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Q1. Using 8085, explain the stack operation; where initial SP value is FFFEh.

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Q2. Suppose, Instruction Pointer (IP) of 8086 is moving in backward memory directions for 12 executing following assembly language codes:

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MOV AX, FA1Ah
NEG AX
ADD AX, A1h
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After the executions of all arithmetic and logical instructions in single-step debug mode with disabling interrupt option, what values would be there in AX and Flag (CF, PF, AF, ZF, SF, OF, IF, TF, and DF) registers?

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- Q1. Derive the machine code for the instruction: **IN AL, F1 h**. Also, show how the derived contents can be stored in different memory locations. 06
- Q2. Your given Student Id format is 20 . . XXXX. Use last 4 (four) digits of your id as a hexa-decimal 09 value (i.e., XXXXh) and consider the following table.

RM \ MOD	MOD			
	00	01	10	11
				W = 0 W = 1
000	[BX] + [SI]	[BX] + [SI] + d8	[BX] + [SI] + d16	AL AX
001	[BX] + [DI]	[BX] + [DI] + d8	[BX] + [DI] + d16	CL CX
010	[BP] + [SI]	[BP] + [SI] + d8	[BP] + [SI] + d16	DL DX
011	[BP] + [DI]	[BP] + [DI] + d8	[BP] + [DI] + d16	BL BX
100	[SI]	[SI] + d8	[SI] + d16	AH SP
101	[DI]	[DI] + d8	[DI] + d16	CH BP
110	d16 (direct address)	[BP] + d8	[BP] + d16	DH SI
111	[BX]	[BX] + d8	[BX] + d16	BH DI

Now, using the table derive the machine code contents of the following MOV instructions and show how many memory locations are required to store the derived machine codes:

- i. MOV AL, [XXXXh]
 - ii. MOV SS: [BX+DI+ XXXXh], DX
 - iii. MOV BX, XXXXh
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- Q1.** Draw the details of READ Bus timing diagram showing all the necessary/required signals of 8086. You should consider that the read operation will be made from a memory address of 01111H and there are 4 WAIT states due to an NMI interrupt. 7
- Q2.** Suppose, while debugging an assembly language program the values of the registers are: Flag=FEB9h, IP=0102h, CS=0700h, SP=FFFAh. Now, if INT₂ 00100001B is requested, derive the memory addresses from where the new IP and CS can be retrieved; Also show the step-by-step changes in memory contents of stack segment along with corresponding SP values while handling the interrupt by the 8086 microprocessor. 8
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