

(1) Consider the vector space of quadratic polynomials

$$V = \{f | f(x) = ax^2 + bx + c\} \quad (1)$$

Are the following three quadratic polynomials a basis for V ?

$$\begin{aligned} f_1(x) &= 3x^2 + x + 6 \\ f_2(x) &= 5x^2 + x + 11 \\ f_3(x) &= -2x^2 - 6x + 4 \end{aligned} \quad (2)$$

- If yes, find the coordinates in terms of this basis for $7x^2 - x - 4$.
- If no, express one of the f_i by the others, $i = 1, 2, 3$.

$$f_1(x) \sim \begin{pmatrix} 3 \\ 1 \\ 6 \end{pmatrix} \quad f_2(x) \sim \begin{pmatrix} 5 \\ 1 \\ 11 \end{pmatrix} \quad f_3(x) \sim \begin{pmatrix} -2 \\ -6 \\ 4 \end{pmatrix}$$

$$\det \begin{pmatrix} \begin{bmatrix} 3 & 5 & -2 \\ 1 & 1 & -6 \\ 6 & 11 & 4 \end{bmatrix} \end{pmatrix} = 0 \quad \text{therefore, the three vectors are linearly dependent and do NOT form a basis of } V$$

$$\begin{pmatrix} 3 \\ 1 \\ 6 \end{pmatrix} = a \cdot \begin{pmatrix} 5 \\ 1 \\ 11 \end{pmatrix} + b \cdot \begin{pmatrix} -2 \\ -6 \\ 4 \end{pmatrix} \Rightarrow \begin{aligned} 5a - 2b &= 3 \\ a - 6b &= 1 \\ 11a + 4b &= 6 \end{aligned}$$

$$\begin{bmatrix} 5 & -2 & 3 \\ 1 & -6 & 1 \\ 11 & 4 & 6 \end{bmatrix} \xrightarrow[R_2 \leftrightarrow R_1]{R_1 - 5R_2} \begin{bmatrix} 5 & -2 & 3 \\ 0 & 28 & -2 \\ 11 & 4 & 6 \end{bmatrix} \xrightarrow[R_2 \rightarrow R_2]{\frac{1}{2} \cdot R_2} \begin{bmatrix} 5 & -2 & 3 \\ 0 & 14 & -1 \\ 11 & 4 & 6 \end{bmatrix} \xrightarrow[R_3 \rightarrow R_3]{11 \cdot R_1 - 5 \cdot R_3} \begin{bmatrix} 5 & -2 & 3 \\ 0 & 14 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 5 & -2 & 3 \\ 0 & 14 & -1 \\ 0 & -42 & 3 \end{bmatrix} \xrightarrow[R_3 \rightarrow R_3]{-\frac{1}{3} \cdot R_3} \begin{bmatrix} 5 & -2 & 3 \\ 0 & 14 & -1 \\ 0 & 14 & -1 \end{bmatrix} \xrightarrow[R_3 \rightarrow R_3]{R_2 - R_3} \begin{bmatrix} 5 & -2 & 3 \\ 0 & 14 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$14b = -1 \quad b = -\frac{1}{14} \quad 5a - \left(-\frac{1}{14}\right) \cdot 2 = 3 \Rightarrow a = \frac{4}{7}$$

$$\begin{pmatrix} 3 \\ 1 \\ 6 \end{pmatrix} = \frac{4}{7} \cdot \begin{pmatrix} 5 \\ 1 \\ 11 \end{pmatrix} - \frac{1}{14} \begin{pmatrix} -2 \\ -6 \\ 4 \end{pmatrix}$$

(2) Consider the vector space of lines in \mathbb{R}^3 going through the origin.

$$W = \{L \mid L : ax + by + cz = 0\} \quad (3)$$

Are the following three lines a basis for W ?

$$\begin{aligned} L_1 &: 2x + 5y + z = 0 \\ L_2 &: x - y - 2z = 0 \\ L_3 &: -3x + 4z = 0 \end{aligned} \quad (4)$$

- If yes, find the coordinates in terms of this basis for $L : 14x + 9y - 12z = 0$.
- If no, express one of the L_i by the others, $i = 1, 2, 3$.

