## Problem report for:

RobotoFlex[GRAD,XOPQ,XTRA,YOPQ,YTAS,YTDE,YTFI,YTLC,YTUC,opsz,slnt,wdth,wght].ttf

sha1:6168f4d27fdd777975ae0de390072471bafb028e

Family name: Roboto Flex

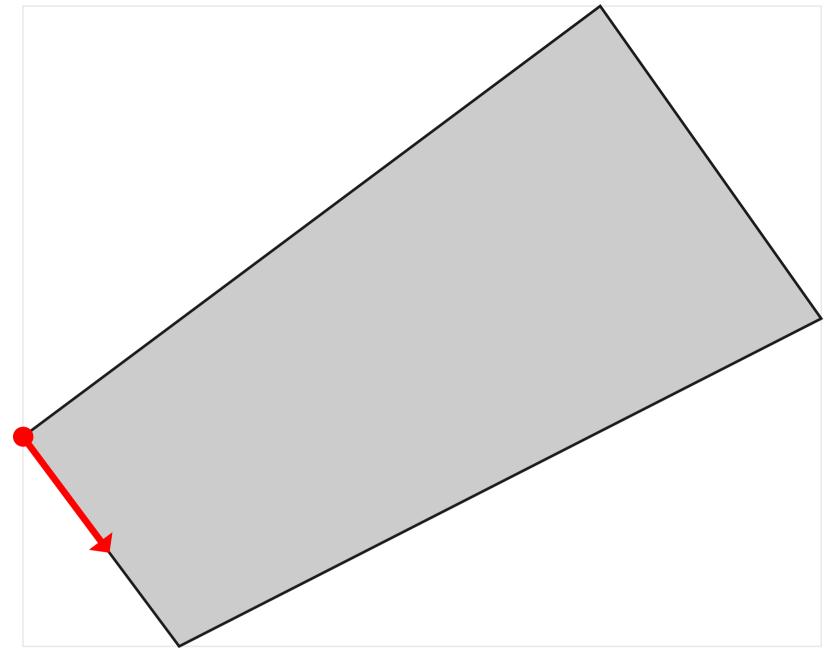
Version: Version 3.200;gftools[0.9.32]

acutecombstack.case tolerance: 0.11

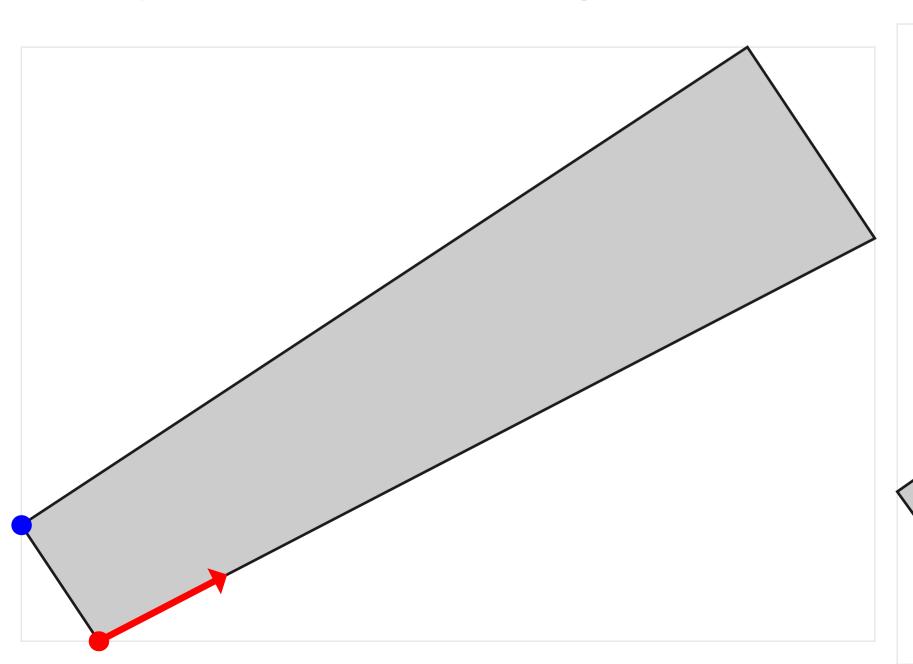
wrong\_start\_point

midway interpolation

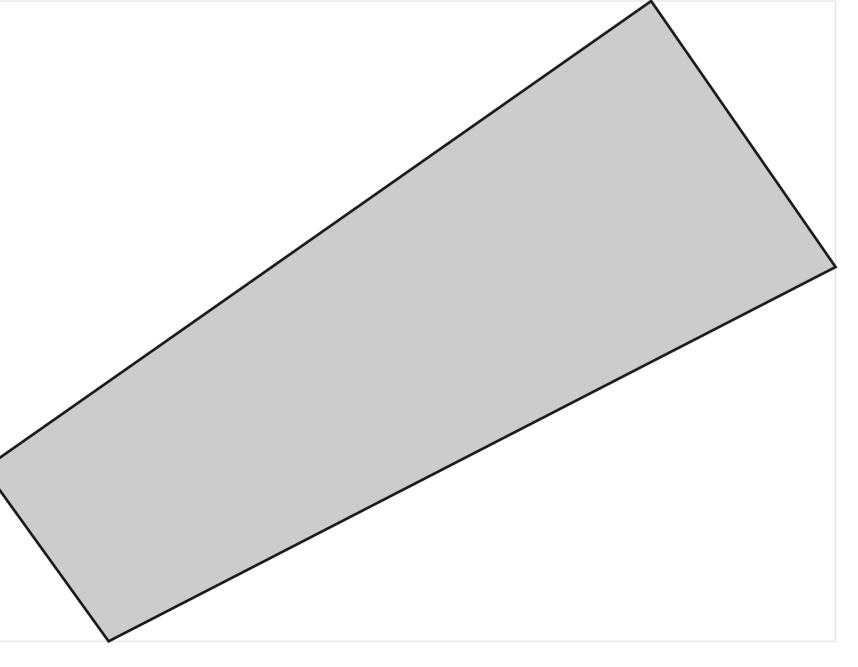
'opsz=8.0 wdth=25.0'



'opsz=8.0 wdth=25.0 wght=100.0'



proposed fix

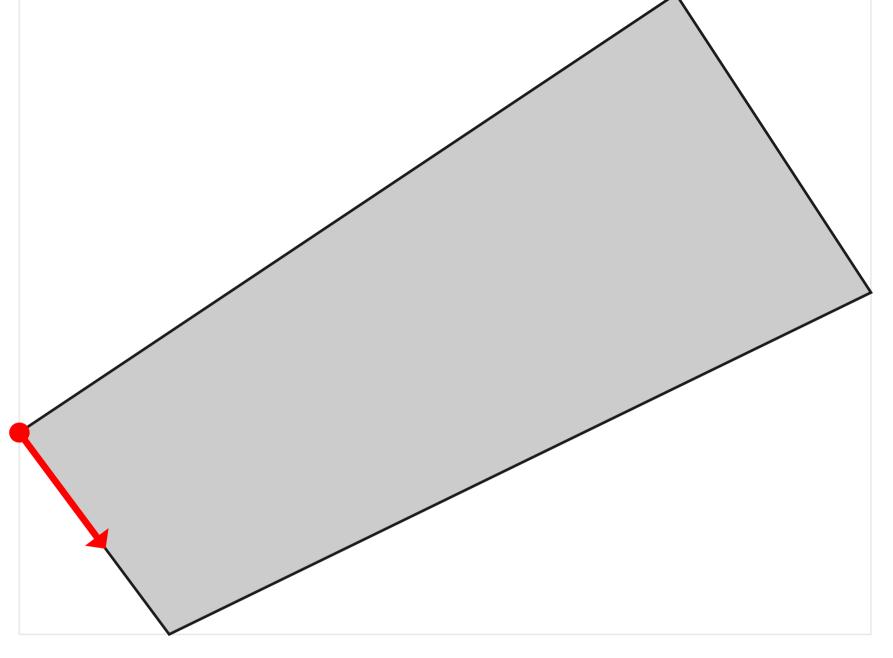


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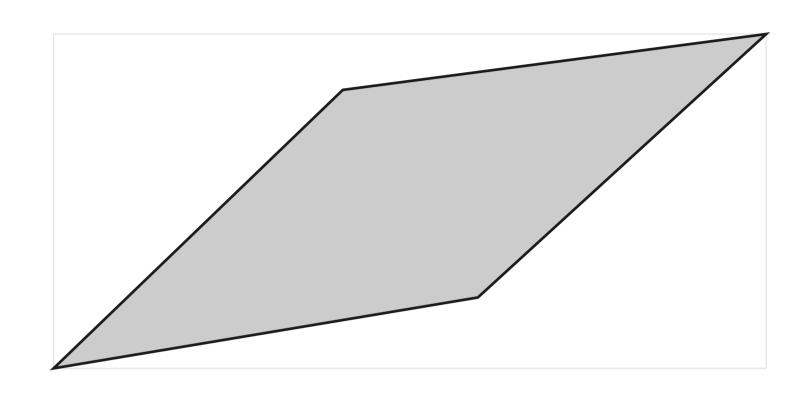
45401

wrong\_start\_point

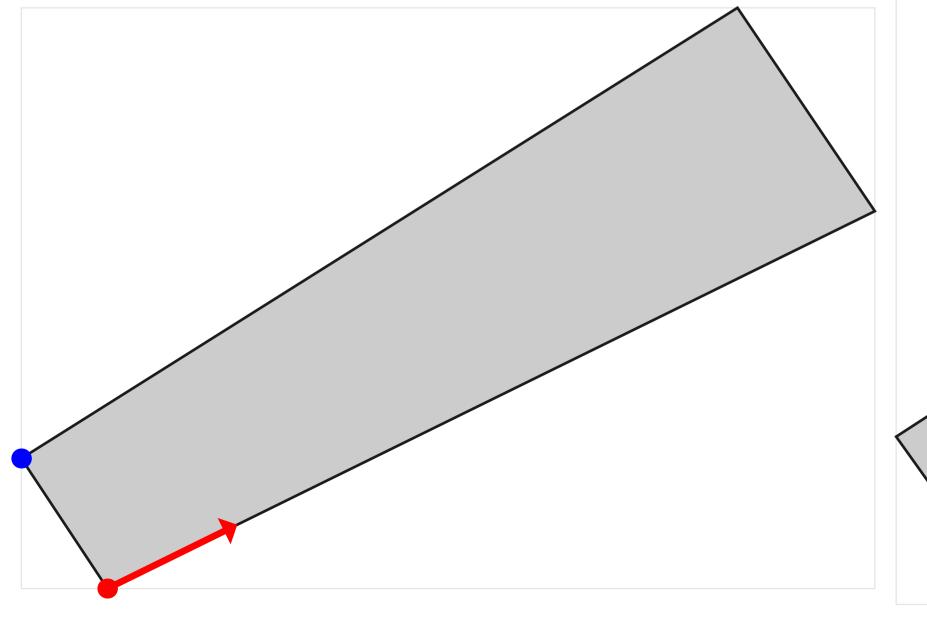


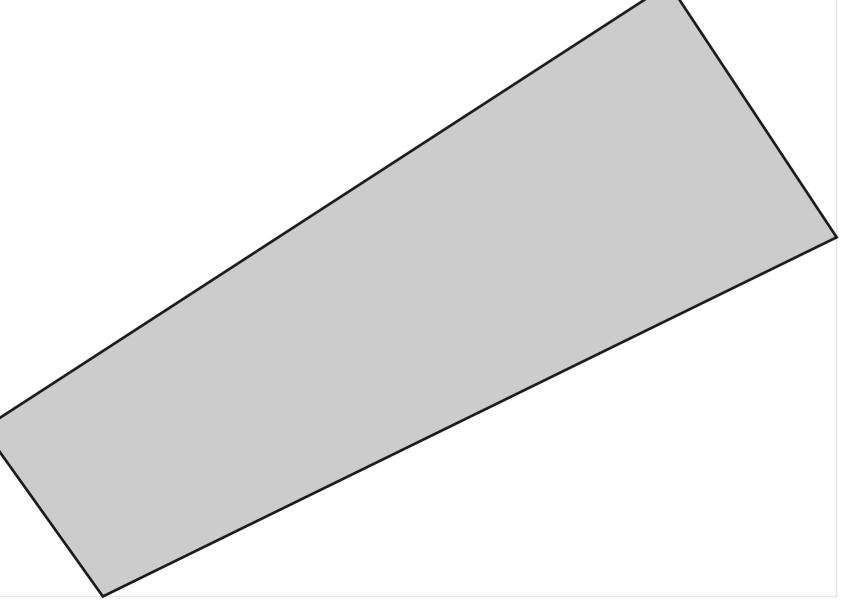


'opsz=8.0 wdth=151.0 wght=100.0'



proposed fix



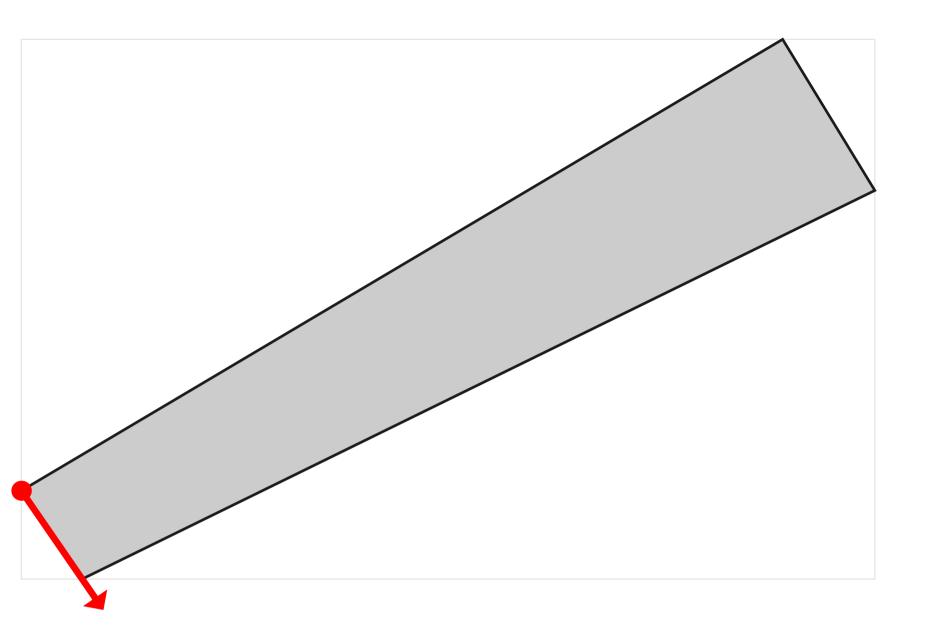


acutecombstack.case

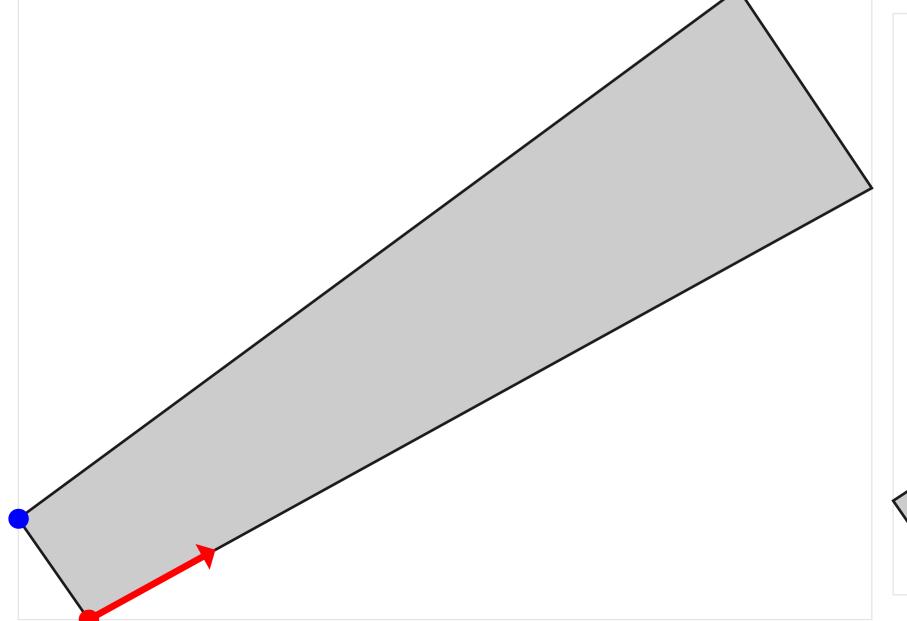
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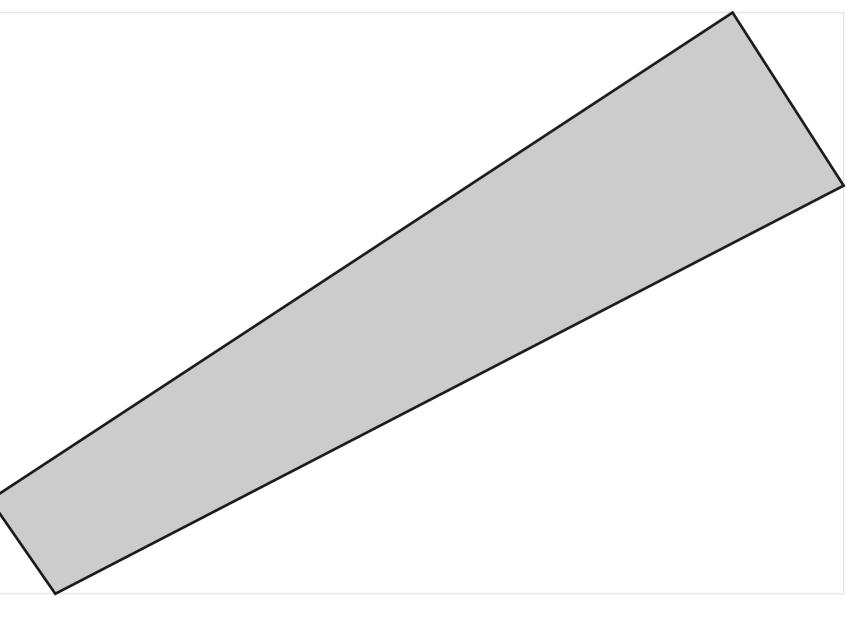
wrong\_start\_point



'GRAD=-200.0 opsz=8.0 wdth=25.0 wght=100.0'



proposed fix

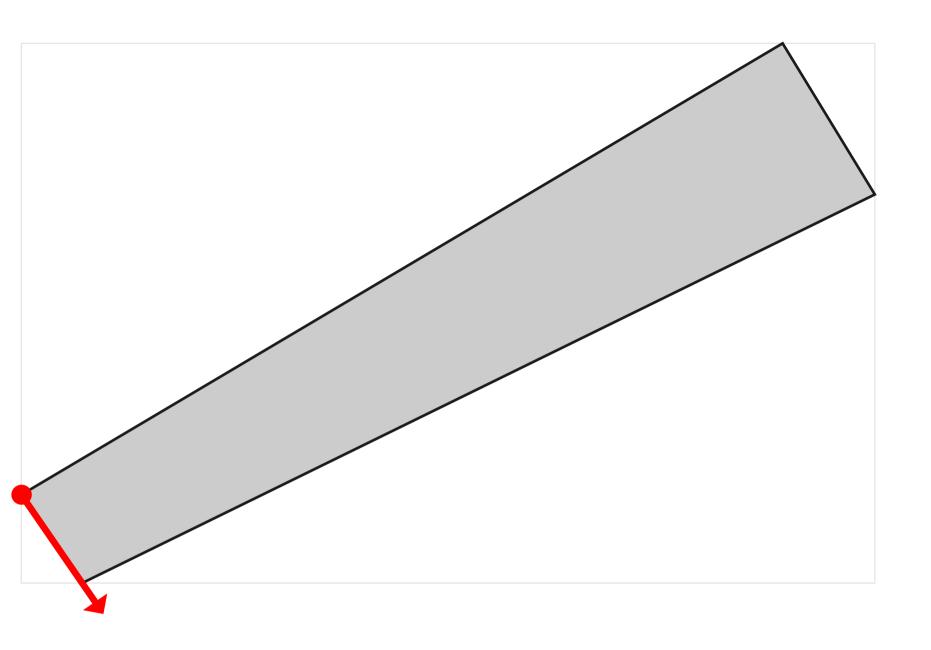


acutecombstack.case

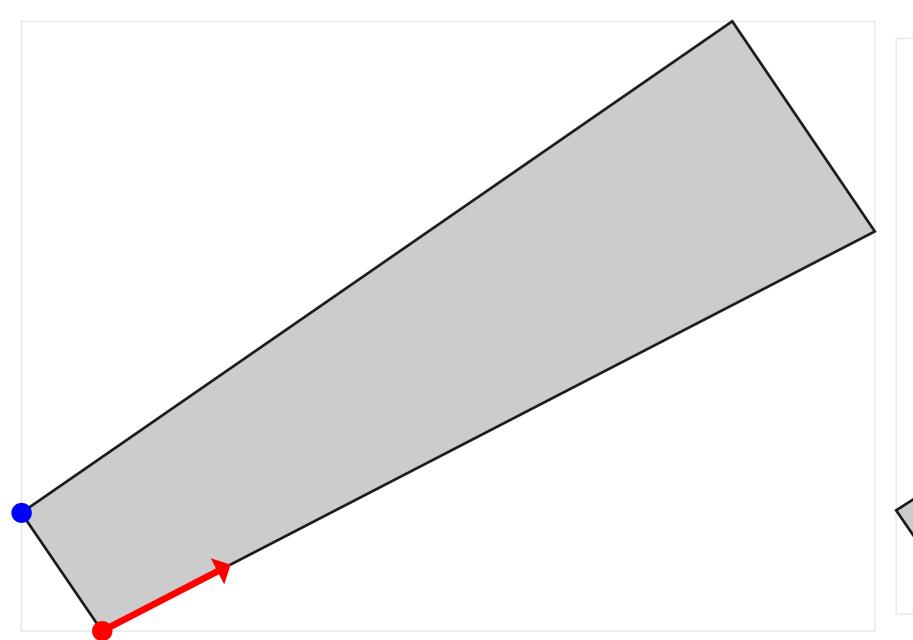
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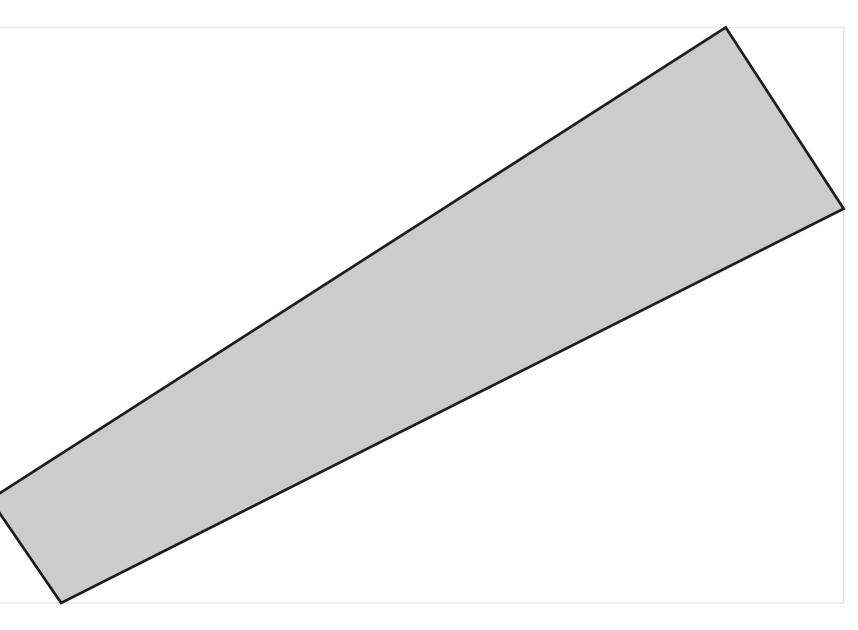
wrong\_start\_point



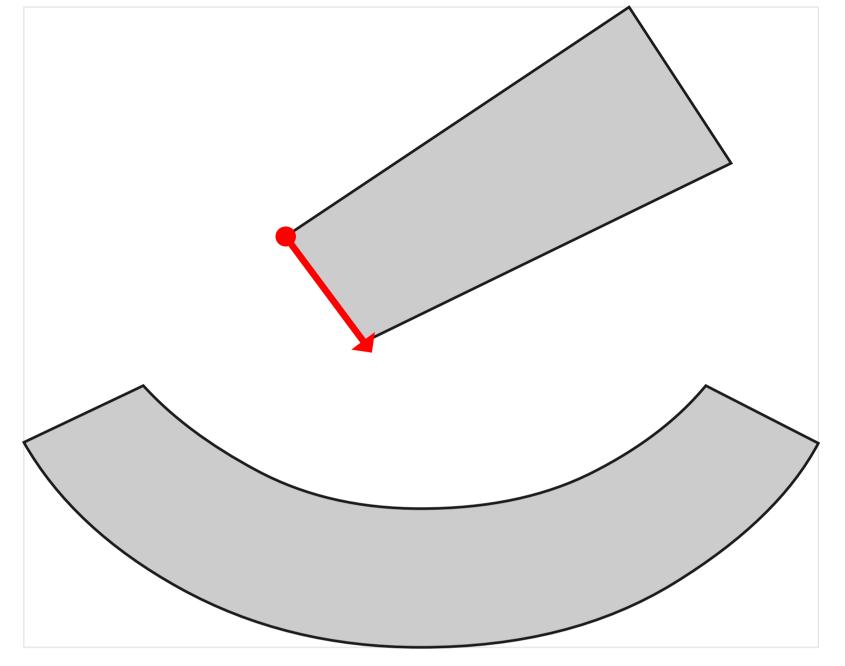
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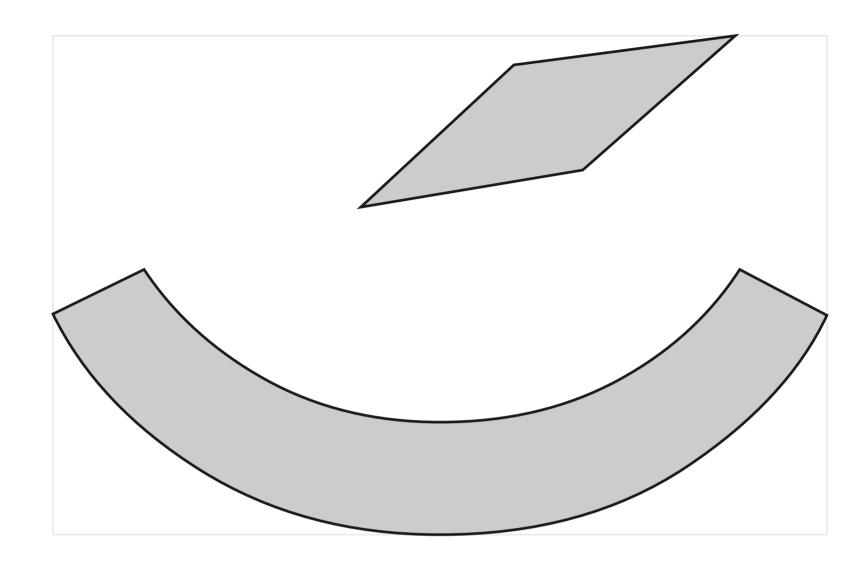
proposed fix



