

Chapter 11

Aircraft Performance

Introduction

This chapter discusses the factors that affect aircraft performance, which include the aircraft weight, atmospheric conditions, runway environment, and the fundamental physical laws governing the forces acting on an aircraft.

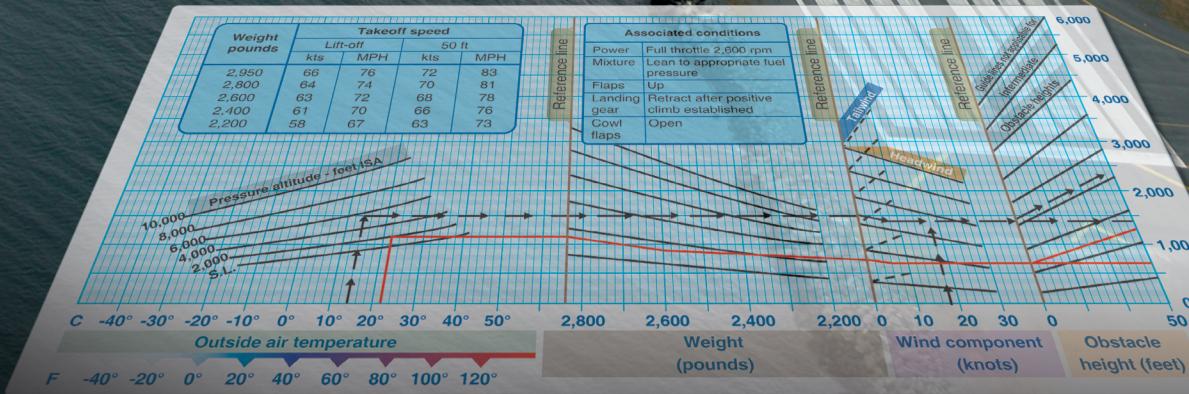
Importance of Performance Data

The performance or operational information section of the Aircraft Flight Manual/Pilot's Operating Handbook (AFM/POH) contains the operating data for the aircraft; that is, the data pertaining to takeoff, climb, range, endurance, descent, and landing. The use of this data in flying operations is mandatory for safe and efficient operation. Considerable knowledge and familiarity of the aircraft can be gained by studying this material.



Conditions		LANDING DISTANCE							
Gross weight lb	Approach speed IAS, MPH	At sea level & 59 °F		At 2,500 ft & 50 °F		At 5,000 ft & 41 °F		At 7,500 ft & 32 °F	
		Ground roll	Total to clear 50 ft OBS	Ground roll	Total to clear 50 ft OBS	Ground roll	Total to clear 50 ft OBS	Ground roll	Total to clear 50 ft OBS
1,600	60	445	1.075	470	1,135	495	1,195	520	1,255

- Note
- Decrease the distances shown by 10% for each 4 knots of headwind.
 - Increase the distance by 10% for each 60 °F temperature increase above standard.
 - For operation on a dry, grass runway, increase distances (both "ground roll" and "total to clear 50 ft obstacle") by 20% of the "total to clear 50 ft obstacle" figure.



It must be emphasized that the manufacturers' information and data furnished in the AFM/POH is not standardized. Some provide the data in tabular form, while others use graphs. In addition, the performance data may be presented on the basis of standard atmospheric conditions, pressure altitude, or density altitude. The performance information in the AFM/POH has little or no value unless the user recognizes those variations and makes the necessary adjustments.

To be able to make practical use of the aircraft's capabilities and limitations, it is essential to understand the significance of the operational data. The pilot must be cognizant of the basis for the performance data, as well as the meanings of the various terms used in expressing performance capabilities and limitations.

Since the characteristics of the atmosphere have a major effect on performance, it is necessary to review two dominant factors—pressure and temperature.

Structure of the Atmosphere

The atmosphere is an envelope of air that surrounds the Earth and rests upon its surface. It is as much a part of the Earth as is land and water. However, air differs from land and water in that it is a mixture of gases. It has mass, weight, and indefinite shape.

Air, like any other fluid, is able to flow and change its shape when subjected to even minute pressures because of the lack of strong molecular cohesion. For example, gas will completely fill any container into which it is placed, expanding or contracting to adjust its shape to the limits of the container.

The atmosphere is composed of 78 percent nitrogen, 21 percent oxygen, and 1 percent other gases, such as argon or helium. Most of the oxygen is contained below 35,000 feet altitude.

Atmospheric Pressure

Though there are various kinds of pressure, pilots are mainly concerned with atmospheric pressure. It is one of the basic factors in weather changes, helps to lift the aircraft, and actuates some of the most important flight instruments in the aircraft. These instruments often include the altimeter, the airspeed indicator (ASI), the vertical speed indicator (VSI), and the manifold pressure gauge.

Though air is very light, it has mass and is affected by the attraction of gravity. Therefore, like any other substance, it has weight; because it has weight, it has force. Since it is a fluid substance, this force is exerted equally in all directions, and its effect on bodies within the air is called pressure. Under standard conditions at sea level, the average pressure

exerted by the weight of the atmosphere is approximately 14.7 pounds per square inch (psi). The density of air has significant effects on the aircraft's performance. As air becomes less dense, it reduces:

- Power, because the engine takes in less air
- Thrust, because the propeller is less efficient in thin air
- Lift, because the thin air exerts less force on the airfoils

The pressure of the atmosphere may vary with time but more importantly, it varies with altitude and temperature. Due to the changing atmospheric pressure, a standard reference was developed. The standard atmosphere at sea level has a surface temperature of 59 degrees Fahrenheit ($^{\circ}\text{F}$) or 15 degrees Celsius ($^{\circ}\text{C}$) and a surface pressure of 29.92 inches of mercury ("Hg) or 1013.2 millibars (mb). [Figure 11-1]

A standard temperature lapse rate is one in which the temperature decreases at the rate of approximately $3.5\ ^{\circ}\text{F}$ or $2\ ^{\circ}\text{C}$ per thousand feet up to 36,000 feet. Above this point, the temperature is considered constant up to 80,000 feet. A standard pressure lapse rate is one in which pressure decreases at a rate of approximately 1 "Hg per 1,000 feet of altitude gain to 10,000 feet. [Figure 11-2] The International Civil Aviation Organization (ICAO) has established this as a worldwide standard, and it is often referred to as International Standard Atmosphere (ISA) or ICAO Standard Atmosphere. Any temperature or pressure that differs from the standard lapse rates is considered nonstandard temperature and pressure. Adjustments for nonstandard temperatures and pressures are provided on the manufacturer's performance charts.

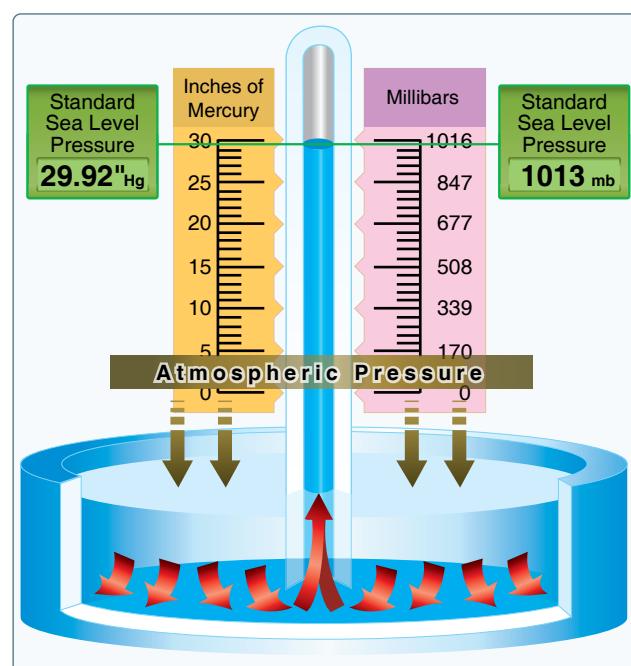


Figure 11-1. Standard sea level pressure.

