

### Big Data Visual Analytics (CS 661)

Instructor: Soumya Dutta

Department of Computer Science and Engineering

Indian Institute of Technology Kanpur (IITK)

email: soumyad@cse.iitk.ac.in

### Study Materials for Lecture 14

- A Gentle Tutorial of the EM Algorithm and its Application to Parameter Estimation for Gaussian Mixture and Hidden Markov Models
- EM Algorithm: https://stephens999.github.io/fiveMinuteStats/intro\_to\_em.html
- SLIC Superpixels Compared to State-of-the-Art Superpixel Methods, Achanta et al.
- Homogeneity guided probabilistic data summaries for analysis and visualization of large-scale data sets, Dutta et al.
- Statistical visualization and analysis of large data using a value-based spatial distribution, Wang et al.

### Mid Sem Exam

- Saturday 22nd Feb 8-10am
- Location: L18 and L19 (OROS)
- Please bring your institute id card (mandatory)
- No classes during Mid Sem week
- Syllabus:
  - Everything up to today's class

### Final Project Group Formation

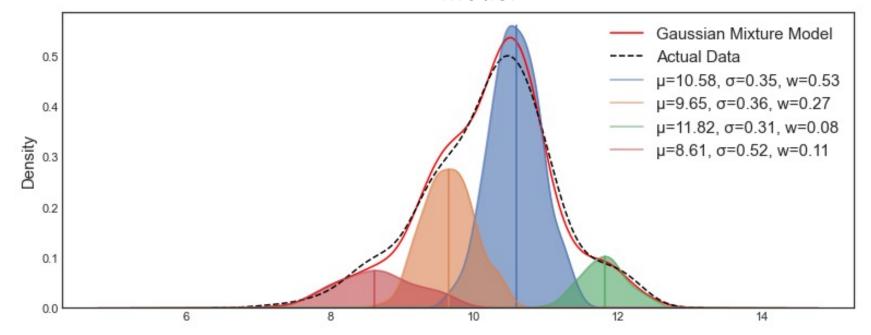
- Form your project team by March 2nd and update the google sheet with details of project members
  - https://docs.google.com/spreadsheets/d/1ZsWmnCRK4XEZV6YezgwM0CNk1 nLMaZXSIPpv1d3WvAs/edit?usp=sharing
  - Group size: 8
  - Those who will not be part of a team, I will help them get assigned to groups

### Parametric Distribution: GMM

 Gaussian Mixture Model (GMM): Represent a probability distribution function as a convex combination of multiple Gaussian functions

$$p(X) = \sum_{i=1}^{K} \omega_i * N(X \mid \mu_i, \sigma_i)$$

 $\omega$  = Weights of the Gaussian components K = Number of Gaussian components in the mixture model



### Parameter Estimation Techniques

- Estimation of Gaussian distribution parameters are trivial
  - Maximum Likelihood Estimate (MLE)
  - Same as computing mean and variance
- Estimation of GMM parameters require Expectation Maximization (EM) algorithm
  - Iterative technique to fit GMM parameters
- Incremental schemes for GMM parameter estimation
  - Fast and approximate method to estimate GMM parameters
  - Can model streaming time-varying data

### Expectation Maximization (EM) for GMM

- Initialize: means  $(\mu)$ , covariances  $(\Sigma)$ , and weights  $(\omega)$
- Iterate until convergence:
  - E-step: Evaluate posterior probabilities given current parameters



$$\gamma_k^n = \frac{\omega_k \mathcal{N}(x^n | \mu_k, \Sigma_k)}{\sum_{j=1}^k \omega_k \mathcal{N}(x^n | \mu_j, \Sigma_j)}$$

 M-step: Update the parameters to maximize the expected log-likelihood of the observed data

$$\omega_k = \frac{N_k}{N}$$
 and  $N_k = \sum_{n=1}^N \gamma_k^n$ 

$$\mu_k = \frac{1}{N_k} \sum_{n=1}^N \gamma_k^n \ x^n$$

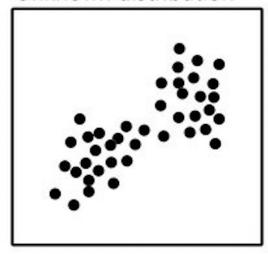
$$\Sigma_{k} = \frac{1}{N_{k}} \sum_{n=1}^{N} \gamma_{k}^{n} (x^{n} - \mu_{k}) (x^{n} - \mu_{k})^{\mathsf{T}}$$

 Evaluate log likelihood at the end of each iteration and check for convergence The theory of the method is much more involved!

