Visualizing and Understanding the Performance of Randomized Optimization Methods

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Motivation

Our goal is to develop a better understanding of optimization algorithms that contain some form of randomization in their inner workings. We develop different ways to visualize the mechanics of an optimization algorithms as it navigates through a decision space, which can be especially challenging as the dimension of the decision space grows.

Background

Given a starting point $\mathbf{x}_0 \in \mathbb{R}^n$, most iterative optimization algorithms can be expressed in the form

$$\boldsymbol{x}_{k+1} = \boldsymbol{x}_k - \alpha_k \boldsymbol{d}_k, \qquad k = 0, 1, 2, \dots, \tag{1}$$

with $d_k \in \mathbb{R}^n$ serving as a scaled direction and α_k being a (nonnegative) step size along d_k . By randomized, we refer to the fact that some component of the algorithm's mechanics depends on one or more random variables.

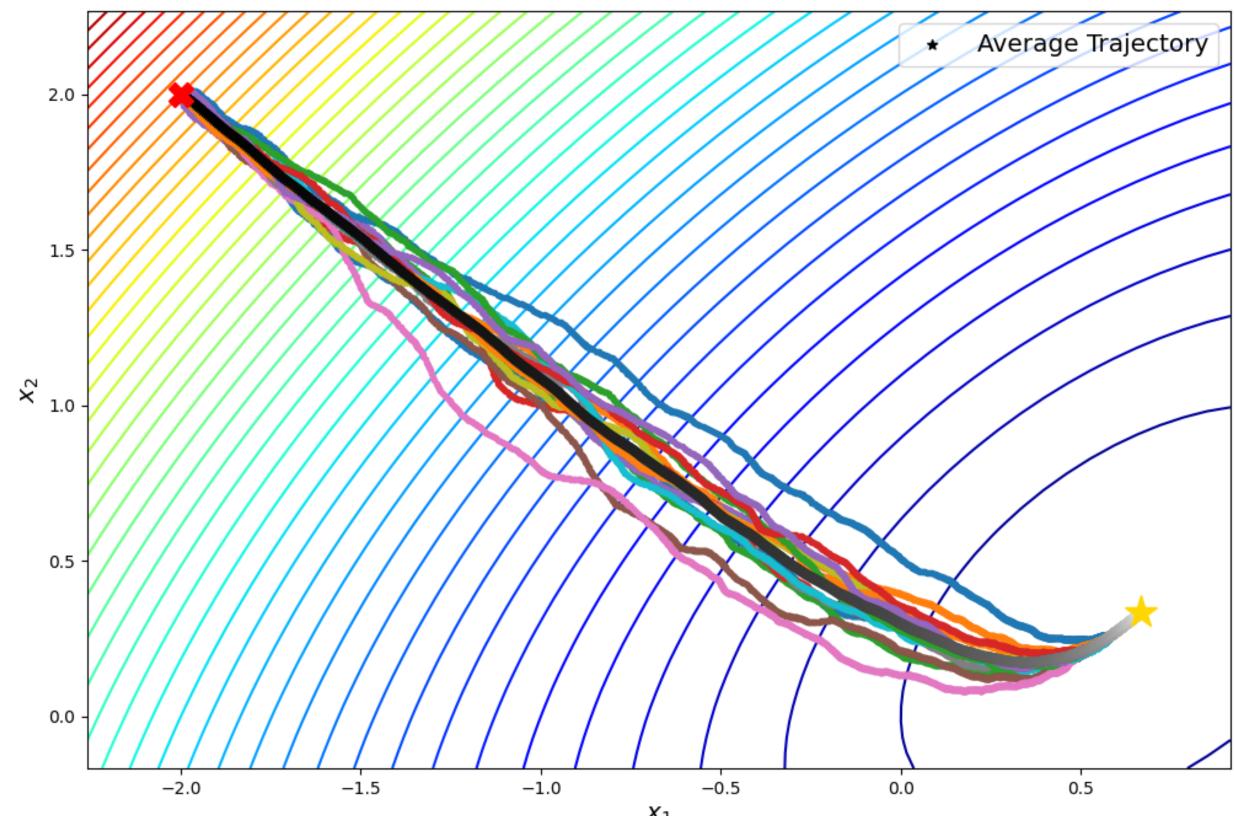


Figure 1: This plot displays a two dimensional convex Nesterov quadratic function using RCD and the Adam optimization method for 15 seeds and 2500 iterations.

