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- Q1.** Using 8085, explain the stack operation; where initial SP value is FFFEh. 03
- Q2.** Suppose, Instruction Pointer (IP) of 8086 is moving in backward memory directions for executing following assembly language codes: 12

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MOV AX, FA1Ah  
NEG AX  
ADD AX, A1h
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After the executions of all arithmetic and logical instructions in single-step debug mode with disabling interrupt option, what values would be there in AX and Flag (CF, PF, AF, ZF, SF, OF, IF, TF, and DF) registers?

- Q1. Derive the machine code for the instruction: **IN AL, F1 h**. Also, show how the derived contents /06 can be stored in different memory locations.
- Q2. Your given Student Id format is 20 .. xxxx. Use last 4 (four) digits of your id as a hexa-decimal 09 value (i.e., xxxxh) and consider the following table.

RM \ MOD					
	00	01	10	W = 0	W = 1
000	[BX] + [SI]	[BX] + [SI] + d8	[BX] + [SI] + d16	AL	AX
001	[BX] + [DI]	[BX] + [DI] + d8	[BX] + [DI] + d16	CL	CX
010	[BP] + [SI]	[BP] + [SI] + d8	[BP] + [SI] + d16	DL	DX
011	[BP] + [DI]	[BP] + [DI] + d8	[BP] + [DI] + d16	BL	BX
100	[SI]	[SI] + d8	[SI] + d16	AH	SP
101	[DI]	[DI] + d8	[DI] + d16	CH	BP
110	d16 (direct address)	[BP] + d8	[BP] + d16	DH	SI
111	[BX]	[BX] + d8	[BX] + d16	BH	DI

Now, using the table derive the machine code contents of the following *MOV instructions* and show how many memory locations are required to store the derived machine codes:

- MOV AL, **[xxxxh]**
- MOV SS:[BX+DI+ **xxxxh**], DX
- MOV BX, **xxxxh**

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- Q1.** Draw the details of READ Bus timing diagram showing all the necessary/required signals of 8086. You should consider that the read operation will be made from a memory address of 01111H and there are 4 WAIT states due to an NMI interrupt. 7
- Q2.** Suppose, while debugging an assembly language program the values of the registers are: Flag=FEB9h, IP=0102h, CS=0700h, SP=FFFAh. Now, if INT 00100001B is requested, derive the memory addresses from where the new IP and CS can be retrieved; Also show the step-by-step changes in memory contents of stack segment along with corresponding SP values while handling the interrupt by the 8086 microprocessor. 8
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