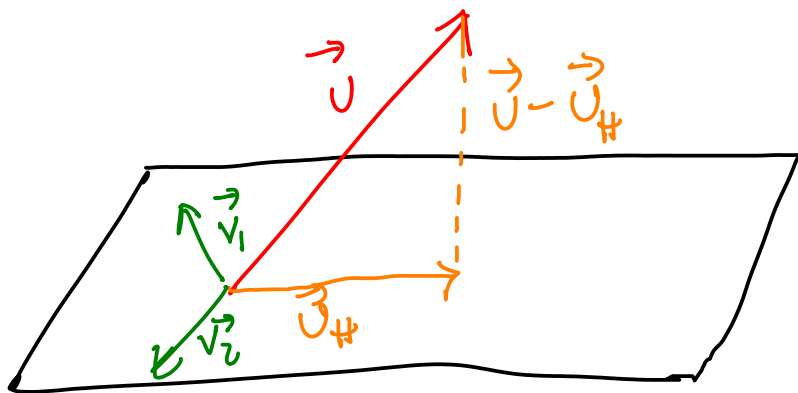


(1) What is the projection of  $\vec{u} = (5, 2, 10)^T$  onto the plane  $H$  characterized by  $2x + y + 3z = 0$ ?



$$u = \begin{pmatrix} 5 \\ 2 \\ 10 \end{pmatrix}$$

$$\text{let } x_1 = 0 \quad y_1 = 1 \quad 2 \cdot 0 + 1 + 3 \cdot z_1 = 0$$

$$\hat{v}_1 = \begin{pmatrix} 0 \\ 1 \\ -\frac{1}{3} \end{pmatrix} \Rightarrow v_1 = \begin{pmatrix} 0 \\ 3 \\ -1 \end{pmatrix} \quad z_1 = -\frac{1}{3}$$

$$\text{let } x_2 = 1 \quad y_2 = 0 \quad 2 \cdot 1 + 0 + 3 \cdot z_2 = 0$$

$$\hat{v}_2 = \begin{pmatrix} 1 \\ 0 \\ -\frac{2}{3} \end{pmatrix} \Rightarrow v_2 = \begin{pmatrix} 3 \\ 0 \\ -2 \end{pmatrix} \quad z_2 = -\frac{2}{3}$$

$$\text{let } u_H = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$(i) \quad 2a + b + 3c = 0$$

$$(ii) \quad (5-a) \cdot 0 + (2-b) \cdot 3 + (10-c) \cdot (-1) = 0$$

$$0a - 3b + c = 4$$

$$(iii) \quad (5-a) \cdot 3 + (2-b) \cdot 0 + (10-c) \cdot (-2) = 0$$

$$-3a + 0b + 2c = 5$$

solve this system of linear equations for  $u = (-1, -1, 1)$

(2) Let  $u$  and  $v$  be some linearly independent vectors. Then the formula for  $u_H$ , where  $H$  is the hyperplane spanned by the basis  $\{v\}$ , is

$$u_H = \left( \frac{u \cdot v}{v \cdot v} \right) v \quad (1)$$

This only works for one-dimensional  $H$ ! Show that it is true by writing  $u_H = av$  for some  $a \in \mathbb{R}$  and isolating  $a$  in

$$(u - av) \perp v$$

$$\text{Let } u = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \text{ and } v = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

$$(u - av) \perp v \Rightarrow$$

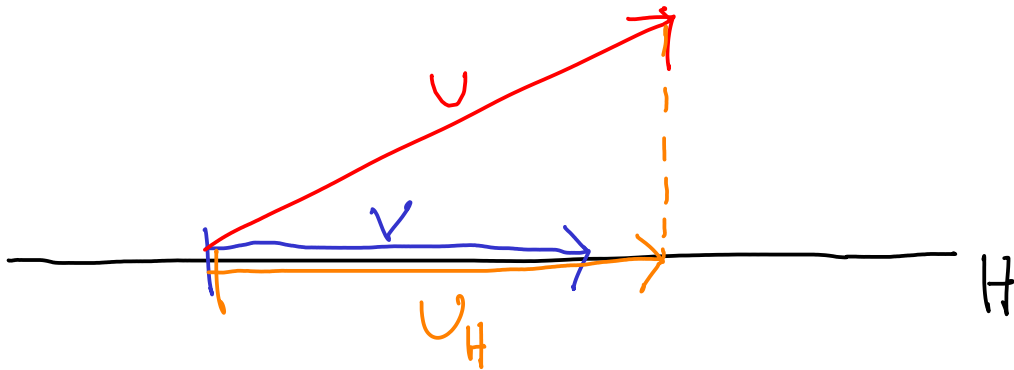
$$(u_1 - av_1)v_1 + (u_2 - av_2)v_2 + (u_3 - av_3)v_3 = 0$$

$$u_1v_1 + u_2v_2 + u_3v_3 - a(v_1v_1 + v_2v_2 + v_3v_3) = 0$$

$$u \cdot v - a \cdot (v \cdot v) = 0$$

$$a = \frac{u \cdot v}{v \cdot v}$$

Let  $H = \text{span}(\{v\})$  with  $v = (-2, 3)^T$ . Find  $u_H$  for  $u = (7, 5)^T$ .



