus sequence.

```
createPWM() \rightarrow None
```

Method that creates the probabilistic matrix. PWMs are probabilistic representations of the characters in biological sequences. It calculates the probability of nucleotide i being found at position j.

```
doCounts ( )
```

Method that implements the counting matrices. :return: counts matrix

```
maskedConsensus() \rightarrow str
```

Method that generates the consensus sequence that is obtained with the characters that have an incidence higher than 50%. :return: string of the consensus sequence with incidence higher than 50%.

```
mostProbableSeq ( seq: str ) \rightarrow int
```

Method implemented to determine the sub-sequence with the highest probability of matching the pattern being searched. :param seq: sequence introduced return: the index of the sub-sequence with higher probability of matching the pattern in search.

```
probAllPositions (seq: str) \rightarrow list
```

Method implemented to calculate the probability of finding patterns in longer sequences and calculate the probability of the pattern occurring at each character in the sequence, ie, of occurring at each sub-sequence of the pattern size. For example, if the pattern size is 3 and the sequence is "ATCGTACG", the method would calculate the probability of the pattern occurring at each of the sub-sequences of size 3, which are "ATC", "TCG", "CGT", "GTA", "TAC", "ACG". :param seq: sequence introduced :return: list of probabilities of the pattern occurring at each subsequence

$probabSeq(seq:str) \rightarrow float$

Method that calculates the probability of a pattern being found in a sequence :param seq: sequence intoduced :return: the probability of a pattern being found in the sequence

```
package_aab.src.MyMotifs.createMatZeros(line_num: int, col_num: int) \rightarrow list
```

Method that creates the matrix of zeros. The matrix of zeros is used as a base to store the counts or probabilities of each character in each position of the biological sequences that are being analyzed. :param line_num: number of lines in the matrix :param col_num: number of columns in the matrix :return: matrix of zeros

```
package_aab.src.MyMotifs.printMat ( mat: list )
```

Method to prints the matrix :param mat: matrix

1.1.13 package_aab.src.MySeq module

```
class package_aab.src.MySeq.MySeq(seq: str, seq_type: str)
```

Bases: object

Class presenting the methods that allow the manipulation of DNA, RNA and protein sequences.

allProtein()

Method that constructs of a list with all the existing and possible proteins in the sequence. The sequence can be proteic or DNA Only executes in case the object is a DNA or AMINO sequence :return: DNA or amino sequence

alphabet()

Method that verifies the type of sequence :return: returns the possible characters of the sequence.

codonTranslate (cod: str) $\rightarrow str$

Method that translates codons into their respective amino acids. :param cod: codon to look for in the codon table :return: amino acid sequence

largestOrfProtein()

Method to get the bigger protein in the sequence :return: string with the bigger protein

longestProteinSeq()

Method searching for the longest protein sequence :return: longest proteic sequence

orfs()

Method that determines the open reading frames (ORF), i.e. the sequences between the initiation codon and the STOP codon. It generates six reading frames of the DNA sequence and the reverse complement. :return: returns ORF's

printSeq()

Method that prints the complete sequence :return: string of the complete sequence

reverseComplement()

Method that inverts and complements the sequence Only executes in case the object is a DNA sequence :return: DNA sequence

$rnaCodon() \rightarrow list$

Method that searches for the codons in the sequence. :returns: list of codons

seqTranslation (initial_pos: int = 0)

Method that performs the translation of the sequence :param initial_pos: determines the initial position of the reading sequence :return:

transcription()

Method that returns the transcript sequence. Replacing of the thymine base 'T' for the uracil base 'U' Only executes in case the object is a DNA sequence :return: RNA sequence

valida()

Method that checks if all the characters in sequence are present in the alphabet defined :return:

$validateSeqRE() \rightarrow bool$

Method that validates the sequence according to the type of characters present through regular expressions. :return: value True or False if the sequences are valid or invalid, respectively

1.1.14 package_aab.src.Popul module

1.1.15 package_aab.src.SuffixTree module

```
class package_aab.src.SuffixTree.SuffixTree ( seqs: str )
```