$$L_1 \sim \begin{pmatrix} 2 \\ 5 \\ 1 \end{pmatrix} \quad L_2 \sim \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \quad L_3 \sim \begin{pmatrix} -3 \\ 0 \\ 4 \end{pmatrix}$$

$$\det \begin{pmatrix} \begin{bmatrix} 2 & 1 & -3 \\ 5 & -1 & 0 \\ 1 & -2 & 4 \end{bmatrix} \end{pmatrix} = -1$$

therefore, the three vectors are linearly independent, and because the vector space is three-dimensional they also span all of V ; it follows that they form a basis

$$\begin{pmatrix} 14 \\ 9 \\ -12 \end{pmatrix} = a \begin{pmatrix} 2 \\ 5 \\ 1 \end{pmatrix} + b \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} + c \begin{pmatrix} -3 \\ 0 \\ 4 \end{pmatrix}$$

$$\begin{bmatrix} 2 & 1 & -3 \\ 5 & -1 & 0 \\ 1 & -2 & 4 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 14 \\ 9 \\ -12 \end{bmatrix} \rightarrow V$$

A

$$A \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = V \Rightarrow$$

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = A^{-1} \cdot V = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$$

$$\begin{pmatrix} 14 \\ 9 \\ -12 \end{pmatrix} = 2 \cdot \begin{pmatrix} 2 \\ 5 \\ 1 \end{pmatrix} + 1 \cdot \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} - 3 \begin{pmatrix} -3 \\ 0 \\ 4 \end{pmatrix}$$

(3) There are three points whose coordinates with measurement errors are

$$\begin{aligned} I &= (595.74, 537.76) \\ J &= (800.92, 658.44) \\ K &= (302.96, 168.88) \end{aligned} \quad (5)$$

From station I , you observe an angle of $158^\circ 49' 21''$, again with the usual measurement error. In the next lesson, we will learn how to adjust the coordinates based on the observed angle. In the meantime, what is the angle between \vec{IJ} and \vec{IK} that you would have expected based on the coordinates? Use the inner product.

$$\begin{aligned} \vec{IJ} &= \begin{pmatrix} 800.92 - 595.74 \\ 658.44 - 537.76 \end{pmatrix} & \vec{IK} &= \begin{pmatrix} 302.96 - 595.74 \\ 168.88 - 537.76 \end{pmatrix} \\ &= \begin{pmatrix} 205.18 \\ 120.68 \end{pmatrix} & &= \begin{pmatrix} -292.78 \\ -368.88 \end{pmatrix} \\ \cos \vartheta &= \frac{\vec{IJ} \cdot \vec{IK}}{\|\vec{IJ}\| \cdot \|\vec{IK}\|} & \vartheta &= 158^\circ 54' 6'' \end{aligned}$$

(4) Find an orthonormal basis for the following vector plane. Identify the normal vector to the plane.

$$-6x + 5y + 8z = 0 \quad \rightarrow \quad (6)$$

orthonormal
vector
 $\vec{n} = \begin{pmatrix} -6 \\ 5 \\ 8 \end{pmatrix}$

find a \vec{b}_1 in the plane
 $x=1 \quad y=0$ (arbitrary)

$$\text{then } -6 \cdot 1 + 5 \cdot 0 + 8z = 0 \Rightarrow z = \frac{3}{4}$$

$$\vec{b}_1 = \begin{pmatrix} 1 \\ 0 \\ 3/4 \end{pmatrix} \Rightarrow \text{also in the plane}$$

$$\hat{b}_1 = \begin{pmatrix} 4 \\ 0 \\ 3 \end{pmatrix}$$

next: find $\vec{b}_2 \perp \hat{b}_1$ with \vec{b}_2 in the plane.

$$\text{let } \vec{b}_2 = \begin{pmatrix} \tilde{x} \\ \tilde{y} \\ \tilde{z} \end{pmatrix} \quad \text{then } -6\tilde{x} + 5\tilde{y} + 8\tilde{z} = 0$$

$$\text{and } 4\tilde{x} + 0\tilde{y} + 3\tilde{z} = 0$$

$$\begin{bmatrix} -6 & 5 & 8 & 0 \\ 4 & 0 & 3 & 0 \end{bmatrix} \xrightarrow[4R_1 - 6R_2]{R_2} \begin{bmatrix} -6 & 5 & 8 & 0 \\ 0 & 20 & 50 & 0 \end{bmatrix} \quad (\text{because } \vec{b}_1 \perp \vec{b}_2)$$

