#### Introduction to Game Theory (1)

Mehdi Dastani BBL-521 M.M.Dastani@uu.nl

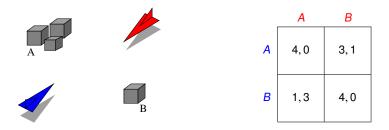
Thanks to Paul Harrenstein and Mathijs de Weerdt who provided me some of these slides.

#### Game Theory

- What is the subject matter of game theory and which phenomena does it help us understand?
- What is the problem of game theory?
- What are the elementary concepts of game theory?
- What is the relevance of game theory to agent research?
- How can game-theoretic concepts be put to use so as to design better systems?

#### Example: Defence-Attack

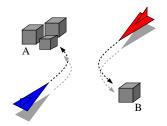
**Situation:** Attacker (Red, column player) can attack either target A or target B, but not both. Defender (Blue, row player) can defend either of two targets but not both. Target A is three times as valuable as Target B.



**Question:** Which target is Red to attack and which target is Blue to defend?

#### Example: Defence-Attack

**Situation:** Attacker (Red, column player) can attack either target A or target B, but not both. Defender (Blue, row player) can defend either of two targets but not both. Target A is three times as valuable as Target B.



	Α	В
Α	4,0	3, 1
В	1,3	4,0

**Question:** Which target is Red to attack and which target is Blue to defend?

#### Battle of the Sexes

John and Mary agreed to go out. They can attend a ballet performance or a box match. Mary would like to go to the ballet performance while John would most of all like to go to the box match. Both prefer to go to the same place rather than different ones. If they cannot communicate, where should they go?

	Fight	Ballet
Fight	2,1	0,0
Ballet	0,0	1,2

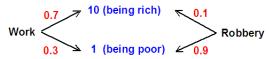
#### Game of Chicken

Two drivers headed each other from opposite directions. The one to turn aside loses. If neither player turn aside, the result is a deadly collision. The best outcome for each driver is to stay straight while the other turns aside and the worst outcome for both driver is to have a deadly collision. In this situation each player wants to secure his/her best outcome, risking the worst scenario.

	Aside	Straight
Aside	0,0	-5,5
Straight	5, -5	-10, -10

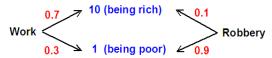
#### Decision Theory: An Agent Plays Against Environment

- An agent is autonomous if it is capable of deciding actions in order to achieve its objectives.
- Classical Decision Theory (Savage 1954)
  - probability and utility functions



#### Decision Theory: An Agent Plays Against Environment

- An agent is autonomous if it is capable of deciding actions in order to achieve its objectives.
- Classical Decision Theory (Savage 1954)
  - probability and utility functions

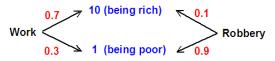


Decision rule = maximum expected utility for each action

$$EU(\alpha) = \sum_{w \in W} U(w) * P(w \mid \alpha)$$

#### Decision Theory: An Agent Plays Against Environment

- An agent is autonomous if it is capable of deciding actions in order to achieve its objectives.
- Classical Decision Theory (Savage 1954)
  - probability and utility functions

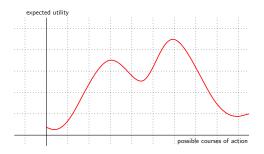


Decision rule = maximum expected utility for each action

$$EU(\alpha) = \sum_{w \in W} U(w) * P(w \mid \alpha)$$

$$EU(Work)$$
 =  $(0.7 * 10) + (0.3 * 1) = 7.3$   
 $EU(Robbery)$  =  $(0.1 * 10) + (0.9 * 1) = 1.9$ 

#### **Decision Theory**



**Issue:** Find the course of action that maximizes expected utility given particular environmental parameters.

#### Utilities and Preferences (1)

- An agent's Utility quantifies its degree of preferences over a set O = {o₁,...,o<sub>n</sub>} of outcomes.
- ▶ "The agent prefers weakly  $o_1$  to  $o_2$ " is denoted by  $o_1 \ge o_2$ .
  - $o_1 > o_2$  iff  $o_1 \ge o_2$  and not  $o_2 \ge o_1$ .
  - $o_1 \sim o_2$  iff  $o_1 \geq o_2$  and  $o_2 \geq o_1$ .
- An agent's Preference, denoted by ≥, over a set of outcomes O is a reflexive, transitive, and complete relation on O.
  - ▶ Reflexivity:  $\forall o \in O : o \succeq o$ .
  - ► Transitivity:  $\forall o_1, o_2, o_3 \in O$ : if  $o_1 \geq o_2$  and  $o_2 \geq o_3$ , then  $o_1 \geq o_3$ .
  - ► Completeness:  $\forall o_1, o_2 \in O : o_1 \succeq o_2 \text{ or } o_2 \succeq o_1 \text{ or } o_1 \sim o_2.$

#### Utilities and Preferences (2)

► Substitutability (indifference in outcomes implies indifference in actions):

If 
$$o_1 \sim o_2$$
, then  $[p:o_1, p_3:o_3,...,p_k:o_k] \sim [p:o_2, p_3:o_3,...,p_k:o_k]$  for all outcomes  $o_3,...,o_k$  and probabilities  $p, p_3,...,p_k(p+\sum_{i=3}^k p_i=1)$ .