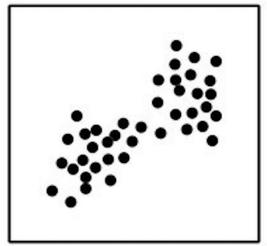
#### For a detailed derivation:

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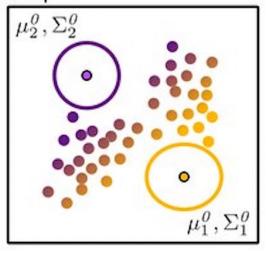
#### Unknown distribution



Unknown distribution

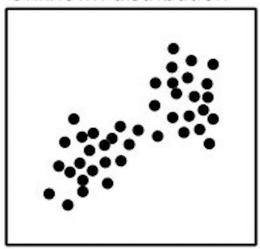


Step 0

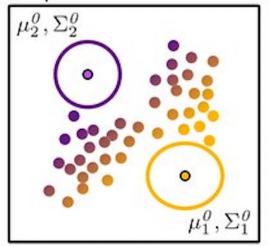


Unknown distribution Step 0 Step 1  $\mu_2^\theta, \Sigma_2^\theta$   $\mu_1^\theta, \Sigma_1^\theta$ 

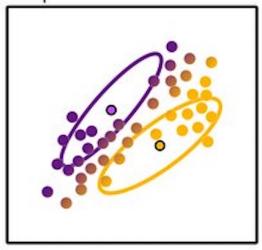
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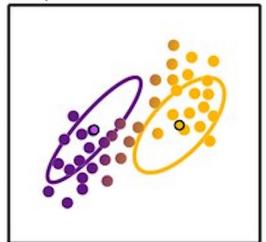
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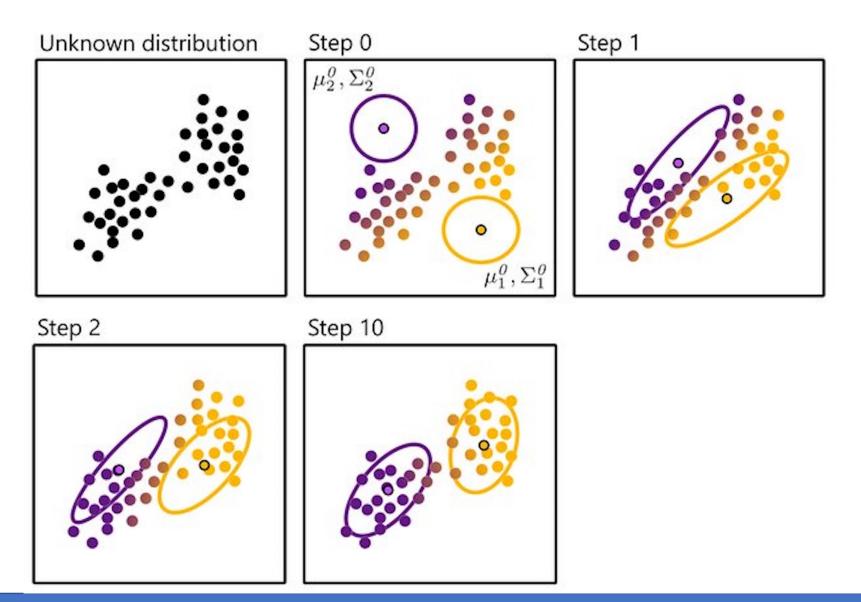


