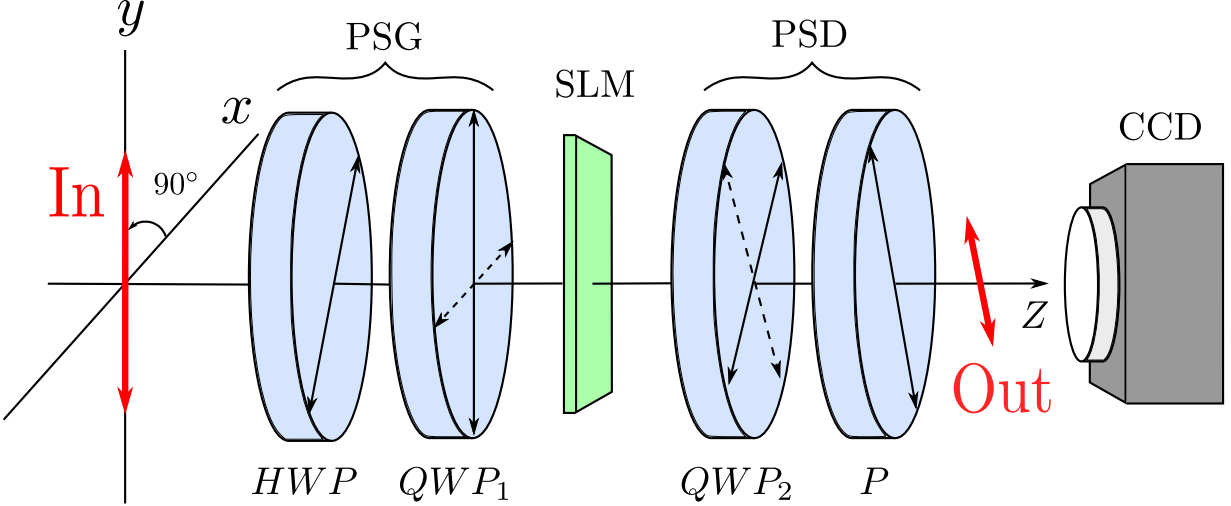

$$J_{Out} = (\mathbf{P\ QWP_2}\ )\,\mathbf{SLM}\ (\mathbf{QWP_1\ HWP})\ J_{In}$$

$$|J> = \begin{pmatrix} J_x \\ J_y \end{pmatrix} = (\mathbf{QWP_1\ HWP})\ In$$