$$\Rightarrow 2\tilde{y} + 5\tilde{z} = 0, \text{ for example } \tilde{y} = 5 \quad \tilde{z} = -2$$

$$\Rightarrow \tilde{x} = \frac{3}{2} \Rightarrow \vec{b}_2 = \begin{pmatrix} 3/2 \\ 5 \\ -2 \end{pmatrix} \Rightarrow \hat{b}_2 = \begin{pmatrix} 3 \\ 10 \\ -4 \end{pmatrix}$$

$$b_1 = (4/5, 0, 3/5)^T \quad b_2 = (3/\sqrt{125}, 10/\sqrt{125}, -4/\sqrt{125})^T$$

(5) Consider the vector

$$\hat{b}_1 = \begin{pmatrix} -5 \\ -7 \\ 4 \end{pmatrix} \quad (7)$$

Find b_1 such that $b_1 \parallel \hat{b}_1$ (b_1 and \hat{b}_1 are parallel) and $\|b_1\| = 1$. Then find vectors b_2, b_3 so that $B = \{b_1, b_2, b_3\}$ is an orthonormal basis of \mathbb{R}^3 . Combine b_1, b_2, b_3 in a matrix M and find the inverse M^{-1} , using software. What do you notice?

$$\tilde{b}_2 \perp \hat{b}_1 \quad \text{let } \tilde{b}_2 = \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} \quad \text{then}$$

$$-5x_2 - 7y_2 + 4z_2 = 0 \quad (\tilde{b}_2 \perp \hat{b}_1)$$

$$\text{let } x_2 = 1 \quad y_2 = 0 \quad (\text{arbitrary}) \quad \text{then}$$

$$-5 + 4z_2 = 0 \Rightarrow z_2 = \frac{5}{4} \Rightarrow \tilde{b}_2 = \begin{pmatrix} 1 \\ 0 \\ 5/4 \end{pmatrix}$$

$$\Rightarrow \hat{b}_2 = \begin{pmatrix} 4 \\ 0 \\ 5 \end{pmatrix} \quad \text{now pick } \tilde{b}_3 \perp \hat{b}_1 \text{ and } \tilde{b}_3 \perp \hat{b}_2 \quad \text{let } \tilde{b}_3 = \begin{pmatrix} x_3 \\ y_3 \\ z_3 \end{pmatrix}$$

$$-5x_3 - 7y_3 + 4z_3 = 0$$

$$4x_3 + 5z_3 = 0$$

$$\text{choose } x_3 = -5 \\ \text{then } z_3 = 4$$

$$\text{and } (-5) \cdot (-5) - 7y_3 + 4 \cdot 4 = 0 \Rightarrow y_3 = \frac{41}{7}$$

$$\Rightarrow \tilde{b}_3 = \begin{pmatrix} -5 \\ 41/7 \\ 4 \end{pmatrix} \Rightarrow \hat{b}_3 = \begin{pmatrix} -35 \\ 41 \\ 28 \end{pmatrix}$$

$$b_3 = \frac{1}{3\sqrt{410}} \cdot (-35, 41, 28)^T$$

$$b_1 = \frac{1}{3\sqrt{101}} \cdot (-5, -7, 4)^T$$

$$b_2 = \frac{1}{\sqrt{41}} \cdot (4, 0, 5)^T$$

First some calculus. We learned at the end of last year that for a function $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ that is differentiable at (x_0, y_0) we can approximate

$$f(x, y) \approx L(x, y) = f(x_0, y_0) + \frac{\partial f}{\partial x}(x_0, y_0)(x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0)(y - y_0)$$

$L(x, y) = z$ is a plane equation for the plane that is tangent to the point $P = (x_0, y_0)$. More generally, if J is the Jacobian matrix

$$J = \begin{bmatrix} \frac{\partial F_1}{\partial x_1} & \cdots & \frac{\partial F_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_m}{\partial x_1} & \cdots & \frac{\partial F_m}{\partial x_n} \end{bmatrix}$$

then for a multivariable function $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ there is a linear approximation at point \vec{a} such that

$$F(\vec{x}) \approx F(\vec{a}) + J(\vec{a})(\vec{x} - \vec{a})$$

All of this theory is a consequence of using Taylor polynomials and cutting them off after the first term (the remainder of the Taylor series expansion becomes an error term for the approximation).