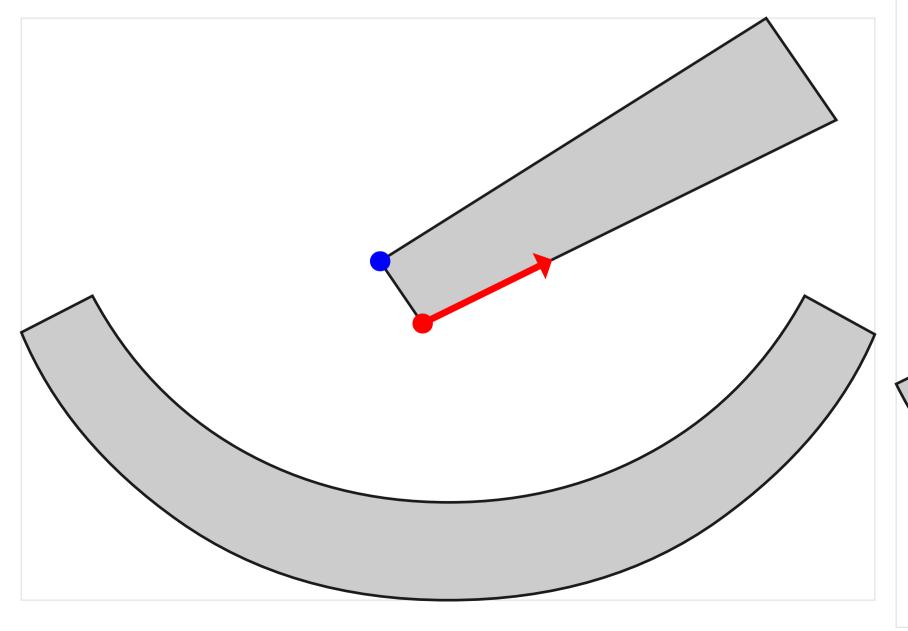
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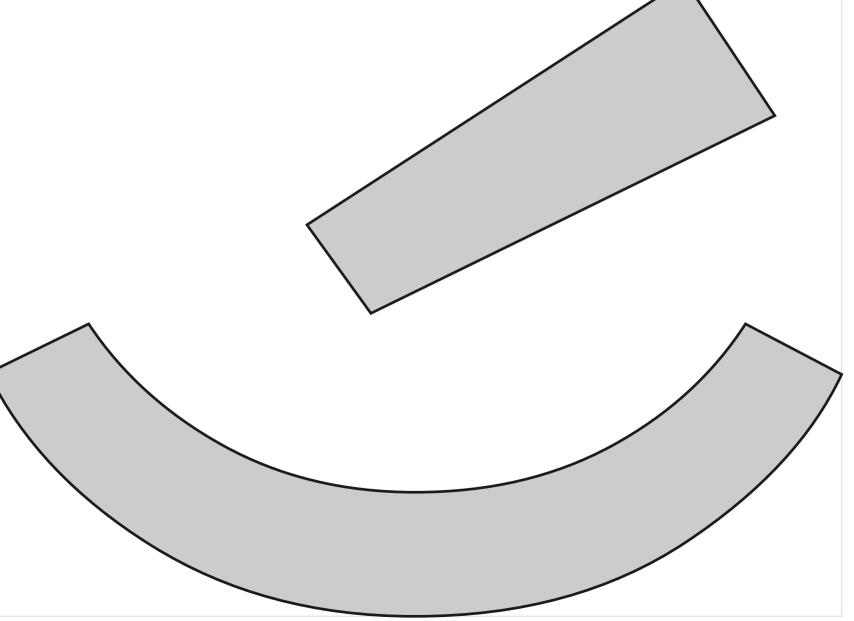


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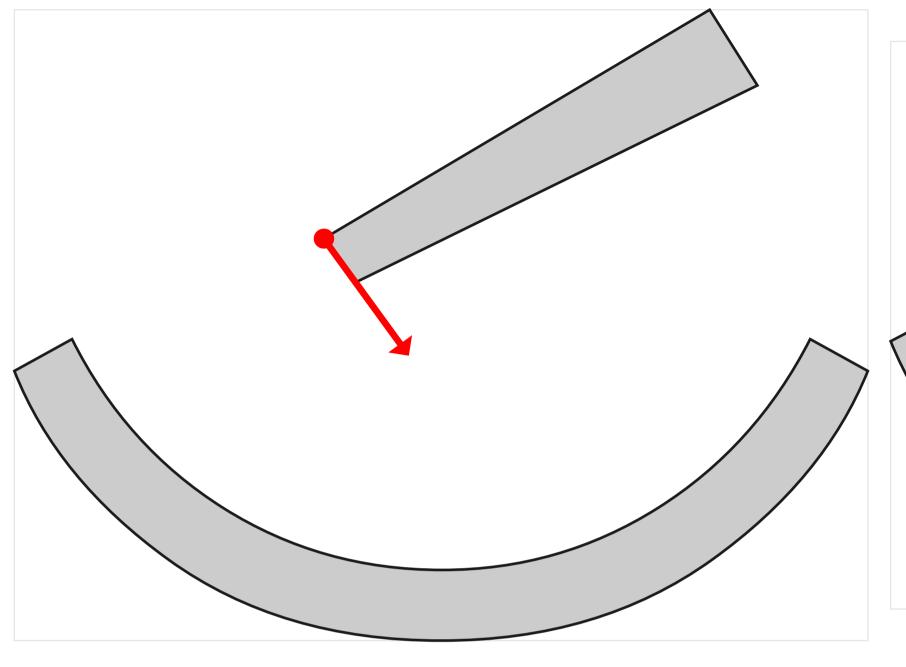


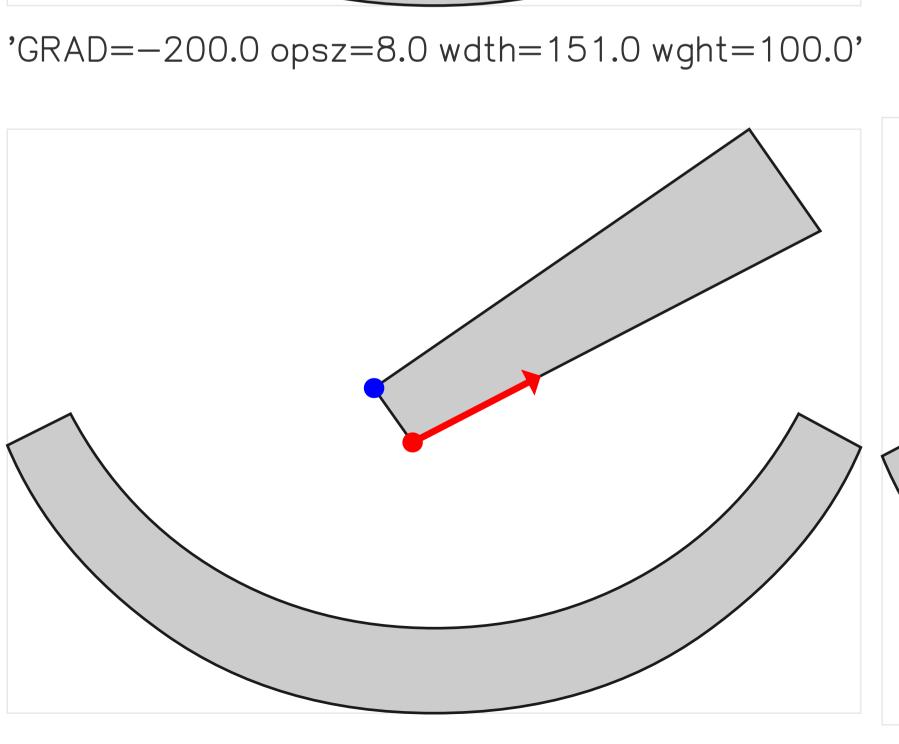
proposed fix

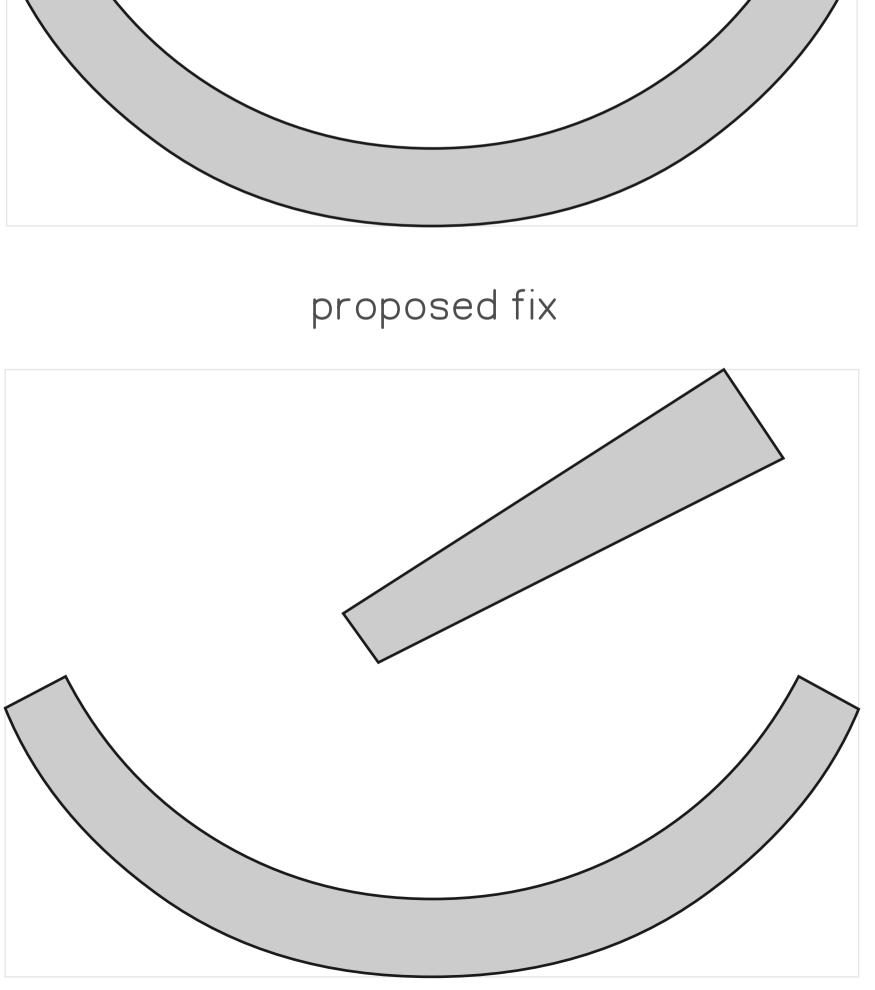




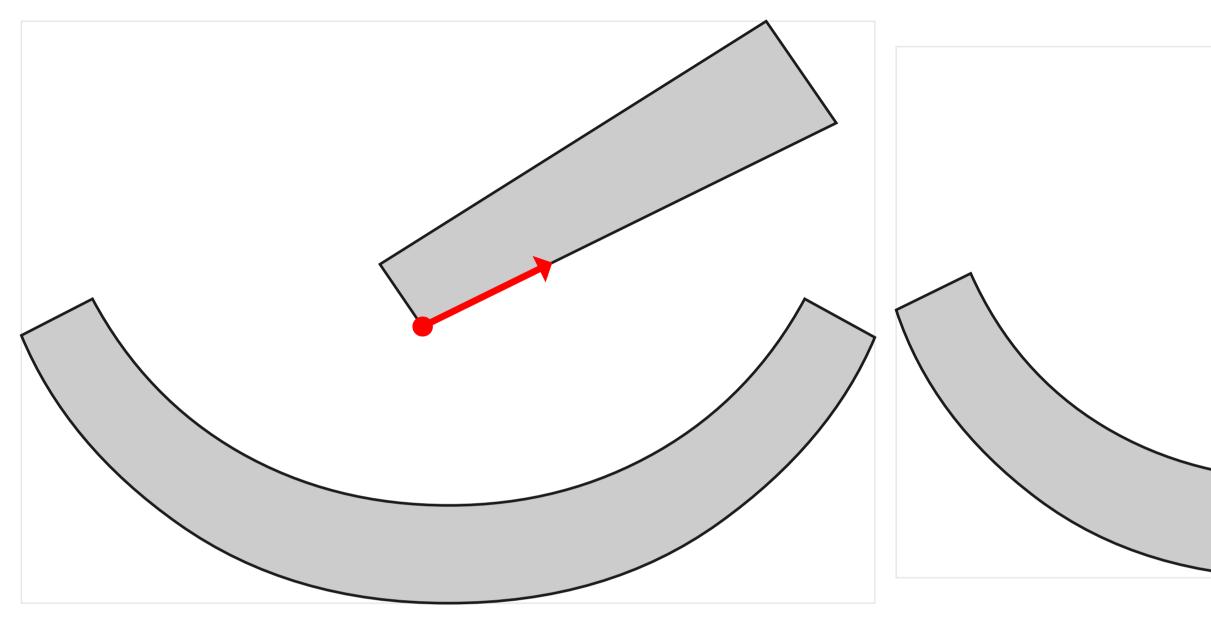
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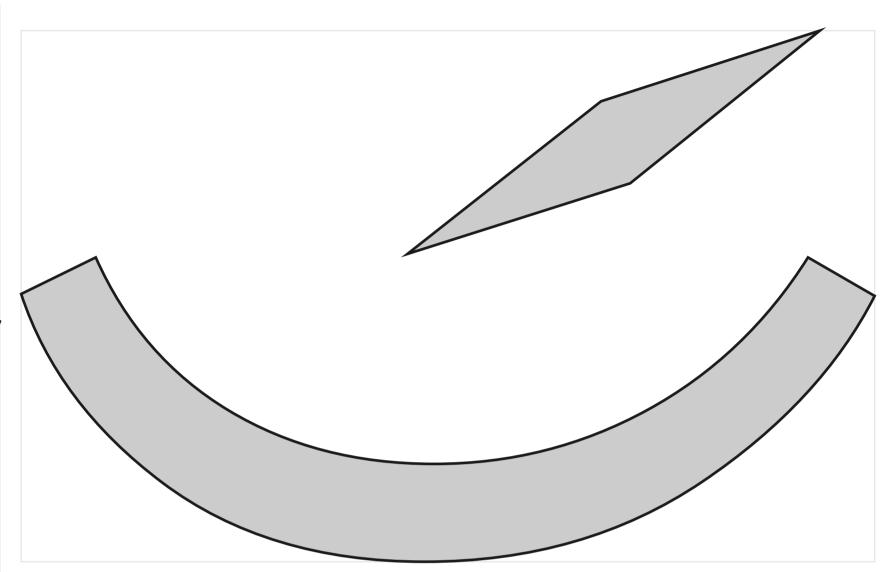






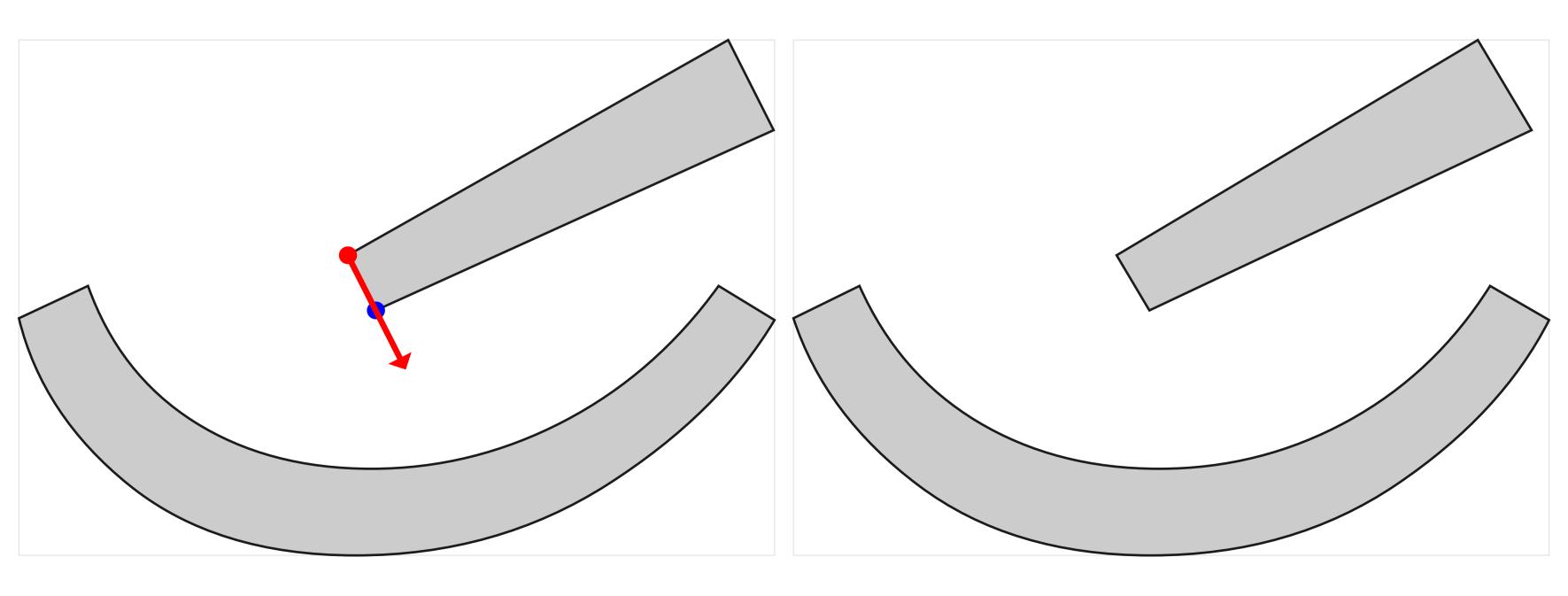
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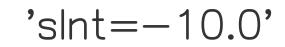


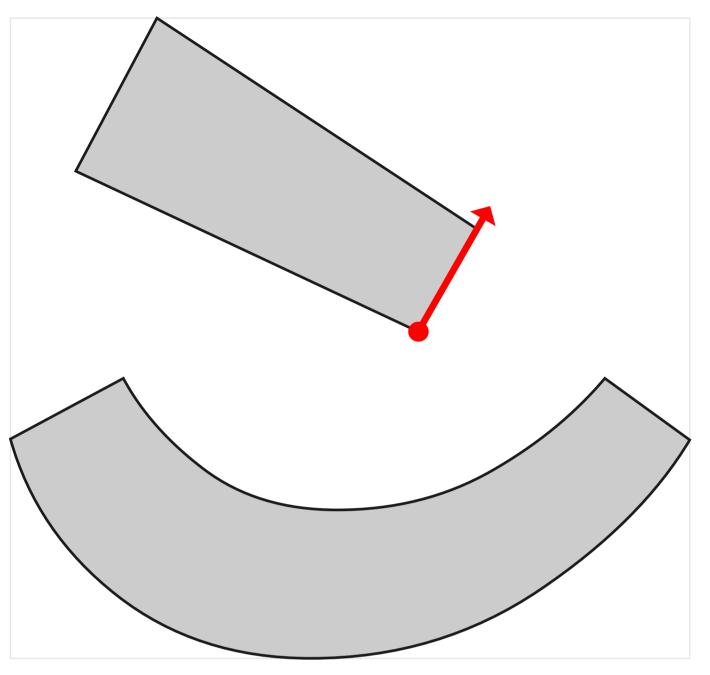


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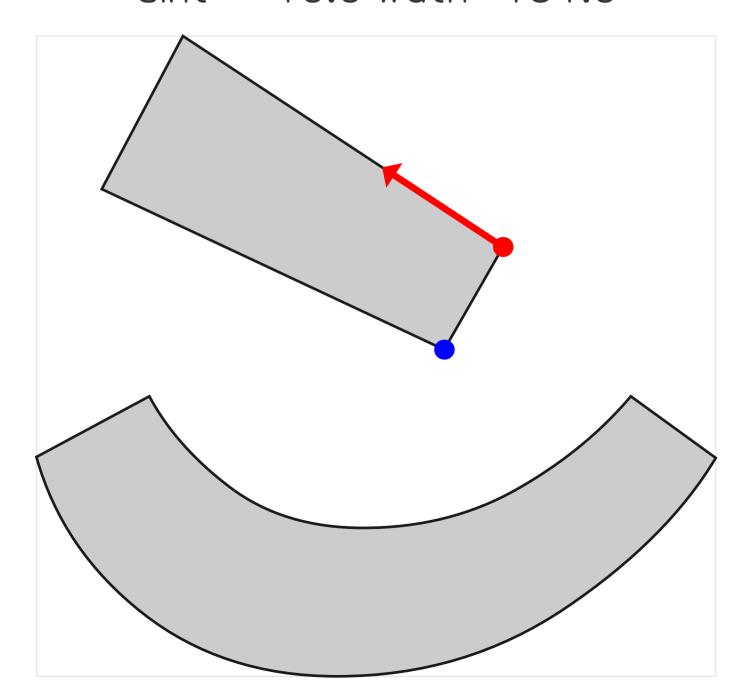
proposed fix

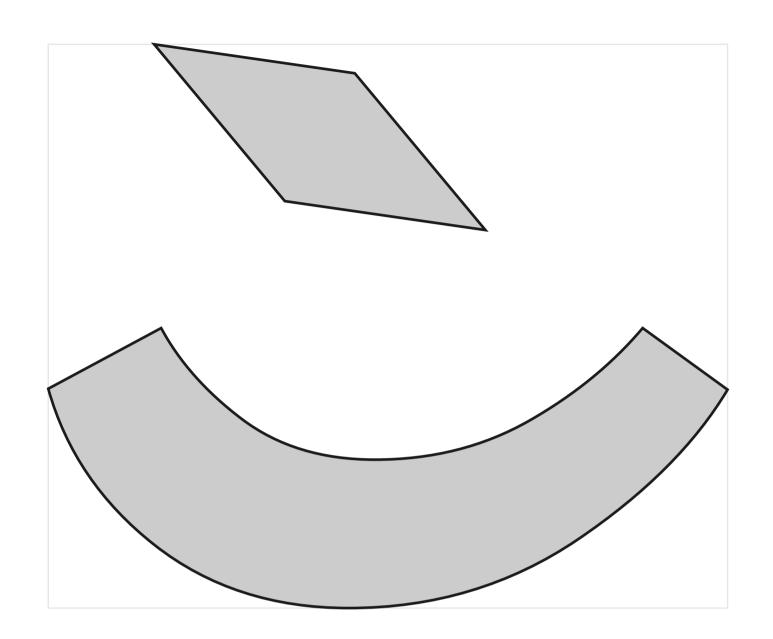




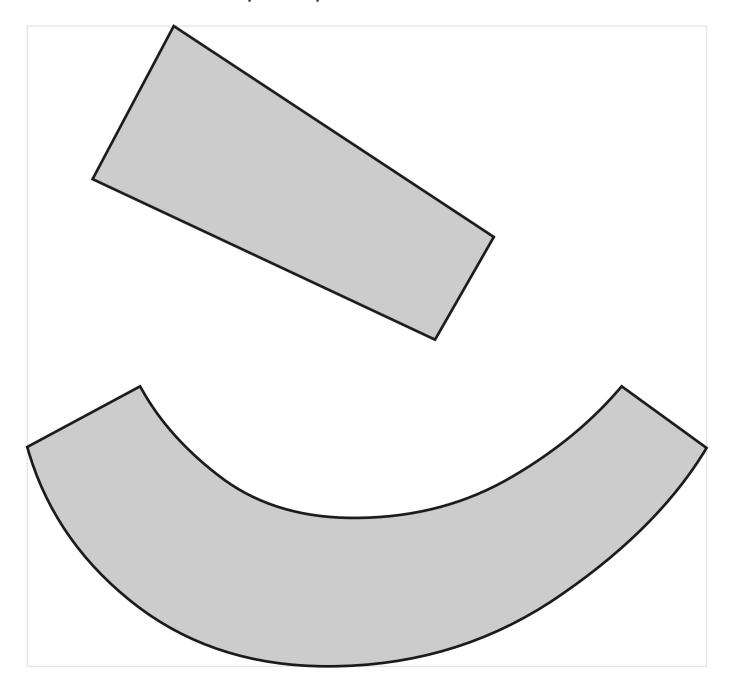


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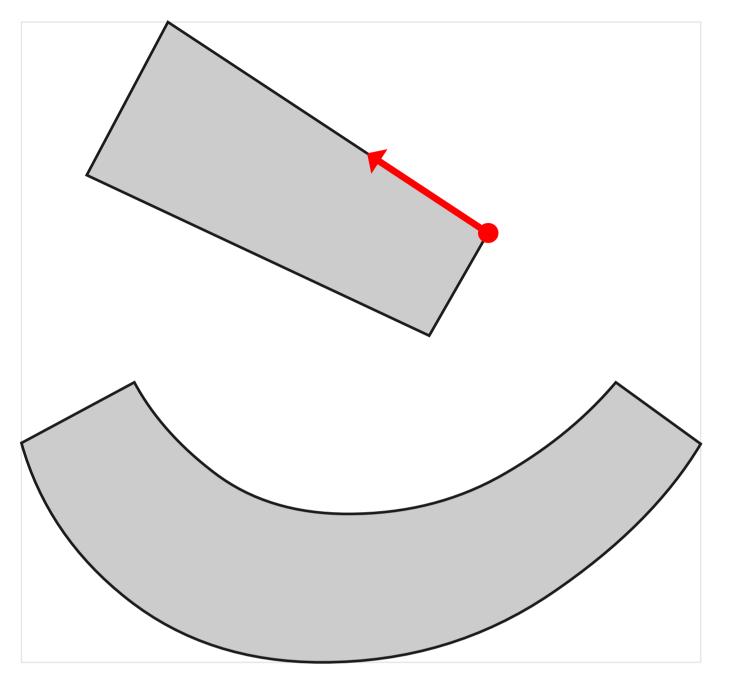
proposed fix