We utilize two methods:

1. Let $\boldsymbol{\xi}_k \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}_n\right)$ be a *n*-dimensional vector of standard Gaussians and then set

$$\boldsymbol{d}_{k}(\boldsymbol{\xi}_{k}) = \left(\nabla_{\boldsymbol{x}} f\left(\boldsymbol{x}_{k}\right)^{\top} \boldsymbol{\xi}_{k}\right) \boldsymbol{\xi}_{k}. \tag{2}$$

2. Randomized coordinate descent (RCD) where one selects an index $\boldsymbol{\xi}_k \sim \mathcal{U}[1,\ldots,n]$ and moves only along this random coordinate:

$$\boldsymbol{d}_{k}(\boldsymbol{\xi}_{k}) = \left(\nabla_{\boldsymbol{x}} f\left(\boldsymbol{x}_{k}\right)^{\top} \boldsymbol{e}_{\boldsymbol{\xi}_{k}}\right) \boldsymbol{e}_{\boldsymbol{\xi}_{k}} = \frac{\partial}{\partial x_{\boldsymbol{\xi}_{k}}} f(\boldsymbol{x}_{k}) \boldsymbol{e}_{\boldsymbol{\xi}_{k}}, \tag{3}$$

where $e_i \in \mathbb{R}^n$ denotes the *i*th column of the *n*-dimensional identity matrix \mathbf{I}_n .

The step size is typically chosen ahead of time. One common choice is to set $\alpha_k = \frac{M}{k+1}$ for all k for some M > 0. Another choice is to select step sizes adaptively based on estimates of second moments, as in the Adam method [1].

Test Functions

Chained alternative Rosenbrock function:

$$f(\boldsymbol{x}) = \sum_{i=1}^{n-1} \left(100 \left(x_i^2 - x_{i+1} \right)^2 + (x_i - 1)^2 \right), \tag{4}$$

with $f(\boldsymbol{x}_*) = 0$ at the unique point $\boldsymbol{x} = \boldsymbol{1}$.

Convex Nesterov [2] quadratic function:

$$f(\boldsymbol{x}) = \frac{1}{2}x_1^2 + \frac{1}{2}x_n^2 - x_1 + \frac{1}{2}\sum_{i=1}^{n-1} (x_{i+1} - x_i)^2,$$
 (5)

which has $f(\boldsymbol{x}_*) = 0$ at the unique point defined by $x_i = 1 - \frac{i}{n+1}$ for $i = 1, \ldots, n$.

Convex funnel function [3]:

$$f(\boldsymbol{x}) = \log\left(1 + 10\|\boldsymbol{x} - \mathbf{1}\|_{2}^{2}\right),\tag{6}$$

which has $f(\boldsymbol{x}_*) = 0$ at the unique point $\boldsymbol{x} = \boldsymbol{1}$.

Two-Dimensional Functions

Consider the comparison between the step size of $\alpha_k = \frac{m}{k+1}$ and the Adam method in Figure 2. Though both eventually get us to a neighborhood of the minima, the Adam method does it with less variability, and fewer iterations.

