Brett Evan Barkley

bbarkley@utexas.edu | https://bebark.github.io/

Education

The University of Texas at Austin, PhD

Computer Science

CPA: 3.95

Focus in Deep Reinforcement Learning and Robotics

University of Maryland, M.S

Aerospace Engineering

GPA: 3.97

GPA: 3.97

Focus in Control Theory and Dynamical Systems

University of Maryland, B.S

Appearance Freeinage (Harrey Program)

Aerospace Engineering (Honors Program) GPA: 4.00

Research Projects

Translating Open-loop Trajectory Optimization into Closed-Loop Policy Optimization

Austin, TX 2023

Research Project with Prof. David Fridovich-Keil

Developed a novel policy optimization algorithm (D4PO) which combined the structure of iLQR/DDP with deterministic policy gradients.

- Hypothesized and validated that incorporating iLQR/DDP feedback gains and value functions improves sample efficiency and reduces sensitivity to exploding gradients in reinforcement learning.
- Demonstrated strong performance in contact-free environments, while highlighting challenges with managing large gradients due to contact dynamics.

Time Symmetric Data for RL, Austin, TX

Austin, TX

Research Project with Profs. David Fridovich-Keil and Amy Zhang

2023

- Investigated the utility of time reversal symmetry in reinforcement learning. Code. Paper.
- Developed a data augmentation technique (TSDA) that leverages time symmetry across a range of RL problems.
- Demonstrated that TSDA can provide SOTA sample efficiency in time symmetric and asymmetric environments.

Professional Experience

Autonomy Aerospace Engineer, Johns Hopkins University Applied Physics Lab (JHU/APL)

2017 - 2022

- Efforts culminated in first ever combat tests between AI and human-piloted F-16s in 2023
- JHU/APL's Air Combat Evolution (ACE) deep reinforcement learning (DRL) lead for sub and full-scale aircraft
- Guidance, control, and aerospace simulation subject matter expert (SME) for JHU/APL ADT and ACE teams

Technical Skills

Languages: Python, C++, Cython, Bash, CUDA

Libraries/Software: JAX, Pytorch, Flax, Brax, Git, LATEX

Selected Publications

- 1. Stealing That Free Lunch The MDP Diversity Problem in Model-Based Reinforcement Learning **Brett Barkley**, David Fridovich-Keil | In preparation
- 2. An Investigation of Time Reversal Symmetry in Reinforcement Learning Brett Barkley, Amy Zhang, David Fridovich-Keil | L4DC 2024