CodeBook

JRB 05MAY2016

This code book describes the variables defined in the tidy1.txt dataset

NOTE: The variable name in the derived dataset (summarybysubjectactivity.txt) are named meanofxxxx where xxx is the original variable name from tidy1 so for example timebodyaccelerationmeany becomes meanoftimebodyaccelerationmeany

ID	Variable Name	Type	measure	axis	domain	description	Unit
1	subject	NA	NA	NA	NA	subject ID	NA
2	activity	NA	NA	NA	NA	actvity	NA
3	time body acceleration mean x	acceleratiomean		X	$_{ m time}$	body	g
4	time body acceleration meany	acceleratiom ean		у	time	body	g
5	time body acceleration meanz	acceleratiomean		${f z}$	time	body	g
6	time body acceleration stddev x	accelerationstd dev		x	time	body	g
7	time body acceleration stddevy	acceleration td dev		У	time	body	g
8	time body acceleration stddev z	accelerationstd dev		${f z}$	time	body	g
9	time gravity acceleration mean x	accelerationtd dev		x	time	body	g
10	time gravity acceleration meany	acceleration dev		У	time	body	g
11	time gravity acceleration meanz	accelerationstd dev		${f z}$	time	body	g
12	time gravity acceleration stddev x	acceleration dev		x	time	gravity	g
13	time gravity acceleration stddevy	acceleratiosstd dev		У	time	gravity	g
14	time gravity acceleration stddev z	accelerationtd dev		${f z}$	time	gravity	g
15	time body acceleration jerk mean x	acceleratiom ean		x	time	jerk	g
16	time body acceleration jerk meany	acceleratiomean		У	time	jerk	g
17	time body acceleration jerk mean z	acceleratiomean		${f z}$	time	jerk	g
18	time body acceleration jerk stddev x	accelerationstd dev		x	time	jerk	g
19	time body acceleration jerk stddevy	accelerationstd dev		У	time	jerk	g
20	time body acceleration jerk stddev z	acceleratiosstd dev		${f z}$	$_{ m time}$	jerk	g

ID	Variable Name	Type	measure	axis	domain	description	Unit
21	timebodygyroscopemeanx	gyroscope	mean	х	time	body	rad/s
22	time body gyroscope meany	gyroscope	mean	У	time	body	$\mathrm{rad/s}$
23	$time body gyroscope mean \\ z$	gyroscope	mean	\mathbf{z}	time	body	$\mathrm{rad/s}$
24	time body gyroscope stddev x	gyroscope	std dev	x	time	body	$\mathrm{rad/s}$
25	time body gyroscope stddevy	gyroscope	std dev	У	time	body	$\mathrm{rad/s}$
26	time body gyroscope stddev z	gyroscope	std dev	\mathbf{z}	time	body	$\rm rad/s$
27	time body gyroscopejerk mean x	gyroscope	mean	x	time	jerk	$\mathrm{rad/s}$
28	time body gyroscopejerk meany	gyroscope	mean	У	time	jerk	$\mathrm{rad/s}$
29	time body gyroscopejerk meanz	gyroscope	mean	\mathbf{z}	time	jerk	$\mathrm{rad/s}$
30	time bodygyroscopejerk stddev x	gyroscope	std dev	x	time	jerk	rad/s
31	timebodygyroscopejerkstddevy	gyroscope	std dev	У	time	jerk	rad/s
32	time bodygyroscopejerk stddevz	gyroscope	std dev	\mathbf{z}	time	jerk	rad/s
33	time body acceleration magnitude stdde	evacceleration	osatd dev	NA	time	magnitude	g
34	time gravity acceleration magnitude std	d æv celerati	o s td dev	NA	time	magnitude	g
35	time body acceleration jerk magnitudes	t dadev leratio	osatd dev	NA	time	magnitude	g
36	time body gyros cope magnitudes td dev	gyroscope	std dev	NA	time	magnitude	rad/s
37	time bodygyroscopejerk magnitude std	d av celerati	osatd dev	x	time	magnitude	rad/s
38	frequency body acceleration mean x	acceleration	omean	x	frequency	body	$_{\mathrm{Hz}}$
39	frequency body acceleration meany	acceleration	omean	У	frequency	body	Hz
40	frequency body acceleration meanz	acceleration	omean	${f z}$	frequency	body	Hz
41	frequency body acceleration stddev x	acceleration	osatd dev	x	frequency	body	$_{\mathrm{Hz}}$
42	frequency body acceleration stddevy	acceleration	osatd dev	У	frequency	body	Hz
43	frequency body acceleration stddev z	acceleration	osatd dev	x	frequency	body	$_{\mathrm{Hz}}$
44	frequencybodyaccelerationjerkmeanx	acceleration	omean	x	frequency	jerk	$_{\mathrm{Hz}}$
45	frequencybodyaccelerationjerkmeany	acceleration	omean	У	time	jerk	$_{\mathrm{Hz}}$
46	frequency body acceleration jerk meanz	acceleration	omean	${f z}$	time	jerk	$_{\mathrm{Hz}}$

ID	Variable Name	Type	measure	axis	domain	description	Unit
47	frequencybodyaccelerationjerkstddev	vxaccelerat	ciosatd dev	х	frequency	jerk	Hz
48	frequency body acceleration jerkst ddevent a state of the state of t	vyaccelerat	ciosatd dev	У	frequency	jerk	$_{\mathrm{Hz}}$
49	frequency body acceleration jerk stddev	vzaccelerat	ciosatd dev	${f z}$	frequency	jerk	$_{\mathrm{Hz}}$
50	frequency body gyroscope mean x	gyroscop	e mean	x	frequency	body	Hz
51	frequency body gyroscope meany	gyroscop	e mean	У	frequency	body	Hz
52	frequency body gyroscope meanz	gyroscop	e mean	${f z}$	frequency	body	Hz
53	frequency body gyroscopest d dev x	gyroscop	e std dev	x	frequency	body	Hz
54	frequency body gyroscopest d devy	gyroscop	e std dev	У	frequency	body	Hz
55	frequency body gyroscopest d dev z	gyroscop	e std dev	${f z}$	frequency	body	Hz
56	frequency body acceleration magnitude	es addelæ rat	ciosatd dev	NA	frequency	magnitude	Hz
57	$frequency body body acceleration jerk \\ \\$	na gorielede s	s tokate vdev	NA	frequency	jerk	Hz
58	frequency body body gyroscope magnitude of the control of the co	u dystośdep	e std dev	NA	frequency	magnitude	Hz
59	frequencybodybodygyroscopejerkma	gwigtrockestp	lelst d dev	NA	frequency	jerk	Hz