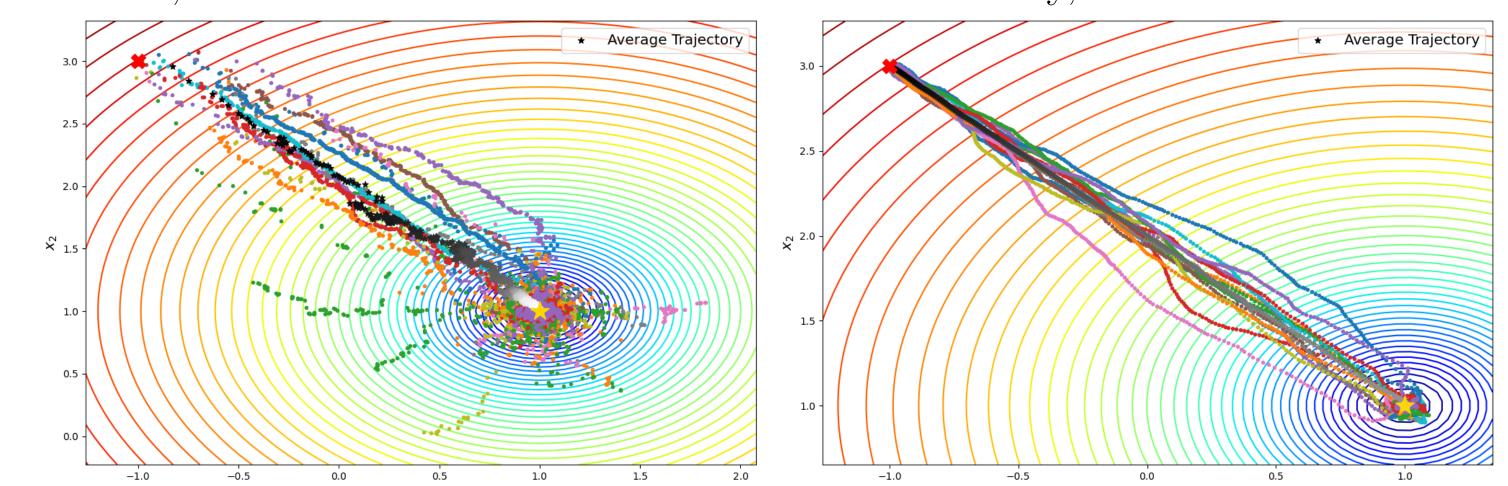


Figure 2: This figure displays the trajectories for 15 seeds and iterations for two optimization methods: (Left) Standard method for selection of α_k , (Right) Adam Optimization Method.

To understand the variability, we calculate standard deviation for each of our \boldsymbol{x} values, essentially creating a two-dimensional confidence interval around each point. However, the standard deviation approach assumes that all components of \boldsymbol{x} are independent. And so, we look at the covariance confidence ellipses.