Altitude (ft)	Pressure ("Hg)	Temperature	
		(°C)	(°F)
0	29.92	15.0	59.0
1,000	28.86	13.0	55.4
2,000	27.82	11.0	51.9
3,000	26.82	9.1	48.3
4,000	25.84	7.1	44.7
5,000	24.89	5.1	41.2
6,000	23.98	3.1	37.6
7,000	23.09	1.1	34.0
8,000	22.22	-0.9	30.5
9,000	21.38	-2.8	26.9
10,000	20.57	-4.8	23.3
11,000	19.79	-6.8	19.8
12,000	19.02	-8.8	16.2
13,000	18.29	-10.8	12.6
14,000	17.57	-12.7	9.1
15,000	16.88	-14.7	5.5
16,000	16.21	-16.7	1.9
17,000	15.56	-18.7	-1.6
18,000	14.94	-20.7	-5.2
19,000	14.33	-22.6	-8.8
20,000	13.74	-24.6	-12.3

Figure 11-2. Properties of standard atmosphere.

Since all aircraft performance is compared and evaluated using the standard atmosphere, all aircraft instruments are calibrated for the standard atmosphere. Thus, certain corrections must apply to the instrumentation, as well as the aircraft performance, if the actual operating conditions do not fit the standard atmosphere. In order to account properly for the nonstandard atmosphere, certain related terms must be defined.

Pressure Altitude

Pressure altitude is the height above the standard datum plane (SDP). The aircraft altimeter is essentially a sensitive barometer calibrated to indicate altitude in the standard atmosphere. If the altimeter is set for 29.92 "Hg SDP, the altitude indicated is the pressure altitude—the altitude in the standard atmosphere corresponding to the sensed pressure.

The SDP is a theoretical level at which the pressure of the atmosphere is 29.92 "Hg and the weight of air is 14.7 psi. As atmospheric pressure changes, the SDP may be below, at, or above sea level. Pressure altitude is important as a basis for determining aircraft performance, as well as for assigning flight levels to aircraft operating at above 18,000 feet.

The pressure altitude can be determined by any of the three following methods:

1. By setting the barometric scale of the altimeter to 29.92 "Hg and reading the indicated altitude,

2. By applying a correction factor to the indicated altitude according to the reported “altimeter setting,” [Figure 11-3]
3. By using a flight computer

Density Altitude

The more appropriate term for correlating aerodynamic performance in the nonstandard atmosphere is density altitude—the altitude in the standard atmosphere corresponding to a particular value of air density.

Density altitude is pressure altitude corrected for nonstandard temperature. As the density of the air increases (lower density altitude), aircraft performance increases. Conversely,

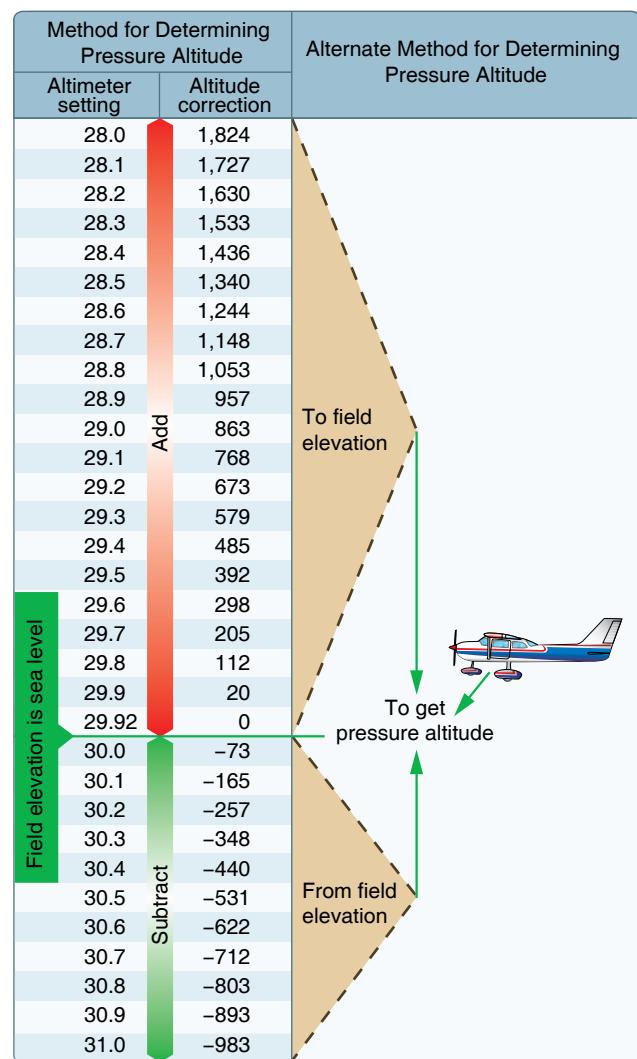


Figure 11-3. Field elevation versus pressure. The aircraft is located on a field that happens to be at sea level. Set the altimeter to the current altimeter setting (29.7). The difference of 205 feet is added to the elevation or a PA of 205 feet.

as air density decreases (higher density altitude), aircraft performance decreases. A decrease in air density means a high density altitude; an increase in air density means a lower density altitude. Density altitude is used in calculating aircraft performance. Under standard atmospheric condition, air at each level in the atmosphere has a specific density; under standard conditions, pressure altitude and density altitude identify the same level. Density altitude, then, is the vertical distance above sea level in the standard atmosphere at which a given density is to be found.

Density altitude is computed using pressure altitude and temperature. Since aircraft performance data at any level is based upon air density under standard day conditions, such performance data apply to air density levels that may not be identical to altimeter indications. Under conditions higher or lower than standard, these levels cannot be determined directly from the altimeter.

Density altitude is determined by first finding pressure altitude and then correcting this altitude for nonstandard temperature variations. Since density varies directly with pressure, and inversely with temperature, a given pressure altitude may exist for a wide range of temperature by allowing the density to vary. However, a known density occurs for any one temperature and pressure altitude. The density of the air, of course, has a pronounced effect on aircraft and engine performance. Regardless of the actual altitude at which the aircraft is operating, it will perform as though it were operating at an altitude equal to the existing density altitude.

For example, when set at 29.92 "Hg, the altimeter may indicate a pressure altitude of 5,000 feet. According to the AFM/POH, the ground run on takeoff may require a distance of 790 feet under standard temperature conditions. However, if the temperature is 20 °C above standard, the expansion of air raises the density level. Using temperature correction data from tables or graphs, or by deriving the density altitude with a computer, it may be found that the density level is above 7,000 feet, and the ground run may be closer to 1,000 feet.

Air density is affected by changes in altitude, temperature, and humidity. High density altitude refers to thin air while low density altitude refers to dense air. The conditions that result in a high density altitude are high elevations, low atmospheric pressures, high temperatures, high humidity, or some combination of these factors. Lower elevations, high atmospheric pressure, low temperatures, and low humidity are more indicative of low density altitude.

Using a flight computer, density altitude can be computed by inputting the pressure altitude and outside air temperature at

flight level. Density altitude can also be determined by referring to the table and chart in *Figures 11-3 and 11-4* respectively.