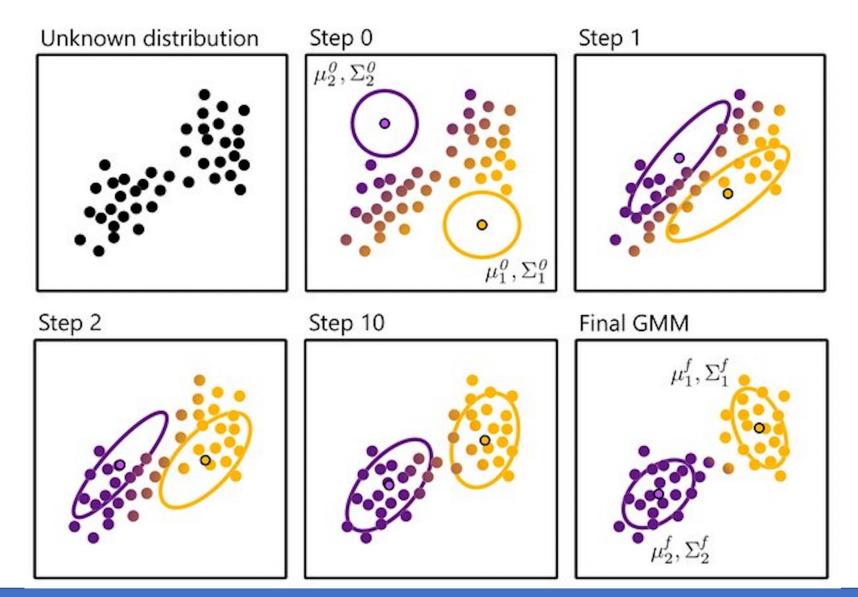
Step 1



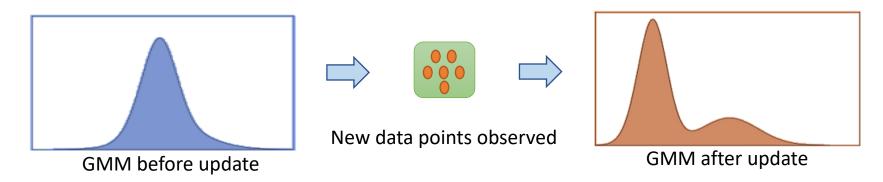
Step 2







## Incremental GMM Modeling for Time-varying Data



• Update weights as:

$$\omega_{k,t} = (1 - \alpha)\omega_{k,t} + \alpha * M_{k,t}$$
,  $M_{k,t} = 1$  for matched dist., 0 for others

• Update means and covariances for the matched distribution as:

$$\mu_t = (1-\rho) \ \mu_{t-1} + \rho x_t$$
 
$$\sigma_t^2 = (1-\rho) \ \sigma_{t-1}^2 + \rho (x_t - \mu_t)^T (x_t - \mu_t)_{,} \quad \rho = \alpha * N(x_t | \mu_k, \sigma_k)$$
 
$$\Sigma_{k,t} = \sigma_k^2 \text{I, where I = Identity matrix, } \alpha = \text{learning rate}$$

# Distribution-based Large Data Summarization and Visualization

### Distribution Models for Big Data Summarization

 Distribution models that can be estimated efficiently and has a compact memory footprint is preferred over other models

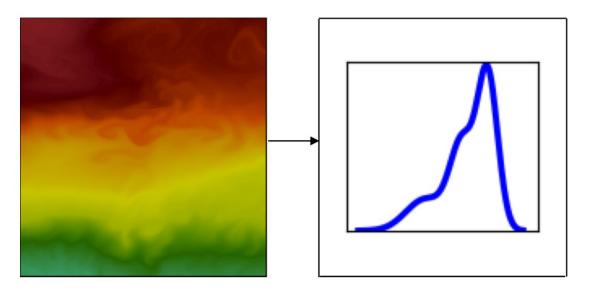
#### For Univariate Data:

- Histograms: Fast but takes more space
- KDE: Computationally expensive and takes more space
- Gaussian: Fast but often the model is too simple
- Gaussian mixture model: Parameter estimation can be a little expensive, but representation is compact

#### For Multivariate Data:

- Many of the standard multivariate models become either slow or space inefficient
- Statistical Copula functions can be used effectively

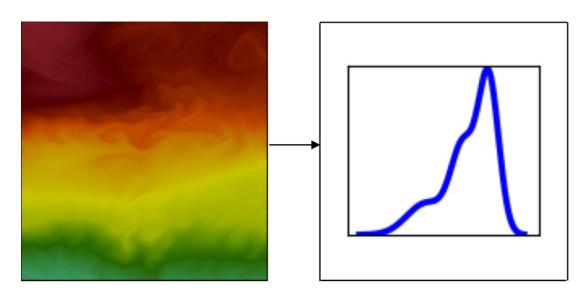
# Distribution-based Data Summarization Strategies



Global distribution model: A single distribution model to represent the entire data set

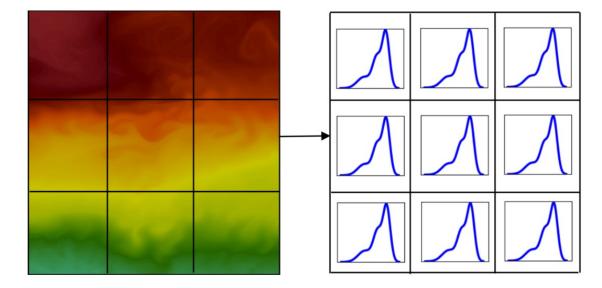
- Significant data reduction is possible
- Coarse representation of the data
- Not suitable for fine grained visual analysis