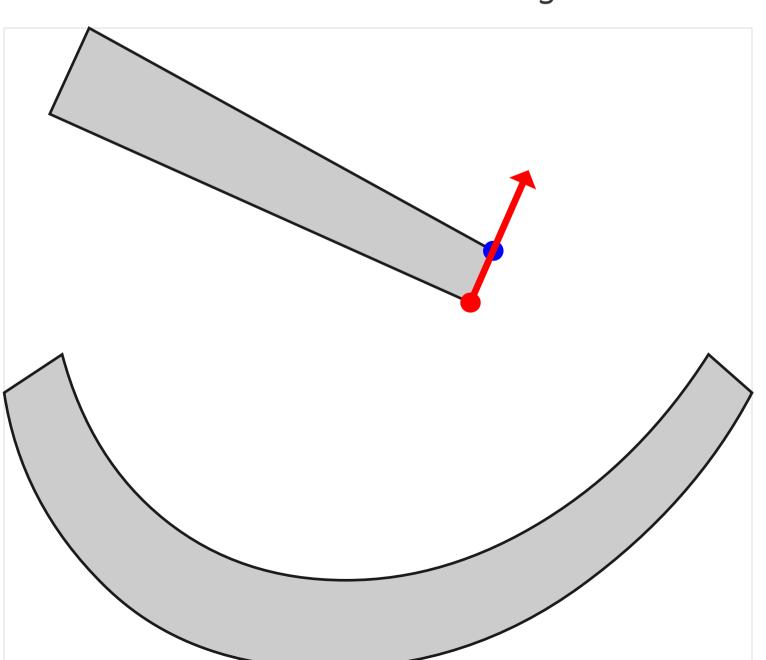
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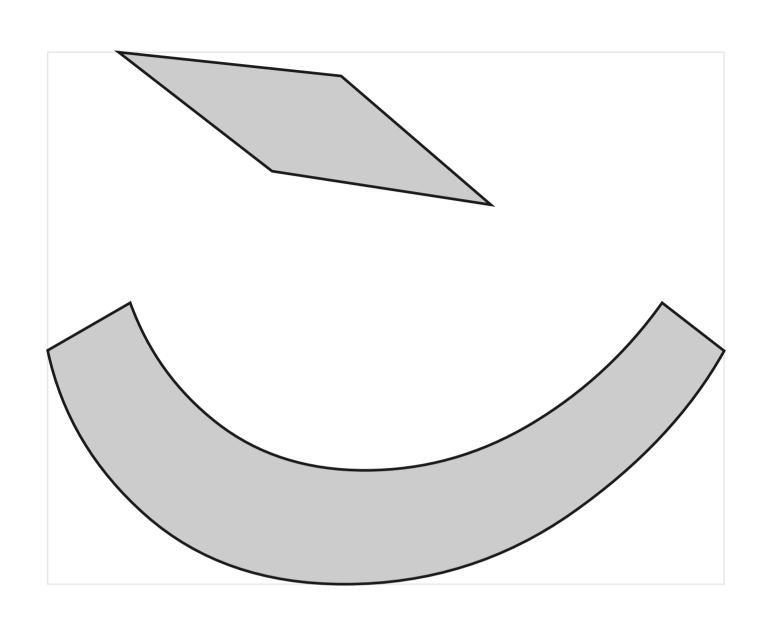
wrong\_start\_point



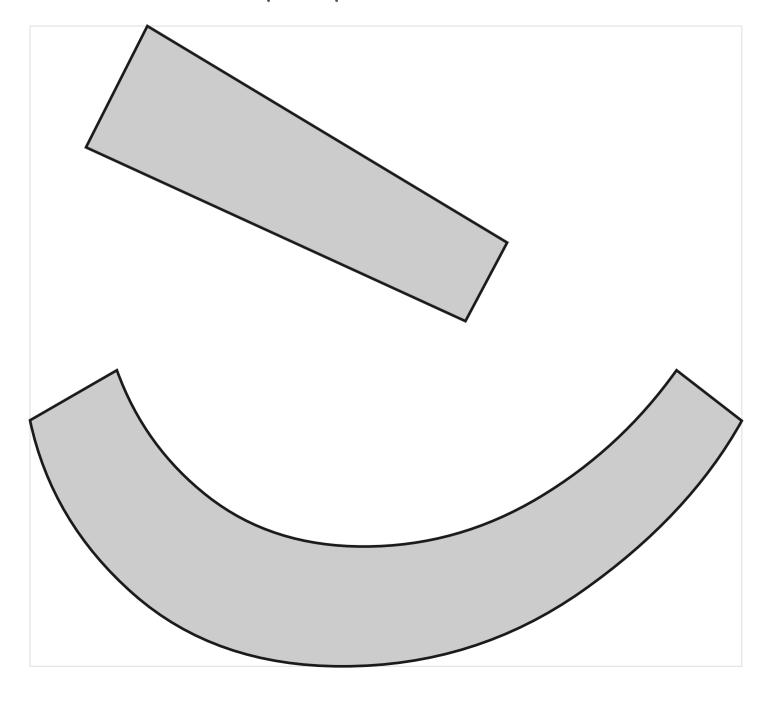


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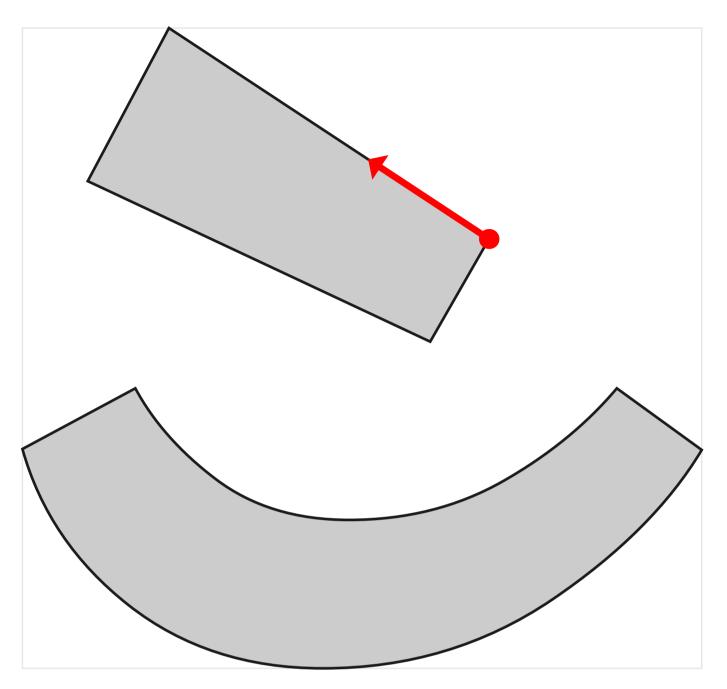




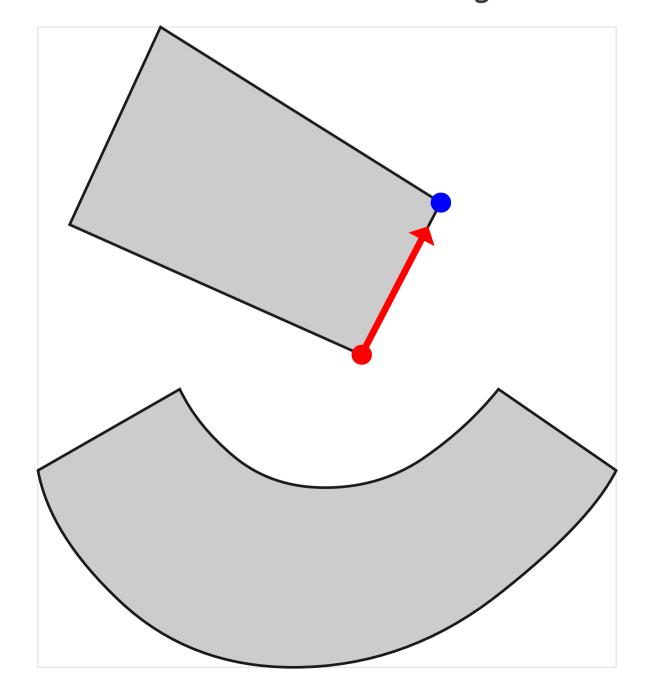
proposed fix

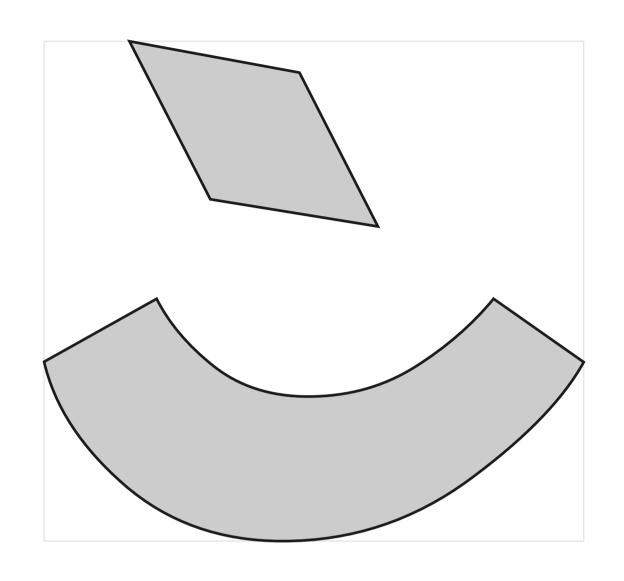


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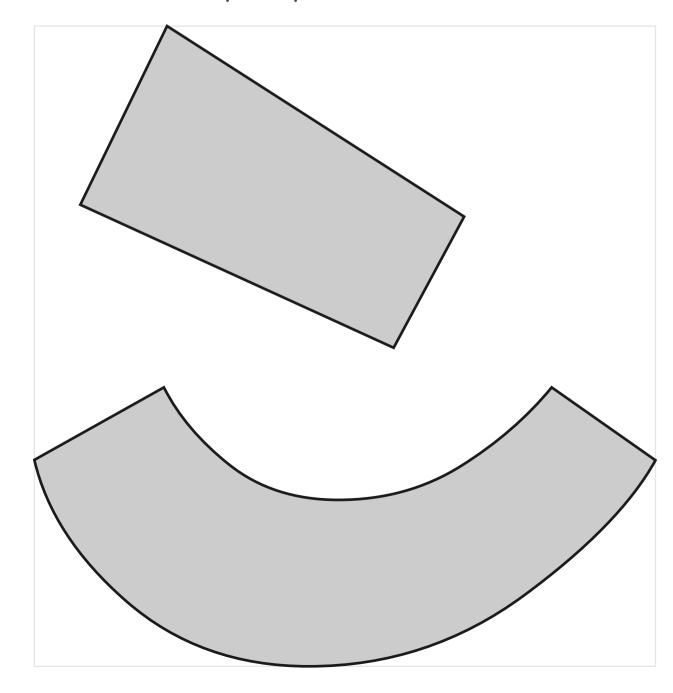


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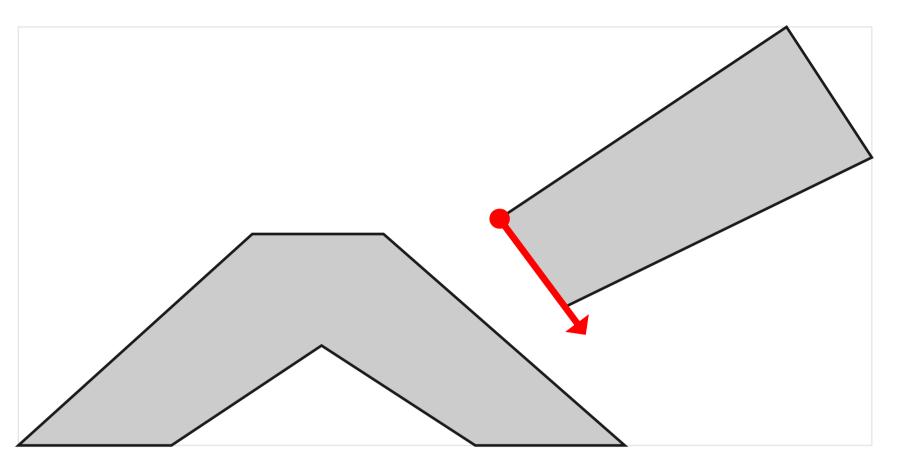


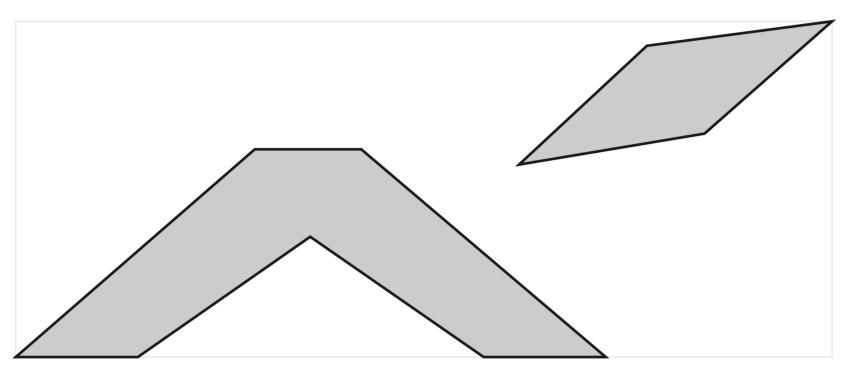


proposed fix



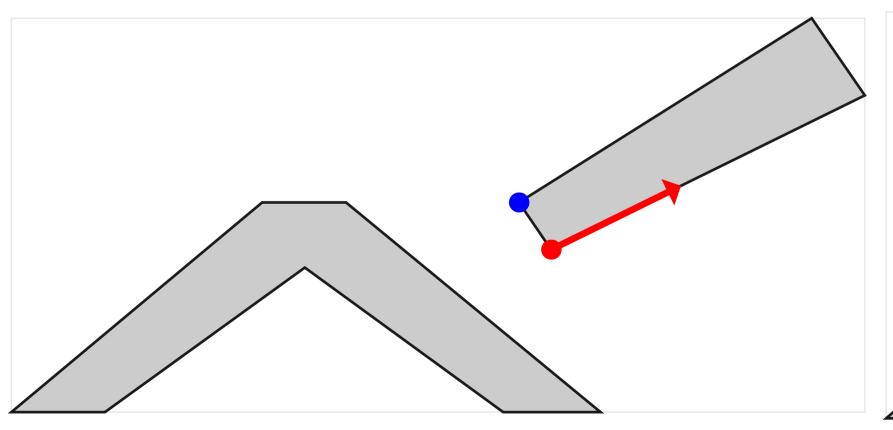
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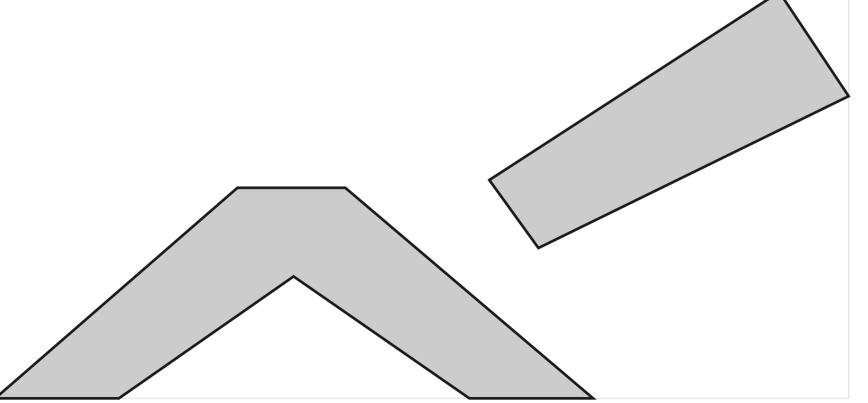




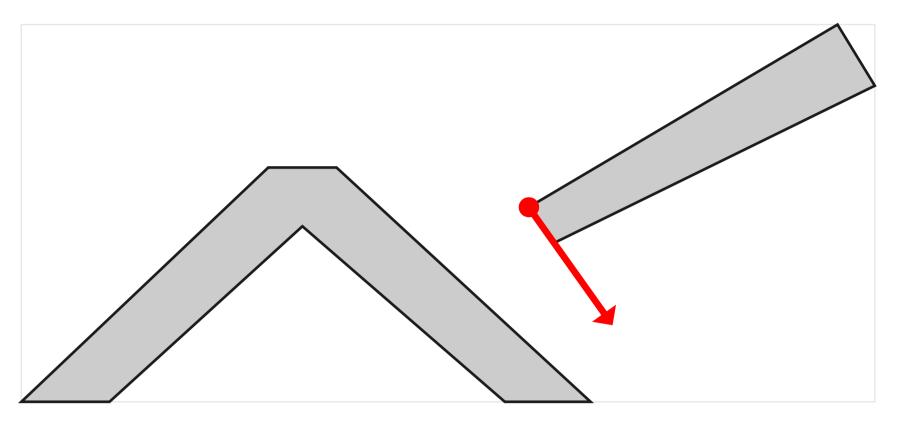
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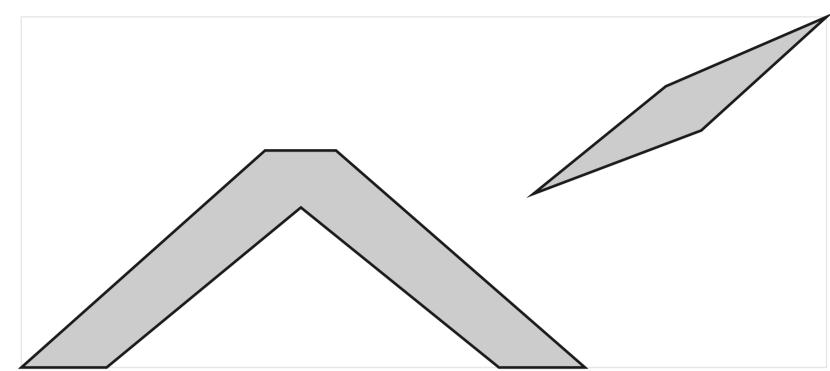
proposed fix





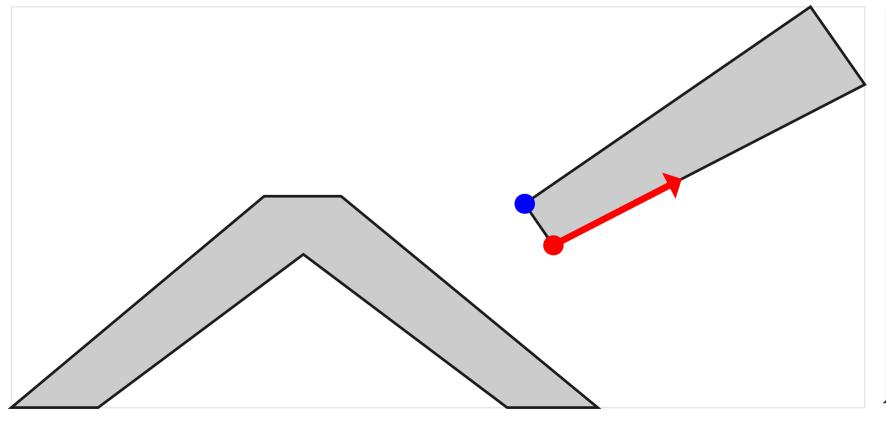
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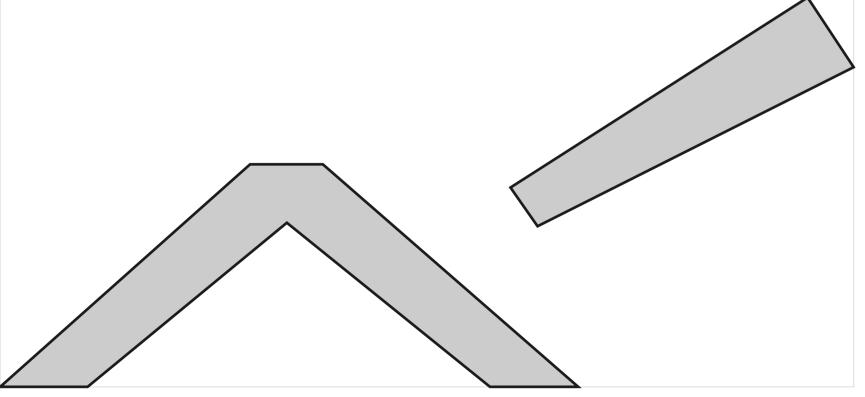




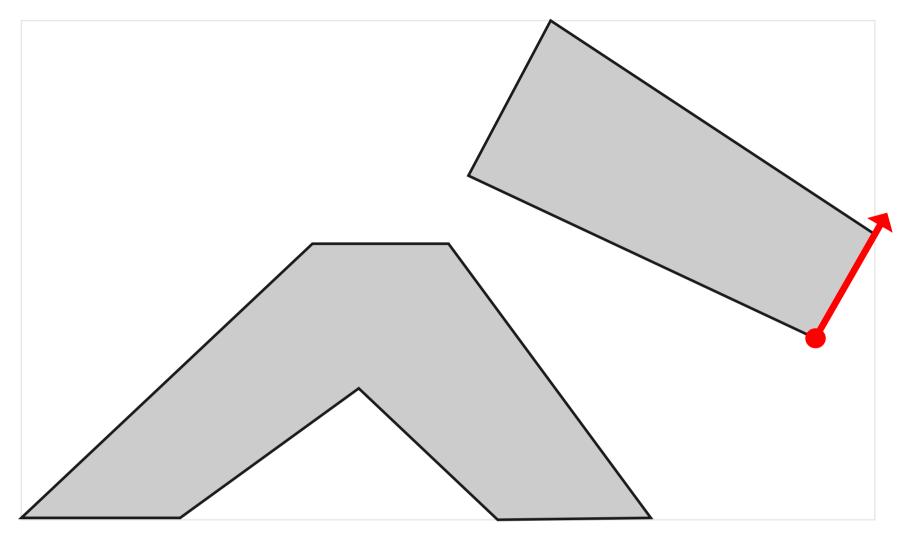
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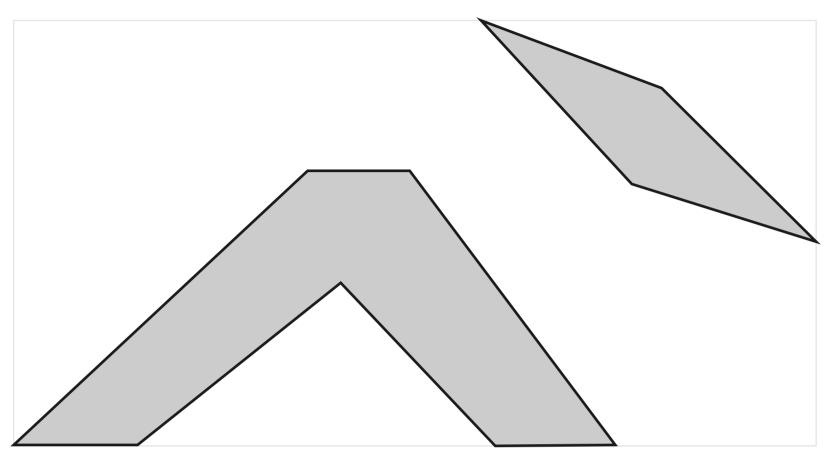
proposed fix





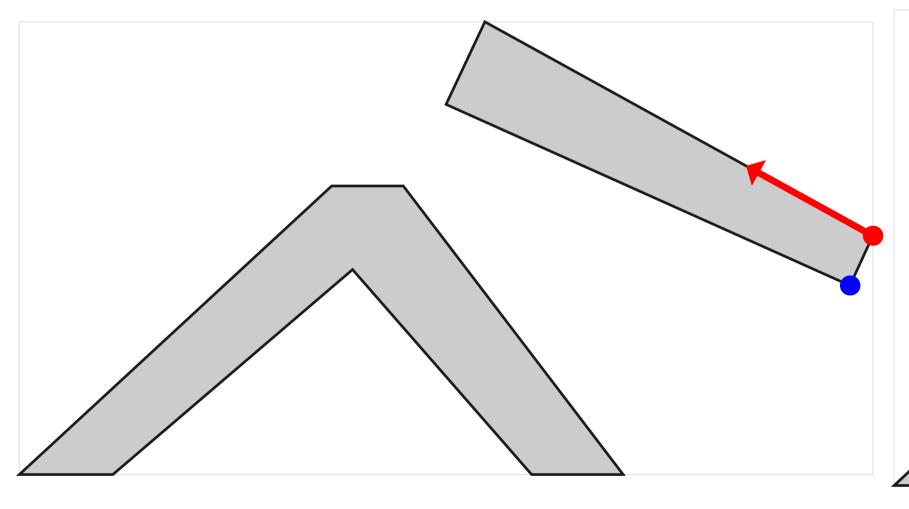
'sInt=-10.0 wdth=25.0'