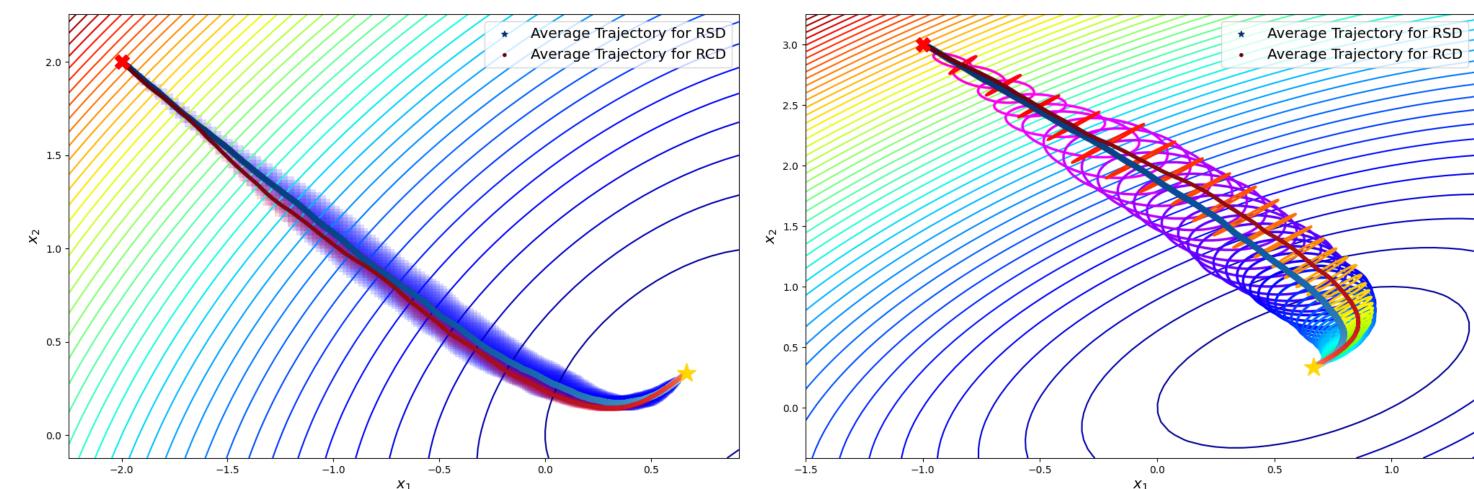


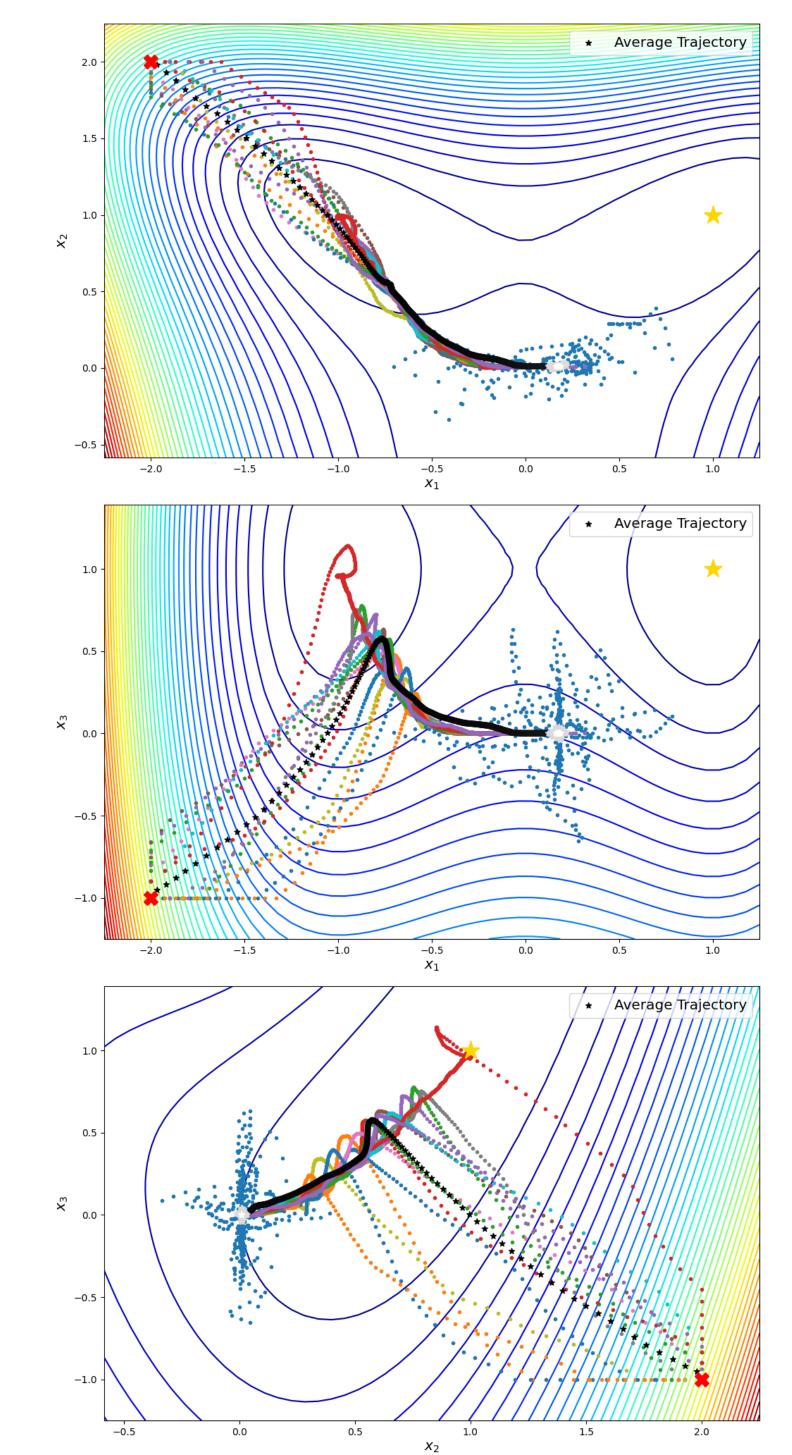
Figure 3: This figure displays the mean trajectories over 15 seeds and iterations for both randomized direction methods: (Left) Standard deviation confidence intervals, (Right) Covariance confidence ellipses.

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N-Dimensional Functions



Below in Figure 5, we project each slice onto their respective planes to understand and view their relationships.

With functions of higher

dimension, we reproduce

the plots by taking two

dimensional slices of each

possible combination for

 $x_i, x_j \in \boldsymbol{x}$ of our trajectories

such that $i, j \in 1, 2, \ldots, n$.