# Distribution-based Data Summarization Strategies



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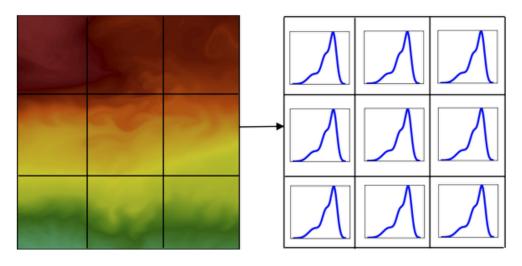


<u>Local distribution model</u>: Data is divided into small blocks and then each block is summarized using a separate distribution model

- Data reduction at an acceptable range is possible
- Fine details of the data and statistical properties are preserved
- Preferred over global model for scientific data summarization

# Local/Region-wise Distribution-based Data Modeling

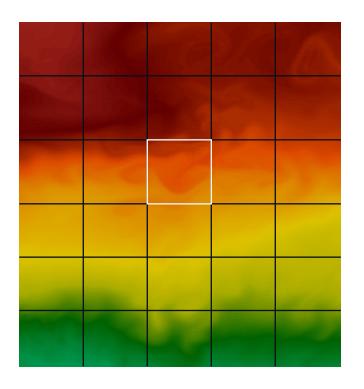
- Local Statistical distribution-based data modeling
  - Partition data into local regions
  - Summarize each region with a statistical distribution model
  - Benefits:
    - Distributions preserve local statistical data properties
    - Reduce data size significantly
    - Enables sampling-based analysis and reconstruction
    - Allows uncertainty quantification



Local distribution-based data model

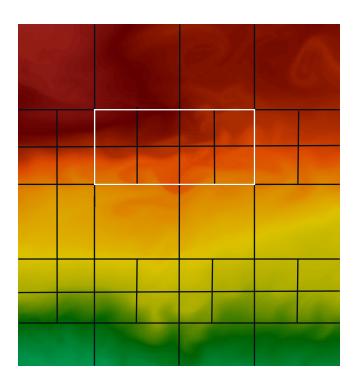
### Goals of a Region-wise Statistical Summarization

- Produce coherent partitions
  - Similar data values are grouped together
  - Partitions are spatially contiguous
- Preserve the statistical properties of the data accurately
  - Minimize sampling errors
  - Efficient feature analysis
- Use appropriate distribution models for summarization
  - A compact storage representation



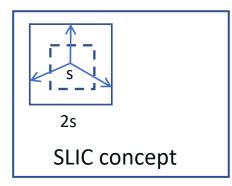
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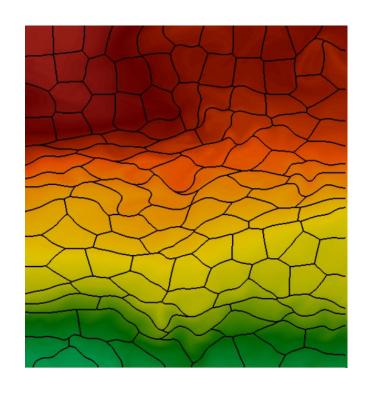


# A Superior Solution for Region-wise Statistical Summarization

- Generate partitions based on data homogeneity
- Simple Linear Iterative Clustering (SLIC)
  - Produces irregular shaped partitions/clusters
  - Value variation inside partitions is minimized
  - Reduced sampling error



$$dist(i, j) = \alpha. \|C_i - P_j\|_2 + (1 - \alpha). \|val_i - val_j\|$$



### SLIC Algorithm Steps

#### Algorithm 1 Efficient superpixel segmentation

- 1: Initialize cluster centers  $C_k = [l_k, a_k, b_k, x_k, y_k]^T$  by sampling pixels at regular grid steps S.
- 2: Perturb cluster centers in an  $n \times n$  neighborhood, to the lowest gradient position.
- 3: repeat
- 4: **for** each cluster center  $C_k$  **do**
- 5: Assign the best matching pixels from a  $2S \times 2S$  square neighborhood around the cluster center according to the distance measure (Eq. 1).
- 6: end for
- 7: Compute new cluster centers and residual error E {L1 distance between previous centers and recomputed centers}
- 8: **until**  $E \leq \text{threshold}$
- 9: Enforce connectivity.