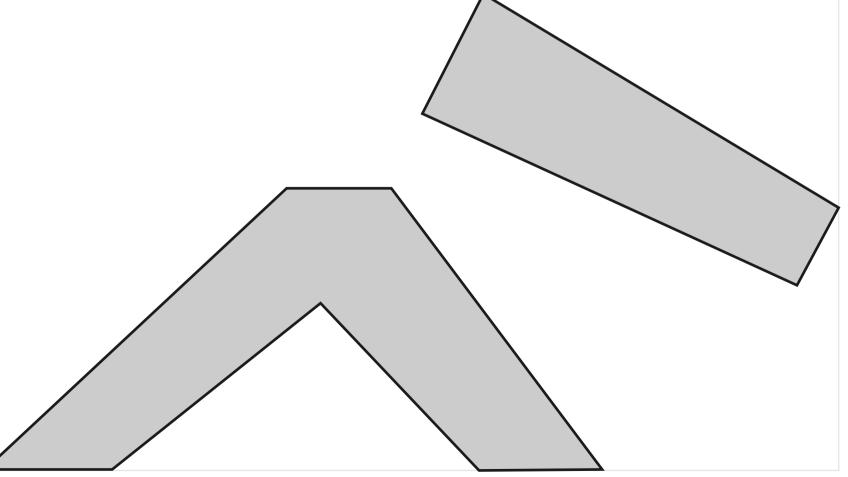




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proposed fix

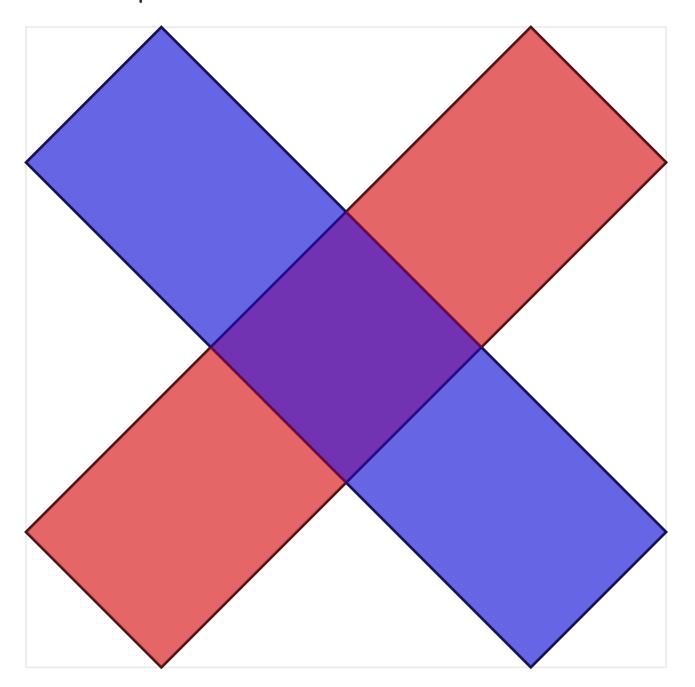




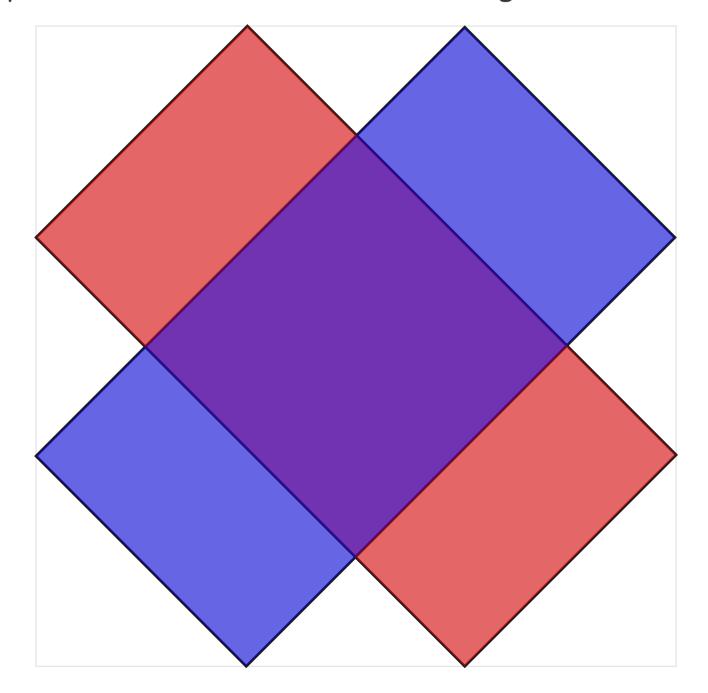


th-25 Ω'

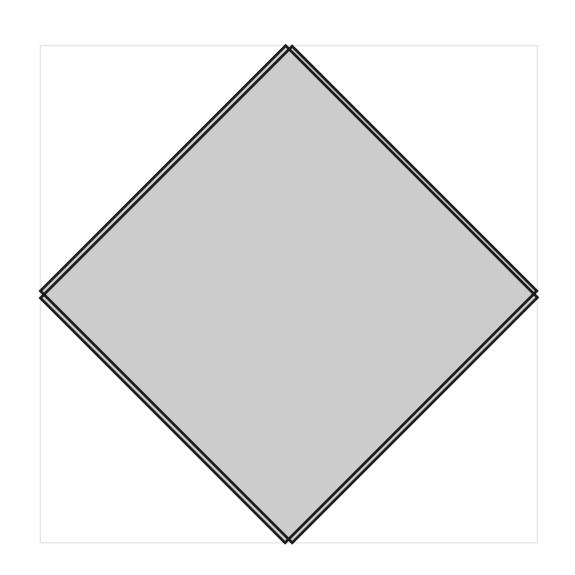
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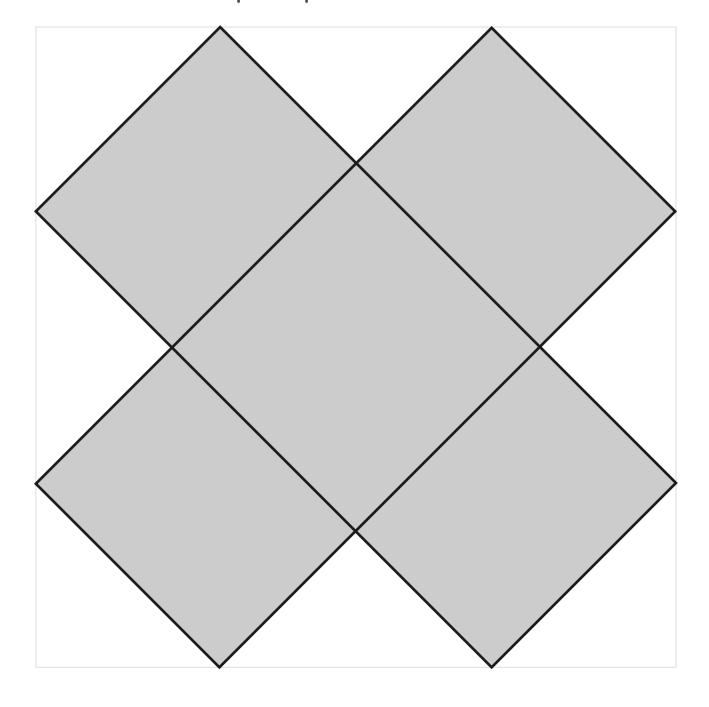
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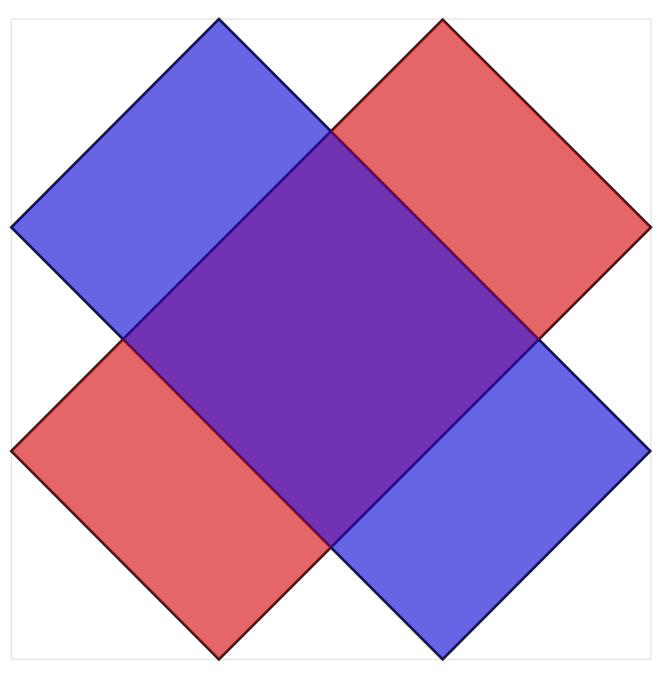
midway interpolation



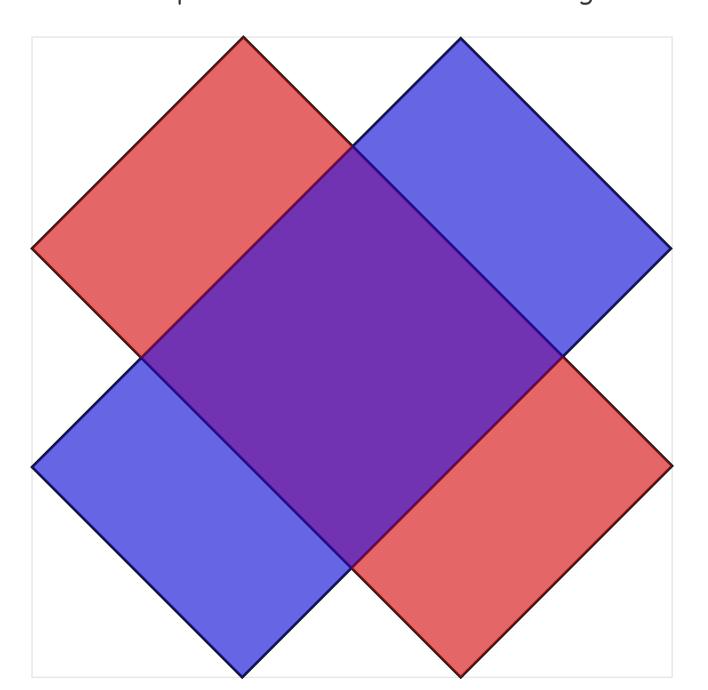
proposed fix

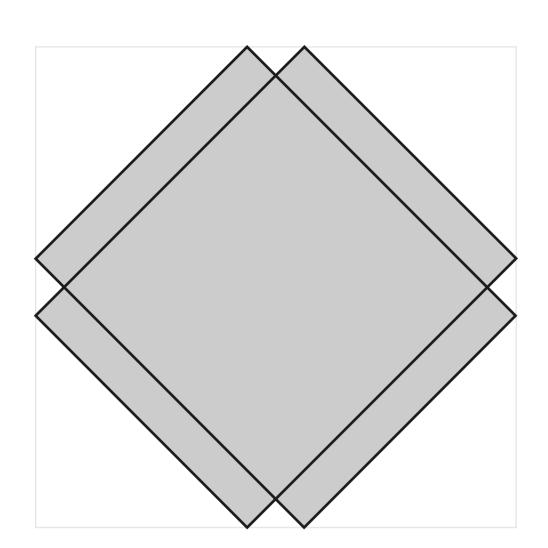


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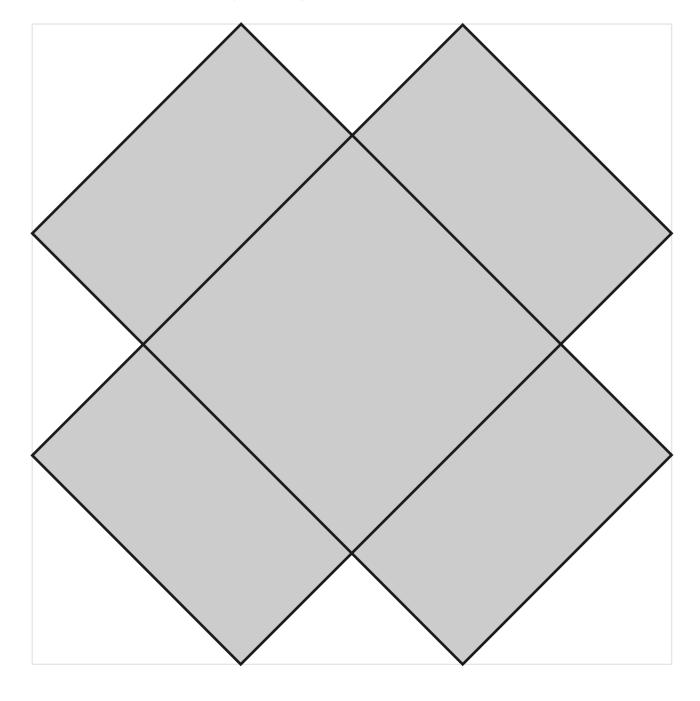


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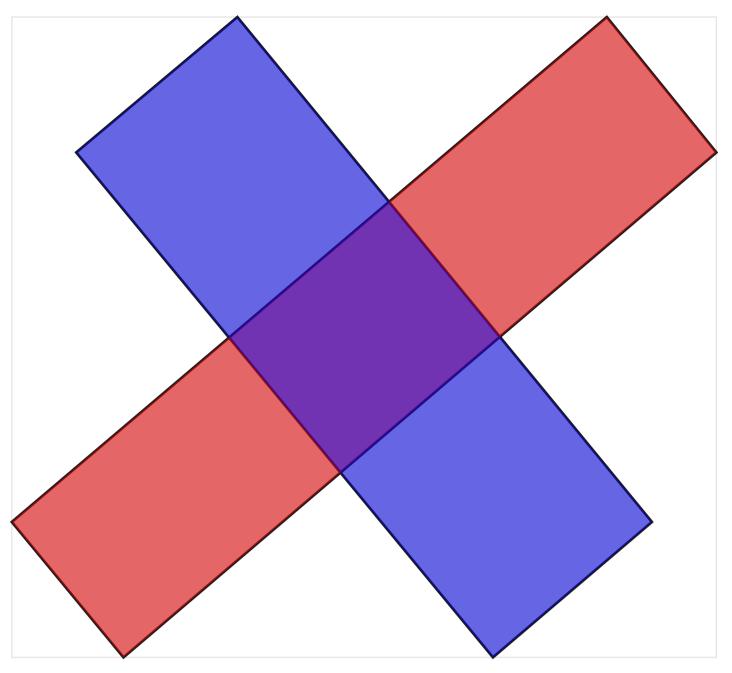




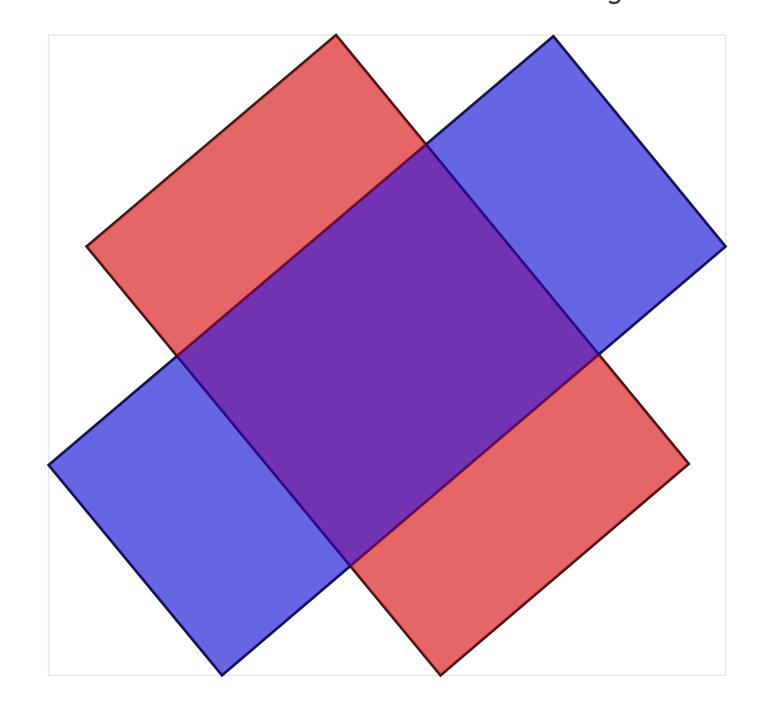
proposed fix



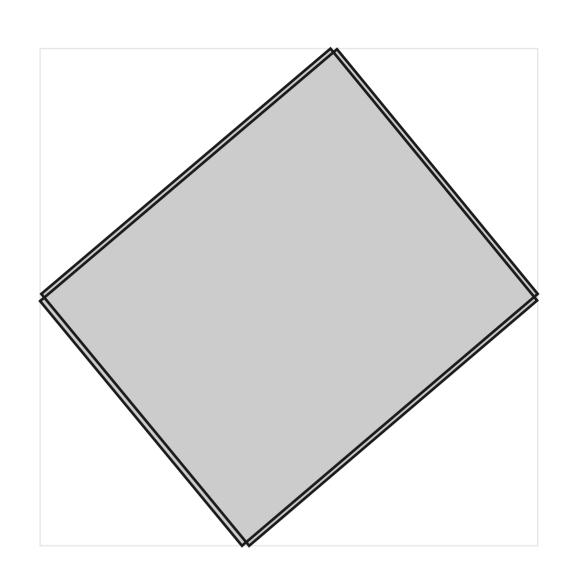
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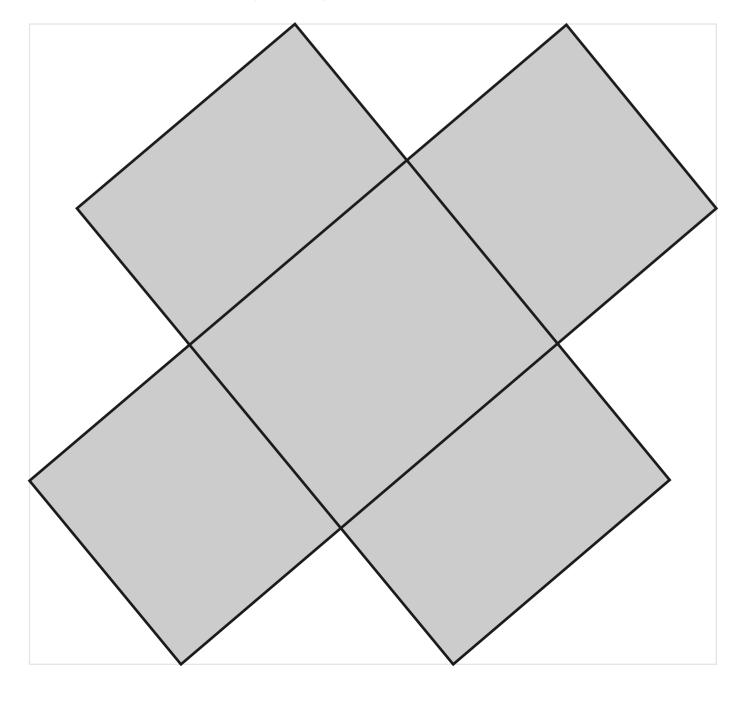
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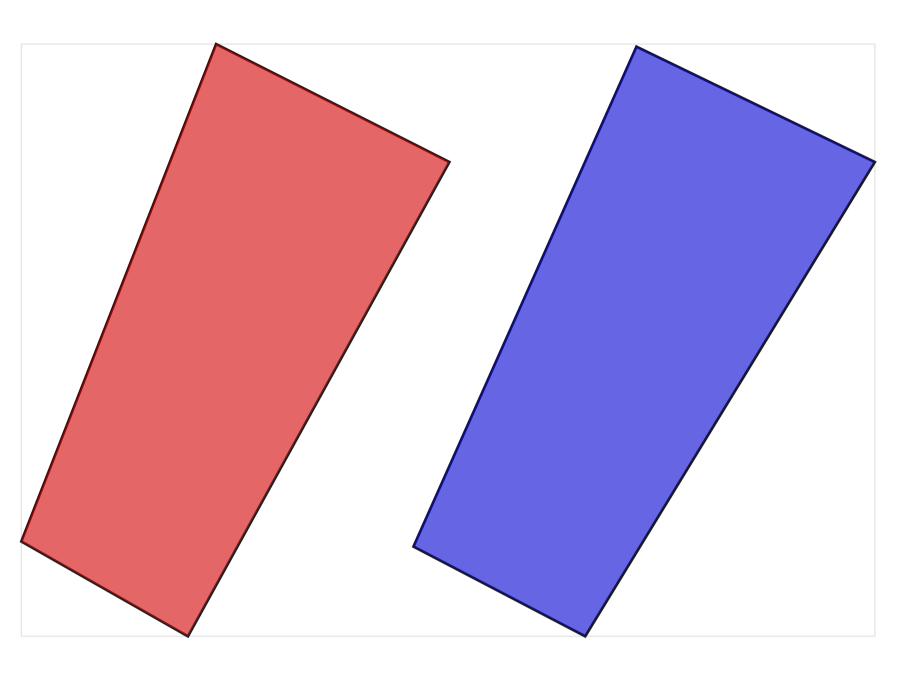
midway interpolation



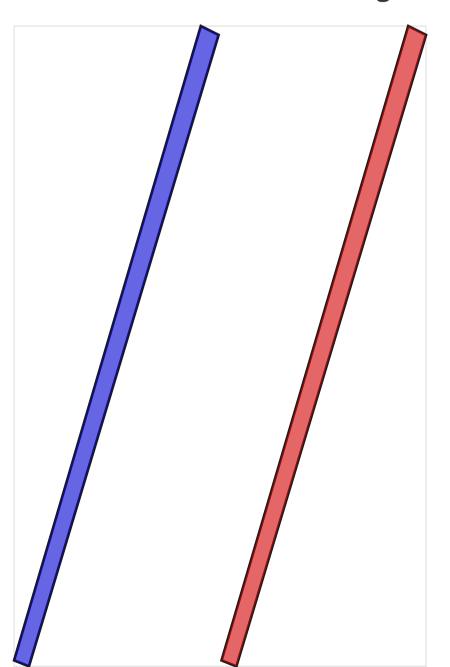
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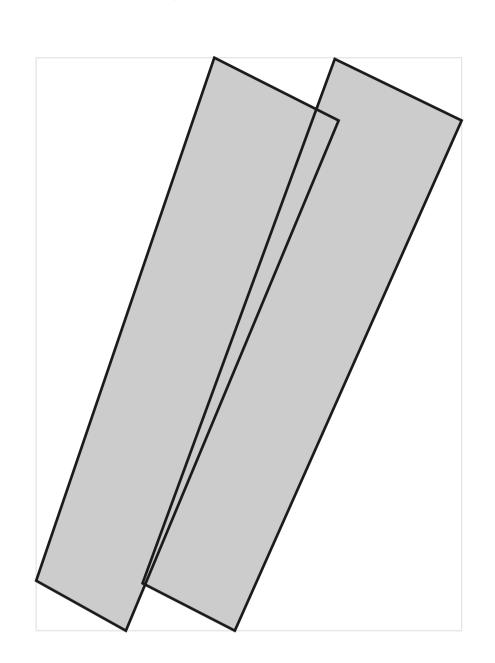


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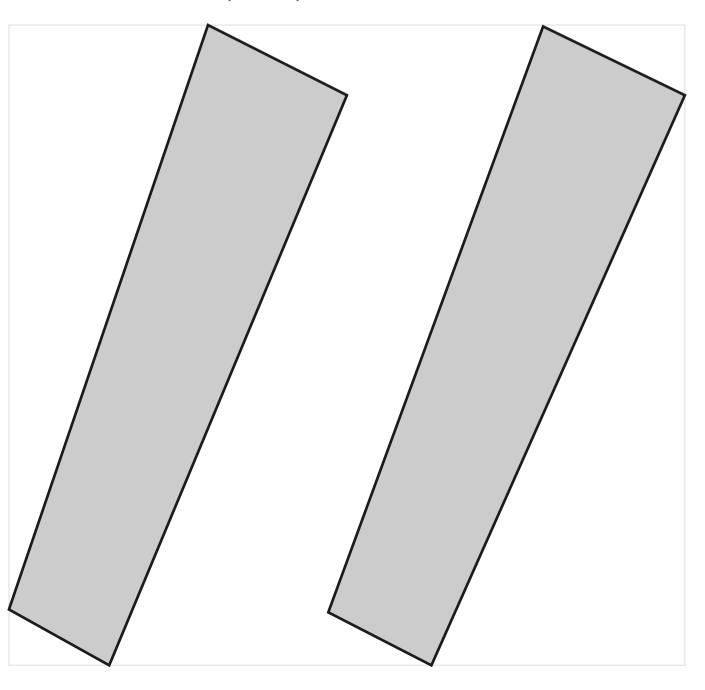