We produce contours that

project on to the two di-

mensional plane of x_i, x_j by

substituting a fixed value

equal to the minima for such

elements in \boldsymbol{x} that are not

 x_i, x_j . This allows us to

visually characterize the role

each element of \boldsymbol{x} plays in

the overall trajectory.

Figure 4: This plot displays all 15 seeds and their mean trajectory along two dimensional slices for the chained alternative Rosenbrock function using RCD and the Adam optimization method with 10000 iterations.

Figure 5: This plot

displays all 15 seeds

trajectory along the

projected along their

respectiv planes for

Rosenbrock function

using RCD and the

Adam optimization

method with 10000

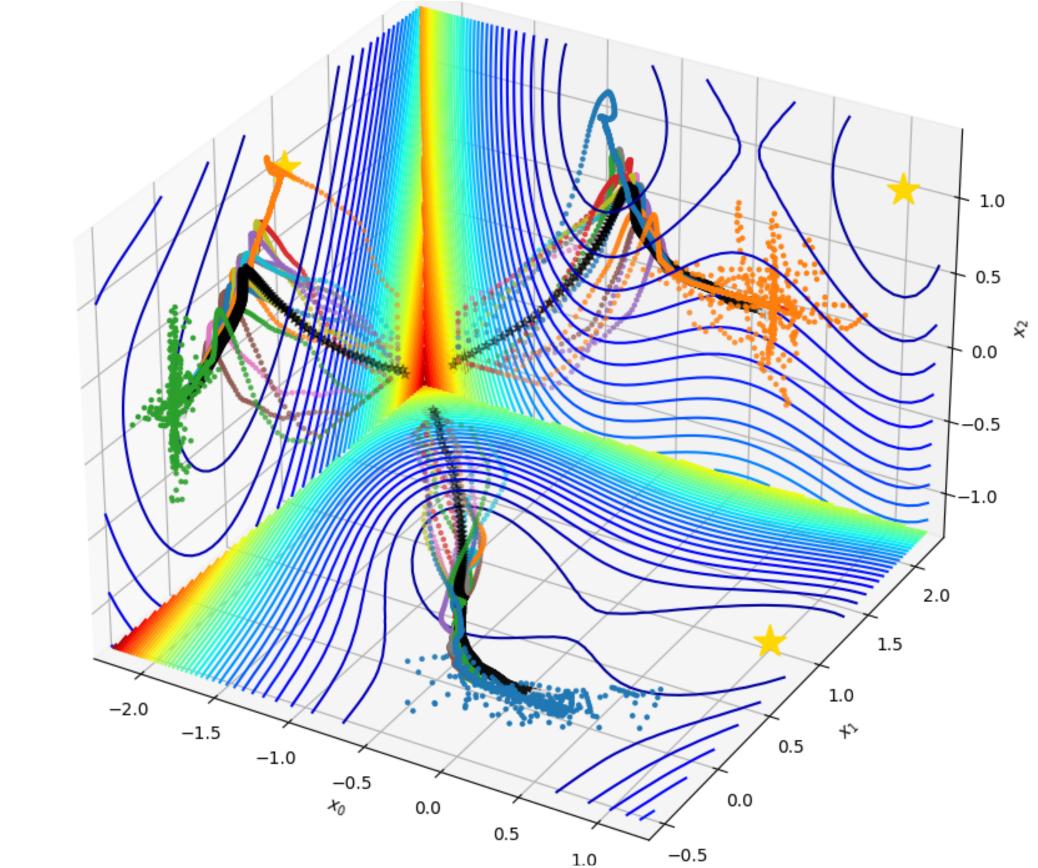
the chained

alternative

iterations.

two dimensional slices

and their mean



Future Work

- Conduct visualizations on additional nonconvex functions with higher dimensionality
- Apply principal component analysis and produce visualizations for the understanding of such principal components

^[1] D. P. Kingma and J. Ba. Adam: A method for stochastic optimization, 2017.

^[2] Y. Nesterov. *Introductory Lectures on Convex Optimization: A Basic Course*, volume 87 of *Applied Optimization*. Springer, 2004. doi: 10.1007/978-1-4419-8853-9.

^[3] S. U. Stich, C. L. Müller, and B. Gärtner. Optimization of convex functions with random pursuit. SIAM Journal on Optimization, 23 (2):1284–1309, 2013. doi: 10.1137/110853613.