Effects of Pressure on Density

Since air is a gas, it can be compressed or expanded. When air is compressed, a greater amount of air can occupy a given volume. Conversely, when pressure on a given volume of air is decreased, the air expands and occupies a greater space. That is, the original column of air at a lower pressure

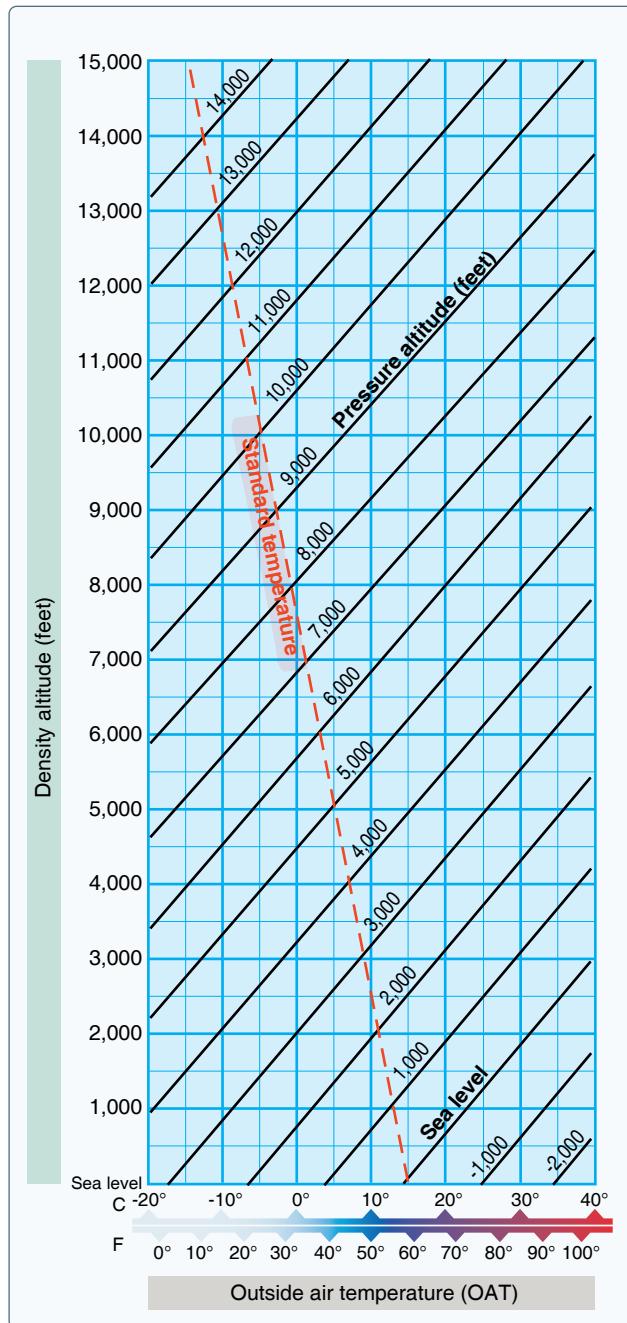


Figure 11-4. Density altitude chart.

contains a smaller mass of air. In other words, the density is decreased. In fact, density is directly proportional to pressure. If the pressure is doubled, the density is doubled, and if the pressure is lowered, so is the density. This statement is true only at a constant temperature.

Effects of Temperature on Density

Increasing the temperature of a substance decreases its density. Conversely, decreasing the temperature increases the density. Thus, the density of air varies inversely with temperature. This statement is true only at a constant pressure.

In the atmosphere, both temperature and pressure decrease with altitude and have conflicting effects upon density. However, the fairly rapid drop in pressure as altitude is increased usually has the dominant effect. Hence, pilots can expect the density to decrease with altitude.

Effects of Humidity (Moisture) on Density

The preceding paragraphs are based on the presupposition of perfectly dry air. In reality, it is never completely dry. The small amount of water vapor suspended in the atmosphere may be negligible under certain conditions, but in other conditions humidity may become an important factor in the performance of an aircraft. Water vapor is lighter than air; consequently, moist air is lighter than dry air. Therefore, as the water content of the air increases, the air becomes less dense, increasing density altitude and decreasing performance. It is lightest or least dense when, in a given set of conditions, it contains the maximum amount of water vapor.

Humidity, also called relative humidity, refers to the amount of water vapor contained in the atmosphere and is expressed as a percentage of the maximum amount of water vapor the air can hold. This amount varies with the temperature; warm air can hold more water vapor, while colder air can hold less. Perfectly dry air that contains no water vapor has a relative humidity of zero percent, while saturated air that cannot hold any more water vapor has a relative humidity of 100 percent. Humidity alone is usually not considered an essential factor in calculating density altitude and aircraft performance; however, it does contribute.

The higher the temperature, the greater amount of water vapor that the air can hold. When comparing two separate air masses, the first warm and moist (both qualities making air lighter) and the second cold and dry (both qualities making it heavier), the first must be less dense than the second. Pressure, temperature, and humidity have a great influence on aircraft performance because of their effect upon density. There is no rule-of-thumb or chart used to compute the effects of humidity on density altitude, but it must be taken into

consideration. Expect a decrease in overall performance in high humidity conditions.

Performance

Performance is a term used to describe the ability of an aircraft to accomplish certain things that make it useful for certain purposes. For example, the ability of an aircraft to land and take off in a very short distance is an important factor to the pilot who operates in and out of short, unimproved airfields. The ability to carry heavy loads, fly at high altitudes at fast speeds, and/or travel long distances is essential for the performance of airline and executive type aircraft.

The primary factors most affected by performance are the takeoff and landing distance, rate of climb, ceiling, payload, range, speed, maneuverability, stability, and fuel economy. Some of these factors are often directly opposed: for example, high speed versus short landing distance, long range versus great payload, and high rate of climb versus fuel economy. It is the preeminence of one or more of these factors that dictates differences between aircraft and explains the high degree of specialization found in modern aircraft.

The various items of aircraft performance result from the combination of aircraft and powerplant characteristics. The aerodynamic characteristics of the aircraft generally define the power and thrust requirements at various conditions of flight, while powerplant characteristics generally define the power and thrust available at various conditions of flight. The matching of the aerodynamic configuration with the powerplant is accomplished by the manufacturer to provide maximum performance at the specific design condition (e.g., range, endurance, and climb).

Straight-and-Level Flight

All of the principal components of flight performance involve steady-state flight conditions and equilibrium of the aircraft. For the aircraft to remain in steady, level flight, equilibrium must be obtained by a lift equal to the aircraft weight and a powerplant thrust equal to the aircraft drag. Thus, the aircraft drag defines the thrust required to maintain steady, level flight. As presented in Chapter 4, Aerodynamics of Flight, all parts of an aircraft contribute to the drag, either induced (from lifting surfaces) or parasite drag.

While parasite drag predominates at high speed, induced drag predominates at low speed. [Figure 11-5] For example, if an aircraft in a steady flight condition at 100 knots is then accelerated to 200 knots, the parasite drag becomes four times as great, but the power required to overcome that drag is eight times the original value. Conversely, when the

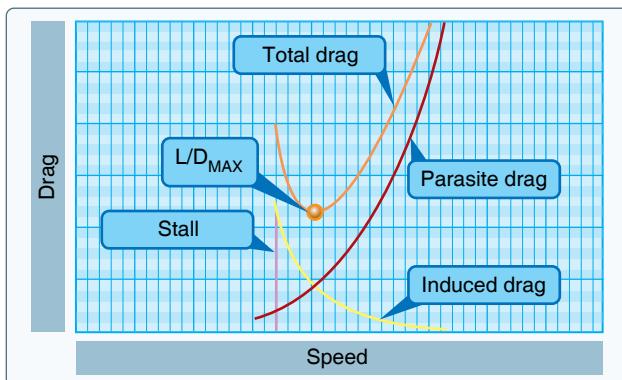


Figure 11-5. Drag versus speed.

aircraft is operated in steady, level flight at twice as great a speed, the induced drag is one-fourth the original value, and the power required to overcome that drag is only one-half the original value.

When an aircraft is in steady, level flight, the condition of equilibrium must prevail. The unaccelerated condition of flight is achieved with the aircraft trimmed for lift equal to weight and the powerplant set for a thrust to equal the aircraft drag.

The maximum level flight speed for the aircraft is obtained when the power or thrust required equals the maximum power or thrust available from the powerplant. [Figure 11-6] The minimum level flight airspeed is not usually defined by thrust or power requirement since conditions of stall or stability and control problems generally predominate.

