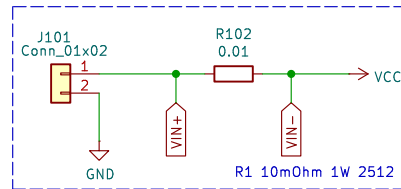


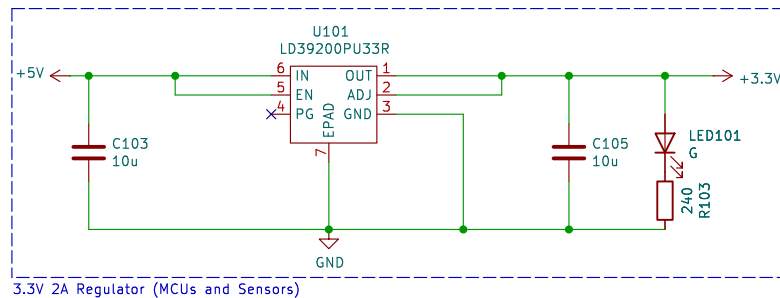
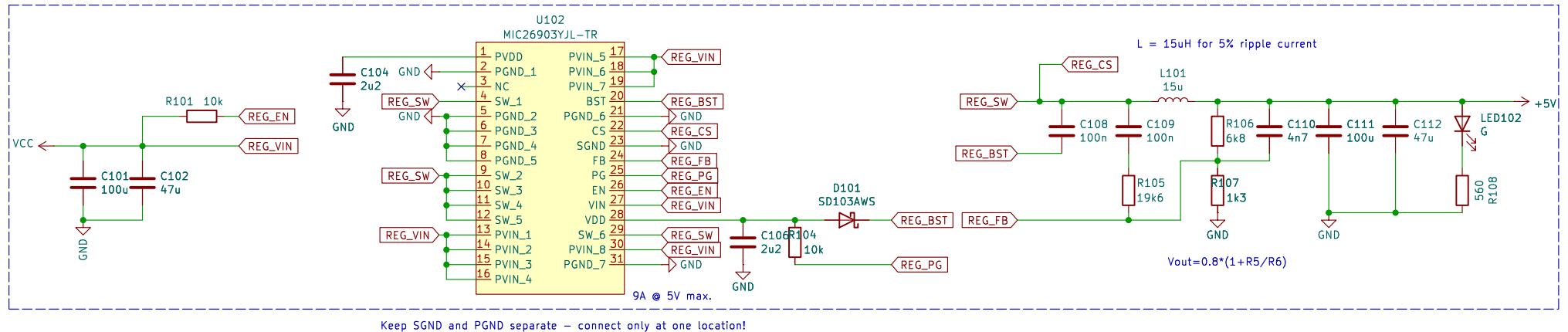
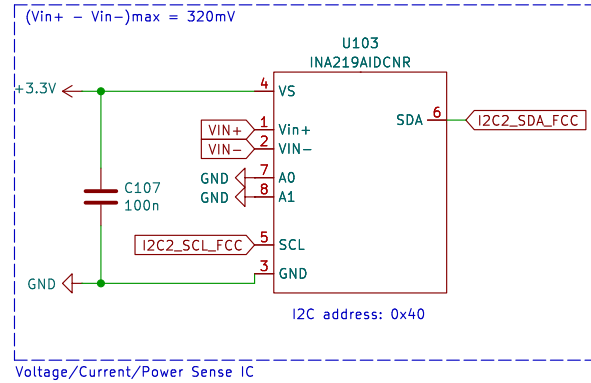
# Power