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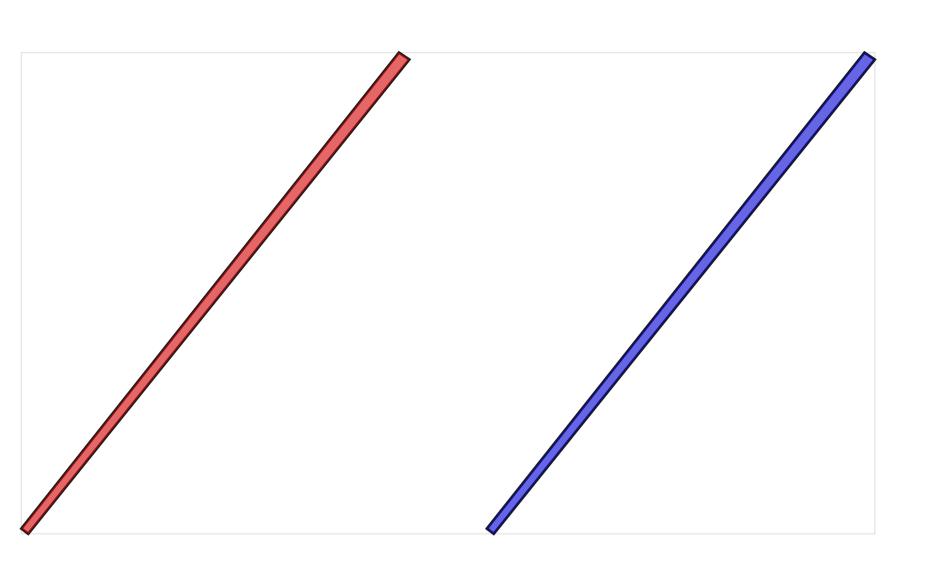


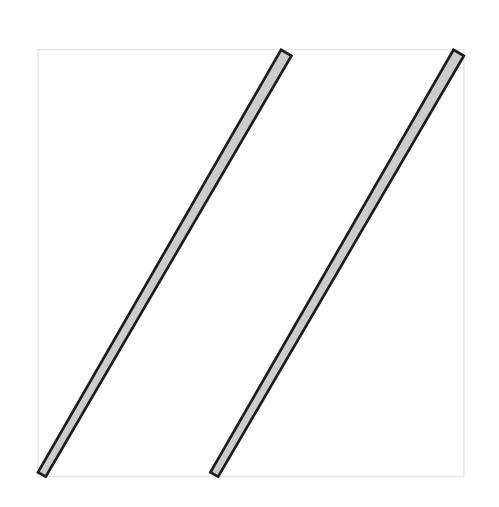


proposed fix

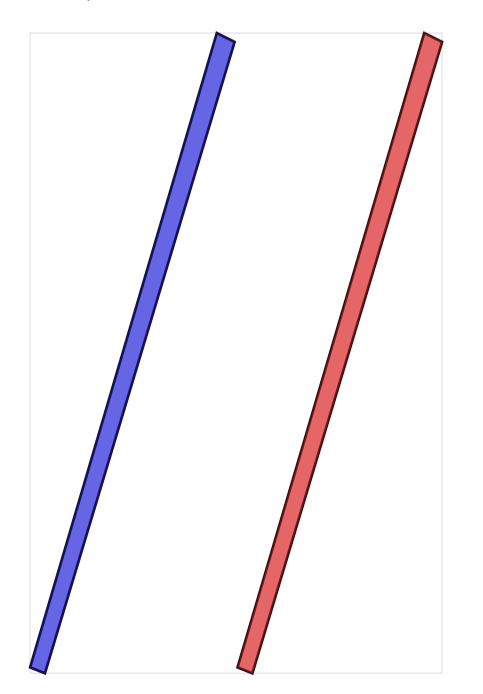


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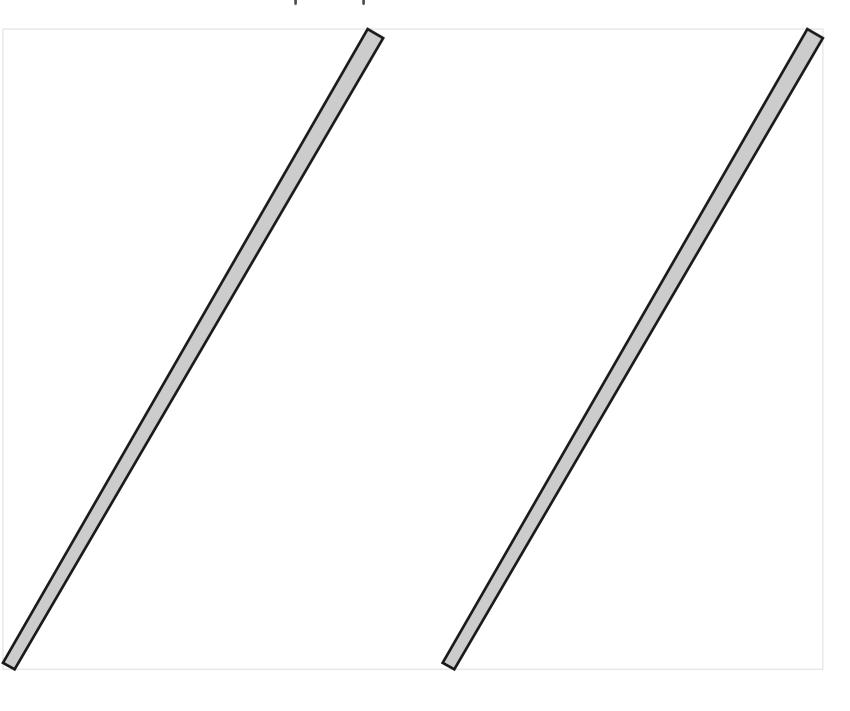




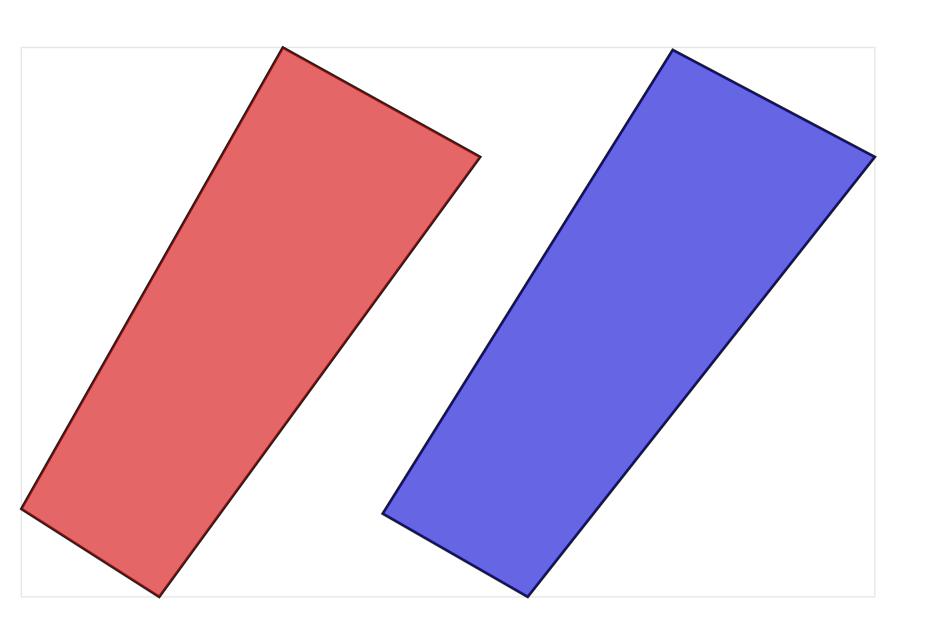
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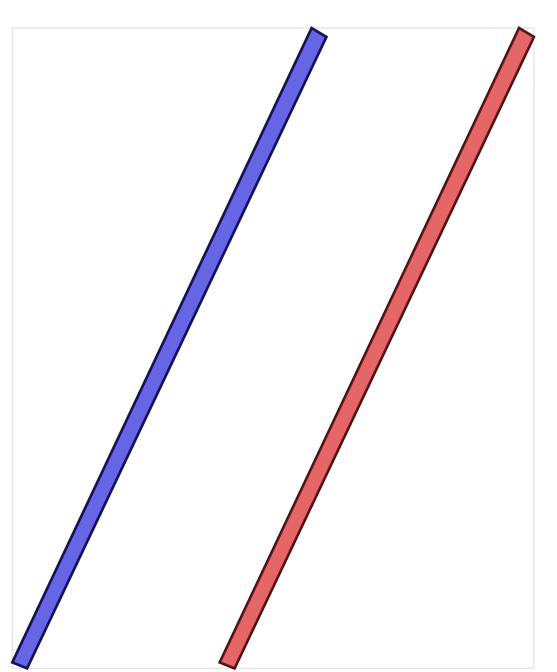
proposed fix

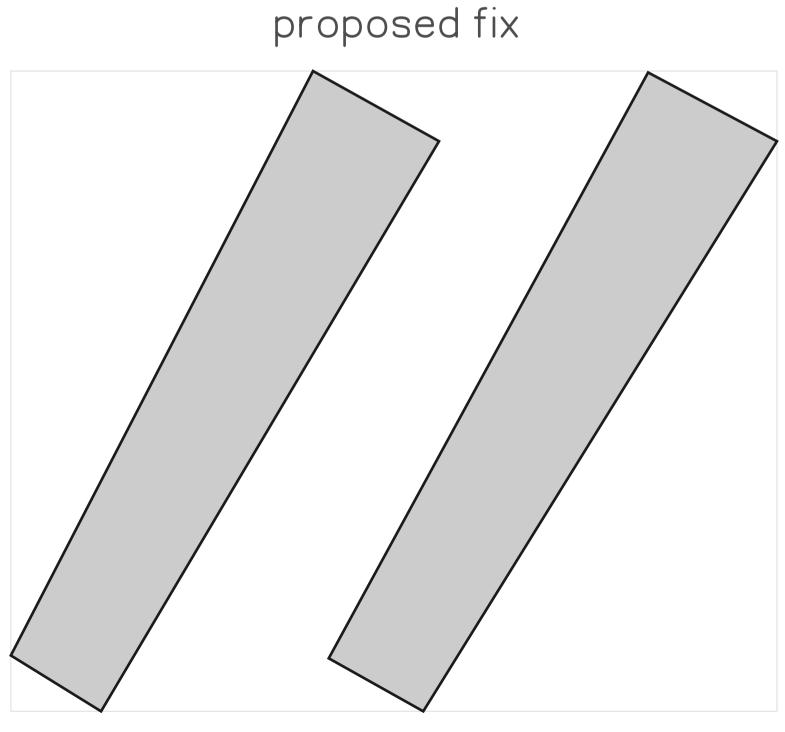


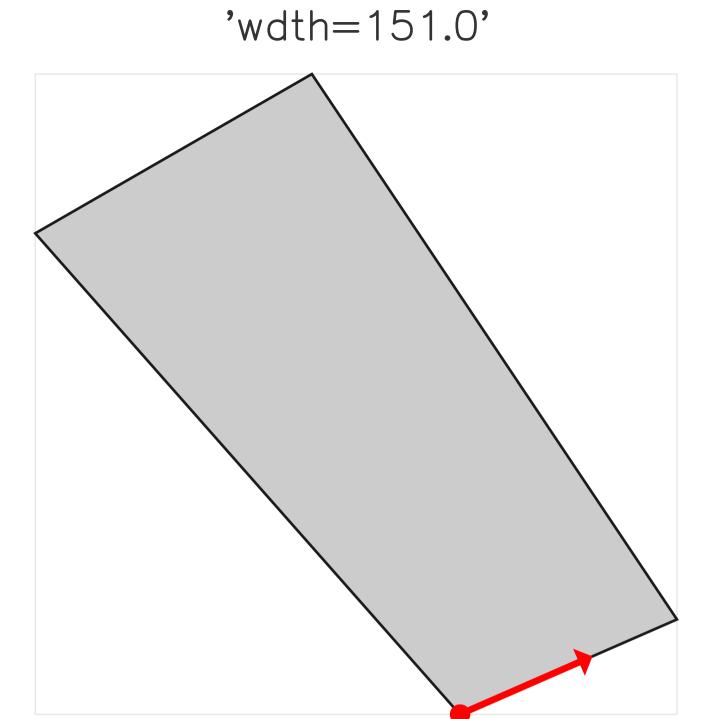
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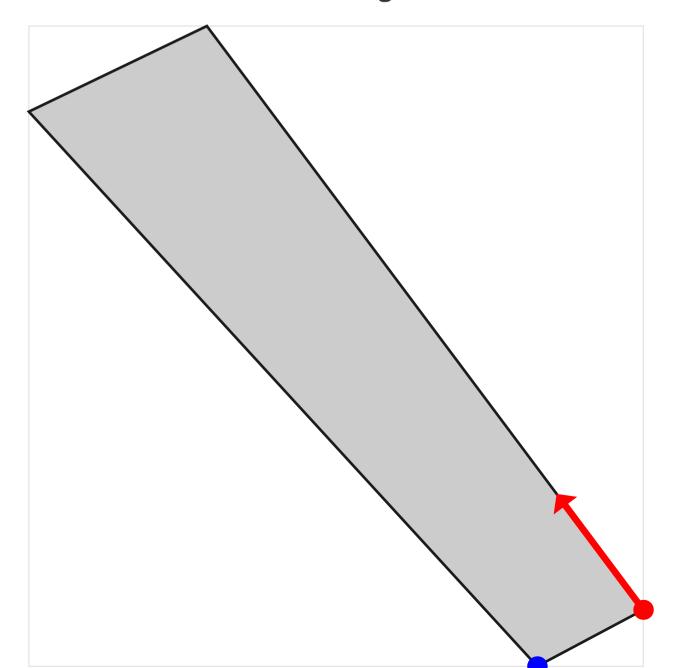
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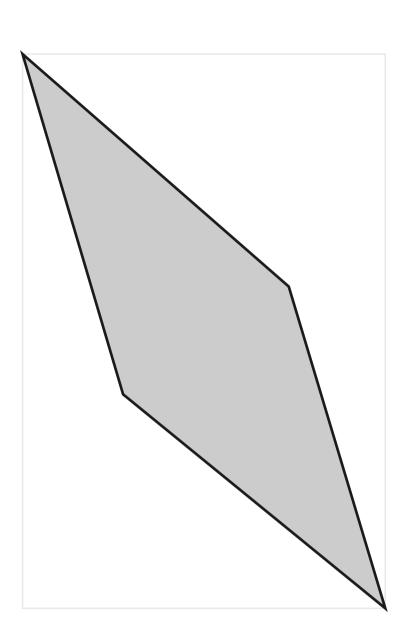




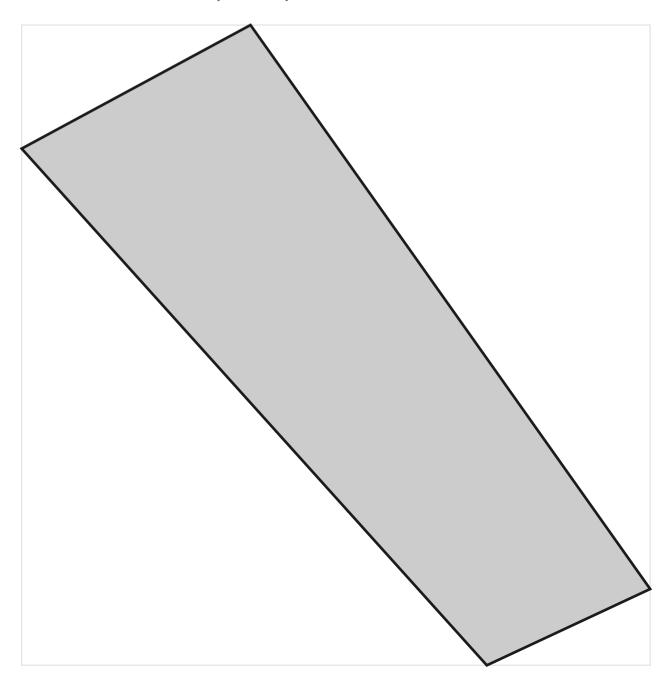


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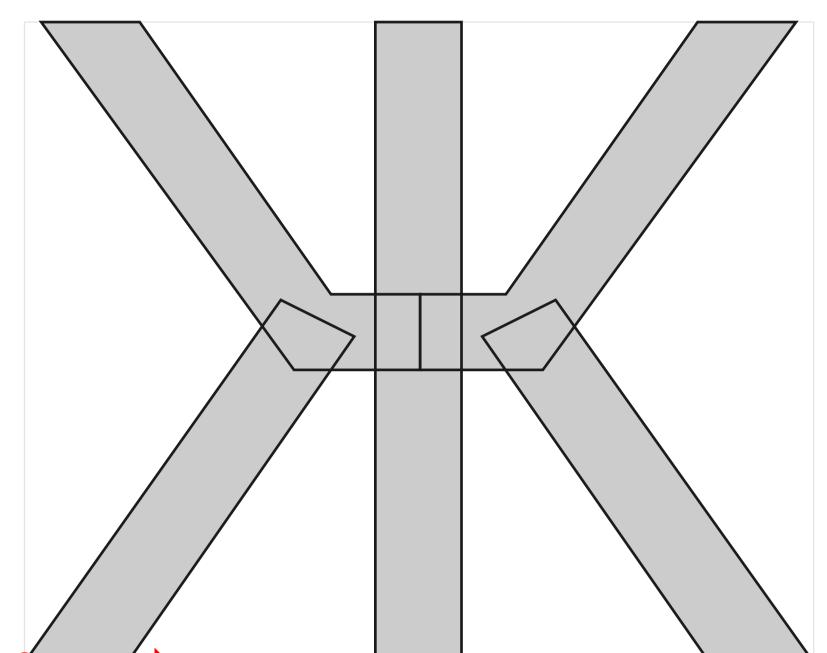




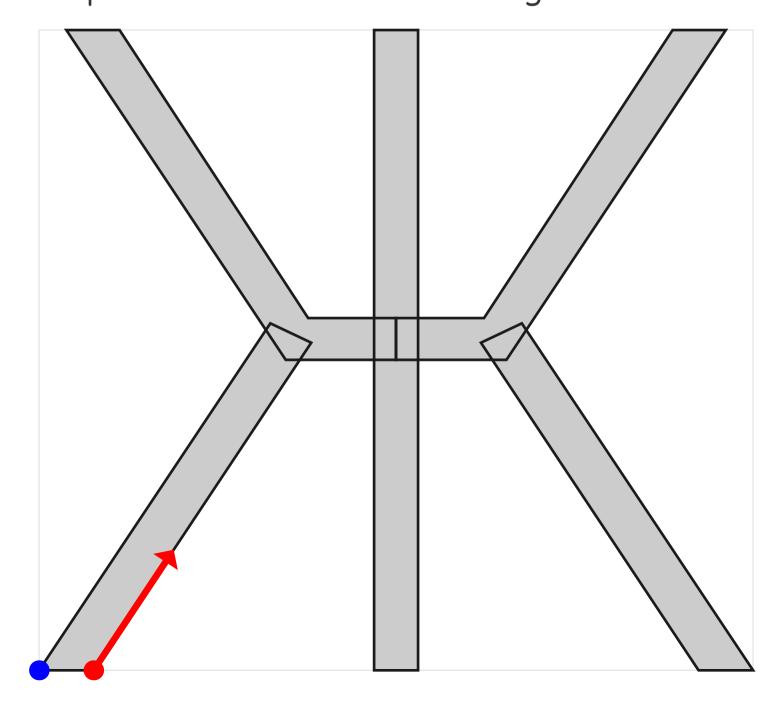
proposed fix



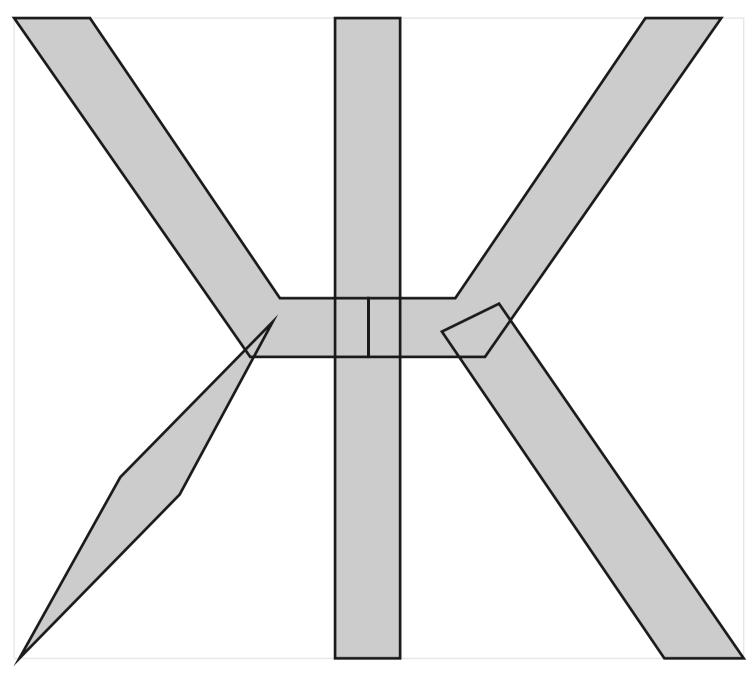
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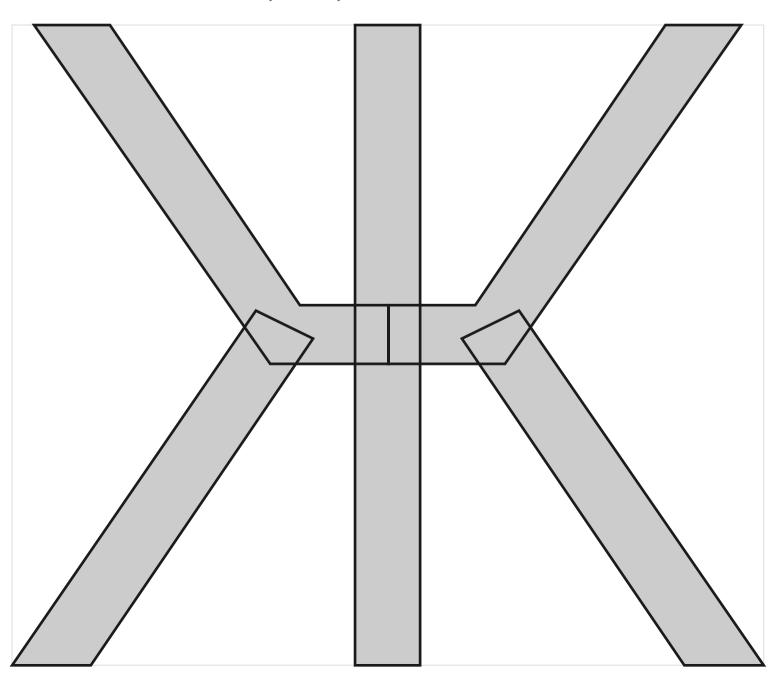
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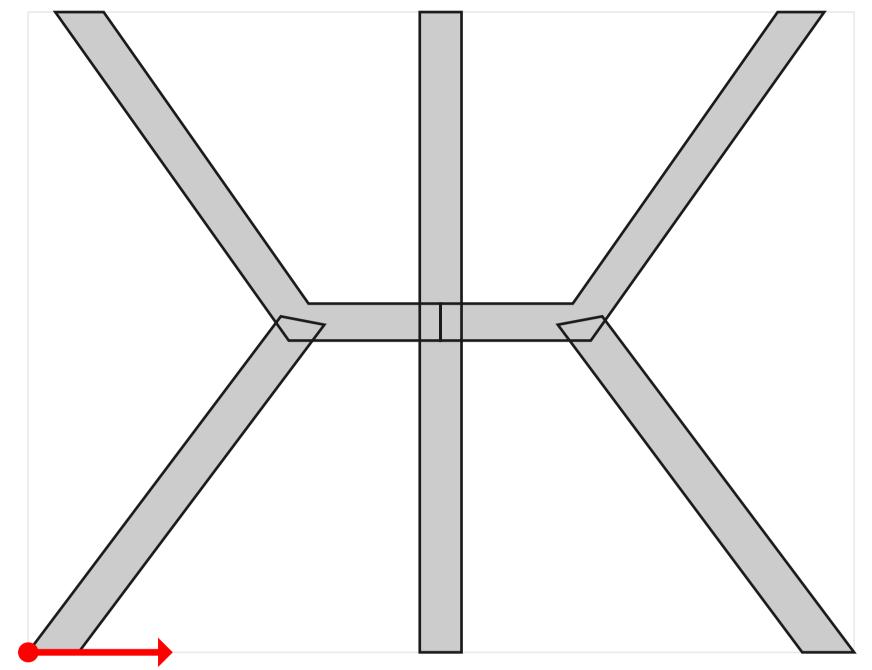
midway interpolation