Climb Performance

If an aircraft is to move, fly, and perform, work must act upon it. Work involves force moving the aircraft. The aircraft acquires mechanical energy when it moves. Mechanical

energy comes in two forms: (1) Kinetic Energy (KE), the energy of speed; (2) Potential Energy (PE), the stored energy of position.

Aircraft motion (KE) is described by its velocity (airspeed). Aircraft position (PE) is described by its height (altitude). Both KE and PE are directly proportional to the object's mass. KE is directly proportional to the square of the object's velocity (airspeed). PE is directly proportional to the object's height (altitude). The formulas below summarize these energy relationships:

$$KE = \frac{1}{2} \times m \times v^2$$

m = object mass
 v = object velocity

$$PE = m \times g \times h$$

m = object mass
 g = gravity field strength
 h = object height

We sometimes use the terms "power" and "thrust" interchangeably when discussing climb performance. This erroneously implies the terms are synonymous. It is important to distinguish between these terms. Thrust is a force or pressure exerted on an object. Thrust is measured in pounds (lb) or newtons (N). Power, however, is a measurement of the rate of performing work or transferring energy (KE and PE). Power is typically measured in horsepower (hp) or kilowatts (kw). We can think of power as the motion (KE and PE) a force (thrust) creates when exerted on an object over a period of time.

Positive climb performance occurs when an aircraft gains PE by increasing altitude. Two basic factors, or a combination of the two factors, contribute to positive climb performance in most aircraft:

1. The aircraft climbs (gains PE) using excess power above that required to maintain level flight, or
2. The aircraft climbs by converting airspeed (KE) to altitude (PE).

As an example of factor 1 above, an aircraft with an engine capable of producing 200 horsepower (at a given altitude) is using only 130 horsepower to maintain level flight at that altitude. This leaves 70 horsepower available to climb. The pilot holds airspeed constant and increases power to perform the climb.

As an example of factor 2, an aircraft is flying level at 120 knots. The pilot leaves the engine power setting constant but applies other control inputs to perform a climb. The climb, sometimes called a zoom climb, converts the airspeed (KE)

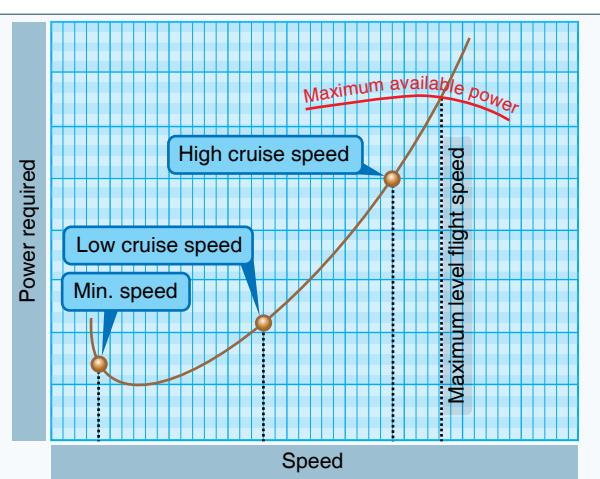


Figure 11-6. Power versus speed.

to altitude (PE); the airspeed decreases to something less than 120 knots as the altitude increases.

There are two primary reasons to evaluate climb performance. First, aircraft must climb over obstacles to avoid hitting them. Second, climbing to higher altitudes can provide better weather, fuel economy, and other benefits. Maximum Angle of Climb (AOC), obtained at V_X , may provide climb performance to ensure an aircraft will clear obstacles. Maximum Rate of Climb (ROC), obtained at V_Y , provides climb performance to achieve the greatest altitude gain over time. Maximum ROC may not be sufficient to avoid obstacles in some situations, while maximum AOC may be sufficient to avoid the same obstacles. [Figure 11-7]

Angle of Climb (AOC)

AOC is a comparison of altitude gained relative to distance traveled. AOC is the inclination (angle) of the flight path. For maximum AOC performance, a pilot flies the aircraft at V_X

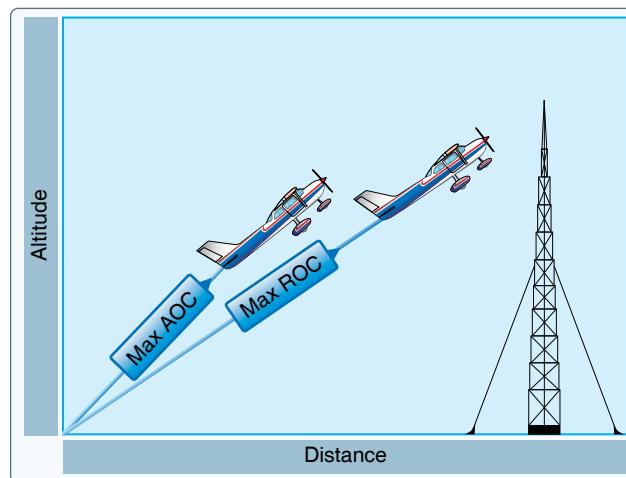


Figure 11-7. Maximum angle of climb (AOC) versus maximum rate of climb (ROC).

so as to achieve maximum altitude increase with minimum horizontal travel over the ground. A good use of maximum AOC is when taking off from a short airfield surrounded by high obstacles, such as trees or power lines. The objective is to gain sufficient altitude to clear the obstacle while traveling the least horizontal distance over the surface.

One method to climb (have positive AOC performance) is to have excess thrust available. Essentially, the greater the force that pushes the aircraft upward, the steeper it can climb. Maximum AOC occurs at the airspeed and angle of attack (AOA) combination which allows the maximum excess thrust. The airspeed and AOA combination where excess thrust exists varies amongst aircraft types. As an example, Figure 11-8 provides a comparison between jet and propeller airplanes as to where maximum excess thrust (for maximum AOC) occurs. In a jet, maximum excess thrust normally occurs at the airspeed where the thrust required is at a minimum (approximately L/D_{MAX}). In a propeller airplane, maximum excess thrust normally occurs at an airspeed below L/D_{MAX} and frequently just above stall speed.

Rate of Climb (ROC)

ROC is a comparison of altitude gained relative to the time needed to reach that altitude. ROC is simply the vertical component of the aircraft's flight path velocity vector. For maximum ROC performance, a pilot flies the aircraft at V_Y so as to achieve a maximum gain in altitude over a given period of time.

Maximum ROC expedites a climb to an assigned altitude. This gains the greatest vertical distance over a period of time. For example, in a maximum AOC profile, a certain aircraft takes 30 seconds to reach 1,000 feet AGL, but covers only 3,000 feet over the ground. By comparison, using its maximum ROC profile, the same aircraft climbs

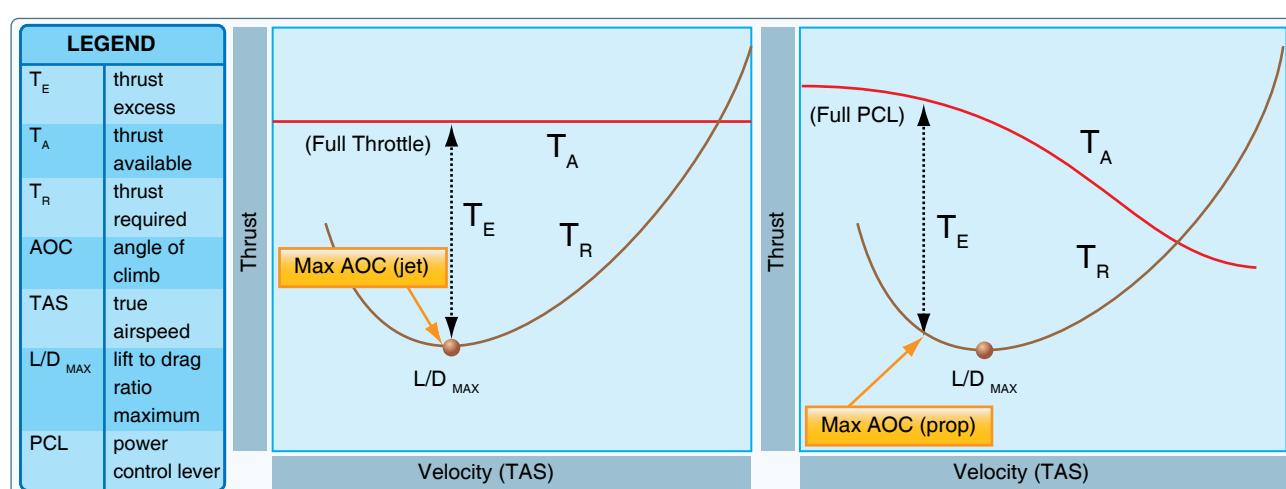


Figure 11-8. Comparison of maximum AOC between jet and propeller airplanes.