Maximum input voltage: 26V



Battery Input and  
Current Sense Resistor

C1, C8 are Al Electrolytics  
C2, C9 are 1210 ceramics  
C1, C2 rated at >= 35V



Aikyam Innovators

Sheet: /

File: Agri\_Drone.kicad\_sch

**Title: Power**

Size: A4

Date: 2024-09-28

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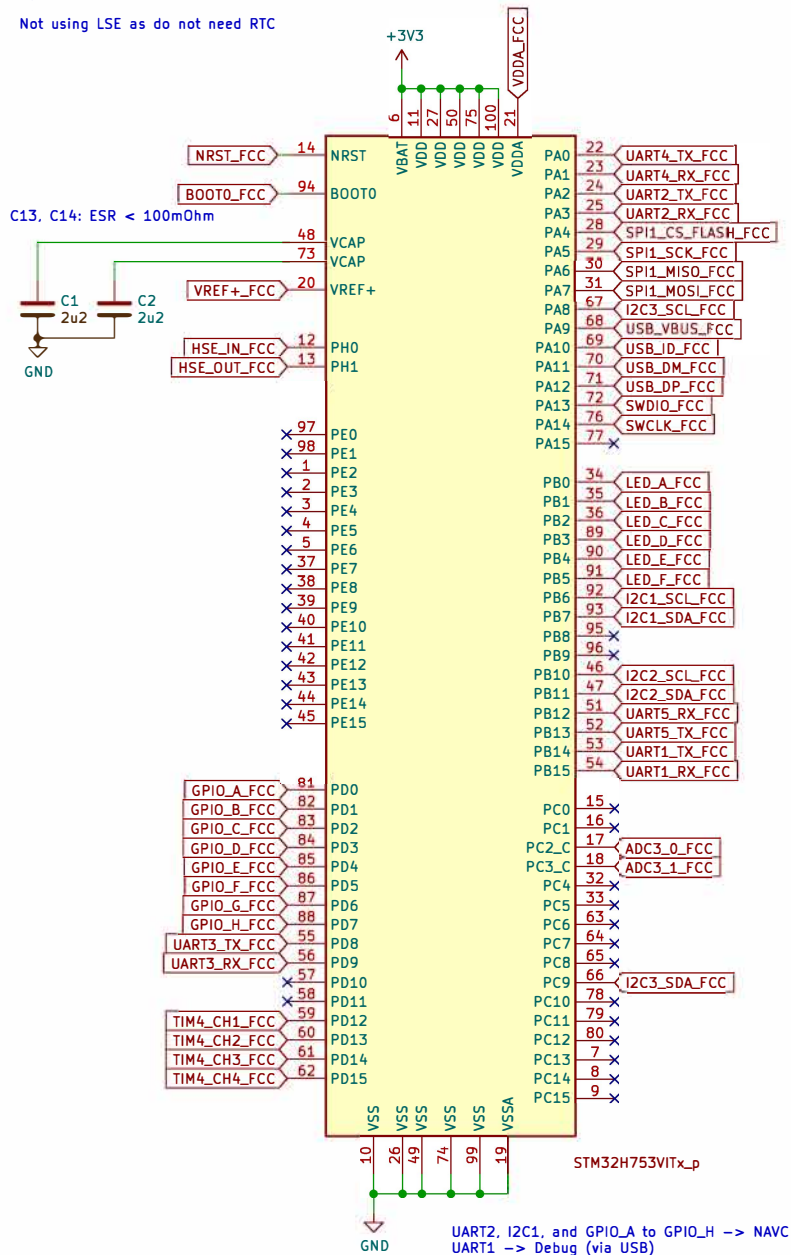
**Rev:**

Id: 1/6

## Flight Control Computer (FCC)

STM32H7: see AN4938

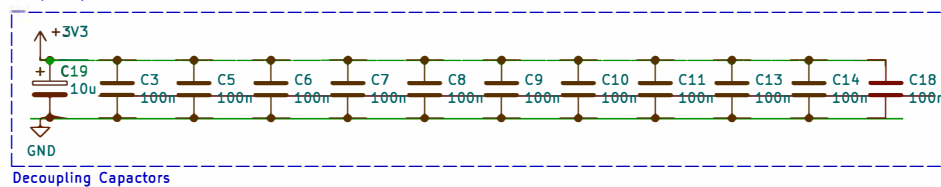
Not using LSE as do not need RTC



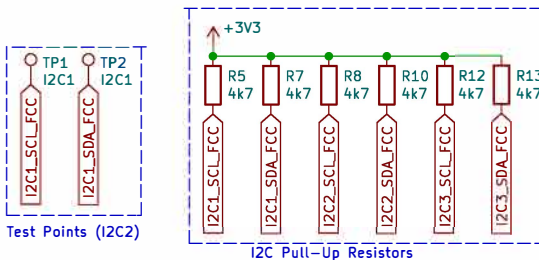
### AN2606 (Bootloaders): USART1 Bootloader (PB14/PB15)

UART2, I2C1, and GPIO\_A to GPIO\_H -> NAVC  
UART1 -> Debug (via USB)  
TIM4 -> PWM/PPM input