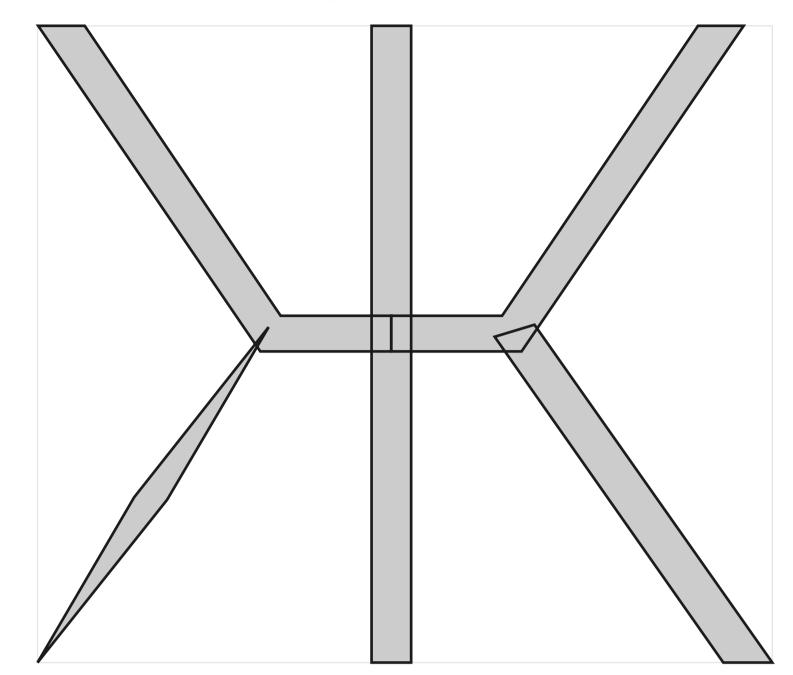
proposed fix



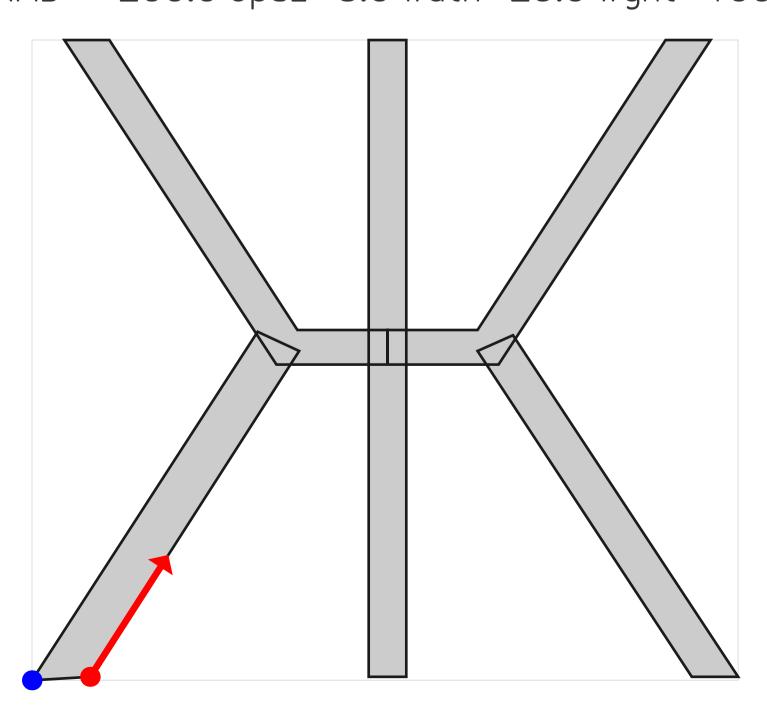
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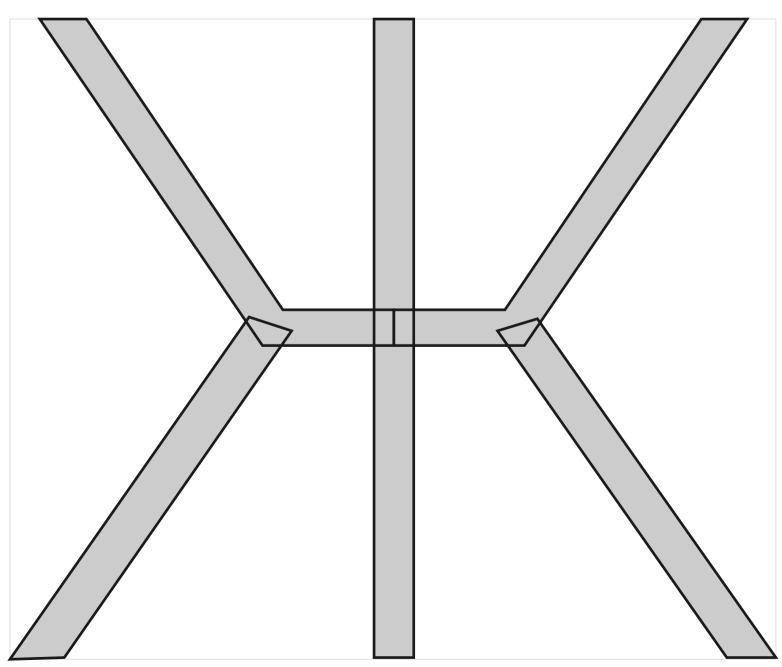


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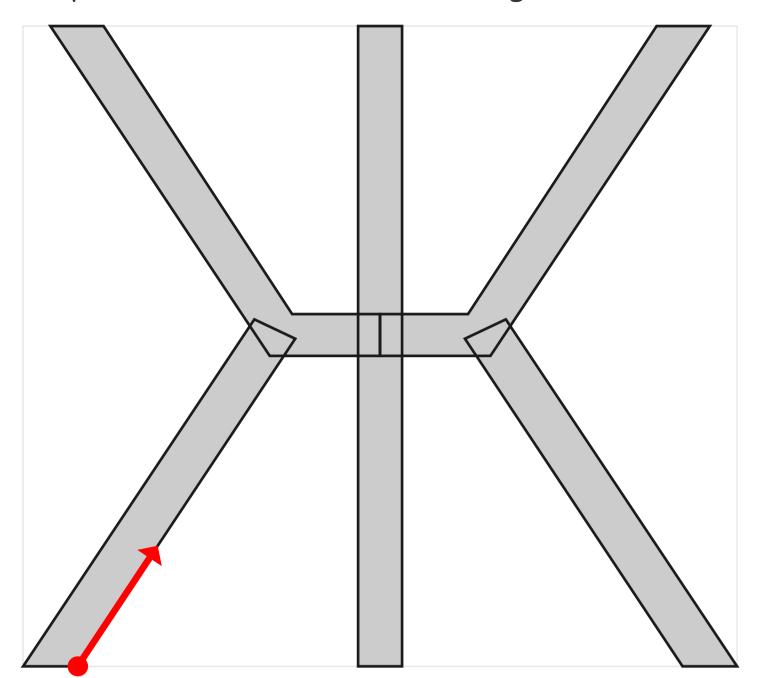


proposed fix

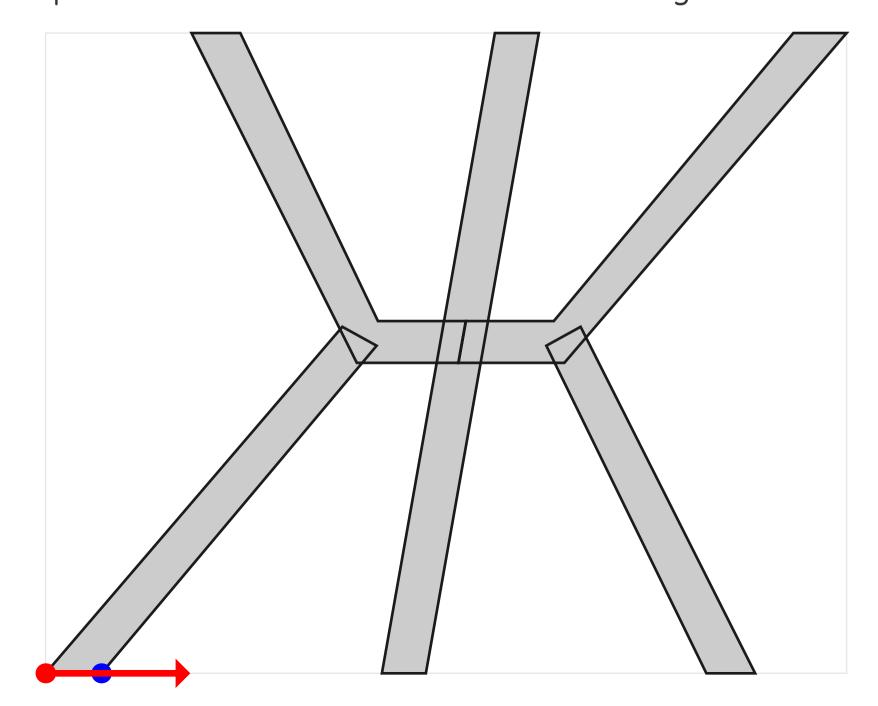




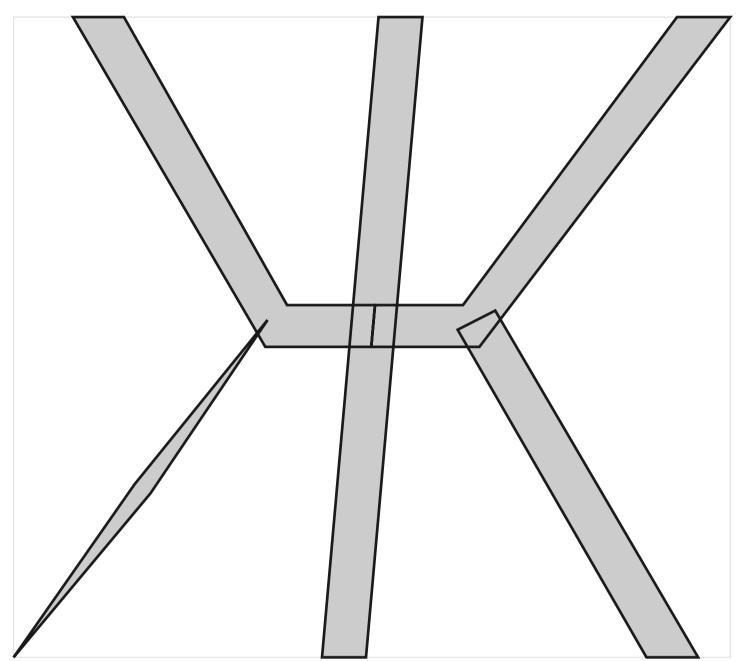
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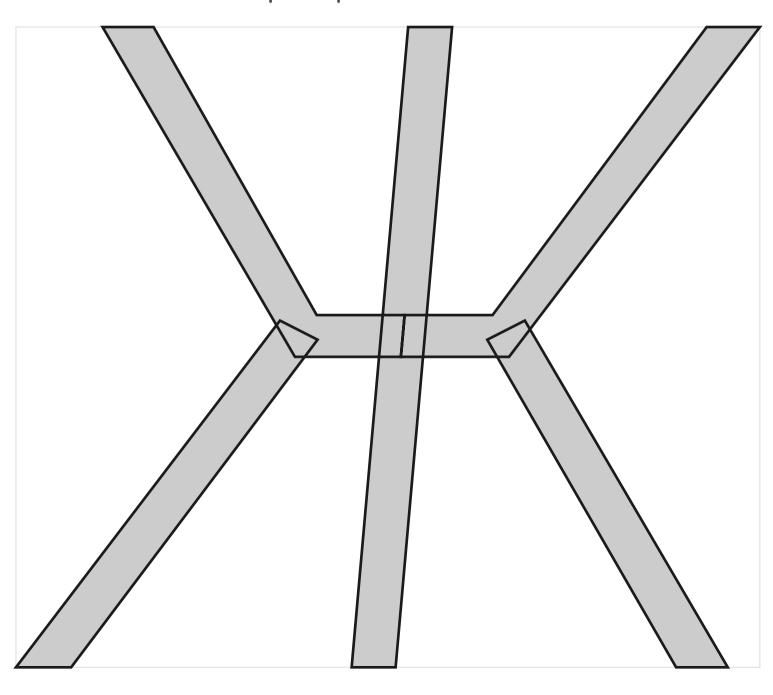
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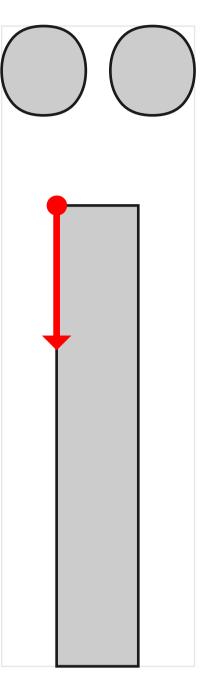
midway interpolation



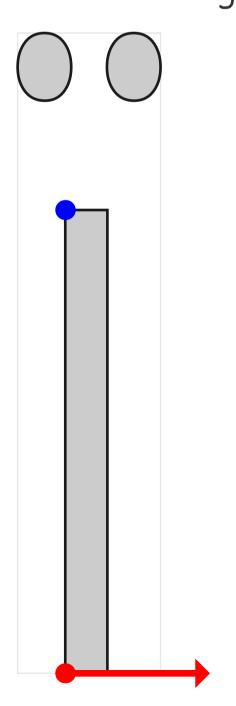
proposed fix



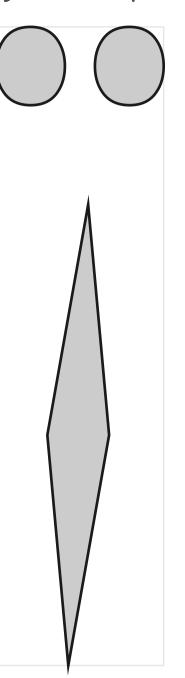
'opsz=8.0 wdth=25.0'



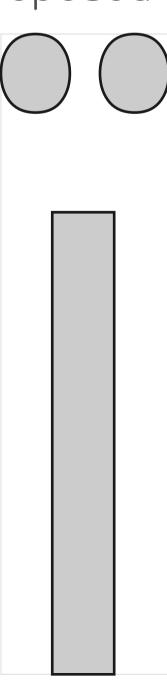
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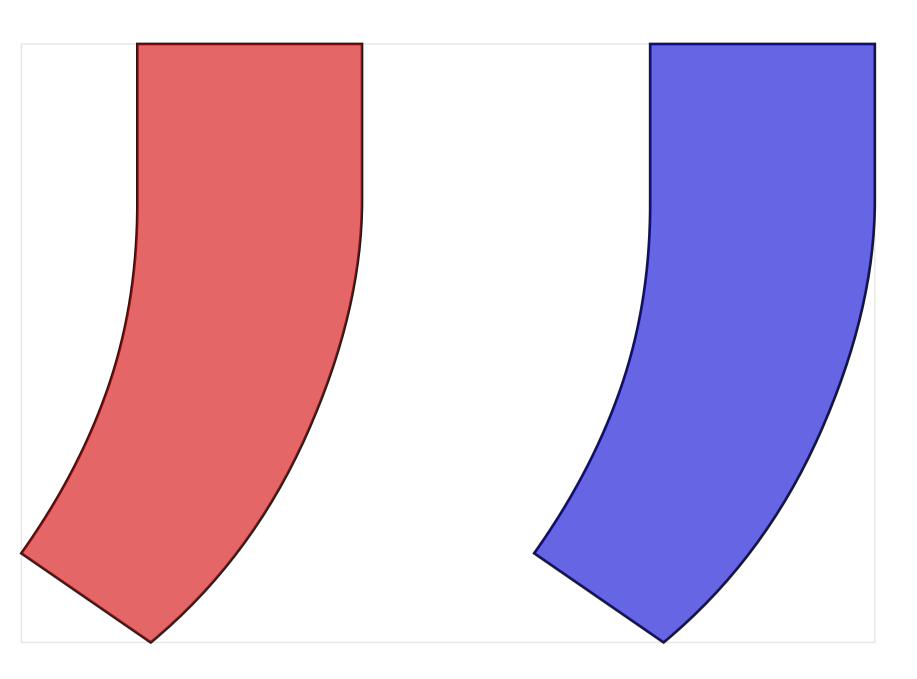
midway interpolation

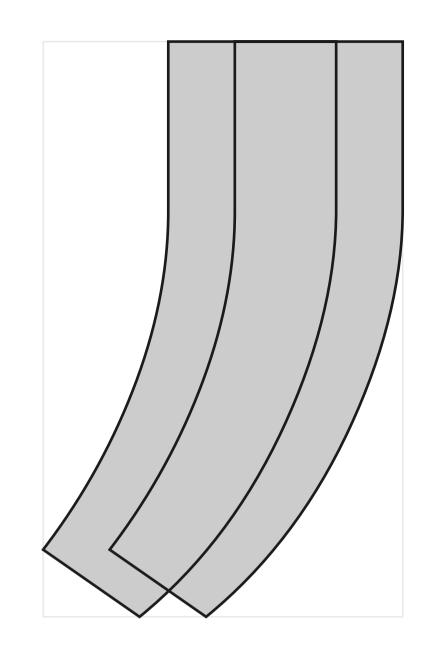


proposed fix



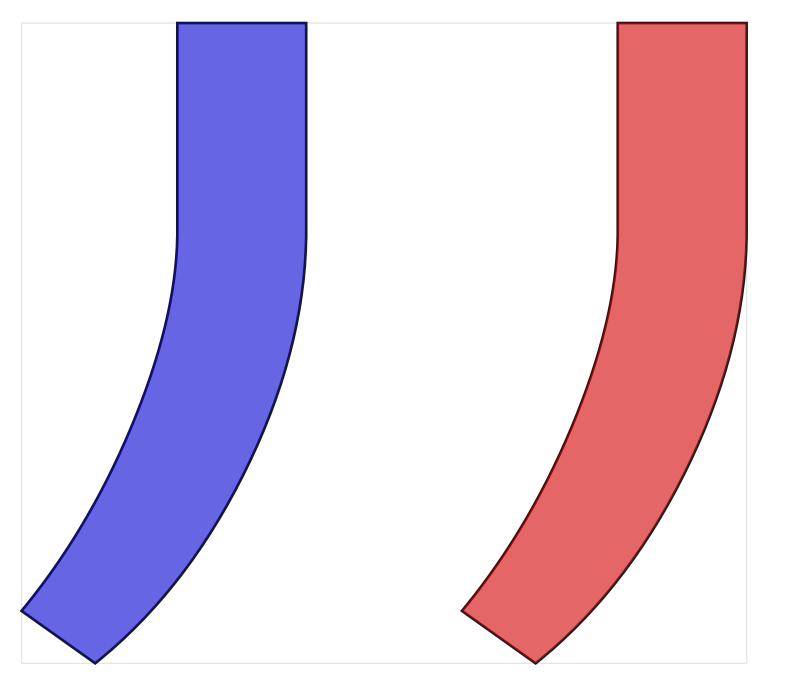
'opsz=8.0 wdth=25.0'

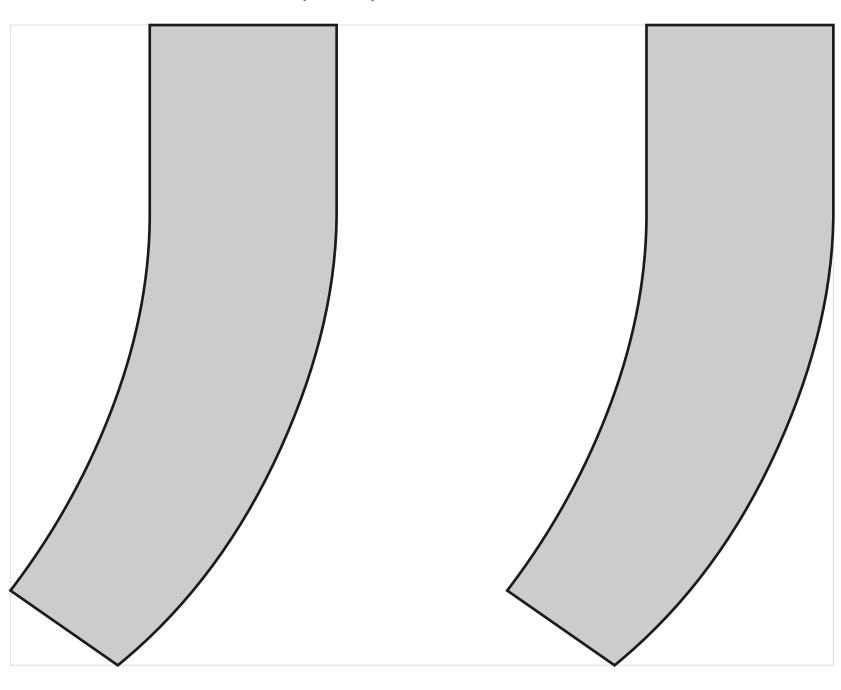




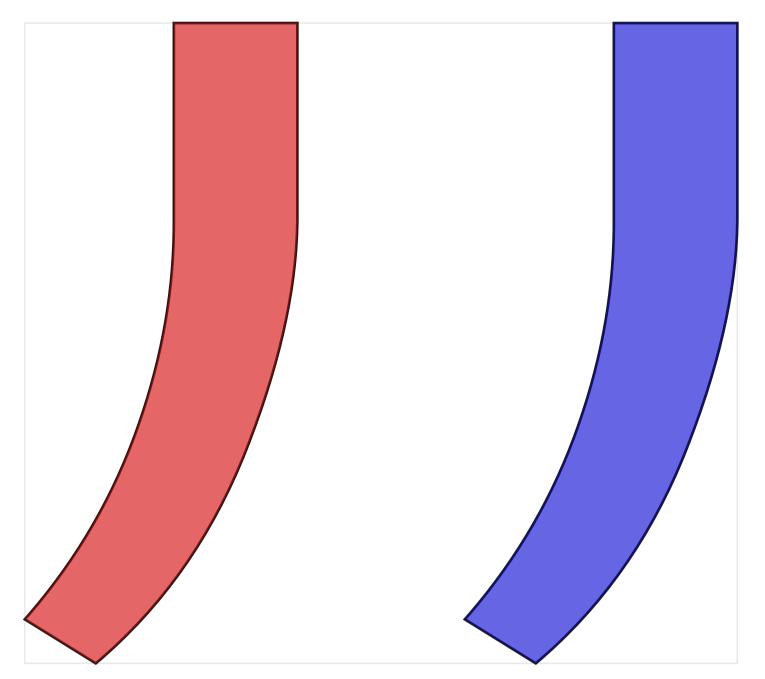
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proposed fix

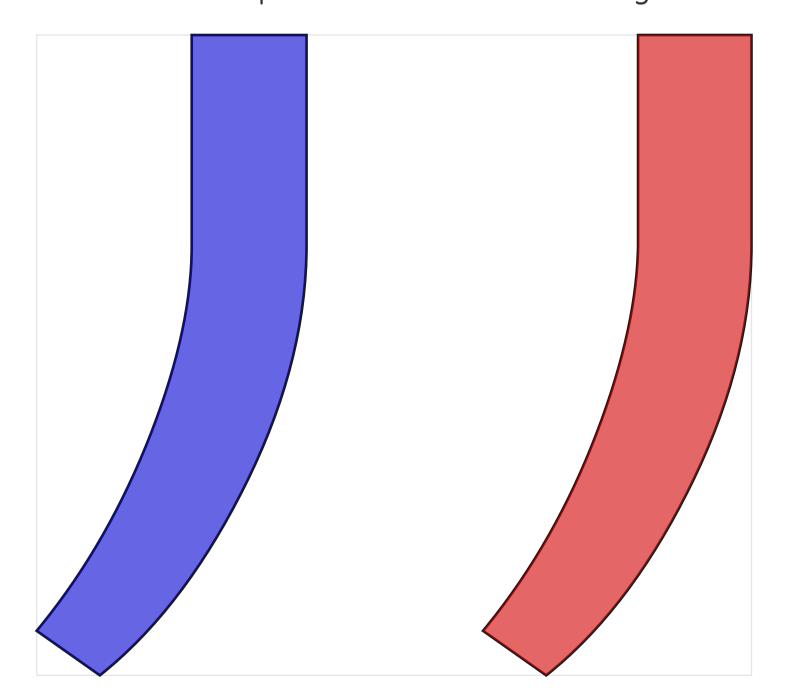




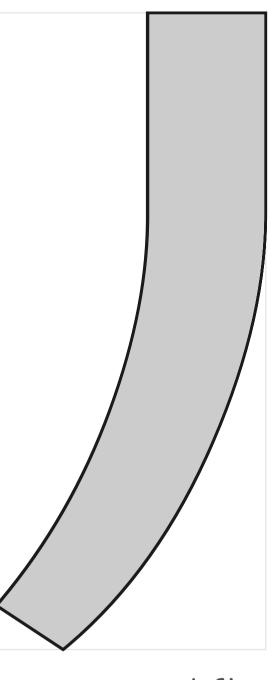
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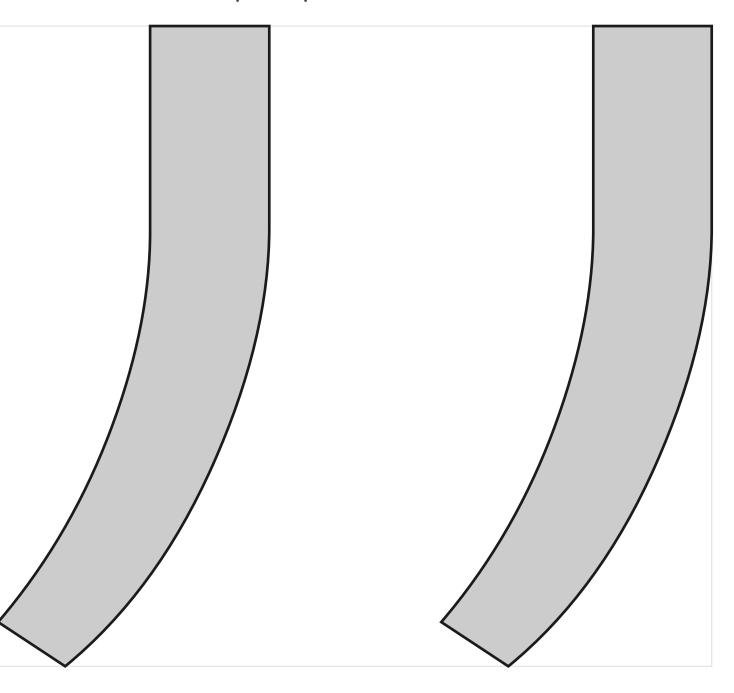
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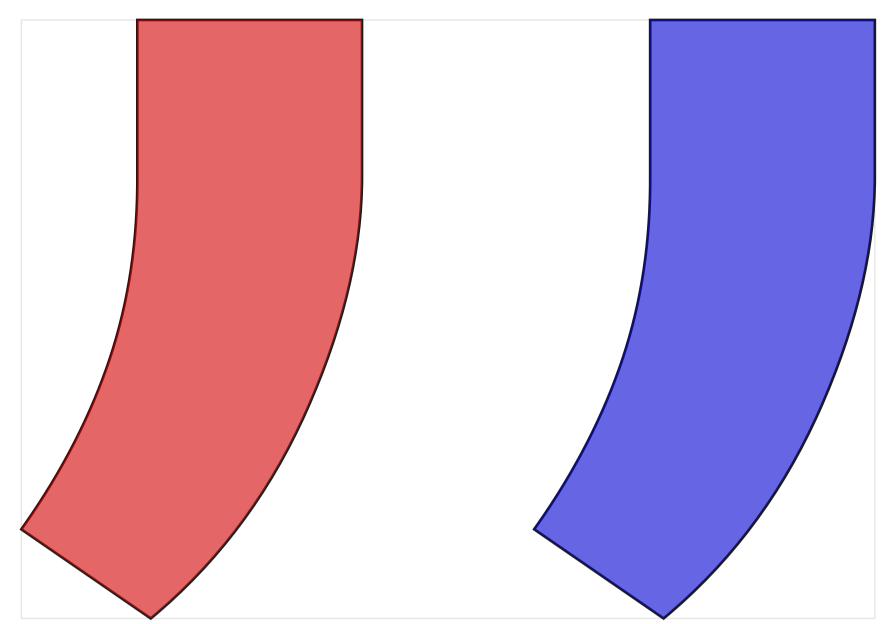
midway interpolation

