

for Mid2 - review

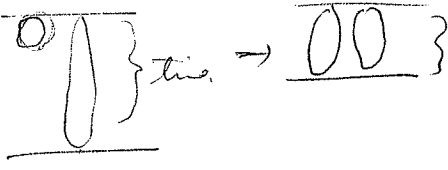
= UK book - parallel software
ch2

vs. shared-mem program — start a process → forks threads
dist. mem program — start multiple processes

SPMD — same program for all threads — for data parallel (also ^{task par.})
MPMD — running a different program on each processor (core)

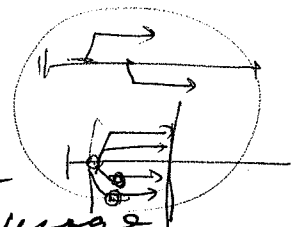
(data parallel ^{divide data}
task parallel ^{divide task}) programming

— process/threads coordination issues

(
— load balancing
— min comm.
— synchronization
) 

— shared-mem program

vs. dynamic threads — high cost for fork/join
static threads — all are forked at once
less efficient resource usage



— non-determinism on thread termination order

— C.S. and mutex control — mutex
semaphore
monitor
busy-waiting

— Thread safety — some serial built-in func malfunction in parallel prog.

- distr. mem system/program issues

- multiple processes ~~on~~, each on different cpu (and op)

- MSG passing API

send/receive

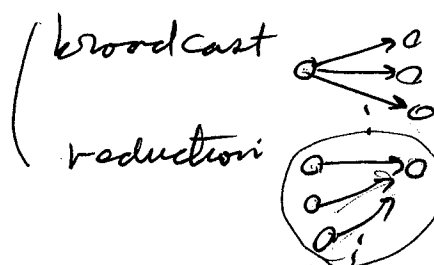
blocked until sender sends msg.

distr. system

[One-sided Comm.



[Collective communication:



- hybrid system programming

MPI + OpenMP — on cluster of multiple machines.

= I/O for parallel programming

suggested rules

(- file access — only a single process/thread accesses any single file
 (- std I/O — (not 2 processes open the same file)
non determinism)

= performance

$$T_p = \frac{T_s}{p}$$

— ideal case: ~~serial~~ linear speedup

but, \neq overheads

{ shared mem — C.S.
 serial
distr. mem
 { data transfer
 I/O speed.

$$\downarrow$$

$$\boxed{\text{ideal speedup} = \frac{T_s}{T_p} = \frac{T_s}{\left(\frac{T_s}{p}\right)} = p}$$

↓ Efficiency (per processor)

$$E = \frac{S}{p} = \frac{\left(\frac{T_s}{T_p}\right)}{p} = \frac{T_s}{p \cdot T_p} = \frac{1}{p} \left(\frac{T_s}{T_p}\right)$$

⇒ effective $T_p = \frac{T_s}{p} + T_{\text{overhead}}$

effective $S = p \cdot \left(\frac{T_s}{T_s + p \cdot T_o}\right)$

< 1

— See real example case graphs

vs.

ideal $T_p = \frac{T_s}{p}$

ideal $S = p$

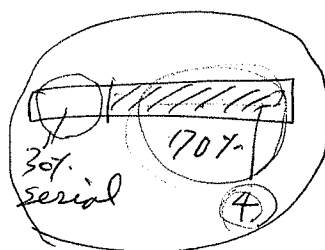
(linear speed up
(E is always 1))

— measuring parallel prog. time — Should exclude I/O time

— elapsed time — CPU time + I/O time

— Amdahl's law

$$S = \frac{1}{(1 - f_e) + \frac{f_e}{s_e}} = 4$$



⊛ Scalability

— parallel prog. is scalable

(if p and $n \Rightarrow E$) same Efficiency
and $(k \times p)$ and $k \times n \Rightarrow E$

vs.

strongly scalable — $(p \text{ and } n \Rightarrow E)$ same E
 $(k \times p, n \Rightarrow E)$ whatever n

weakly scalable — $p \text{ and } n \Rightarrow E$ same E
 $(k \times p, k \times n \Rightarrow E)$

parallel program design steps

1. partition
2. Communication
3. aggregation - simplify - reduce comm. cost.
4. mapping - assign tasks to process/threads



