Reply to Associate Editor and Reviewers

We appreciate the reviewers' valuable comments and suggestions and have made every effort to address them comprehensively. Enclosed, we have provided responses to each reviewer's comments in the upcoming pages of this document. Additionally, you will find the updated version of the manuscript along with a supplementary document detailing the changes made in comparison to the original submission.

Before jumping into details, there is one common concern among the reviewers regarding the model of the reactor. We realize the initial manuscript lacks a detailed discussion on this matter. However, we would like to emphesize that the key contribution of this work is to address a spatially distributed chemical engineering setup considering the existance of the recycle stream without neglecting the intrinsic time delay it imposes on the system. To be more specific, the main idea of our submission revolves around developing a strategy for designing an optimal controller with no need for model reduction by capturing the state delay as an additional PDE coupled with the original system. Although the control theory for spatially distributed systems with state-delays are not uncommon in other fields, such as signal processing and mechanical systems, this work is the first to address this problem in the context of chemical engineering. Therefore, we have intentilnally kept the model simple yet realistic to demonstrate the proposed control strategy. Nevertheless, we have included a more detailed discussion on the model and its limitations in the revised manuscript to better match the scope of the journal and address the reviewers' concerns.

We hope that the revised manuscript meets the standards of the journal and is suitable for publication.

Sincerely yours,

Behrad Moadeli, Guilherme Ozorio Cassol and Stevan Dubljevic

Reviewer 1

The comments of Reviewer 1, along with our responses to each comment, are included below:

"This work presents a boundary optimal control strategy for axial tubular reactors with first-order irreversible chemical reaction incorporating a delayed recycle stream. The mathematical description takes the form of a system of coupled parabolic and hyperbolic PDEs. An infinite-dimensional approach is applied to derive a linear quadratic regulator with and without observer. Numerical studies show that the proposed controller is able to stabilize the system. The manuscript is clear and well written and addresses a challenging control problem in chemical engineering. The following comments and suggestions may improve the presentation so that it is considered for publication."

1. Page 3 - "Many chemical, petrochemical, and biochemical unit operation processes are modelled as distributed parameter systems (DPS)."

A few specific examples of these chemical processes would help to motivate the problem this paper addresses

Authors Reply:

Examples have been added to the introduction and the manuscript has been revised accordingly.

- 2. Page 5 "PIDEs"
 - What does PIDEs stand for?

Authors Reply:

Thanks for pointing this out. The acronym should have been defined in the manuscript. It stands for Partial Integro-Differential Equations. The manuscript has been revised accordingly.

- 3. Page 5 "a configuration common in industrial processes"
 - Examples of these processes would illustrate the need and motivation to address the associated control problem

Authors Reply:

Examples have been added to the introduction and the manuscript has been revised accordingly.

- 4. Page 6 "The resulting PDE that describes the reactor model is given by:"
 - I suggest to specify the assumptions leading to the reactor model, like isothermal operation, constant properties, constant pressure, \dots

Authors Reply:

- 5. Page 7 Eq (2)
 - What is the physical meaning of the manipulated variable u(t)?

Authors Reply:

The title has been revised based on the suggested terminology.

- 6. Page 7 " $x_2(\zeta, t)$ is introduced as a new state variable to account for the concentration along the recycle stream"
 - Why is x_2 a function of ζ ? How does x_2 change across the recycle? What kind of law does it follow? To me, it seems like x_2 only changes with respect to time

Authors Reply:

The title has been revised based on the suggested terminology.

- 7. Page 8 Eq (5)
 - Please make a distinction between the symbol for domain and for diffusivity to avoid confusion

Authors Reply:

The title has been revised based on the suggested terminology.

- 8. Page 12 Riesz-spectral operator ${\mathfrak A}$
 - Although a rigorous proof is not necessary, it would be good if the authors explain why $\mathfrak A$ is a Riesz-spectral operator. I guess its eigenvalues and eigenfunctions satisfy the requirements, like having multiplicity one and forming a Riesz basis, respectively.

Authors Reply:

The title has been revised based on the suggested terminology.

- 9. Page 12 \mathfrak{R} being positive semi-definite operator
 - Should \(\mathfrak{R} \) be self-adjoint and coercive?

Authors Reply:

The title has been revised based on the suggested terminology.

- 10. Page 12 The LQR problem
 - Is Problem 12 well-posed, does J have a finite value for at least one u?

Authors Reply:

- 11. Page 18 unstable dynamics of the model
 - Why is the zero-input response considered unstable? Is it a qualitatively assessment? What is the physical meaning of Figure 9?

Authors Reply:

The title has been revised based on the suggested terminology.

- 12. Page 18 "The goal is to stabilize the system using an optimal control strategy"
 - What are the values of matrices Q and R in the objective function?
 - Are x deviation variables? What is the setpoint?

Authors Reply:

The title has been revised based on the suggested terminology.

