

28	BEVEL_GEAR		
27	GEAR_FOR_LINK5_6		
26	BEARNING6		
25	MOTOR_GEARI7		
2 4	MOTOR_NEMAI7		
23	PULLEY_2ND5		
22	BEVEL_GEARI		
21	GEAR_FOR_LINK4_5		
20	BEARNING 4		
9	GRIPPERI		
18	BEARING_BASEI		
1 7	GEAR3		
16	SUBMOTOR_GEAR2		
15	MOTOR_GEARI		
4	MOTOR_NEMA23		
13	PULLY2_3_ATTACHMENT		
12	BELT2_31		
	PULLEY_2ND		
10	LINK_SIX		
9	LINK_FIVE		
8	LINK_FOUR		
7	BELTMECH		
6	LINK3		
5	BEARNING3		
4	SECOND_LINK		
3	BEARING		
2	LINK_FIRST		
	BASE_PLATE		
I T E M N O	BODY NAME	Quantity	NOTES

WARSAW UNIVERSITY OF TECHNOLOGY DEPARTMENT OF ROBOTICS			
Item No	. ~	rt Name	Material
Checked	by - Prot. Krz	ysztof Mianowski	