

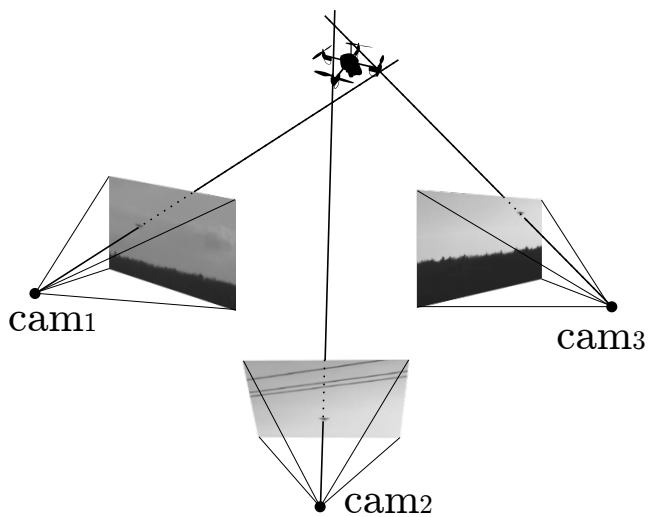
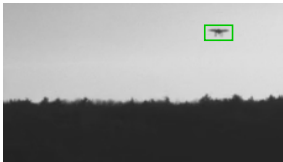
cam1



cam2



cam3



tracking



triangulation



localization