to 1,500 feet in 30 seconds but covers 6,000 feet across the ground. Note that both ROC and AOC maximum climb profiles use the aircraft's maximum throttle setting. Any differences between max ROC and max AOC lie primarily in the velocity (airspeed) and AOA combination the aircraft manual specifies. [Figure 11-7]

ROC performance depends upon excess power. Since climbing is work and power is the rate of performing work, a pilot can increase the climb rate by using any power not used to maintain level flight. Maximum ROC occurs at an airspeed and AOA combination that produces the maximum excess power. Therefore, maximum ROC for a typical jet airplane occurs at an airspeed greater than L/D_{MAX} and at an AOA less than L/D_{MAX} AOA. In contrast, maximum ROC for a typical propeller airplane occurs at an airspeed and AOA combination closer to L/D_{MAX} . [Figure 11-9]

Climb Performance Factors

Since weight, altitude and configuration changes affect excess thrust and power, they also affect climb performance. Climb performance is directly dependent upon the ability to produce either excess thrust or excess power. Earlier in the book it was shown that an increase in weight, an increase in altitude, lowering the landing gear, or lowering the flaps all decrease both excess thrust and excess power for all aircraft. Therefore, maximum AOC and maximum ROC performance decreases under any of these conditions.

Weight has a very pronounced effect on aircraft performance. If weight is added to an aircraft, it must fly at a higher AOA to maintain a given altitude and speed. This increases the induced drag of the wings, as well as the parasite drag of the aircraft. Increased drag means that additional thrust is needed to overcome it, which in turn means that less reserve thrust is available for climbing. Aircraft designers go to great lengths

to minimize the weight, since it has such a marked effect on the factors pertaining to performance.

A change in an aircraft's weight produces a twofold effect on climb performance. First, a change in weight changes the drag and the power required. This alters the reserve power available, which in turn, affects both the climb angle and the climb rate. Secondly, an increase in weight reduces the maximum ROC, but the aircraft must be operated at a higher climb speed to achieve the smaller peak climb rate.

An increase in altitude also increases the power required and decreases the power available. Therefore, the climb performance of an aircraft diminishes with altitude. The speeds for maximum ROC, maximum AOC, and maximum and minimum level flight airspeeds vary with altitude. As altitude is increased, these various speeds finally converge at the absolute ceiling of the aircraft. At the absolute ceiling, there is no excess of power and only one speed allows steady, level flight. Consequently, the absolute ceiling of an aircraft produces zero ROC. The service ceiling is the altitude at which the aircraft is unable to climb at a rate greater than 100 feet per minute (fpm). Usually, these specific performance reference points are provided for the aircraft at a specific design configuration. [Figure 11-10]

The terms "power loading," "wing loading," "blade loading," and "disk loading" are commonly used in reference to performance. Power loading is expressed in pounds per horsepower and is obtained by dividing the total weight of the aircraft by the rated horsepower of the engine. It is a significant factor in an aircraft's takeoff and climb capabilities. Wing loading is expressed in pounds per square foot and is obtained by dividing the total weight of an airplane in pounds by the wing area (including ailerons) in square feet. It is the airplane's wing loading that determines the landing

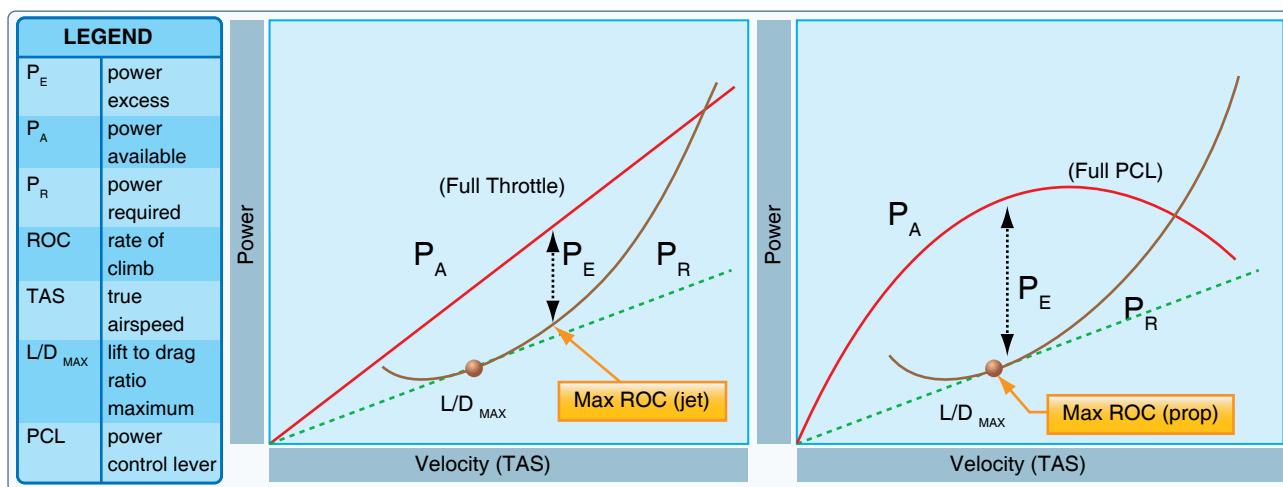


Figure 11-9. Comparison of maximum ROC between jet and propeller airplanes.

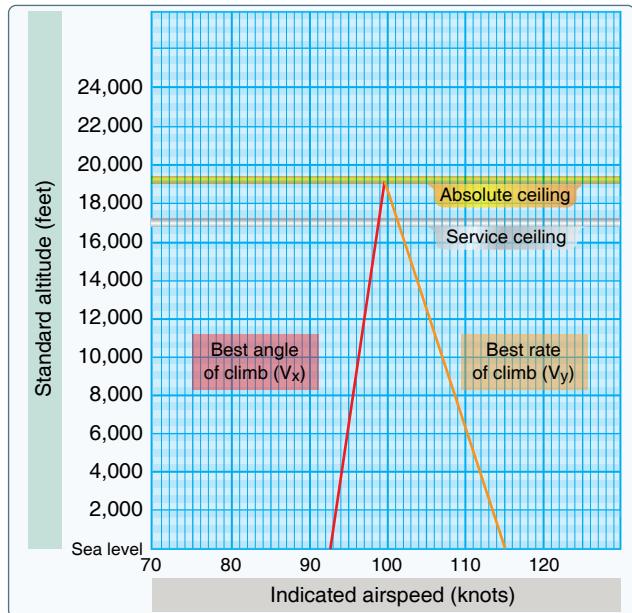


Figure 11-10. Absolute and service ceiling.

speed. Blade loading is expressed in pounds per square foot and is obtained by dividing the total weight of a helicopter by the area of the rotor blades. Blade loading is not to be confused with disk loading, which is the total weight of a helicopter divided by the area of the disk swept by the rotor blades.