Let $f(x, y) = \sqrt{1 - x^2 - y^2}$ (half-sphere above xy -plane)

$$\frac{\partial f}{\partial x}(x, y) = -\frac{x}{\sqrt{1 - x^2 - y^2}} \quad \frac{\partial f}{\partial y} = -\frac{y}{\sqrt{1 - x^2 - y^2}}$$

$$z = \sqrt{1 - 0.2^2 - 0.3^2} - \frac{0.2}{\sqrt{1 - 0.2^2 - 0.3^2}}(x - 0.2) - \frac{0.3}{\sqrt{1 - 0.2^2 - 0.3^2}}(y - 0.3)$$

$$\Rightarrow z = \sqrt{0.87} - \frac{1}{\sqrt{0.87}}(0.2x - 0.04) - \frac{1}{\sqrt{0.87}}(0.3y - 0.09)$$

$$\sqrt{0.87} z = 0.87 - 0.2x + 0.04 - 0.3y + 0.09$$

$$0.2x + 0.3y + \sqrt{0.87} z = 1$$

this is the tangent plane equation using calculus

for the linear algebra approach, consider that P is in the tangent plane and that the vector from O to P is a normal vector to the tangent plane

$$P = (0.2, 0.3, \sqrt{0.87}) \quad \vec{OP} = \vec{n} = \begin{pmatrix} 0.2 \\ 0.3 \\ \sqrt{0.87} \end{pmatrix}$$

then the equation for the tangent plane is

$$0.2(x - 0.2) + 0.3(y - 0.3) + \sqrt{0.87}(z - \sqrt{0.87}) = 0$$

$$0.2x + 0.3y + \sqrt{0.87} z = 1$$

this is the tangent plane equation using linear algebra

(7) Solve the following system of linear equations. Use software.

$$\begin{array}{rrcr} 4a & + & b & - & c & = & -12 \\ 3a & - & 2b & + & 4c & = & -5 \\ -a & + & 8b & - & 14c & = & -9 \end{array} \quad (8)$$

If the system is consistent and dependent, provide your answer in the form

$$S = \{u \in \mathbb{R}^3 \mid u \text{ corresponds to } \vec{u} = \vec{v}_0 + s_1 \vec{v}_1 + \dots + s_n \vec{v}_n\} \quad (9)$$

where n is the dimension of the solution space and $s_i \in \mathbb{R}$ for $i = 1, \dots, n$. Note that $(-3, 2, 2)^T$ solves the system.

Since $\begin{pmatrix} -3 \\ 2 \\ 2 \end{pmatrix}$ solves the equation, $\vec{v}_0 = \begin{pmatrix} -3 \\ 2 \\ 2 \end{pmatrix}$

det $\left(\begin{bmatrix} 4 & 1 & -1 \\ 3 & -2 & 4 \\ -1 & 8 & -14 \end{bmatrix} \right) = 0$ use elementary row operations for

$$\begin{bmatrix} 4 & 1 & -1 & -12 \\ 3 & -2 & 4 & -5 \\ -1 & 8 & -14 & -9 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & -5 & -7 \\ 0 & 11 & -19 & -16 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

the last equation is redundant; the system is consistent with infinitely many solutions

find a solution that is not $\begin{pmatrix} -3 \\ 2 \\ 2 \end{pmatrix}$

$$11b - 19c = -16 \quad \text{choose } b=0 \quad \text{then } c = \frac{16}{19}$$

and $a = -3 \cdot 0 + 5 \cdot \frac{16}{19} - 7 = -\frac{53}{19}$

then $\left(-\frac{53}{19}, 0, \frac{16}{19}\right)^T$ is a solution and

$$\vec{v}_1 = \begin{pmatrix} -53/19 \\ 0 \\ 16/19 \end{pmatrix} - \begin{pmatrix} -3 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 4/19 \\ -2 \\ -22/19 \end{pmatrix}$$

we are only interested in the direction of v_1 , so we can multiply by 19 for

$$S = \{v \in \mathbb{R}^3 \mid v \sim \vec{v} = \begin{pmatrix} -3 \\ 2 \\ 2 \end{pmatrix} + s_1 \begin{pmatrix} 4 \\ -38 \\ -22 \end{pmatrix}, s_1 \in \mathbb{R}\}$$