$$u_H = \left( \frac{u \cdot v}{v \cdot v} \right) v = \left( \frac{\begin{pmatrix} 7 \\ 5 \end{pmatrix} \begin{pmatrix} -2 \\ 3 \end{pmatrix}}{\begin{pmatrix} -2 \\ 3 \end{pmatrix} \begin{pmatrix} -2 \\ 3 \end{pmatrix}} \right) \begin{pmatrix} -2 \\ 3 \end{pmatrix} =$$

$$\left( \frac{7 \cdot (-2) + 5 \cdot 3}{(-2) \cdot (-2) + 3 \cdot 3} \right) \begin{pmatrix} -2 \\ 3 \end{pmatrix} = \frac{1}{13} \cdot \begin{pmatrix} -2 \\ 3 \end{pmatrix} = \begin{pmatrix} -\frac{2}{13} \\ \frac{3}{13} \end{pmatrix}$$

(4) Let's try (1) again with a different strategy: What is the projection of  $\vec{u} = (5, 2, 10)^T$  onto the plane  $H$  characterized by  $2x + y + 3z = 0$ ?

$$v_1 = \begin{pmatrix} 0 \\ 3 \\ -1 \end{pmatrix} \quad \hat{v}_2 = \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} \text{ with } v_2 \perp v_1 \text{ and } v_2 \in H$$

$$(i) \quad 0 \cdot x_2 + 3y_2 - z_2 = 0 \quad (v_2 \perp v_1)$$

$$(ii) \quad 2x_2 + y_2 + 3z_2 = 0 \quad (v_2 \in H)$$

$$\text{let } z_2 = 3 \Rightarrow y_2 = 1$$

$$2x_2 + 1 + 3 \cdot 3 = 0 \quad v_2 = \begin{pmatrix} -5 \\ 1 \\ 3 \end{pmatrix}$$

$$2x_2 = -10$$

$$x_2 = -5$$

$$v_{H(v_1)} = \left( \frac{\begin{pmatrix} 5 \\ 2 \\ 10 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 3 \\ -1 \end{pmatrix}}{\begin{pmatrix} 0 \\ 3 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 3 \\ -1 \end{pmatrix}} \right) \begin{pmatrix} 0 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1.2 \\ 0.4 \end{pmatrix}$$

$$v_{H(v_2)} = \left( \frac{\begin{pmatrix} 5 \\ 2 \\ 10 \end{pmatrix} \cdot \begin{pmatrix} -5 \\ 1 \\ 3 \end{pmatrix}}{\begin{pmatrix} -5 \\ 1 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} -5 \\ 1 \\ 3 \end{pmatrix}} \right) \begin{pmatrix} -5 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ 0.2 \\ 0.6 \end{pmatrix}$$

$$v_H = v_{H(v_1)} + v_{H(v_2)} = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

(5) Consider the system of non-linear equations

$$\begin{aligned} 3^x - y^2 &= 2 \\ xy + \cos(y - 5) &= 16 \end{aligned} \quad (2)$$

To solve it numerically, we need to linearize the following function around an initial estimate of the solution  $x = 4, y = 4$ .

$$f((x, y)^T) = \begin{pmatrix} e^{x \ln 3} - y^2 - 2 \\ xy + \cos(y - 5) - 16 \end{pmatrix} \quad (3)$$

Find the Jacobian of  $f$  and derive the linearization of the function around  $x = 4, y = 4$ .

$$f_1(x, y) = e^{x \ln 3} - y^2 - 2 \quad f_2(x, y) = xy + \cos(y - 5) - 16$$

$$\frac{\partial f_1}{\partial x} = (\ln 3) e^{x \ln 3} \quad \frac{\partial f_1}{\partial y} = -2y$$

$$\frac{\partial f_2}{\partial x} = y \quad \frac{\partial f_2}{\partial y} = x + \sin(y - 5)$$

$$f(x, y) \approx f(4, 4) + J(4, 4) \begin{pmatrix} x - 4 \\ y - 4 \end{pmatrix} =$$

$$\begin{bmatrix} 3^4 - 4^2 - 2 \\ 4 \cdot 4 + \cos(-1) - 16 \end{bmatrix} + \begin{bmatrix} (\ln 3) \cdot 3^4 & -2 \cdot 4 \\ 4 & 4 + \sin(-1) \end{bmatrix} \begin{bmatrix} x - 4 \\ y - 4 \end{bmatrix} =$$

$$\begin{bmatrix} 63 \\ 0.54030 \end{bmatrix} + \begin{bmatrix} 88.9876 & -8 \\ 4 & 3.1585 \end{bmatrix} \begin{bmatrix} x - 4 \\ y - 4 \end{bmatrix} =$$

$$\begin{bmatrix} 88.9876x - 8y - 260.9504 \\ 4x + 3.1585y - 28.0937 \end{bmatrix}$$

You can convert these back into a system of linear equations that approximates the original system of non-linear equations. Solve it to get a better approximation than  $x=4, y=4$ . Use the new approximation to repeat the process until you are satisfied with the precision of your solution. This is called Newton's method.