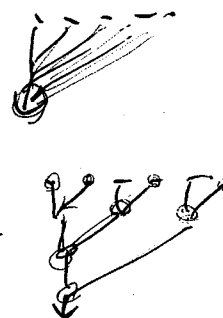
et) serial prog → parallel prog.

histogram making

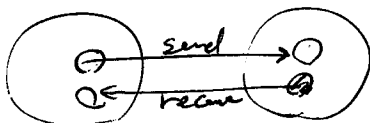
issues

- Race Condition - C.S.

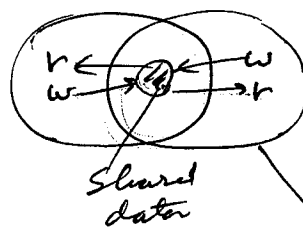
- reduction - by 1 process only
by full-tree reduction



- msg passing Comm.



- shared-mem Comm



How to implement this in java threads?

⇒ each thread holds shared-obj and read/write on the shared-obj

- Java Threads

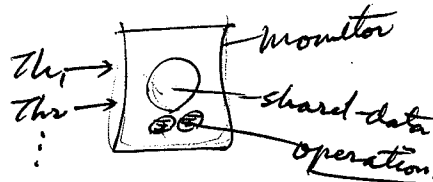
concept

when create the thread object,

pass shared-obj

- readers/writers in java threads

- monitor mechanism

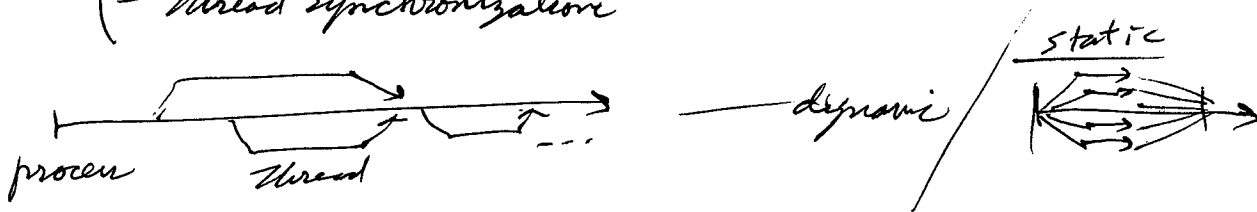


only 1 thread at a time accesses

(synchronized methods)

mk. ch4 - shared-mem program with pthreads

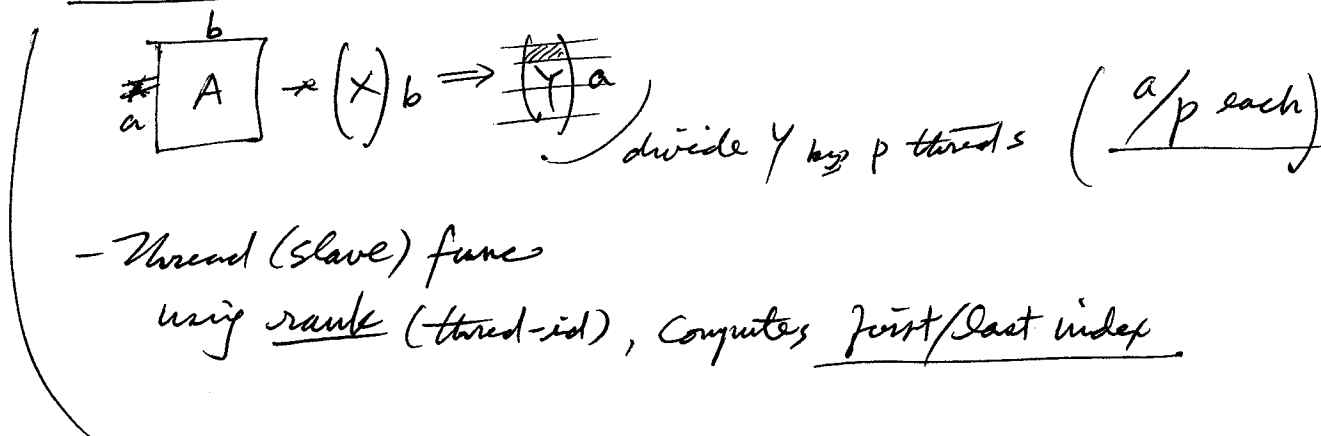
- issues
- C.S.
 - Thread synchronization



- each thread has its stack/heap (private)

ex) multiple threads call same func \rightarrow each thread has its own copy of func's param, local vars.

ex matrix-vector multiplication



- Thread (slave) func
using rank (thread-id), computes first/last index.