(8) Solve the following system of linear equations. Use software.

$$\begin{array}{rrcrcl} 6x & & -4z & + & 5w & = & 23 \\ -3x & + & 8y & + & 3z & - & w & = & -14 \\ 9x & + & 8y & - & 5z & + & 9w & = & 32 \\ & & 16y & + & 2z & + & 3w & = & -5 \end{array} \quad (10)$$

If the system is consistent and dependent, provide your answer in the form

$$S = \{u \in \mathbb{R}^4 \mid u \text{ corresponds to } \vec{u} = \vec{v}_0 + s_1 \vec{v}_1 + \dots + s_n \vec{v}_n\} \quad (11)$$

where n is the dimension of the solution space and $s_i \in \mathbb{R}$ for $i = 1, \dots, n$.

Note that $(2, -1, 1, 3)^T$ solves the system.

$\vec{v}_0 = (2, -1, 1, 3)^T$ → solution #1

use software!

$$\begin{bmatrix} 6 & 0 & -4 & 5 & 23 \\ -3 & 8 & 3 & -1 & -14 \\ 9 & 8 & -5 & 9 & 32 \\ 0 & 16 & 2 & 3 & -5 \end{bmatrix} \sim \begin{bmatrix} 3 & 8 & -1 & 4 & 9 \\ 0 & 16 & 2 & 3 & -5 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

the system is consistent with infinitely many solutions, the solution space has dimension 2

$16y + 2z + 3w = -5$ choose $y=0$ $z=0$

then $w = -\frac{5}{3}$ and $x = \frac{47}{9}$ solution #2

$$\vec{v}_1 = \begin{pmatrix} 47/9 \\ 0 \\ 0 \\ -5/3 \end{pmatrix} - \begin{pmatrix} 2 \\ -1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 29/9 \\ 1 \\ -1 \\ -14/3 \end{pmatrix}$$

I am only interested in the direction of v_1 , so multiply by 9

$$\vec{v}_1 = \begin{pmatrix} 29 \\ 9 \\ -9 \\ -42 \end{pmatrix}$$

$16y + 2z + 3w = -5$ choose $z=0$ $w=0$

then $16y = -5 \Rightarrow y = -\frac{5}{16}$ and $x = \frac{23}{6}$ solution #3

$$\vec{v}_2 = \begin{pmatrix} 23/6 \\ -5/16 \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 2 \\ -1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 11/6 \\ 11/16 \\ -1 \\ -3 \end{pmatrix}$$

$$\vec{v}_2 = \begin{pmatrix} 88 \\ 33 \\ -48 \\ -144 \end{pmatrix}$$

use v_0 , v_1 , and v_2 to construct the solution set

(9) Find all interior angles for and the plane equation containing the triangle with points

$$P = (-6, -2, -7), Q = (-2, 1, 6), R = (-8, 3, -5) \quad (12)$$

Hint: Use the dot product to find the interior angles. Use the cross product to find a normal vector to the plane. Remember that the cross product of two vectors is

$$\vec{v} \times \vec{w} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} \quad (13)$$

and is perpendicular to both \vec{v} and \vec{w} . If $P = (p_x, p_y, p_z)$ is a point on a plane and $\vec{n} = (n_x, n_y, n_z)^T$ is a normal vector to the plane, then the plane equation is (why?)

$$n_x(p_x - x) + n_y(p_y - y) + n_z(p_z - z) = 0 \quad (14)$$

$$\vec{PQ} = \begin{pmatrix} 4 \\ 3 \\ 13 \end{pmatrix} \quad \vec{PR} = \begin{pmatrix} -2 \\ 5 \\ 2 \end{pmatrix}$$

$$\begin{aligned} \vec{PQ} \times \vec{PR} &= (3 \cdot 2 - 13 \cdot 5) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} - (4 \cdot 2 - (-2) \cdot 13) \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + \\ & (4 \cdot 5 - (-2) \cdot 3) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -59 \\ -34 \\ 26 \end{pmatrix} = \vec{n} \end{aligned}$$

plane equation:

$$-59(x + 6) - 34(y + 2) + 26(z + 7) = 0$$

$$-59x - 34y + 26z = -240$$