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Problem Set 1
         1 a) dh - dh dx => d (h(x(t))) - dh dx
dt = dx dt (h(x(t))) - dx dt
              b) ah = (xin(10)) (Bcos (Bt)) = Bcos (Bt) = B cot (Bt)
               c) din = at (h'(x(t)) x'(t)) = h"(x(t))(x'(t)) + h'(x(t)) x"(t)
     2. a) \frac{\oldots = \frac{d}{dt} = \frac{d}{dt} \left(f(t)g(t)) = f(t)g'(t) + f'(t)g(t)
             3. 9) \sin(x) \approx x - \frac{x^3}{3!}. \sin(x) = \frac{x^3}{(2n+1)!} \times \frac{x^{n+1}}{(2n+1)!} \times \frac{x^{n+1
                       cos(x)+isin(x)=1+ix-x2-ix3+x4=eix .. eix=ccs(x)+isin(x)
             e) e' + e' odd power > 0 even power -> double cos(x) = \frac{1}{2}(e' + e'')
             4. cos(x)= = (ex +ex) = 7 cos(x) = 4(ex +2ex +2ex +ex) = 4 (cos(2x)+isin(2x)+cos(-2x)+isin(-2x)+2)
                                                                                           \cos^2(x) = \frac{1}{4}(2\cos(2x) + 1) = \frac{1 + \cos(2x)}{2} .. \cos^2(\Theta) = \frac{1 + \cos(2\theta)}{2}
           5. ax -by(x)=q=>p=-b P=+bx. ((=bx dy -be y)dx=(5ebx q dx
                                                                                Product 5 = -bx y = e -bx - a + 6 => y= -a + 6.
                                                               \vec{f} = \vec{a} + \vec{b} \cos(90) = 0 = \frac{\vec{e} - \vec{f}}{1811\vec{f}1} = \vec{e} \cdot \vec{f} = 0 = (\vec{a}, + \vec{b},)(\vec{a}, -\vec{c},) + (\vec{a}_2 + \vec{b}_2)(\vec{a}_2 - \vec{c}_2)
                                                                   B+c=a=> bx(b+c)=bxa=bxb+bxd=bxa=bxa=>bxc=bxa
                                                                 => |b||c|sin(TI-B) = |b||a|sin(c) => |c|sin(a) = |a|sin(c) => |a| = |a|
     5日 A·B=3×+49-42=1A || B| cos(豆)=0 2=0=73×=-4y B=4で-3分+0元 は三百日=4で-3分
         b) A×B= 12 3 4-4 - (0-12)2-(0+16)3+(-9-16)k=-122-165-25k=2 121= J44+256+625 = J1025
                                                                           2=121 = -12 1 - 11025 } - 51025 k
     c) Bxc= | 2 3 0 = (-75-0)2-(100-0)3+(64+36)2=-752-1003+1002=-25(32+43-42)=-25A

\vec{c}_{i} = \vec{r}_{i} - \vec{c}_{o} t_{i} \\
= \vec{r}_{i} - \frac{\vec{r}_{i} t_{i}}{T} + \frac{\vec{r}_{i} t_{i}}{T} = \frac{\vec{r}_{i} (T + t_{i}) - \vec{r}_{i} t_{i}}{T} \\
= \vec{r}_{i} - \frac{\vec{r}_{i} t_{i}}{T} + \frac{\vec{r}_{i} t_{i}}{T} = \frac{\vec{r}_{i} (T + t_{i}) - \vec{r}_{i} t_{i}}{T}

                                                                                                                                                                    ¿ (t,+T-t)= - +
                                                                                                                                                                              10. \left[\frac{vh}{g}\right] = \frac{m^2}{5} \frac{5^2}{m} = \frac{m}{5} \left[\frac{51v^2}{v^2}\right] = \frac{m^3}{5^2} \frac{5^2}{m^2} = m^2 \left[\frac{v^2}{g}\right] = \frac{m^2}{5^2} \frac{5^2}{m} = m^2 \left[\frac{v^2}{g}\right] = \left[\frac{m^3}{5^2} \frac{5^2}{m}\right] = m^2 \left[\frac{v^2}{g}\right] = \frac{m^2}{5^2} \frac{5^2}{m} = m^2
                                                                                                                                                                 Lxt bc no ax x=vot
            V70, L70
                                                                                                                                                                 tay be constant qy y=at => Lxv2
            h200, L 200
                                                                                                                                                               vate be constant qu'aveat
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