- issues

- C.S. - sel: busy-waiting \times
- synchro. mutex \rightarrow \checkmark
- producer/consumer semaphore \checkmark
- condition var
- read/write locks
- false sharing

↓
 - C.S. { multiple threads try to access shared mem
 → race condition

9) π computation $\pi = 4 * (1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \dots)$

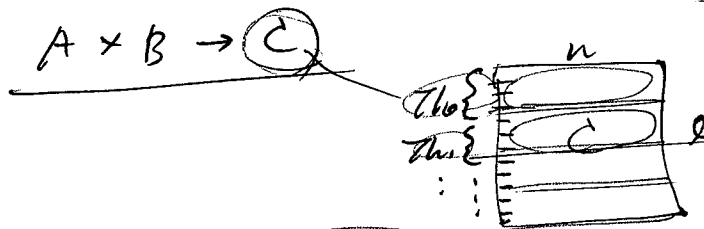
global sum update → sol: mutex ✓
busy waiting - too much overheads
Semaphore

- prog 3 - matrix multi
 with pthreads

$$C_{ij} = \sum_{k=0}^{n-1} A_{ik} * B_{kj}$$

- nested for-loops

serial algo → parallel algo. { block divide way
rotational way



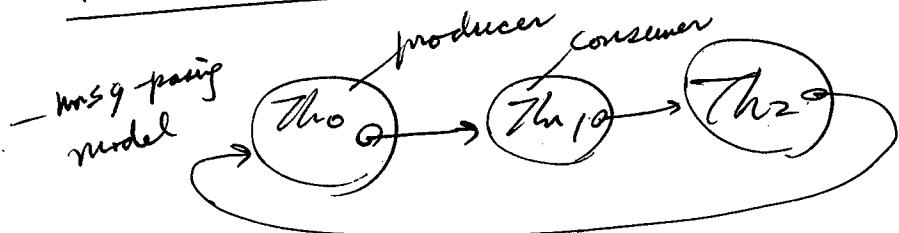
(l/p) each th.

1001/4
 Th₀ - start-idp
 end-idp

load balancing
 (Some threads are assigned more)

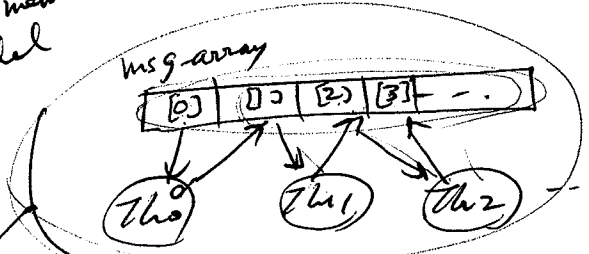
84.7

Producer Consumer Synchronization



care
Thread-ordering is important

- shared-mem model



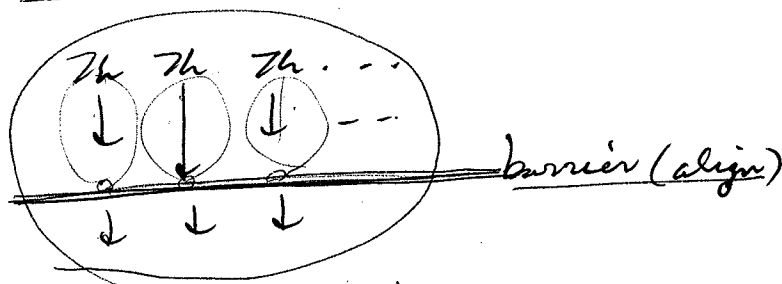
each thread sends to next, then reads from prev. Th.

issue
 How to synchronize?