Range Performance

The ability of an aircraft to convert fuel energy into flying distance is one of the most important items of aircraft performance. In flying operations, the problem of efficient range operation of an aircraft appears in two general forms:

1. To extract the maximum flying distance from a given fuel load
2. To fly a specified distance with a minimum expenditure of fuel

A common element for each of these operating problems is the specific range; that is, nautical miles (NM) of flying distance versus the amount of fuel consumed. Range must be clearly distinguished from the item of endurance. Range involves consideration of flying distance, while endurance involves consideration of flying time. Thus, it is appropriate to define a separate term, specific endurance.

$$\text{specific endurance} = \frac{\text{flight hours}}{\text{pounds of fuel}}$$

or

$$\text{specific endurance} = \frac{\text{flight hours/hour}}{\text{pounds of fuel/hour}}$$

or

$$\text{specific endurance} = \frac{1}{\text{fuel flow}}$$

Fuel flow can be defined in either pounds or gallons. If maximum endurance is desired, the flight condition must provide a minimum fuel flow. In *Figure 11-11* at point A, the airspeed is low and fuel flow is high. This would occur during ground operations or when taking off and climbing. As airspeed is increased, power requirements decrease due to aerodynamic factors, and fuel flow decreases to point B. This is the point of maximum endurance. Beyond this point, increases in airspeed come at a cost. Airspeed increases require additional power and fuel flow increases with additional power.

Cruise flight operations for maximum range should be conducted so that the aircraft obtains maximum specific range throughout the flight. The specific range can be defined by the following relationship.

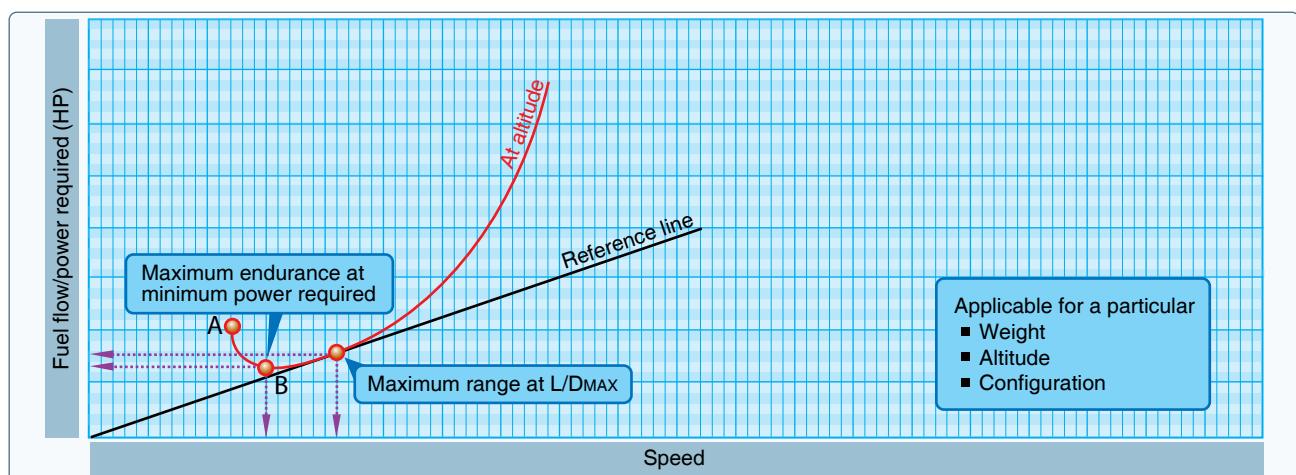


Figure 11-11. Airspeed for maximum endurance.

$$\text{specific range} = \frac{\text{NM}}{\text{pounds of fuel}}$$

or

$$\text{specific range} = \frac{\text{NM/hour}}{\text{pounds of fuel/hour}}$$

or

$$\text{specific range} = \frac{\text{knots}}{\text{fuel flow}}$$

If maximum specific range is desired, the flight condition must provide a maximum of speed per fuel flow. While the peak value of specific range would provide maximum range operation, long-range cruise operation is generally recommended at a slightly higher airspeed. Most long-range cruise operations are conducted at the flight condition that provides 99 percent of the absolute maximum specific range. The advantage of such operation is that one percent of range is traded for three to five percent higher cruise speed. Since the higher cruise speed has a great number of advantages, the small sacrifice of range is a fair bargain. The values of specific range versus speed are affected by three principal variables:

1. Aircraft gross weight
2. Altitude
3. The external aerodynamic configuration of the aircraft.

These are the source of range and endurance operating data included in the performance section of the AFM/POH.

Cruise control of an aircraft implies that the aircraft is operated to maintain the recommended long-range cruise condition throughout the flight. Since fuel is consumed during cruise, the gross weight of the aircraft varies and optimum airspeed, altitude, and power setting can also vary. Cruise control means the control of the optimum airspeed, altitude, and power setting to maintain the 99 percent maximum specific range condition. At the beginning of cruise flight, the relatively high initial weight of the aircraft requires specific values of airspeed, altitude, and power setting to produce the recommended cruise condition. As fuel is consumed and the aircraft's gross weight decreases, the optimum airspeed and power setting may decrease, or the optimum altitude may increase. In addition, the optimum specific range increases. Therefore, the pilot must provide the proper cruise control procedure to ensure that optimum conditions are maintained.

Total range is dependent on both fuel available and specific range. When range and economy of operation are the principal goals, the pilot must ensure that the aircraft is operated at the

recommended long-range cruise condition. By this procedure, the aircraft is capable of its maximum design-operating radius or can achieve flight distances less than the maximum with a maximum of fuel reserve at the destination.

A propeller-driven aircraft combines the propeller with the reciprocating engine for propulsive power. Fuel flow is determined mainly by the shaft power put into the propeller rather than thrust. Thus, the fuel flow can be related directly to the power required to maintain the aircraft in steady, level flight, and on performance charts power can be substituted for fuel flow. This fact allows for the determination of range through analysis of power required versus speed.

The maximum endurance condition would be obtained at the point of minimum power required since this would require the lowest fuel flow to keep the airplane in steady, level flight. Maximum range condition would occur where the ratio of speed to power required is greatest. [Figure 11-11]

The maximum range condition is obtained at maximum lift/drag ratio (L/D_{MAX}), and it is important to note that for a given aircraft configuration, the L/D_{MAX} occurs at a particular AOA and lift coefficient and is unaffected by weight or altitude. A variation in weight alters the values of airspeed and power required to obtain the L/D_{MAX} . [Figure 11-12] Different theories exist on how to achieve max range when there is a headwind or tailwind present. Many say that speeding up in a headwind or slowing down in a tail wind helps to achieve max range. While this theory may be true in a lot of cases, it is not always true as there are different variables to every situation. Each aircraft configuration is different, and there is not a rule of thumb that encompasses all of them as to how to achieve the max range.

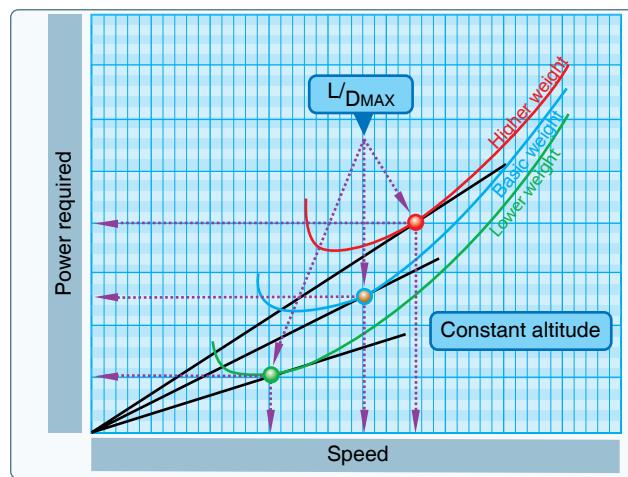


Figure 11-12. Effect of weight.