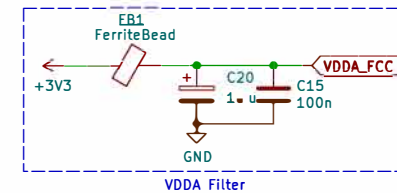
C15, C27, C29 Tantalum



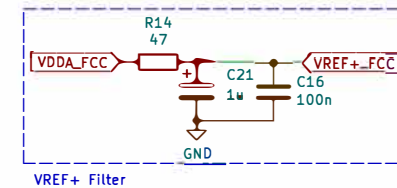
## Decoupling Capacitors



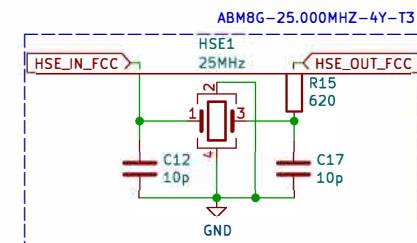
### Test Points (I2C2)



VDDA Filter



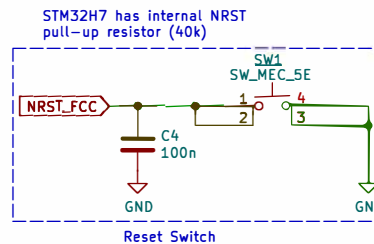
VREF+ Filter



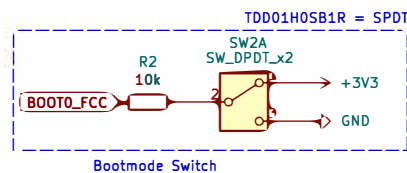
High Speed External Crystal

$$C32 = C33 = 2 * (CL - C_{stray}) \quad R_{ext} = 1/(2 * \pi * f * CL)$$

$$C_{stray} = \{2pF, 5pF\}$$



### Reset Switch



## Bootmode Switch

**Aikyam Innovator**

Sheet: /Flight controller Computer/

File: FCC.kicad\_sch

**Title: Flight Controller Computer**

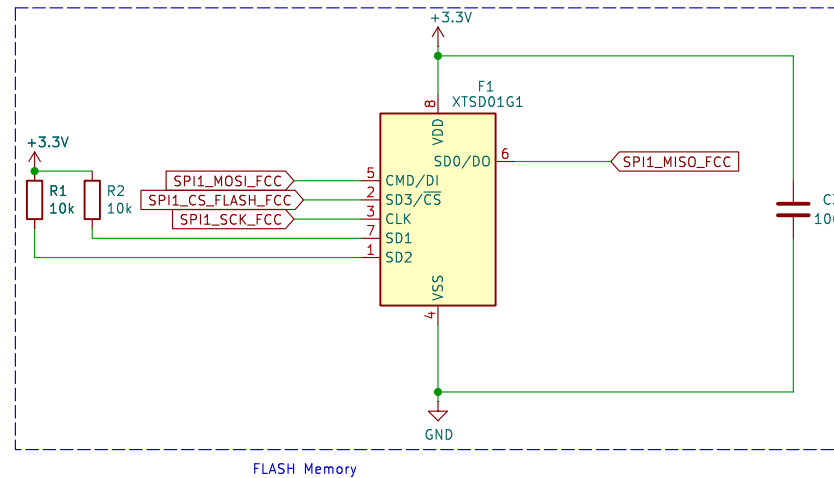
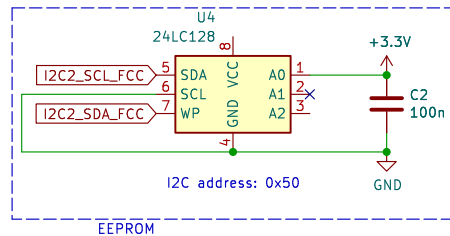
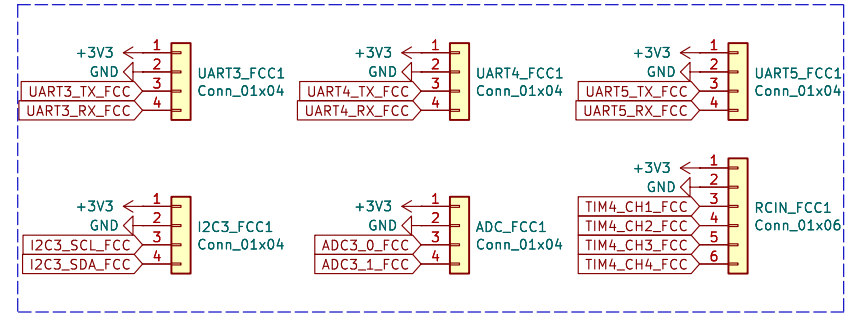
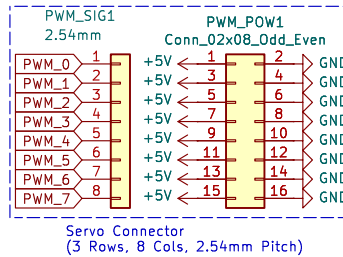
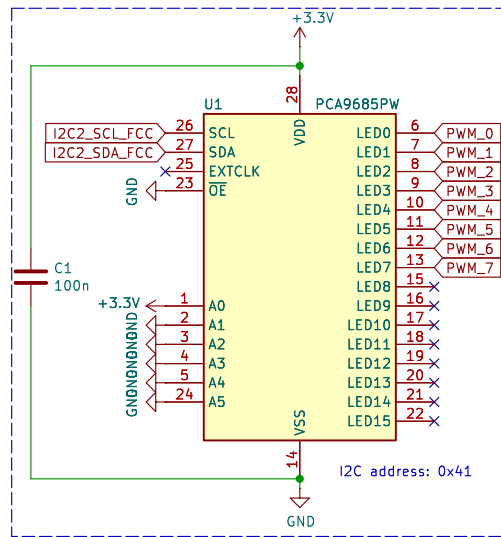
Size: A4	Date: 2024-09-28
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Rev:

Id: 2/6

# FCC Peripherals



**Aikyam Innovators**

Sheet: /FCC Peripheral/  
File: FCCPeripherals.kicad\_sch

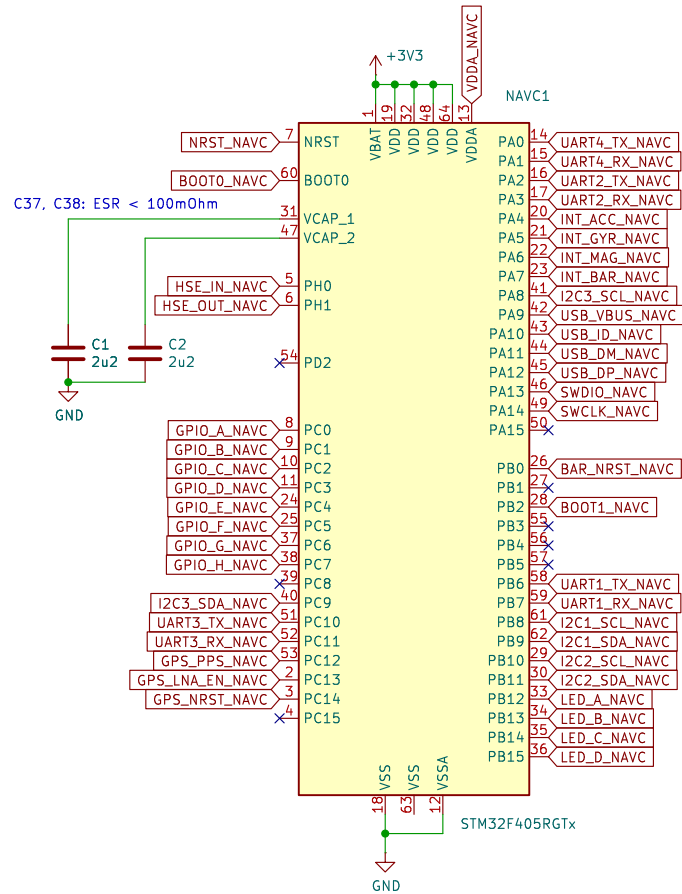
**Title: FCC Peripheral**

Size: A4 Date: 2024-09-28

KiCad E.D.A. 8.0.5

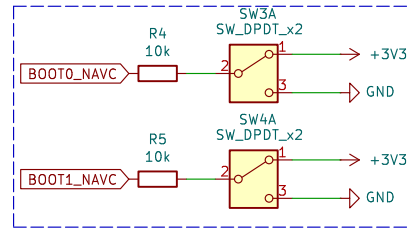
**Rev:**  
Id: 3/6

# Navigation Computer (NAVC)

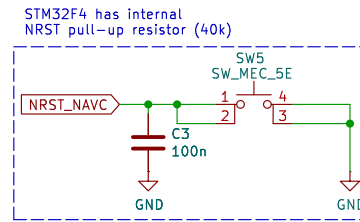


UART2, I2C2, and GPIO\_A to GPIO\_H -> FCC  
UART3 -> Debug (via USB)