↓
producer-consumer synchro.

Sol: busy-waiting — high cost
mutex — X
semaphore — V (best)

§ 4.8 — Barrier and Condition var

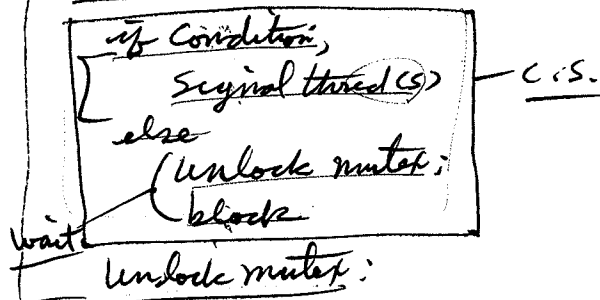


— implementation of barrier

(
 — busy-waiting — X
 — mutex — X
 — semaphore — X — may cause race condition
 ✓ condition var
) — problem on reusing the barrier ^{for 2nd}
 — pthread supports

actually, condition var
& mutex

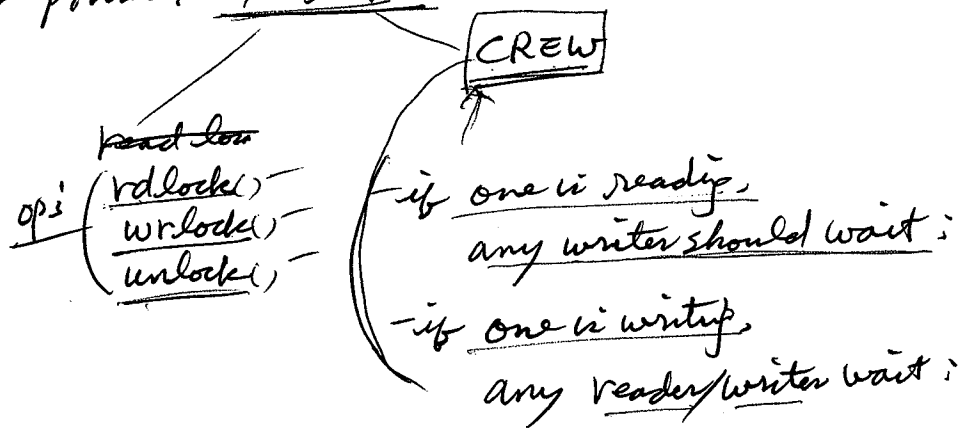
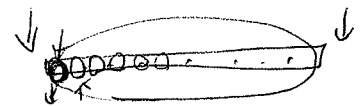
Concept: lock mutex:



§4.9 read/write locks - pthread supports

multiple threads r/w big data structure

- Sol: (1. one mutex for entire data structure
2. one mutex per each ele. - worst
3. using pthread r/w locks - best time)

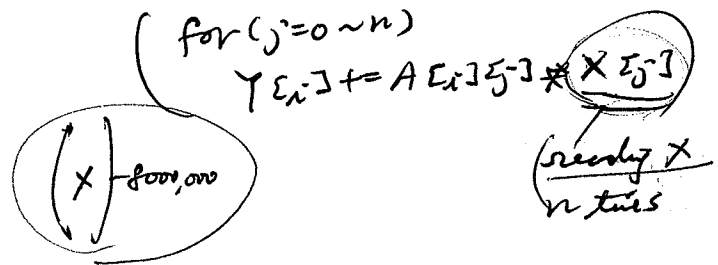


§4.10 Cache coherence and false sharing

ex) matrix-vector multiplication

matrix $\begin{matrix} m \\ \boxed{A} \\ n \end{matrix} * \begin{pmatrix} x \end{pmatrix}_{8000} = \begin{pmatrix} y \end{pmatrix}_8$ (each cache line = 64 B (8 doubles))

- (1. $A[i]$ $8000,000 * 8$ - worst in cache - w miss
2. $A[i]$ $8000 * 8000$
3. $A[i]$ $8 * 8000,000$ - worst in cache - R miss)



Mid2