

Tribhuvan University Institute of Science and Technology

 ${\bf Lab~Report} \\ {\bf On} \\ {\bf Implement~Point,~Segment,~and~Test~for~5~dimensions~of~point-line~classification.}$

Submitted to Jagdish Bhatt Central Department of Computer Science and Information Technology Tribhuvan University, Kirtipur Kathmandu, Nepal

> Submitted by Bedram Tamang Roll No: 14/75

```
class Point:
    def __init__(self):
        self.points = []
    def getPoint(self):
        return self.points
    def set3DPoint(self):
        print ("Enter_2D_point:_eg._2,3,4")
        self.points = tuple(map(int, input().split(',')))
        return self.getPoint()
    def set2DPoint(self):
        print ("Enter_2D_point: leg. 2.3")
        self.points = tuple(map(int, input().split(',')))
        return self.getPoint()
    def displayPoint(self):
        print(self.points)
Segement.py
from Point import Point
class Segment:
    \mathbf{def} __init__(self):
        self.p1 = []
        self.p2 = []
    def setPoints(self):
        self.p1 = Point().set2DPoint()
        self.p2 = Point().set2DPoint()
        return self.getPoints()
    def getPoints(self):
        return [self.p1, self.p2]
PointLineClassification.py
from Segment import Segment
from Point import Point
class PointLineClassification:
    def __init__(self):
        self.p1, self.p2 = Segment().setPoints()
        self.testPoint = Point().set2DPoint()
    def classify (self):
        if (self.p1[0] = self.testPoint[0] & self.p1[1] = self.
           testPoint[1]):
           print("Test_point_is_start_point.")
        elif (self.p2[0] = self.testPoint[0] & self.p2[1] = self.
           testPoint[1]):
            print("Test_point_is_end_point.")
        if (self.p2[1] < self.testPoint[1] or self.testPoint[0] > self.
           p2[0]):
```

```
\mathbf{print} \, (\, "\, \mathsf{Test} \, \lrcorner \, \mathsf{point} \, \lrcorner \, \mathsf{is} \, \lrcorner \, \mathsf{beyond} \, \lrcorner \, \mathsf{line} \, \lrcorner \, \mathsf{segment} \, . \, "\, )
            \mathbf{elif} \ (\, \mathrm{self.p1} \, [1] \, > \, \mathrm{self.testPoint} \, [1] \ \mathbf{or} \ \mathrm{self.testPoint} \, [0] \, < \, \mathrm{self}
                 print("Test_point_is_behind_line_segment.")
            elif ((self.p1[1] < self.testPoint[1] & self.p2[1] < self.
                testPoint[1]) or
            self.testPoint[0] > self.pl[0] and self.testPoint[0] < self.p2
                [1]):
                 print("Test_point_is_between_the_line_segment.")
Main.py
from Point import Point
from Segment import Segment
 from \ \ PointLineClassification \ \ import \ \ PointLineClassification 
if __name__ = "__main__":
     # print(Point().set2DPoint())
     # print(Segment().setPoints())
     PointLineClassification().classify()
```