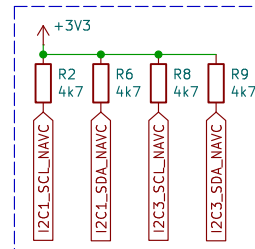
AN2606 (Bootloaders): USART3 Bootloader PC10/PC11



Bootmode Switches

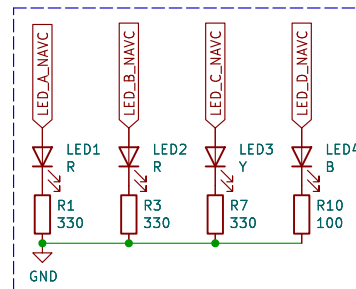


Reset Switch

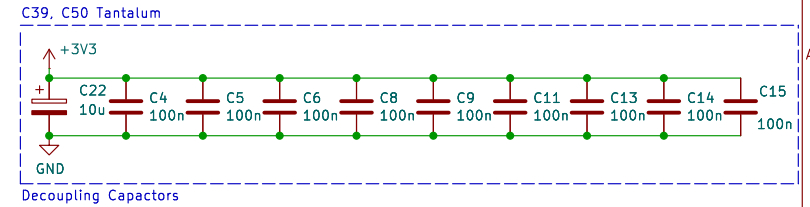


I2C Pull-Up Resistors

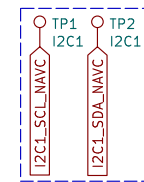
I2C2\_NAVC already pulled up by I2C1\_FCC resistors!



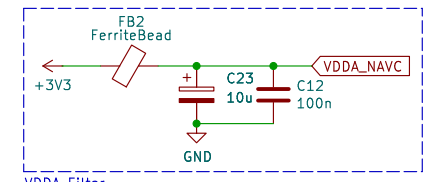
Indicator LEDs



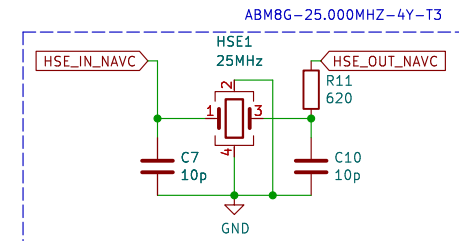
Decoupling Capacitors



Test Points (I2C1)



