# **COMP20007 Design of Algorithms**

Hashing

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Lecture 15

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- This lecture: Hash Tables.

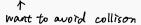
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- Average case performance for Search, Insert and Delete:  $\Theta(1)$
- Requires a hash function:  $h(K) \rightarrow i \in [0, m-1]$ .
- A hash function should:
  - Be efficient  $(\Theta(1))$ .
  - Distribute keys evenly (uniformly) along the table.



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- Sometimes this is possible: postcodes, for example.
- Many times it is not:
  - m is too large (need to preallocate) = g. for postcode, you need to preallocate 100000 elevant
  - Unbounded integers (student IDs)
  - Non-integer keys (games)

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- Allow us to set the size m.
- Small *m* results in lots of collisions, large *m* takes excessive memory. Best *m* will vary.

## Hashing Strings

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- Each character can be mapped to a *binary* string of length 5 ( $2^5 = 32$ ).

We can think of a string as a long binary number:

$$M \ Y \ K \ E \ Y \ \mapsto 01100 11000 0101 000100 11000 \ (= 13379736)$$

$$13379736 \mod 101 = 64$$

So 64 is the position of string M Y K E Y in the hash table.

## **Hashing Strings**

We deliberately chose 
$$m$$
 to be prime.

Will be cancelled by  $32$ 

$$13379736 = 12 \times 32^4 + 24 \times 32^3 + 10 \times 32^2 + 4 \times 32 + 24$$

With m = 32, the hash value of any key is the last character's value! if last character is the same, many collisions

another problem for hashing strings:

O very long string, the number calculated is very large

-> overflow

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$$h(s) = (\sum_{i=0}^{|s|-1} chr(s_i) \times 32^{|s|-i-1}) \mod m$$

where m is a prime number. For example,

$$h(V E R Y L O N G K E Y) = (21 \times 32^{10} + 4 \times 32^{9} + \cdots) \mod 101$$

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The term between parenthesis can become quite large and result in overflow.

## Horner's Rule

Instead of

$$21 \times 32^{10} + 4 \times 32^9 + 17 \times 32^8 + 24 \times 32^7 \cdots$$

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Now utilize these properties of modular arithmetic:

$$(x+y) \bmod m = ((x \bmod m) + (y \bmod m)) \bmod m$$
$$(x \times y) \bmod m = ((x \bmod m) \times (y \bmod m)) \bmod m$$

So for each sub-expression it suffices to take values modulo m.

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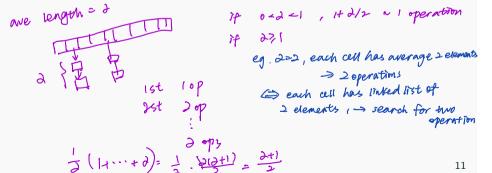
Practical efficiency will depend on the table load factor:

$$\alpha = n/m$$
  $n = \#$  total of records

Assign multiple records per cell (usually through a linked list)

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- Requires extra memory.

## Linear Probing

Populate successive empty cells.

move until find an empty cell

We will only have 0-d=1 in this case Populate successive empty cells.

- Much harder analysis, simplified results show:
- A sucessful search requires  $(1/2) \times (1 + 1/(1 \alpha))$  operations on average.
- An unsucessful search requires  $(1/2) \times (1+1/(1-\alpha)^2)$  operations on average.

  only make sense for n < 2 < 1

If we don't allocate extra space, if 2>1, means all spaces are fully allocated, when d=1, worst case O(n)

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- Similar numbers for Insert. Delete virtually impossible.
- Does not require extra memory.
- Worst case  $\Theta(n)$  with a bad hash function and/or



clusters.



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- First try: h(K)  $(h(k)+o\cdot S(k))$  mod m = h(k)
- Second try:  $(h(K) + s(K)) \mod m$
- Third try:  $(h(K) + 2s(K)) \mod m$
- ...

if 
$$s(k)=1$$
  
 $(h(k)+0. s(k))$  mod  $m=h(k)$  since  $xx \mod m$   
 $=h(k)$   
 $(h(k)+(-1))$  mod  $m$   
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Both Linear Probing and Double Hashing are sometimes referred as *Open Addressing* methods.

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- High load factors deteriorate the performance of a hash table (for linear probing, ideally we should have  $\alpha < 0.9$ ).
- Rehashing allocates a new table (usually around double the size) and move every item from the previous table to the new one.
- Very expensive operation, but happens infrequently.

Hash Tables:

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- Requires good collision handling.

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That being said, if hashing is applicable, a well-tuned hash table will typically outperform BSTs.

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**Next lecture:** what happens if records/data is too large?