- 13. Page 20 "Both optimal feedback gains are able to successfully stabilize the system within finite time horizon."
 - It would be interesting to see how the delay time affects the stabilizing capabilities of the feedback regulator. What would happen a shorter and larger values of τ

Authors Reply:

The title has been revised based on the suggested terminology.

- 14. Page 26 "The proposed framework may be extended to more complex diffusion-convection reactor configurations, such as non-isothermal reactors"
 - Can this framework be applied to reaction systems described with more complex and highly nonlinear reaction kinetics?

Authors Reply:

Reviewer 2

The comments of Reviewer 2, along with our responses to each comment, are included below:

"The problem presented in the article is well-posed and written. The purpose is to present a novel approach to address the problem of intrinsic delay when there is a recycle stream in a process. However, I recommend submitting it to a journal focused on Control. This opinion is based on the following concerns regarding the process of a chemical reactor with recycle:"

1. Why is relevant to consider Danckwerts boundary conditions for the problem of control? Have you compared your results with those obtained considering other boundary conditions?

Authors Reply:

The title has been revised based on the suggested terminology.

2. Concerning the recycle stream, have you studied the effect of the R, the recycle ratio, on your results? Please comment.

Authors Reply:

The title has been revised based on the suggested terminology.

3. The authors used as the case study the problem of an axial dispersion tubular reactor incorporating diffusion, convection, and a first-order irreversible chemical reaction described by equations (1)-(2). While this is sufficient to present their approach, it is far from being extended to the more general problem, non-isothermal, and with more general kinetics such as biochemical or catalytic.

Authors Reply:

The title has been revised based on the suggested terminology.

4. I recommend submitting it to a journal focused on Control.

Authors Reply:

Reviewer 3

The comments of Reviewer 3, along with our responses to each comment, are included below:

"In this work, the authors address the optimal control of an axial tubular reactor with a recycle stream. They model the intrinsic time delay from the recycling process using a system of coupled parabolic and hyperbolic partial differential equations. The control input is applied at the inlet, and a continuous-time optimal linear quadratic regulator is designed to stabilize the system. Numerical simulations indicate effective full-state feedback regulator and observer-based regulator. This work presents an interesting methodology but there are some minor considerations that the authors need to address before this article can be published:"

1. **Major comment:** In section 4, the authors indicate that they discretized each state in space using 100 grid points. They must indicate if those points are equidistributed and how they came up with such discretization grid. Note that multiple works [1, 2, 3] have demonstrated that the selection and distribution of the discretization grid plays a crucial role in the computation of optimal control laws, i.e., a control law can be claimed to be optimal or not using the criterion of the Pontryagin's Minimum Principle (PMP). The reviewer recommends to assess the criterion of the Hamiltonian function (i.e., the PMP) to demonstrate that the discretization implemented is accurate and the solutions obtained for the control are optimal.

Authors Reply:

The title has been revised based on the suggested terminology.

2. The manuscript lacks conclusions or further discussion about the control trajectories' results, such as the quality of the control actions or improvements in process operation (e.g., avoidance of constraint violations, disturbance rejection, etc.). Although the authors included several figures illustrating the process dynamics and control trajectories, these are not discussed in sufficient depth, i.e., avoid leaving the reader to draw their own conclusions from the figures. Additionally, the reviewer recommends reducing the number of figures, which could allow more space for further discussion of the results.

Authors Reply:

The title has been revised based on the suggested terminology.

3. In section 3.1.3, the authors present the values for parameters R and D but provide no further details about the model's sensitivity to these parameters. Please include a detailed explanation of how these values were selected and discuss any potential limitations if the parameters are chosen incorrectly.

Authors Reply:

The title has been revised based on the suggested terminology.

4. In section 4, the authors indicate that the process model was discretized in time and space, however, they mention that they obtained a system of ordinary differential equations (ODEs). Please clarify how this full discretization resulted in a system of ODEs.

Authors Reply:

5. The manuscript has some typos that the authors must correct, e.g., ...setting for of distributed..., Then two full-state... In page 5, the acronym PIDEs is not previously defined. For section 4.3, the reviewer recommends to modify the expression "Last but not least" aiming not loose the formality of the manuscript.

Authors Reply:

The title has been revised based on the suggested terminology.

6. The reviewer recommends to include a tables of nomenclature

Authors Reply:

References

- [1] Palma-Flores O, Ricardez-Sandoval LA. Selection and refinement of finite elements for optimal design and control: A Hamiltonian function approach. AIChE Journal. 2023;69(5):e18009.
- [2] Assassa F, Marquardt W. Optimality-based grid adaptation for input-affine optimal control problems. Computers & chemical engineering. 2016;92:189-203.
- [3] Chen W, Shao Z, Biegler LT. A bilevel NLP sensitivity-based decomposition for dynamic optimization with moving finite elements. AIChE Journal. 2014;60(3):966-79.