# Oscar Beijbom

CONTACT UCSD/CSE EBU3b Rm. 4148

9500 Gilman Drive, Dept 0404

La Jolla, CA 92093

+1 (858) 888 - 2189

http://vision.ucsd.edu/~beijbom/website oscar.beijbom@gmail.com

**EDUCATION** 

### University of California, San Diego

Ph.D. in Computer Science, expected graduation date: June 2015 M.S. in Computer Science, June 2012

#### **Lund University**

B.S. & M.S. in Engineering Physics, March 2007. GPA 4.9 (3-5 scale)

### ACADEMIC EXPERIENCE

## Department of Computer Science, UCSD

 $Graduate\ Student\ Researcher$ 

San Diego, USA.

September 2009 -

"Annotating the worlds oceans: computer vision methods for scientific data analysis" Advisor: Professor David Kriegman

- Texture based recognition & segmentation in organic images.
- Cost sensitive learning for Support Vector Machines and Boosting.
- Underwater color correction methods for computer vision.
- CoralNet: A web tool for automated underwater image annotation
  - Manual and automated annotation of user uploaded images
  - Used by researchers, agencies and private parties globally
  - Provides a ever-growing web-scale dataset for texture based image analysis.

#### Department of Mathematics, Lund University

M.S. Thesis Scholar

Lund, Sweden

September 2006 - March 2007

"Single image focus level assessment using Support Vector Machines"

Advisor: Professor Karl Astrom.

My thesis work was done in collaboration with a company in Lund, Sweden: Cellavision AB. Cellavision manufactures equipment for automatic analysis of blood smears. [www.cellavision.com]

- Developed novel method for autofocus that utilize a multi-class machine learning methodology and low-level image features, including color and texture.
- Worked with Cellavision engineers to collect training and test data.
- The developed method is protected with an international patent, and it's implemented in the Cellavision products. The Master's thesis received several awards.

#### Department of Mathematics

Research Assistant

Lund, Sweden

March 2007 - June 2007

SME-robot is a large, international EU financed project. [www.smerobot.org]

• Worked on robot camera calibration using structure from motion.

## Professional Experience

## Hövding AB

Malmö, Sweden

Head of Research
June 2007 - September 2009

I was the first employee at Hövding, the company behind the "invisible" bicycle helmet with the same name. The helmet is a collar that is worn around the neck. It contains a folded up airbag that inflates and protects the user in the event of an accident. Hövding received the 2011 Index Award. [www.hovding.com]

- Responsible for development for the accident detection system.
- Developed a real time algorithm, based on machine learning, that takes data from motion sensors as input, and determines if the rider is in an accident.

- Managed large-scale data collection with stunt actors and students.
- Worked with subcontractors to develop and identify hardware components.
- Hired and managed a team of engineers.
- The method I developed is implemented and runs on an embedded system in the Hövding helmets. International patent is pending.

### McKinsey & Company

Junior Consultant

Stockholm, Sweden

June 2005 - September 2005

McKinsey is a management consulting firm, advising corporations, banks, and holding companies on strategic and tactical issues. [www.mckinsey.com]

 Worked in a small team to quickly collect and analyze data for tasks such as mergers & acquisitions, procurement, and marketing.

### Teaching EXPERIENCE

# Department of Computer Science, UCSD

Teaching Assistant

San Diego, USA

2013 -

• Introduction to Computer Vision. Led sections, gave occasional lectures, prepared and graded homework assignments.

#### **Lund University**

 $Graduate\ student\ instructor$ 

Lund, Sweden

2001 - 2004

- Linear Algebra. Prepared and led sections.
- Calculus. Prepared and led sections.
- Static and Dynamic mechanical systems. Prepared and led sections.
- Programming in Java. Prepared and led sections and labs.

# PATENTS

- Publications & O. Beijbom, P.J. Edmunds, D.I. Kline, G.B. Mitchell, D. Kriegman. "Automated Annotation of Coral Reef Survey Images". IEEE Conference on Computer Vision and Pattern Recognition (CVPR), Providence, Rhode Island, 2012.
  - O. Beijbom. "Domain Adaptations for Computer Vision Applications". Research exam: University of California San Diego, arXiv:1211.4860, April 2012.
  - O. Beijbom. "A method, device, and computer program product for event detection while preventing misclassifications" (W83960002). International filing date: 20.07.2009.
  - S. Hedlund, O. Beijbom, M. Almers. "A method for determining an in-focus position and a vision inspection system" (PCT/EP20008/051993). International filing date: 19.02.2008.
  - O. Beijbom. "Single Image Focus Level Assessment Using Support Vector Machines". Master's Thesis Report, Lund University, 2007.

### Conference Talks

- O. Beijbom, T. Treibitz, B. P. Neal, D. Kriegman, S. Belongie, P.J.Edmunds, D.I.Kline, B.G.Mitchell, "Automated Coral Reef Image Annotation Using Computer Vision", International Coral Reef Symposium, 2012.
- O. Beijbom, T. Treibitz, B. P. Neal, D. Kriegman, S. Belongie, P. J. Edmunds, D. I. Kline, B. G. Mitchell, "Automated Coral Reef Analysis Using Computer Vision", American Society of Limnology and Oceanography Aquatic Sciences Meeting, 2011.

#### Services

### Östgöta Nation Student Choir

Chairman

Lund, Sweden

2004 - 2005

The Östgöta Nation Student Choir is a choir at Lund University with  $\sim 50$  singers.

• Hired a new conductor.

- Organized concerts and events.
- Planned the repertoire.

TekonomordenFounderLund, Sweden2002 - 2005

Tekonomorden brings economics and engineering students together by arranging exclusive dinners for invited members every semester.

 $\bullet$  Cofounders, and event manager.

SKILLS Languages: Native Swedish, fluent English, good Spanish and German

Programming Languages: C, C++, Java, Python, MATLAB, Prolog, OCaml

Other omputer skills: Vim (editing), Django(web development)