Bases: object

Class that creates a suffix tree of a pattern that will be searched in a sequence. It allows pre-processing a target sequence, making its search more efficient. It is the solution to pre-process very large sequences, discovering which trees contain a given pattern, finding out the longest common substring in a set of sequences and calculating the maximum overlap of a set of sequences.

```
add_node ( origin, symbol: str, leaf_num=-1 ) \rightarrow None
```

Method that adds nodes to the tree. :param origin: current node :param symbol: character referring to the node to be added :param leaf_num: leaf number (-1 is default, correspond to an internal node)

add_suffix (p, suf_num)

Method that adds suffix to the tree. :param p: pattern :param suf_num: suffix number for leaves or -1 for non-leaves

check_seqs()

Method that verifies if the sequence introduced is a string

find_pattern (pattern)

Method that looks for patterns (trie) starting from the root until it reaches the end node or fails the search. :param pattern: pattern to search for :return: list of sheets below a given node or none (if search fails)

get_leafes_below (node)

Auxiliary method to collect all the leafes below a given node. param node: node from which the information of the sheets below this one are searched. :return: list of sheets below a given node.

print_tree()

Method that prints the tree structure (dictionary)

suffix_tree_from_seq(text)

Method that creates the suffix tree by adding a symbol ("\$") at the end of the sequence and calls the previous method for each suffix in the sequence -> no suffix will be prefixed with another suffix. :param text: sequence that will be added to the tree

```
package_aab.src.SuffixTree.test()
```

1.1.16 package_aab.src.Trie module

```
class package_aab.src.Trie.Trie ( seqs: str )
```

Bases: object

Class responsible for implementing the prefix tree that allows pre-processing of a set of patterns. The symbols of a given alphabet are associated with the arcs of a tree. The trie is built from a set of patterns, starting from the root node and iterating each pattern, adding the necessary nodes so that the tree contains the path from the root to the leaf, representing the pattern.

```
check_seqs()
```

Method that verifies if the sequence is a string

```
insert ( seq: str ) \rightarrow None
```

Method that inserts the sequences into the trie :param seq: sequences introduced :return:

```
insert\_sequence (seq) \rightarrow None
```

Method that inserts a single sequence into the trie. :param seq: sequence introduced :return:

```
matches ( seq ) \rightarrow bool
```

Method that verifies if a given sequence matches any sequence present in the trie :param seq: sequence introduced :return: booleano

```
print_trie()
```

Method that prints the tree structure (dictionary)

1.1.17 package_aab.src.debrujin module

```
{\bf class} \ {\tt package\_aab.src.debrujin.DeBruijnGraph} \ ({\it frags: list} \ )
```

Bases: MyGraph

Class implemented to represent Bruijn graphs. These represent the fragments (k-mers) as arcs of the graph and the nodes as sequences of size k-1, corresponding to prefixes or suffixes of the fragments. This class is a subclass of MyGraph and thus inherits all the methods defined in it.

```
add_edge ( o: str, d: str )
```

Method that adds the arc (o,d) to the graph, checking that it doesn't already exist there param o: arc vertice param d: vertex of arc

```
create_deBruijn_graph (frags: list )
```

Method implementing the creation of a DeBruijn graph :param frags: a set of sequences

```
in\_degree (v: str) \rightarrow int
```

Method that calculates the degree of entry of node v :param v: node :return: returns the node's degree of entry

```
seq\_from\_path (path: list) \rightarrow str
```

Method that gets the sequence from the constructed path. param path: path of the list graph :return: returns the sequence represented by the constructed path

```
package_aab.src.debrujin.composition (k: int, seq: str) \rightarrow list
```

Method that recovers the original sequence, giving as input values the obtained sequence and the value of k param k: size of the fragments param seq: sequence obtained :return: returns the original sequence in list

```
package_aab.src.debrujin.prefix (seq: str) \rightarrow str
```

Method that gets the sequence prefix obtained in the "seq_from_path" method. :param seq: sequence represented by the constructed path :return: returns the sequence prefix seq, which corresponds to the sequence except the last character

package_aab.src.debrujin.suffix (seq: str) \rightarrow str

Method that gets the sequence suffix obtained in the "seq_from_path" method. :param seq: sequence represented by the constructed path :return: returns the sequence suffix seq, which corresponds to the sequence except the first character

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