The variations of speed and power required must be monitored by the pilot as part of the cruise control procedure to maintain the L/D_{MAX} . When the aircraft's fuel weight is a small part of the gross weight and the aircraft's range is small, the cruise control procedure can be simplified to essentially maintaining a constant speed and power setting throughout the time of cruise flight. However, a long-range aircraft has a fuel weight that is a considerable part of the gross weight, and cruise control procedures must employ scheduled airspeed and power changes to maintain optimum range conditions.

The effect of altitude on the range of a propeller-driven aircraft is illustrated in *Figure 11-13*. A flight conducted at high altitude has a greater true airspeed (TAS), and the power required is proportionately greater than when conducted at sea level. The drag of the aircraft at altitude is the same as the drag at sea level, but the higher TAS causes a proportionately greater power required.

NOTE: The straight line that is tangent to the sea level power curve is also tangent to the altitude power curve.

The effect of altitude on specific range can also be appreciated from the previous relationships. If a change in altitude causes identical changes in speed and power required, the proportion of speed to power required would be unchanged. The fact implies that the specific range of a propeller-driven aircraft would be unaffected by altitude. Actually, this is true to the extent that specific fuel consumption and propeller efficiency are the principal factors that could cause a variation of specific range with altitude. If compressibility effects are negligible, any variation of specific range with altitude is strictly a function of engine/propeller performance.

An aircraft equipped with a reciprocating engine experiences very little, if any, variation of specific range up to its absolute altitude. There is negligible variation of brake

specific fuel consumption for values of brake horsepower below the maximum cruise power rating of the engine that is the lean range of engine operation. Thus, an increase in altitude produces a decrease in specific range only when the increased power requirement exceeds the maximum cruise power rating of the engine. One advantage of supercharging is that the cruise power may be maintained at high altitude, and the aircraft may achieve the range at high altitude with the corresponding increase in TAS. The principal differences in the high altitude cruise and low altitude cruise are the TAS and climb fuel requirements.

Region of Reversed Command

The aerodynamic properties of an aircraft generally determine the power requirements at various conditions of flight, while the powerplant capabilities generally determine the power available at various conditions of flight. When an aircraft is in steady, level flight, a condition of equilibrium must prevail. An unaccelerated condition of flight is achieved when lift equals weight, and the powerplant is set for thrust equal to drag. The power required to achieve equilibrium in constant-altitude flight at various airspeeds is depicted on a power required curve. The power required curve illustrates the fact that at low airspeeds near the stall or minimum controllable airspeed, the power setting required for steady, level flight is quite high.

Flight in the region of normal command means that while holding a constant altitude, a higher airspeed requires a higher power setting and a lower airspeed requires a lower power setting. The majority of aircraft flying (climb, cruise, and maneuvers) is conducted in the region of normal command.

Flight in the region of reversed command means flight in which a higher airspeed requires a lower power setting and a lower airspeed requires a higher power setting to hold altitude. It does not imply that a decrease in power produces lower airspeed. The region of reversed command is encountered in the low speed phases of flight. Flight speeds below the speed for maximum endurance (lowest point on the power curve) require higher power settings with a decrease in airspeed. Since the need to increase the required power setting with decreased speed is contrary to the normal command of flight, the regime of flight speeds between the speed for minimum required power setting and the stall speed (or minimum control speed) is termed the region of reversed command. In the region of reversed command, a decrease in airspeed must be accompanied by an increased power setting in order to maintain steady flight.

Figure 11-14 shows the maximum power available as a curved line. Lower power settings, such as cruise power, would also appear in a similar curve. The lowest point on

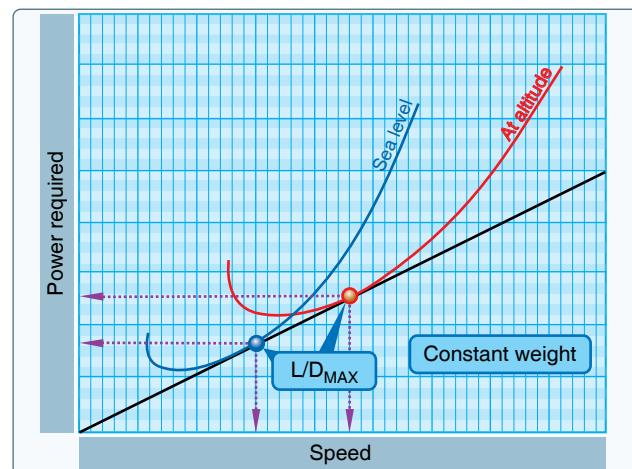


Figure 11-13. Effect of altitude on range.

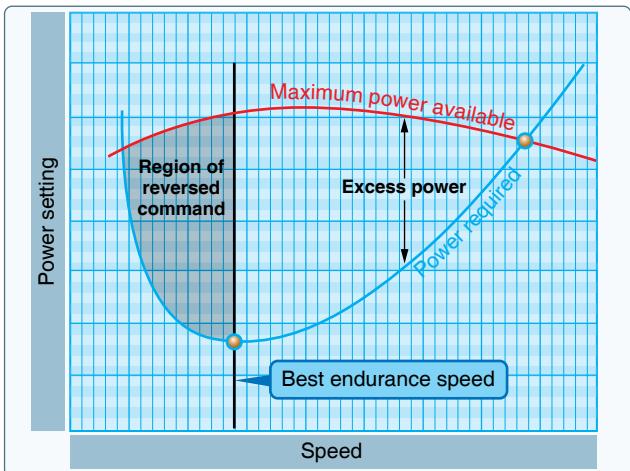


Figure 11-14. Power required curve.

the power required curve represents the speed at which the lowest brake horsepower sustains level flight. This is termed the best endurance airspeed.

An airplane performing a low airspeed, high pitch attitude power approach for a short-field landing is an example of operating in the region of reversed command. If an unacceptably high sink rate should develop, it may be possible for the pilot to reduce or stop the descent by applying power. But without further use of power, the airplane would probably stall or be incapable of flaring for the landing. Merely lowering the nose of the airplane to regain flying speed in this situation, without the use of power, would result in a rapid sink rate and corresponding loss of altitude.

If during a soft-field takeoff and climb, for example, the pilot attempts to climb out of ground effect without first attaining normal climb pitch attitude and airspeed, the airplane may inadvertently enter the region of reversed command at a dangerously low altitude. Even with full power, the airplane may be incapable of climbing or even maintaining altitude. The pilot's only recourse in this situation is to lower the pitch attitude in order to increase airspeed, which inevitably results in a loss of altitude.

Airplane pilots must give particular attention to precise control of airspeed when operating in the low flight speeds of the region of reversed command.

Takeoff and Landing Performance

The majority of pilot-caused aircraft accidents occur during the takeoff and landing phase of flight. Because of this fact, the pilot must be familiar with all the variables that influence the takeoff and landing performance of an aircraft and must strive for exacting, professional procedures of operation during these phases of flight.

Takeoff and landing performance is a condition of accelerated and decelerated motion. For instance, during takeoff an aircraft starts at zero speed and accelerates to the takeoff speed to become airborne. During landing, the aircraft touches down at the landing speed and decelerates to zero speed. The important factors of takeoff or landing performance are:

- The takeoff or landing speed is generally a function of the stall speed or minimum flying speed.
- The rate of acceleration/deceleration during the takeoff or landing roll. The speed (acceleration and deceleration) experienced by any object varies directly with the imbalance of force and inversely with the mass of the object. An airplane on the runway moving at 75 knots has four times the energy it has traveling at 37 knots. Thus, an airplane requires four times as much distance to stop as required at half the speed.
- The takeoff or landing roll distance is a function of both acceleration/deceleration and speed.