VDDA Filter



High Speed External Crystal

$C52 = C53 = 2 * (CL - Cstray)$   
 $Cstray = \{2pF, 5pF\}$

$Rext = 1/(2 * \pi * f * CL2)$

Aikyam Innovators

Sheet: /NAVC/  
File: NAVC.kicad\_sch

Title: NAVC

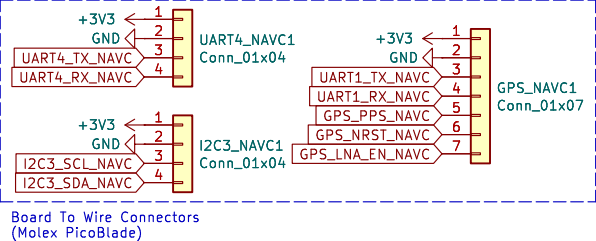
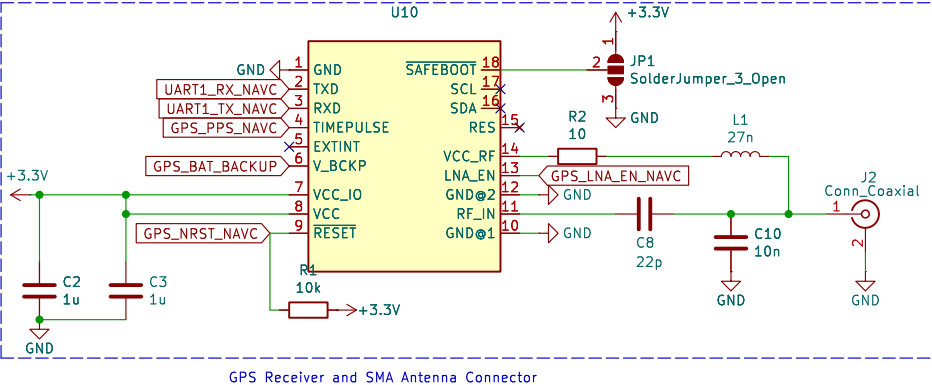
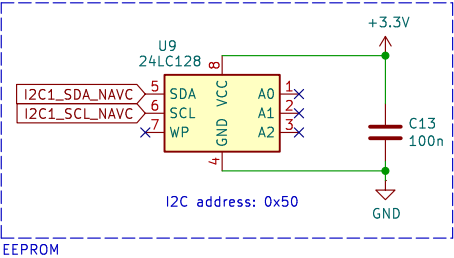
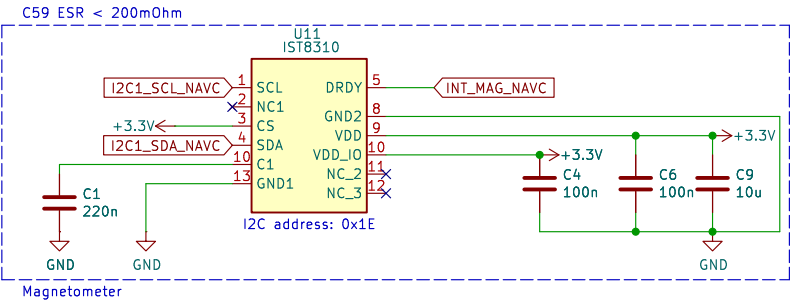
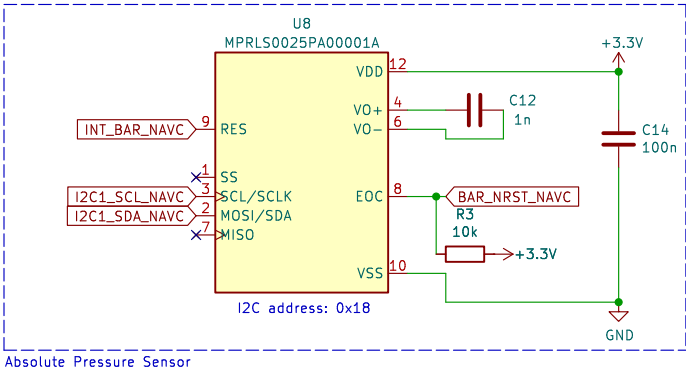
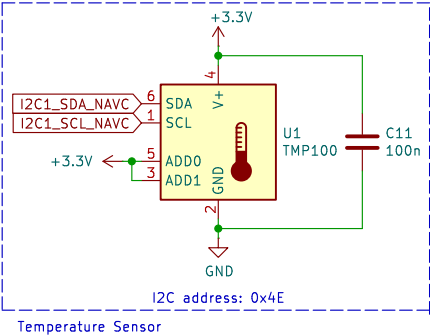
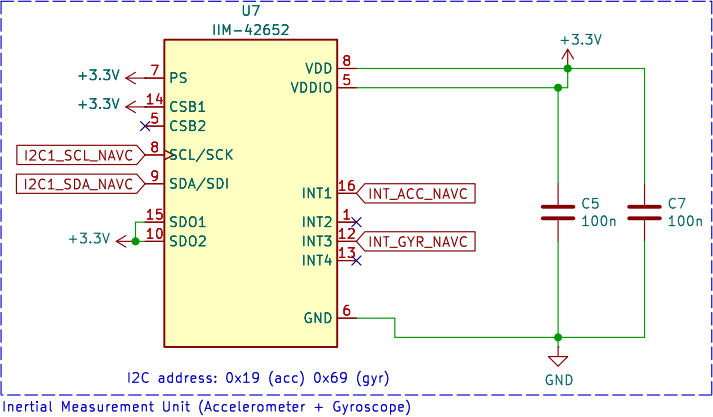
Size: A4 Date: 2024-09-28