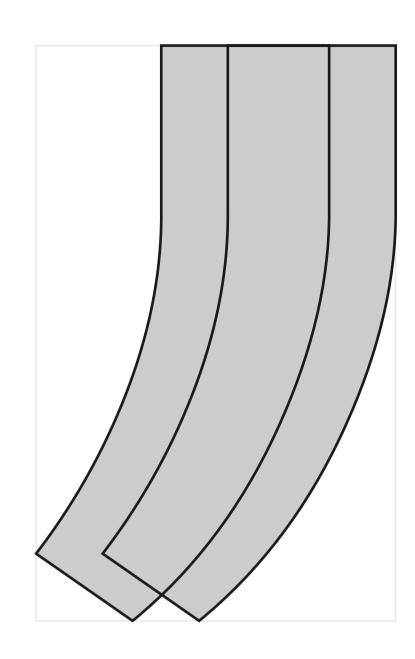


proposed fix



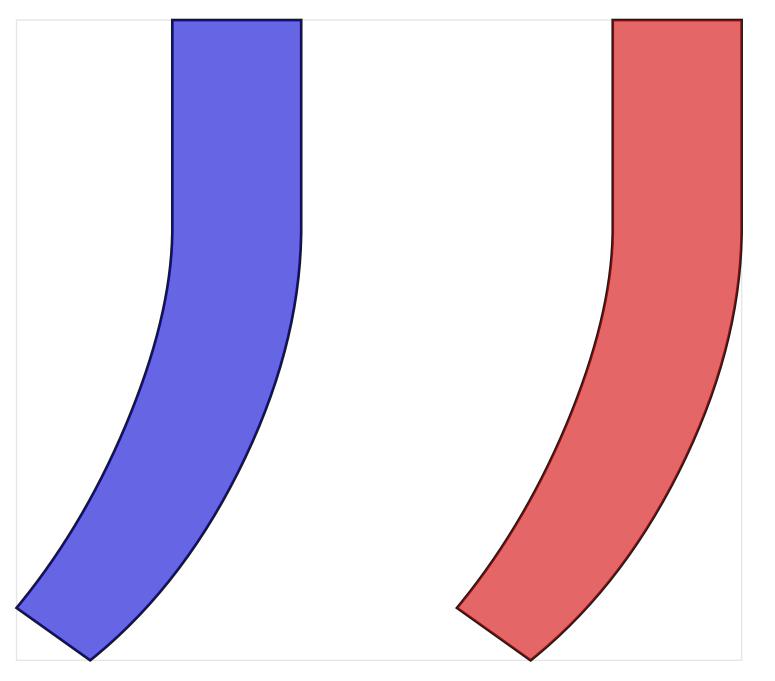
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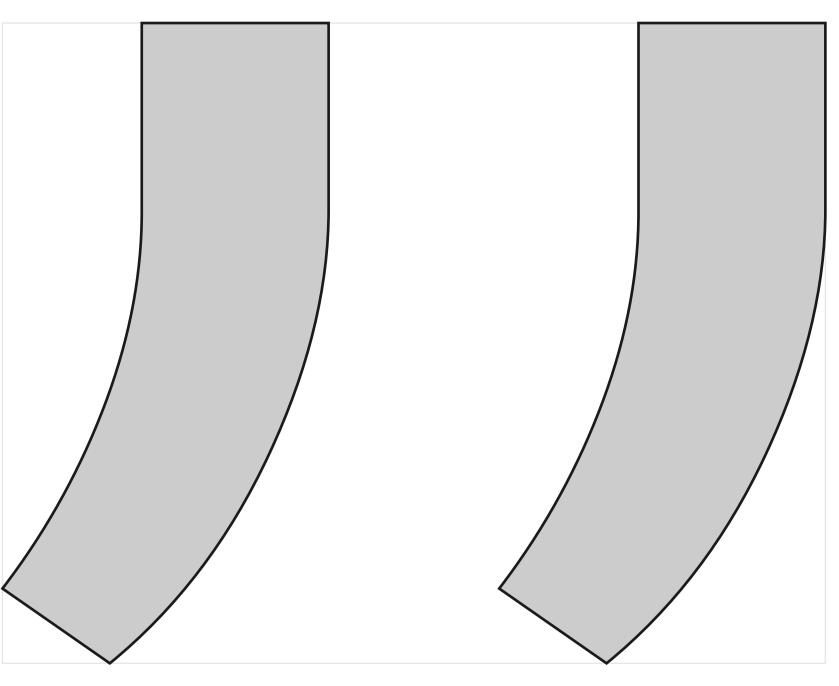




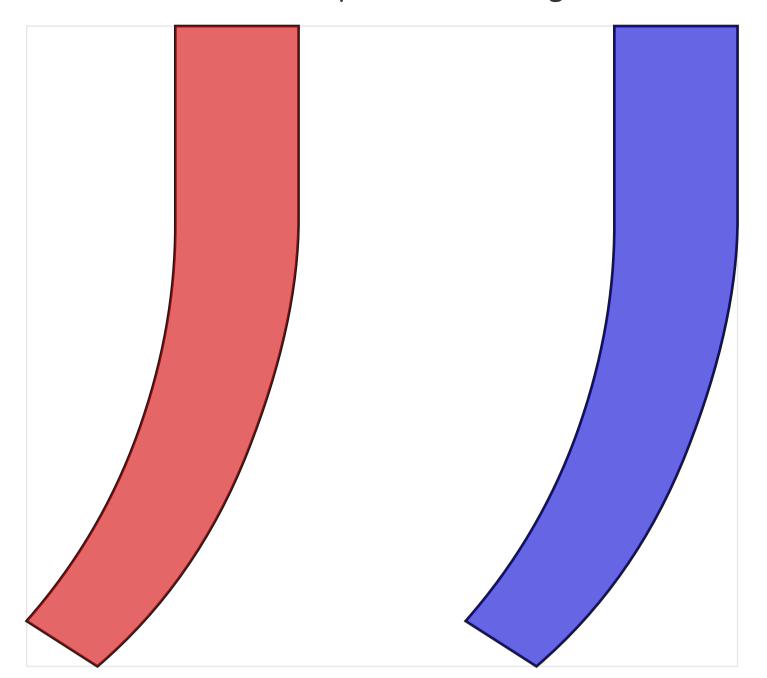
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proposed fix

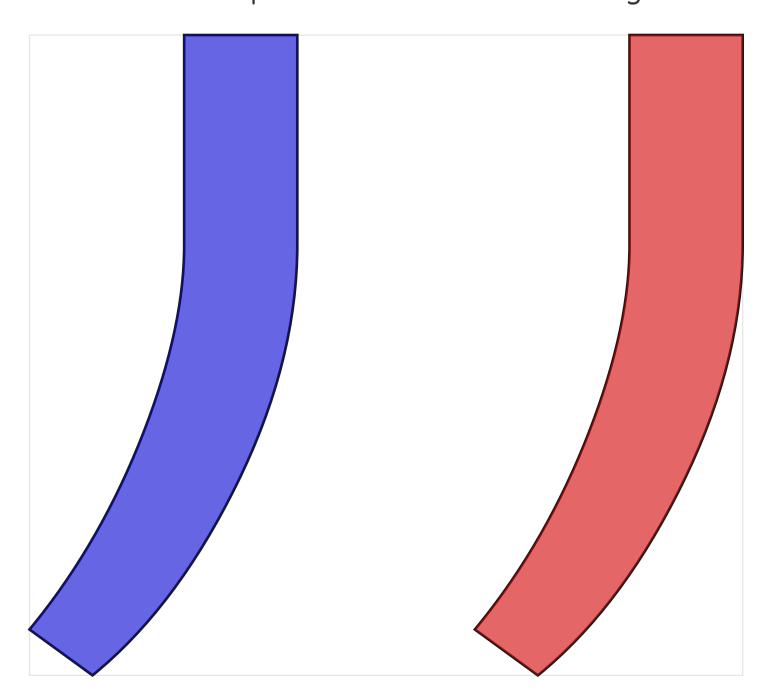




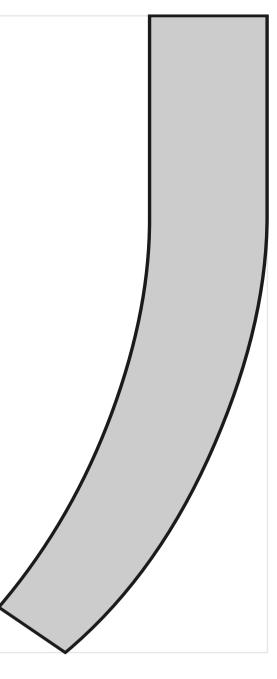
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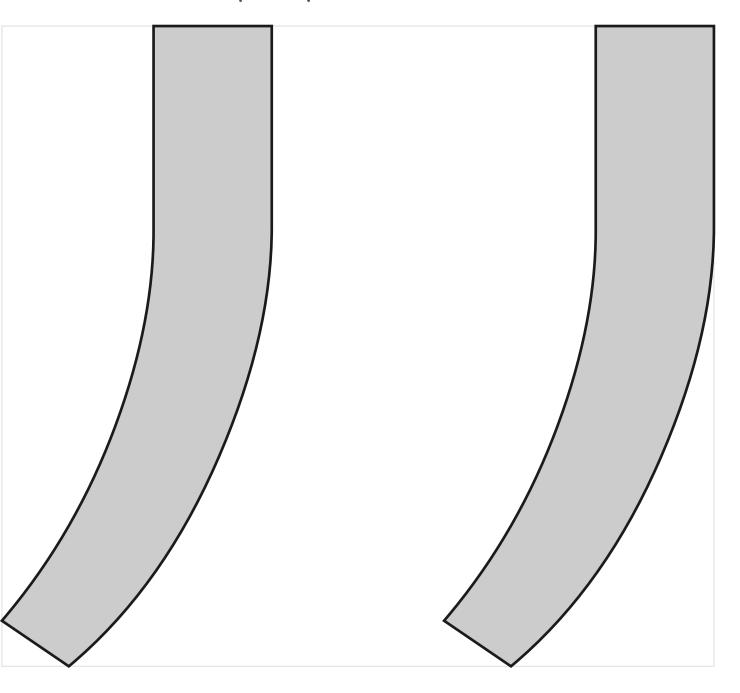
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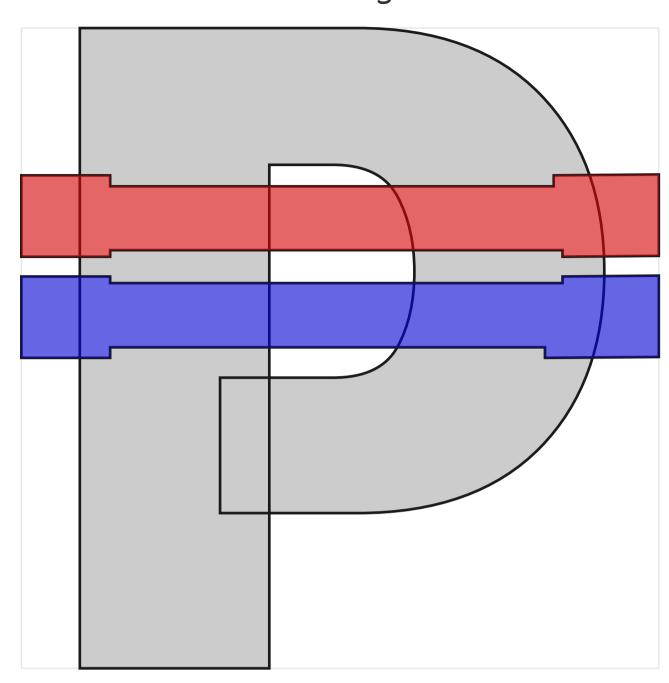
midway interpolation



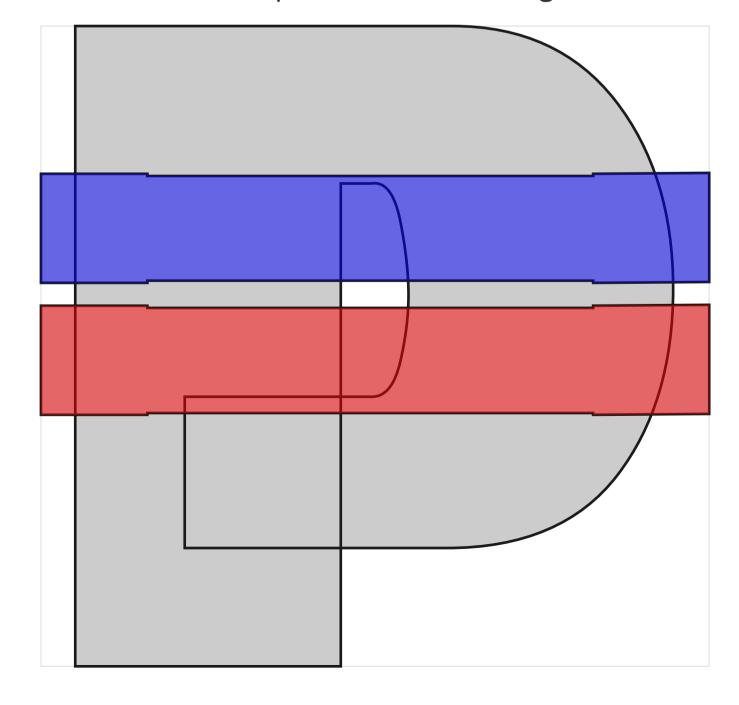
proposed fix



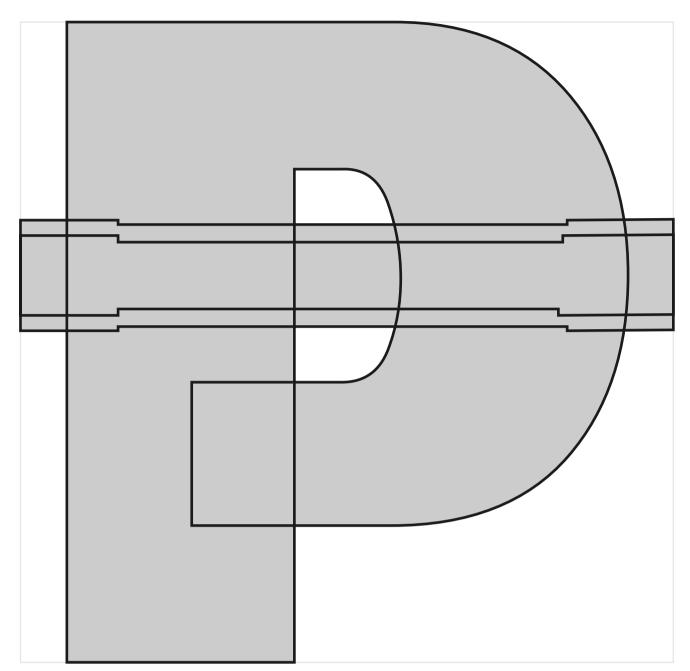
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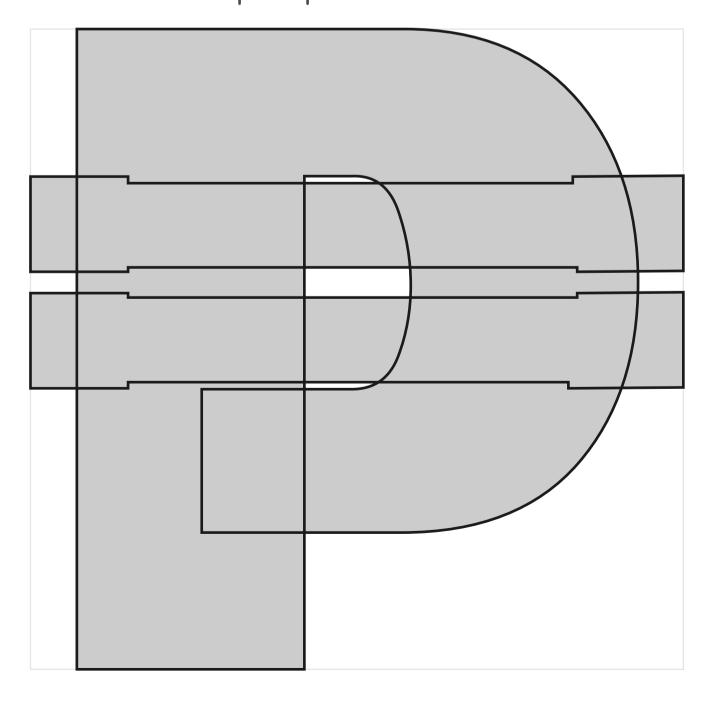
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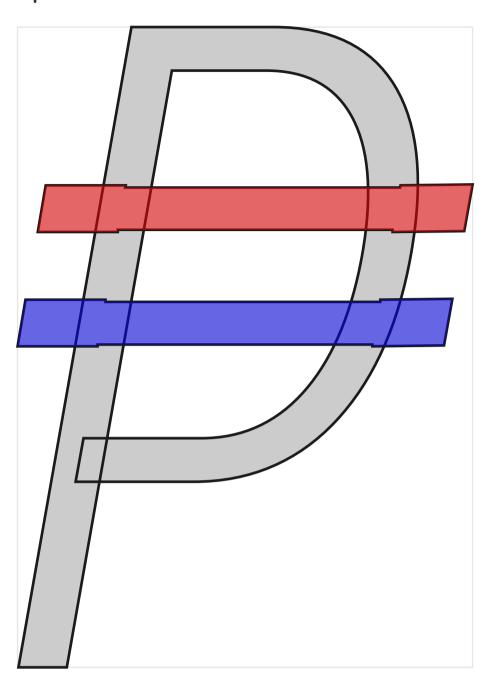
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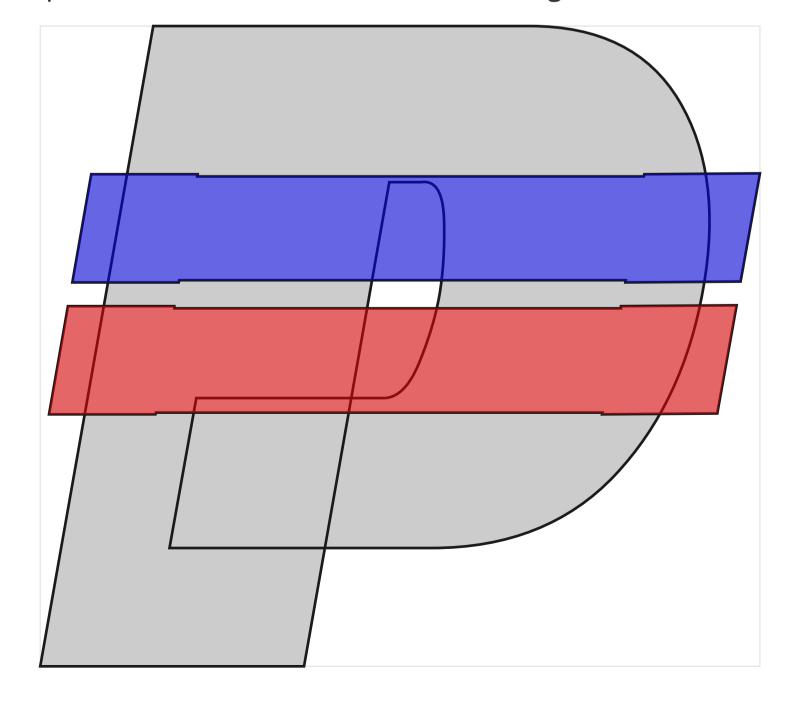
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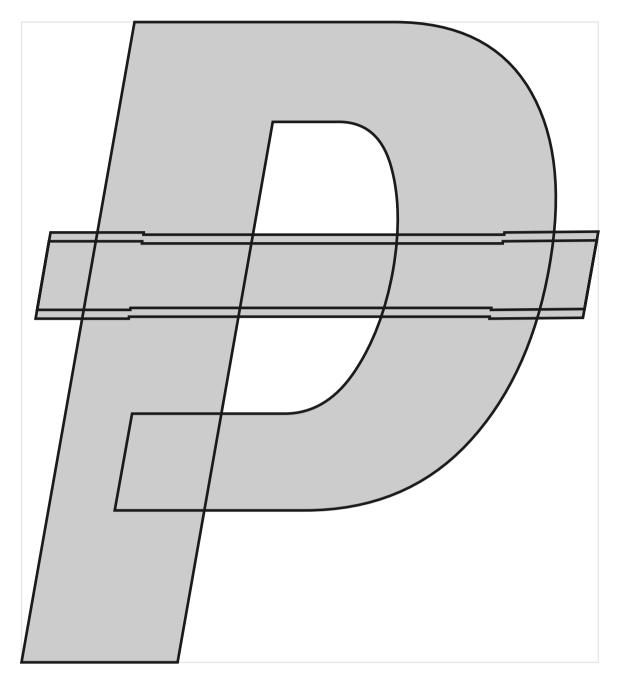
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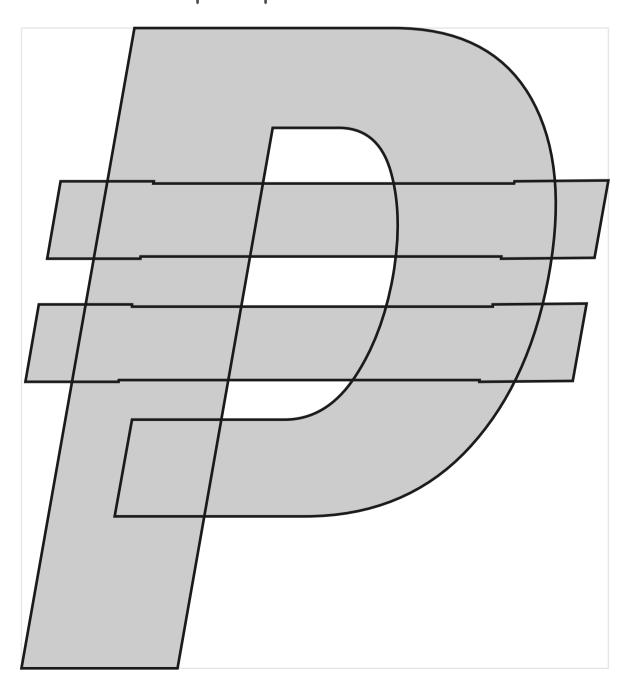
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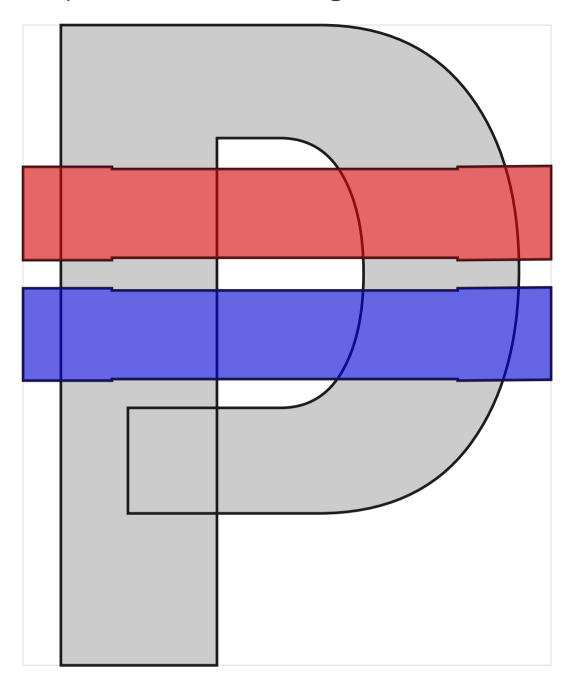
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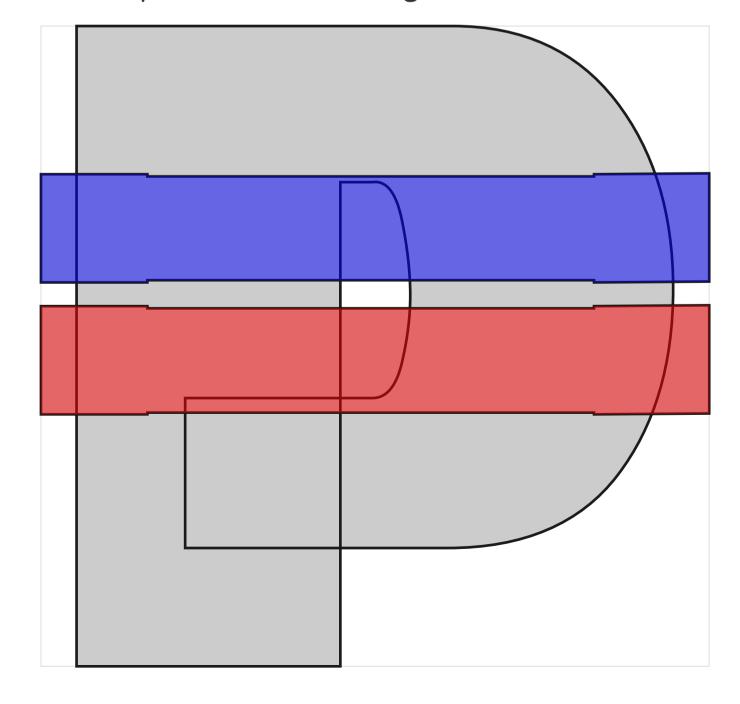
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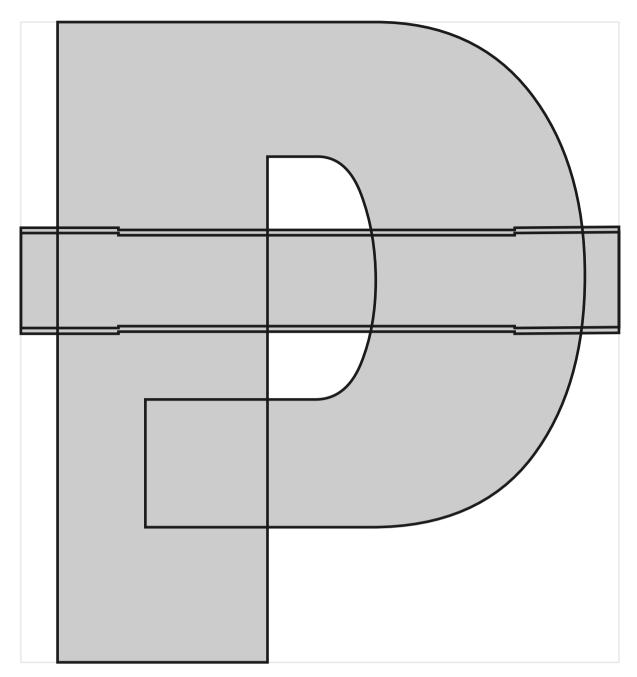
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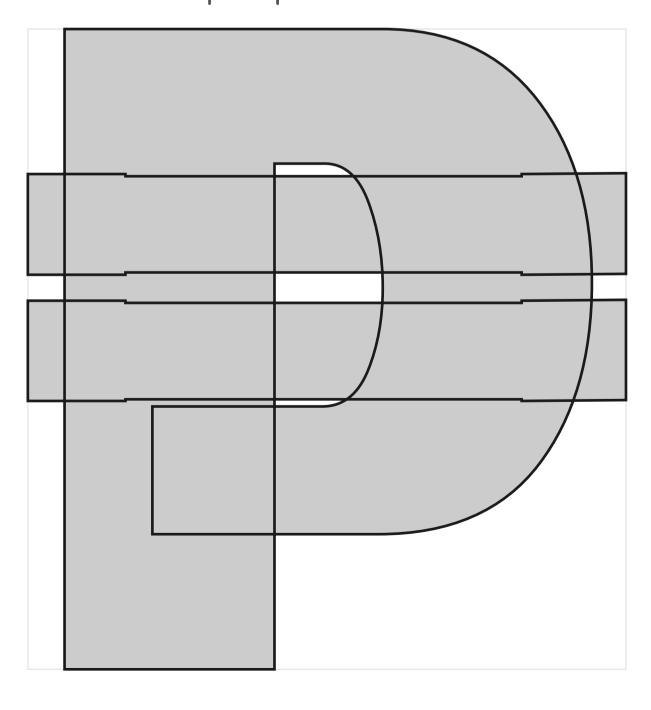
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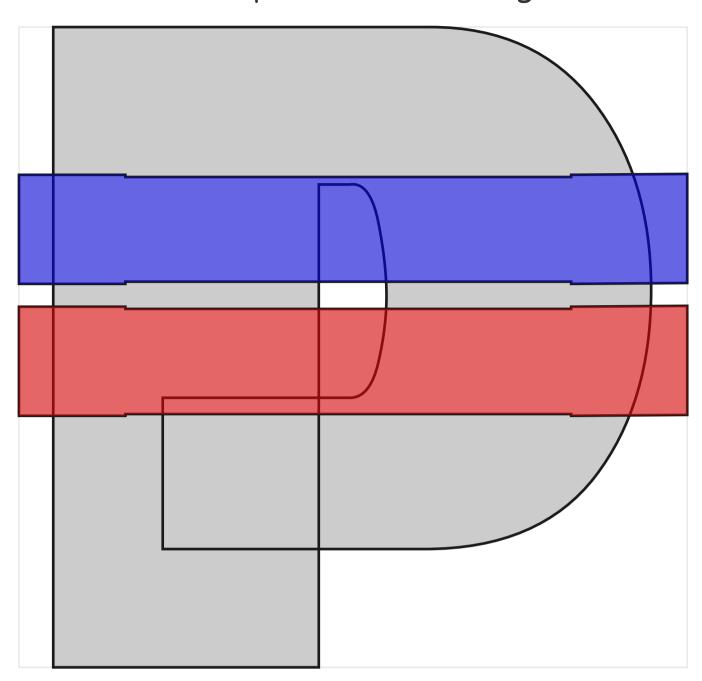
midway interpolation



