

Drone Specifications Data Sheet

Electronic Components

1. Flight Controller

- **Model:** Pixhawk PX4
- **Features:** Supports autonomous flight, customizable with Ardupilot firmware, compatible with various sensors and peripherals.
- **Interfaces:** UART, I2C, CAN, PWM
- **Power Input:** 4.8V-5.4V
- **Dimensions:** 81.5mm x 50mm x 15.5mm
- **Weight:** 38g

2. GPS Module

- **Model:** Ublox NEO-M8N GPS
- **Features:** High-precision GNSS receiver, GPS + GLONASS support
- **Interface:** UART (NMEA output)
- **Power Consumption:** ~50mA
- **Accuracy:** 2.5m CEP

3. Battery

- **Model:** Tattu 6S 22000mAh 22.2V 25C LiPo Battery Pack with XT90 Connector
- **Capacity:** 22000mAh
- **Voltage:** 22.2V
- **Discharge Rate:** 25C
- **Weight:** ~1.5-1.8 kg per battery

4. Power Distribution Board (PDB)

- **Model:** Matek Systems PDB-XT90
- **Max Current:** 200A
- **Output Ports:** 5V, 12V
- **Weight:** 15g

5. Multispectral Camera (DIY)

- **Filters:**
 - Near Infrared Filter (700-1000nm) – Hoya R72 Infrared Filter
 - Red Filter (620-750nm) – Schott RG630 Long-Pass Filter + Thorlabs FELH0750/Schott BG40 IR-Cut Filter (Combination)
 - Red Edge Filter (700-750nm) – Schott RG715 Long-Pass Filter + Thorlabs FELH0750/Schott BG40 IR-Cut Filter (Combination)
 - Green Filter (500-600nm) – Wratten 58 Green Filter
- **Use:** Vegetation health monitoring (NDVI, GNDVI, LAI, etc.)

6. Thermal Camera

- **Model:** Waveshare MLX90640
- **Resolution:** 32x24 pixels
- **Interface:** I2C
- **Field of View:** 55°x35°
- **Temperature Range:** -40°C to +300°C

7. RGB Cameras x5

- **Model:** Raspberry Pi Camera Module 3 NoIR
- **Resolution:** 12MP (4608x2592)
- **Interface:** CSI-2
- **Power Consumption:** Low to moderate, depending on usage
- **Sensor:** Sony IMX708
- **Field of View:** 75°
- **Dimensions:** 25x24x11.5 mm
- **Infrared Sensitivity:** Yes

8. Communication Module

- **Model:** RFM95 LoRa Module
- **Range:** 10-15 km (LOS)
- **Frequency:** 868/915 MHz
- **Interface:** SPI

9. Microcontroller

- **Model:** Raspberry Pi 4/5
- **Processor:** Quad-core ARM Cortex-A72 @ 1.5GHz
- **RAM:** 4GB/8GB
- **Interfaces:** USB, GPIO, I2C, SPI, UART
- **Operating System:** Linux (Raspberry Pi OS)

10. Control Algorithm

- **Software:** Ardupilot (Open Source)
- **Customization:** Minor modifications for specific tasks like crop monitoring and fertilizer spraying

Sensors and Peripherals

1. Temperature Sensor

- **Model:** DHT22 (AM2302)
- **Type:** Digital sensor (I2C)
- **Temperature Range:** -40°C to +80°C
- **Humidity Range:** 0-100%

2. Atmospheric Pressure Sensor

- **Model:** BMP280
- **Type:** Barometric sensor (I2C)
- **Pressure Range:** 300-1100 hPa
- **Altitude Resolution:** ±1 meter

3. CO2 Sensor

- **Model:** MH-Z19
- **Type:** NDIR CO2 sensor (UART)
- **Measurement Range:** 0-5000 ppm

4. Ultrasonic Sensor

- **Model:** HC-SR04
- **Range:** 2cm to 400cm
- **Interface:** Digital Trigger & Echo pins

Motors and Propulsion

1. BLDC Motors

- **Model:** 3508 700KV
- **Voltage:** 11.1V-22.2V
- **Thrust:** ~1.2 kg per motor

2. Propellers

- **Model:** Gemfan 15x6
- **Size:** 15 inches
- **Material:** Composite

3. Electronic Speed Controller (ESC)

- **Model:** T-Motor F60A
- **Max Current:** 60A
- **Voltage:** 2S-6S LiPo

4. Sprinklers

- **Model:** TeeJet AIXR 11004-VP
- **Flow Rate:** 0.5-1.0 L/min

Mechanical Components

1. Frame

- **Material:** Carbon Fibre/ Aluminium Alloy
- **Dimensions:** 1000mm - 1200mm
- **Weight:** 1000-1500g

2. Tank

- **Material:** High-Density Polyethylene (HDPE)
- **Capacity:** 10L

Software and Control

1. Ground Station

- **Control Software:** Ardupilot Mission Planner (PC-based)
 - **Communication:** Telemetry link via LoRa/Radio
 - **Features:** Waypoint navigation, live sensor data, automated flight control
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Environmental Data Integration

- **Multispectral Analysis:** NDVI, GNDVI, LAI metrics for vegetation health monitoring using custom multispectral camera setup
 - **Thermal Imaging:** Detection of heat variations for environmental analysis
 - **GPS and Altitude Data:** For precise navigation and altitude holding, integrated with barometric and GPS data
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Endurance and Performance

- **Flight Time:** ~25-35 minutes (depending on payload and weather conditions)
 - **Max Payload:** ~10-12 kg (including sensors, cameras, and liquid tank)
 - **Max Altitude:** 120m (above ground level per regulatory limits)
 - **Range:** 10-15 km (with LoRa communication)
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Applications

- **Precision Agriculture:** Crop health monitoring, nutrient, and pesticide spraying
- **Environmental Monitoring:** Temperature, CO2, and humidity tracking
- **Aerial Mapping:** High-resolution terrain and multispectral imaging