



$$J_{Out} = (\mathbf{P} \mathbf{QWP}_2) \mathbf{SLM} (\mathbf{QWP}_1 \mathbf{HWP}) J_{In}$$

$$\underbrace{\hspace{10em}}_{|J\rangle = \begin{pmatrix} J_x \\ J_y \end{pmatrix}} = (\mathbf{QWP}_1 \mathbf{HWP}) J_{In}$$

$$I = | \langle J | \mathbf{SLM} | J \rangle |^2$$

$$= \left| \begin{pmatrix} J_x & J_y \end{pmatrix} \begin{pmatrix} X + iY & Z + iW \\ -Z + iW & X - iY \end{pmatrix} \begin{pmatrix} J_x \\ J_y \end{pmatrix} \right|^2$$