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Id: 4/6

# NAVC Peripherals



Aikyam Innovators

Sheet: /NAVC Perripheral/  
File: NAVCPeripherals.kicad\_sch

Title: NAVC Peripheral

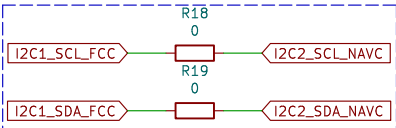
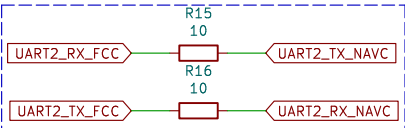
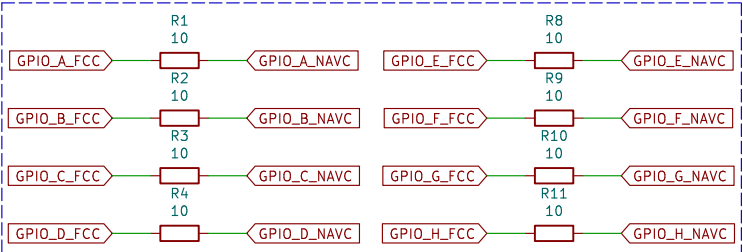
Size: A4 Date: 2024-09-28

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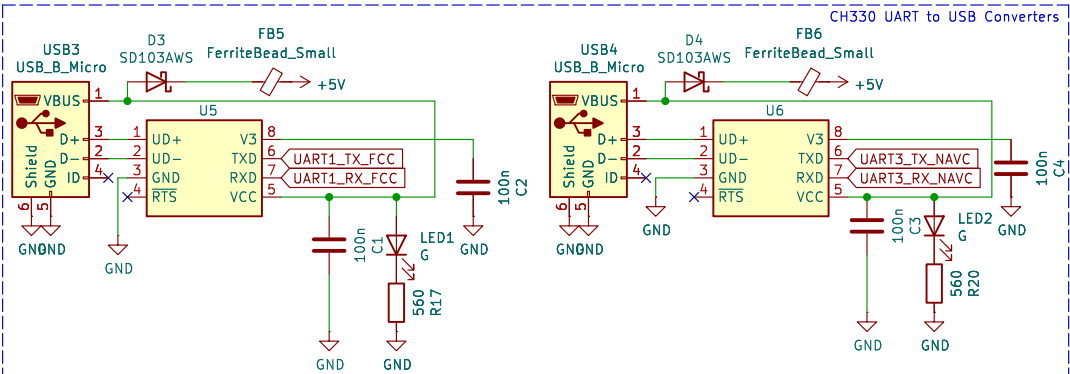
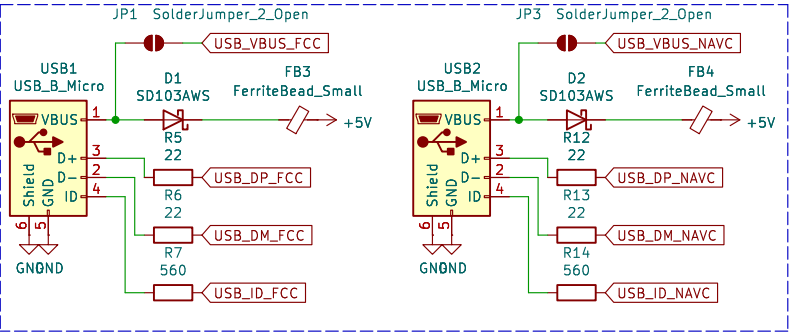
Rev:

Id: 5/6

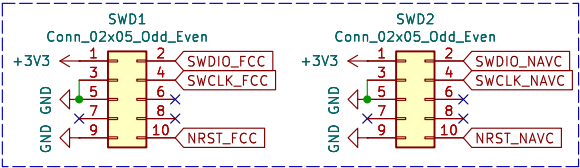
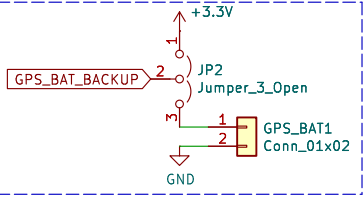
# Connections (FCC <-> NAVC)



## Connectors (Programming & Debug)



## GPS Backup Battery



Aikyam Innovators

Sheet: /Connections/  
File: Connections.kicad\_sch

Title: Connections

Size: A4  
KiCad E.D.A. 8.0.5

Date: 2024-09-28

Rev:  
Id: 6/6