Decomposability (indifference in actions with similar expected outcomes):

if 
$$\forall o_i \in O : P(o_i \mid \frac{l_1}{1}) = P(o_i \mid \frac{l_2}{2})$$
, then  $\frac{l_1}{1} \sim \frac{l_2}{1}$ 

Monotonicity:

if 
$$o_1 > o_2$$
 and  $p > q$ , then  $[p : o_1, 1-p : o_2] > [q : o_1, 1-q : o_2]$ 

Continuity:

if 
$$o_1 > o_2$$
 and  $o_2 > o_3$ , then  $\exists p \in [0, 1]$  such that  $o_2 \sim [p : o_1, 1 - p : o_3]$ 



#### Utilities and Preferences (3)

**Lemma**: If a preference relation  $\succeq$  satisfies completeness, transitivity, decomposability, and monotonicity, and if  $o_1 > o_2 > o_3$ , then  $\exists p \in [0,1]$  such that

- $ightharpoonup \forall p': p' < p: o_2 > [p': o_1; 1 p': o_3],$ and
- $ightharpoonup \forall p'': p'' > p: [p'': o_1; 1-p'': o_3] > o_2$

**Theorem: (Von Neumann and Morgenstern, 1944)** If a preference relation  $\geq$  satisfies Reflexivity, Transitivity, Completeness, Substitutability, Decomposability, Monotonicity, and Continuity, then there exists a utility function  $u:O\to [0,1]$  with the properties that:

- $u(o_1) \ge u(o_2)$  iff  $o_1 \ge o_2$ , and
- $u([p_1:o_1,\ldots,p_k:o_k]) = \sum_{i=1}^k p_i u(o_i).$

#### Utilities and Preferences (4)

**Fact:** All preference relations over a countable set *O* are representable by a utility function. These utility functions are invariant under monotonically increasing functions.

**Fact:** Let  $O = \mathbb{R} \times \mathbb{R}$  and  $\geq$  be the *lexicographic order on O*:

$$(o_1, o_1') \gtrsim (o_2, o_2')$$
 iff  $o_1 > o_2$  or both  $o_1 = o_2$  and  $o_1' \ge o_2'$ 

Then,  $\geq$  *cannot* be represented by a utility function.

#### Lexicographical Preference Order

**Fact:** Let  $O = \mathbb{R} \times \mathbb{R}$  and  $\geq$  be the *lexicographic order on O*:

$$(o_1, o_1') \gtrsim (o_2, o_2')$$
 iff  $o_1 > o_2$  or both  $o_1 = o_2$  and  $o_1' \ge o_2'$ 

Then,  $\geq$  *cannot* be represented by a utility function.

**Proof:** Assume such a utility function "u" exists. Then, for all positive  $r \in \mathbb{R}$ , it holds  $(r,2) \gtrsim (r,1)$  iff u(r,2) > u(r,1), and there exists a rational number  $q \in \mathbb{Q}$  such that

$$u(r,2) > q_r > u(r,1)$$

Note that there exists always a rational number between any two real numbers. Now take two real numbers r and r' such that r > r'. We have  $(r, 1) \gtrsim (r', 2)$  iff u(r, 1) > u(r', 2) and therefore

$$u(r,2) > q_r > u(r,1) > u(r',2) > q_{r'} > u(r',1)$$

This means that if  $r \neq r'$  then  $q_r \neq q_{r'}$ . Moreover, it is always the case that if  $q_r \neq q_{r'}$  then  $r \neq r'$ . Together these two facts imply the existence of a one to one mapping between  $\mathbb R$  and  $\mathbb Q$  (a bijection between  $\mathbb R$  and  $\mathbb Q$ ). However, such a bijection does not exists.



**Point of Departure:** Game theory as *interactive* decision theory.

**Issue:** Assume many agents operating in the same environment each faced with a different optimization problem.





**Point of Departure:** Game theory as *interactive* decision theory.

**Issue:** Assume many agents operating in the same environment each faced with a different optimization problem.





**Observation I:** Dependence of the outcome on *all* the players' actions

Hence, the optimality of an action depends on the optimality of the other players' actions. As this holds for all players, a circularity threatens.

