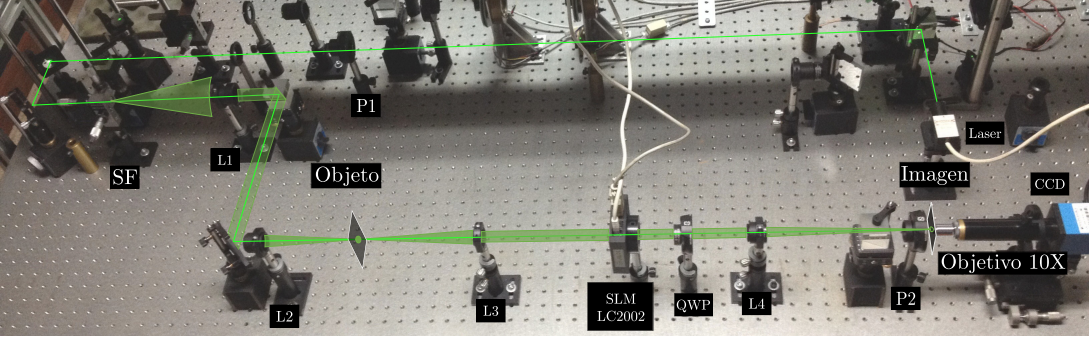
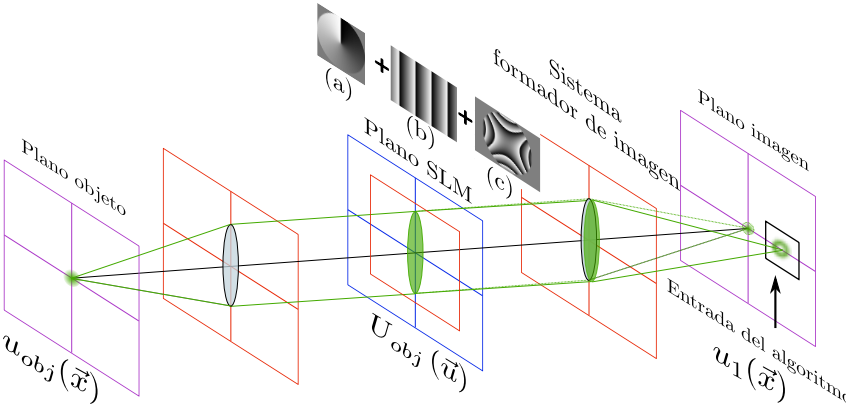

SF
L1
P1
Objeto
L2
L3
SLM
LC2002
QWP
L4
P2
Imagen
Laser
CCD
Objetivo 10X


(a)
(b)
(c)
Plano objeto
Plano SLM
Sistema formador de imagen
Plano imagen
Entrada del algoritmo
$u_{obj}(\vec{x})$
$U_{obj}(\vec{u})$
$u_1(\vec{x})$