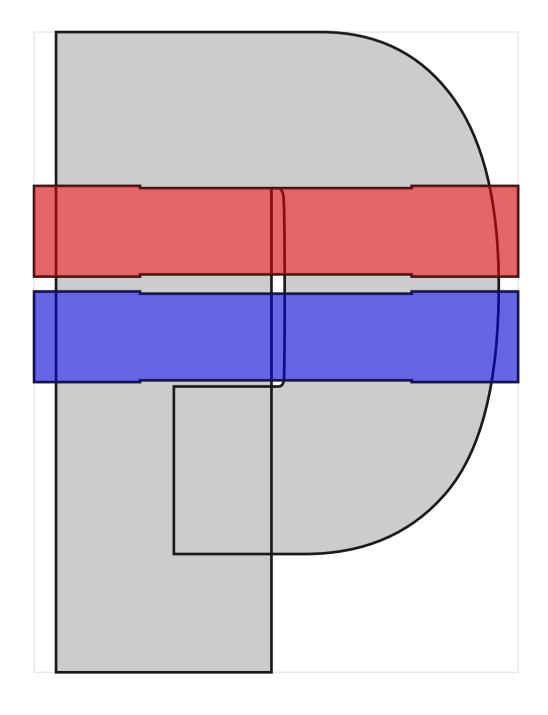
proposed fix



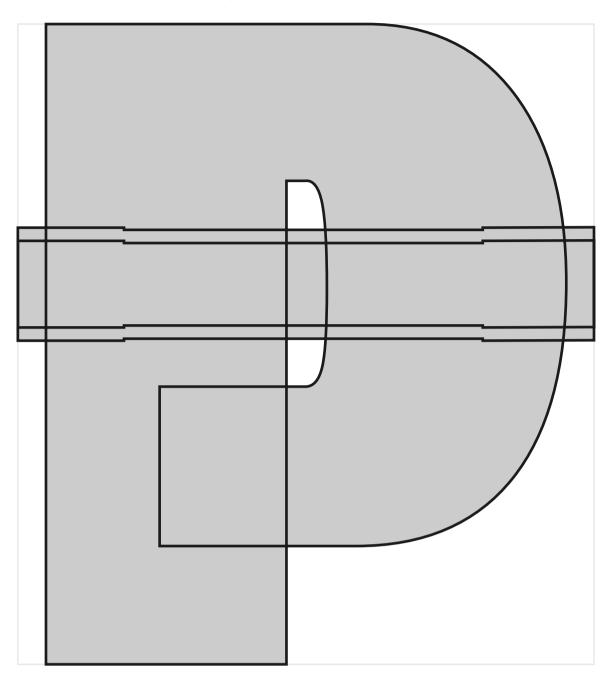
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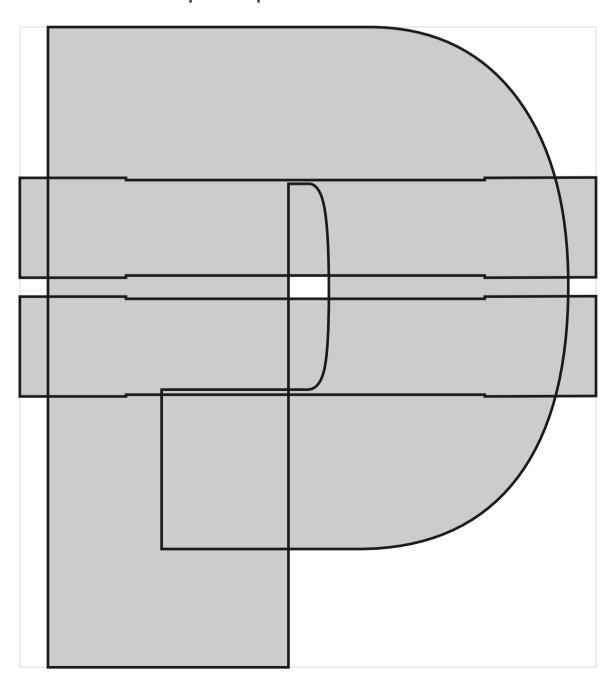
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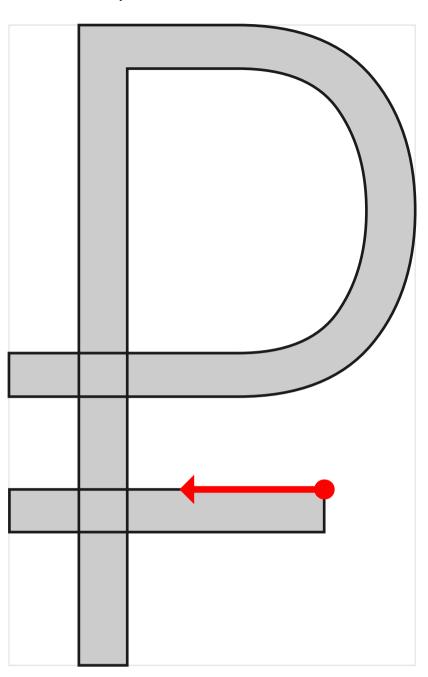
midway interpolation



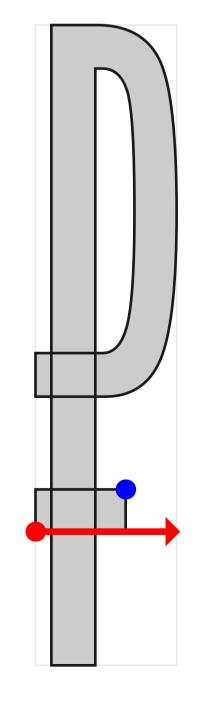
proposed fix



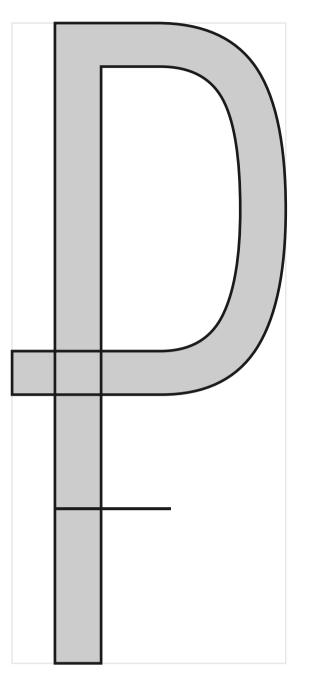
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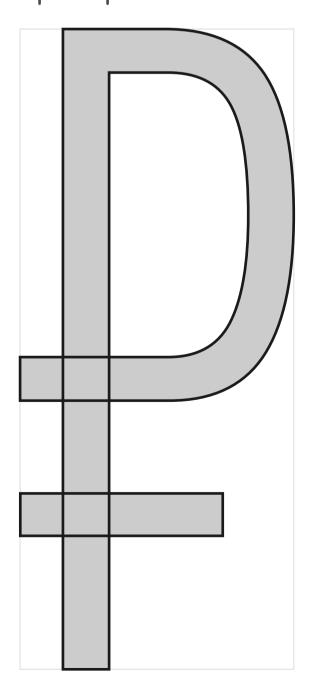
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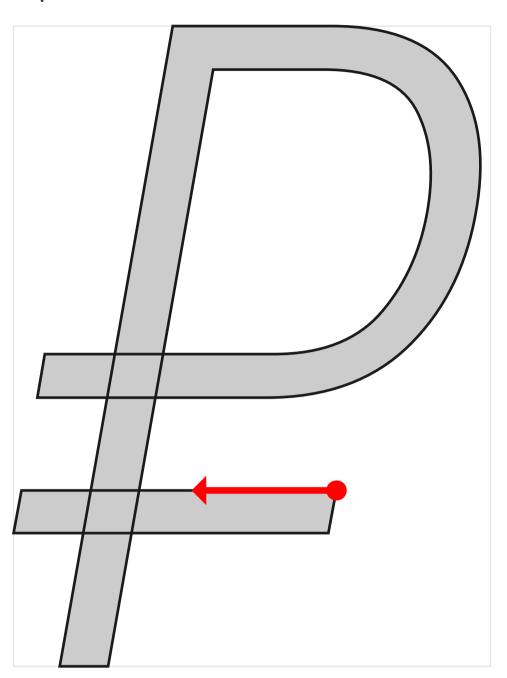
midway interpolation



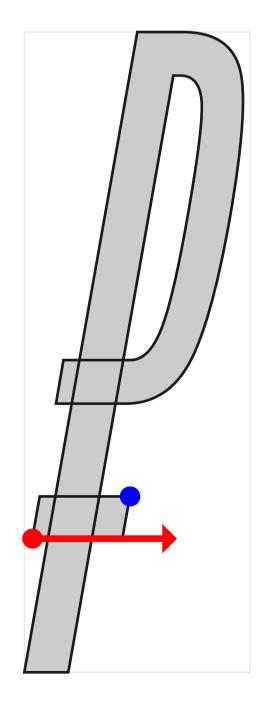
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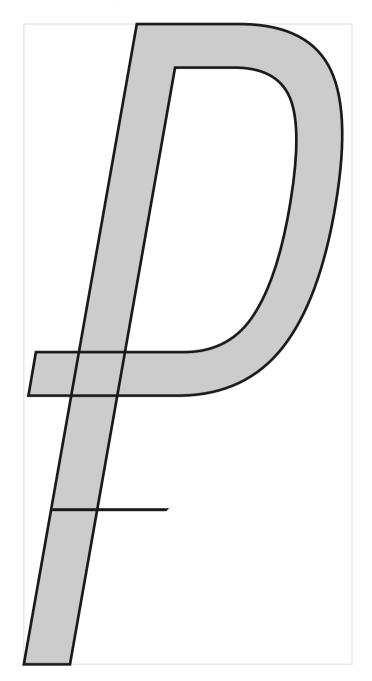
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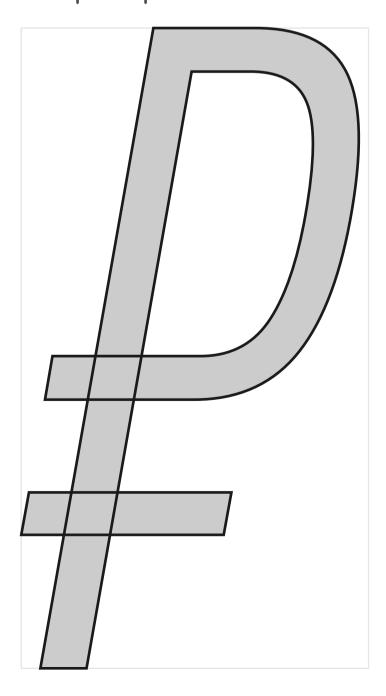
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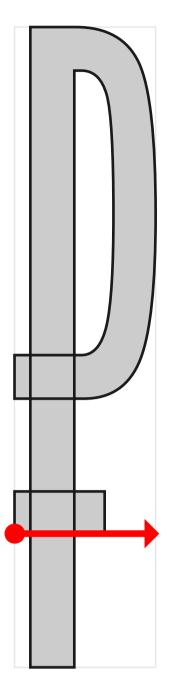
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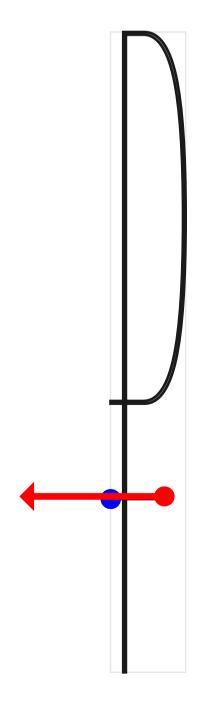
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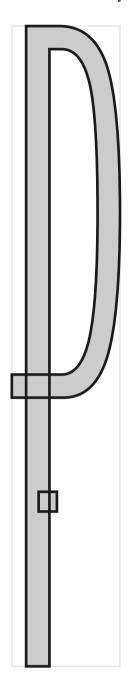


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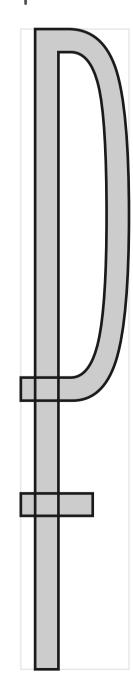


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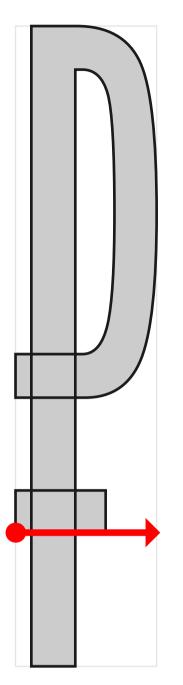




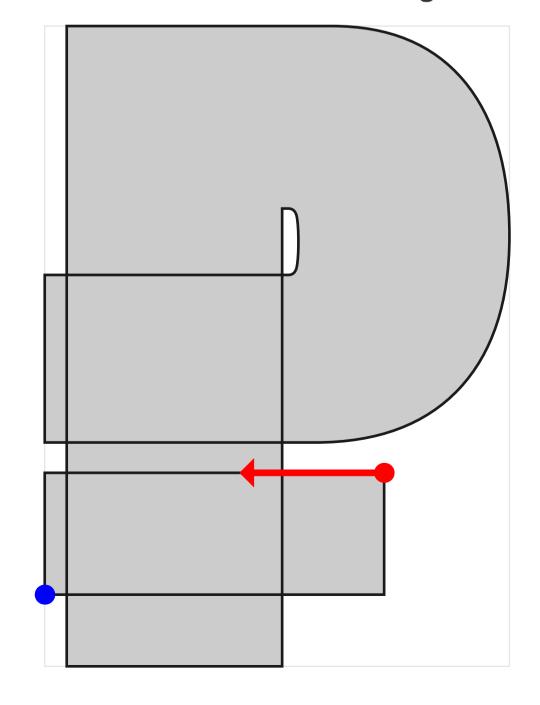
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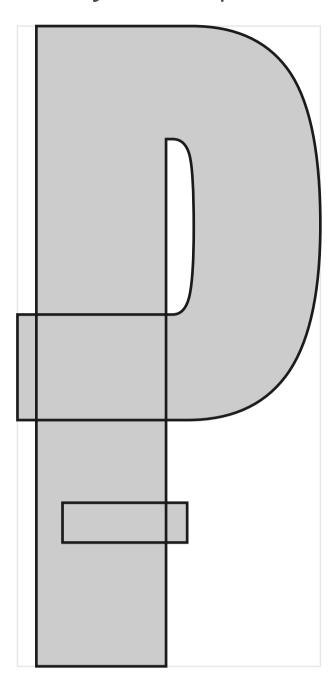
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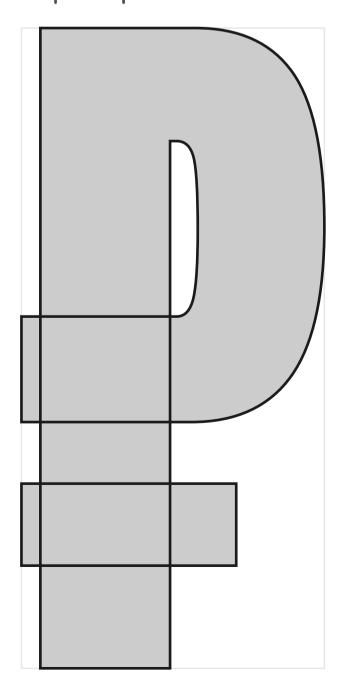
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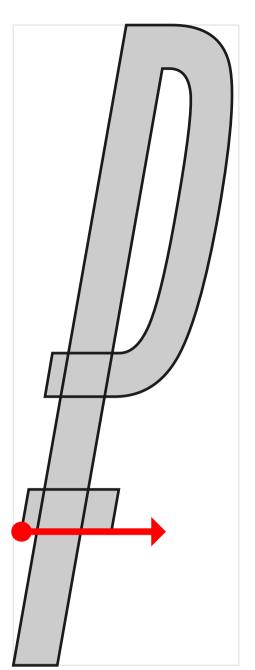
midway interpolation



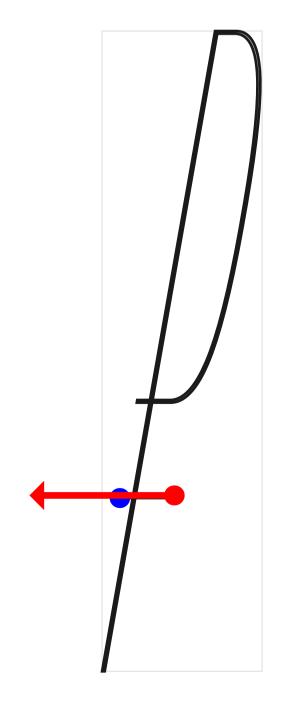
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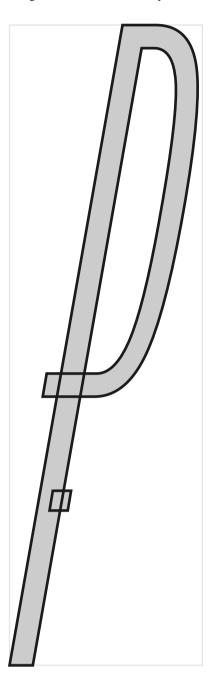


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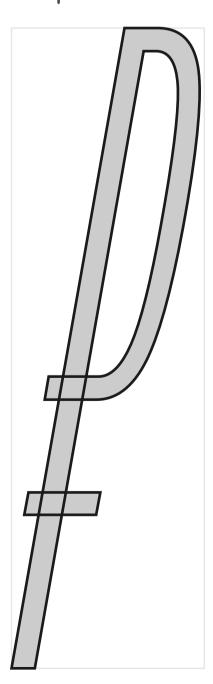


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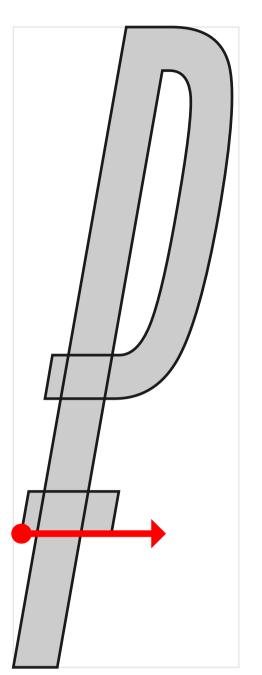




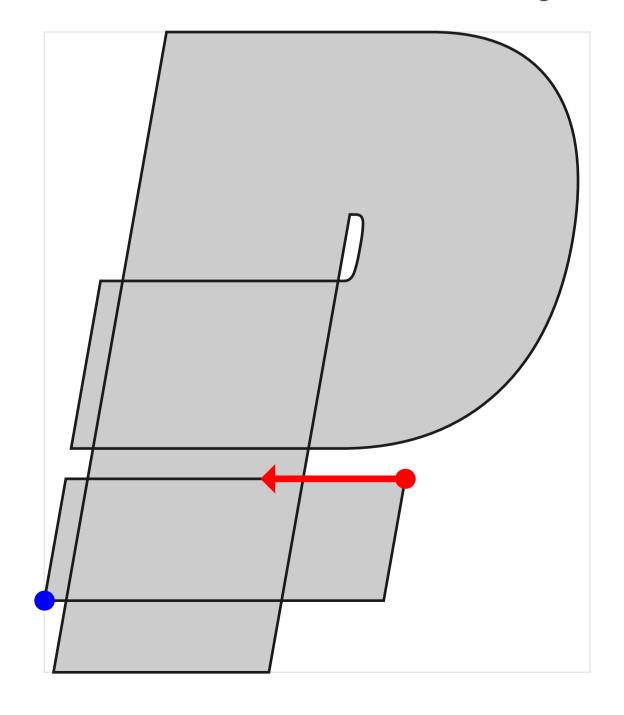
proposed fix



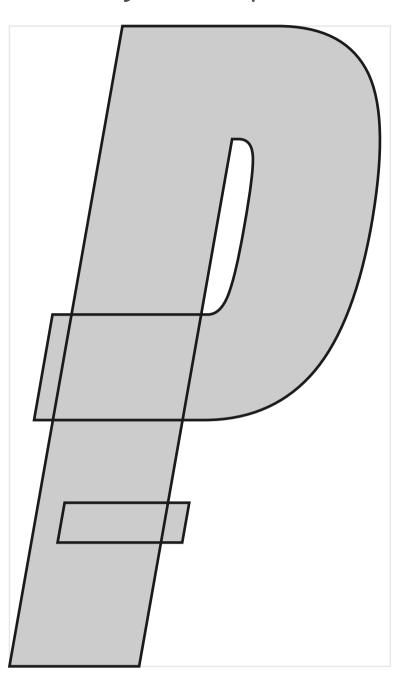
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'opsz=144.0 slnt = -10.0 wdth = 25.0 wght = 1000.0'



midway interpolation



proposed fix