**Point of Departure:** Game theory as *interactive* decision theory.

**Issue:** Assume many agents operating in the same environment each faced with a different optimization problem.





**Observation I:** Dependence of the outcome on *all* the players' actions

Hence, the optimality of an action depends on the optimality of the other players' actions. As this holds for all players, a circularity threatens.

**Observation II:** Yet, the other players' decisions cannot be considered parameters of the environment in an obvious way.

**Point of Departure:** Game theory as *interactive* decision theory.

**Issue:** Assume many agents operating in the same environment each faced with a different optimization problem.





**Observation I:** Dependence of the outcome on *all* the players' actions

Hence, the optimality of an action depends on the optimality of the other players' actions. As this holds for all players, a circularity threatens.

**Observation II:** Yet, the other players' decisions cannot be considered parameters of the environment in an obvious way.

**Conclusion:** New mathematical concepts required to take over the role of the optimum, *solution concepts*.

#### Nobel Prizes for Game Theory













1972 Arrow
1978 Simon
1994 Nash, Harsanyi, Selten
1996 Vickrey
1998 Sen
2005 Aumann and Schelling
2007 Hurwicz, Maskin and Myerson

Welfare theory
Decision making
Equilibria
Incentives
Welfare economics

Conflict and cooperation Mechanism design













- Players: Who is involved?
- Rules: What can the players do? What do they know when they move?
- Outcomes: What will happen when the players move in a particular way?
- Preferences: What are the players' preferences over the possible outcomes?

	Fight	Ballet
Fight	2,1	0,0
Ballet	0,0	1,2

**Definition:** A *game form* is a quadruple (N, A, O, g) where:

- N is a set of n players
- ▶  $A = A_1 \times \cdots \times A_n$ , an *n*-dimensional space of *strategy profiles*, where  $A_i$  denote the set of *strategies* of player i
- O is a set of outcomes
- ▶  $g: A \rightarrow O$  is an outcome function

**Definition:** A *game form* is a quadruple (N, A, O, g) where:

- N is a set of n players
- ▶  $A = A_1 \times \cdots \times A_n$ , an *n*-dimensional space of *strategy profiles*, where  $A_i$  denote the set of *strategies* of player i
- O is a set of outcomes
- ▶  $g: A \rightarrow O$  is an outcome function

**Definition:** A *strategic game* is a quintuple (N, A, O, g, u), where:

- $\triangleright$  (N, A, O, g) is a game form
- ▶  $u = (u_1, ..., u_n)$ , where  $u_i : A \to \mathbb{R}$  is a utility function for player i.

**Definition:** A *game form* is a quadruple (N, A, O, g) where:

- N is a set of n players
- A = A₁ x···× An, an n-dimensional space of strategy profiles, where Ai denote the set of strategies of player i
- O is a set of outcomes
- ▶  $g: A \rightarrow O$  is an outcome function

**Definition:** A *strategic game* is a quintuple (N, A, O, g, u), where:

- $\triangleright$  (N, A, O, g) is a game form
- ▶  $u = (u_1, ..., u_n)$ , where  $u_i : A \to \mathbb{R}$  is a utility function for player i.

We write (N, A, u) instead of (N, A, O, g, u) by assuming A = O.



#### Preferences and Utilities in Games

Let O be a set of outcomes.

- $\triangleright \gtrsim_i \subseteq O \times O$ , reflexive, transitive and complete
- $\geq (\geq_1,\ldots,\geq_n)$

#### **Notations:**

- $o_1 \sim_i o_2$  if both  $o_1 \gtrsim_i o_2$  and  $o_2 \gtrsim_i o_1$
- $o_1 \succ_i o_2$  if both  $o_1 \gtrsim_i o_2$  and not  $o_2 \gtrsim_i o_1$
- $a \gtrsim_i a'$  if  $g(a) \gtrsim_i g(a')$

**Definition:** A *utility function*  $u_i$ :  $O \to \mathbb{R}$  represents preferences  $\succeq_i$  over outcomes O so that:

$$u_i(o_1) \ge u_i(o_2)$$
 iff  $o_1 \gtrsim_i o_2$ 

**Notation:** For a a strategy in a game, we write  $u_i(a) = u_i(g(a))$ .

#### **Security Level**

**Definition:** The pure security level of a player is the least payoff he can guarantee himself, no matter what strategies the other players play, i.e.:

$$\max_{a\in A} \min_{b\in A} (u_i(b_1,\ldots,a_i,\ldots,b_n)).$$

0,4	3, 1
1,2	2,3

1,0	0, 1
0, 1	1,0