



$$J_{Out} = (\mathbf{P} \mathbf{QWP}_2) \mathbf{SLM} (\mathbf{QWP}_1 \mathbf{HWP}) J_{In}$$

$$I = |J_{Out}|^2 = J_{Out}^\dagger J_{Out} = \begin{pmatrix} J_x^* & J_y^* \end{pmatrix} \begin{pmatrix} J_x \\ J_y \end{pmatrix}$$