Runway Surface and Gradient

Runway conditions affect takeoff and landing performance. Typically, performance chart information assumes paved, level, smooth, and dry runway surfaces. Since no two runways are alike, the runway surface differs from one runway to another, as does the runway gradient or slope. [Figure 11-15]

Runway surfaces vary widely from one airport to another. The runway surface encountered may be concrete, asphalt, gravel, dirt, or grass. The runway surface for a specific airport is noted in the Chart Supplement U.S. (formerly Airport/Facility Directory). Any surface that is not hard and smooth increases the ground roll during takeoff. This is due to the inability of the tires to roll smoothly along the runway. Tires can sink into soft, grassy, or muddy runways. Potholes or other ruts in the pavement can be the cause of poor tire movement along the runway. Obstructions such as mud, snow, or standing water reduce the airplane's acceleration down the runway. Although muddy and wet surface conditions can reduce friction between the runway and the tires, they can also act as obstructions and reduce the landing distance. [Figure 11-16] Braking effectiveness is another consideration when dealing with various runway types. The condition of the surface affects the braking ability of the aircraft.

The amount of power that is applied to the brakes without skidding the tires is referred to as braking effectiveness. Ensure that runways are adequate in length for takeoff acceleration and landing deceleration when less than ideal surface conditions are being reported.

TAKEOFF DISTANCE MAXIMUM WEIGHT 3800 LBS

CONDITIONS:

Flaps 10°
2850 RPM, Full Throttle and Mixture Set at Placard Fuel Flow Prior to Brake Release
Cowl Flaps Open
Paved, Level, Dry Runway
Zero Wind

SHORT FIELD

MIXTURE SETTING	
PRESS ALT	PPH
S.L.	144
2000	138
4000	132
6000	126
8000	120

NOTES:

1. Short field technique as specified in Section 4.
2. Landing gear extended until takeoff obstacle is cleared.
3. Where distance value has been deleted, climb performance after lift-off is less than 150 fpm. Rate of climb is based on landing gear extended and flaps 10° at takeoff speed.
4. Decrease distances 10% for each 10 knots headwind. For operation with tailwinds up to 10 knots, increase distances by 10% for each 2.5 knots.
5. For operation on a dry, grass runway, increase distances by 15% of the "ground roll" figure.

WEIGHT LBS	TAKEOFF SPEED KIAS	PRESS ALT FT	0°C		10°C		20°C		30°C		40°C	
			LIFT	AT	GRND	TOTAL TO CLEAR						

Figure 11-15. Takeoff distance chart.

The gradient or slope of the runway is the amount of change in runway height over the length of the runway. The gradient is expressed as a percentage, such as a 3 percent gradient. This means that for every 100 feet of runway length, the runway height changes by 3 feet. A positive gradient indicates the runway height increases, and a negative gradient indicates the runway decreases in height. An upsloping runway impedes acceleration and results in a longer ground run during takeoff. However, landing on an upsloping runway typically reduces the landing roll. A downsloping runway aids in acceleration on takeoff resulting in shorter takeoff distances. The opposite is true when landing, as landing on a downsloping runway increases landing distances. Runway slope information is contained in the Chart Supplement U.S. (formerly Airport/Facility Directory). [Figure 11-17]

Water on the Runway and Dynamic Hydroplaning

Water on the runways reduces the friction between the tires and the ground and can reduce braking effectiveness. The ability to brake can be completely lost when the tires are hydroplaning because a layer of water separates the tires from the runway surface. This is also true of braking effectiveness when runways are covered in ice.

When the runway is wet, the pilot may be confronted with dynamic hydroplaning. Dynamic hydroplaning is a condition in which the aircraft tires ride on a thin sheet of water rather than on the runway's surface. Because hydroplaning wheels are not touching the runway, braking and directional control are almost nil. To help minimize dynamic hydroplaning, some runways are grooved to help drain off water; most runways are not.



Figure 11-16. An aircraft's performance during takeoff depends greatly on the runway surface.

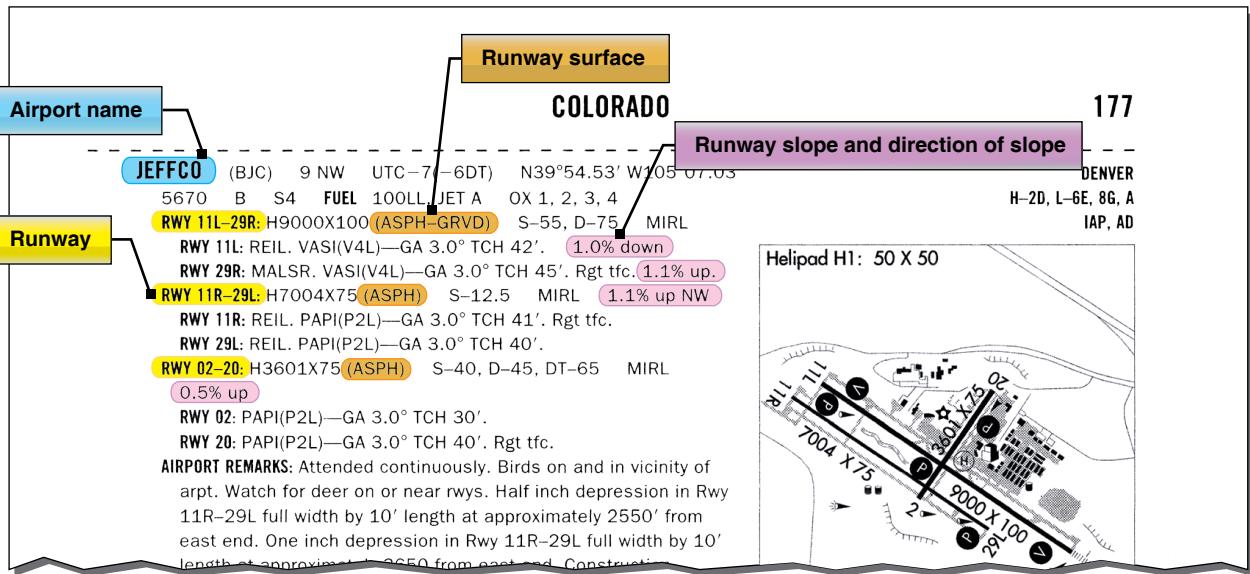


Figure 11-17. Chart Supplement U.S. (formerly Airport/Facility Directory) information.

Tire pressure is a factor in dynamic hydroplaning. Using the simple formula in *Figure 11-18*, a pilot can calculate the minimum speed, in knots, at which hydroplaning begins. In plain language, the minimum hydroplaning speed is determined by multiplying the square root of the main gear tire pressure in psi by nine. For example, if the main gear tire pressure is at 36 psi, the aircraft would begin hydroplaning at 54 knots.

Landing at higher than recommended touchdown speeds exposes the aircraft to a greater potential for hydroplaning. And once hydroplaning starts, it can continue well below the minimum initial hydroplaning speed.

On wet runways, directional control can be maximized by landing into the wind. Abrupt control inputs should be avoided. When the runway is wet, anticipate braking problems

well before landing and be prepared for hydroplaning. Opt for a suitable runway most aligned with the wind. Mechanical braking may be ineffective, so aerodynamic braking should be used to its fullest advantage.

Takeoff Performance

The minimum takeoff distance is of primary interest in the operation of any aircraft because it defines the runway requirements. The minimum takeoff distance is obtained by taking off at some minimum safe speed that allows sufficient margin above stall and provides satisfactory control and initial ROC. Generally, the lift-off speed is some fixed percentage of the stall speed or minimum control speed for the aircraft in the takeoff configuration. As such, the lift-off is accomplished at some particular value of lift coefficient and AOA. Depending on the aircraft characteristics, the lift-off speed is anywhere from 1.05 to 1.25 times the stall speed or minimum control speed.

To obtain minimum takeoff distance at the specific lift-off speed, the forces that act on the aircraft must provide the maximum acceleration during the takeoff roll. The various forces acting on the aircraft may or may not be under the control of the pilot, and various procedures may be necessary in certain aircraft to maintain takeoff acceleration at the highest value.

The powerplant thrust is the principal force to provide the acceleration and, for minimum takeoff distance, the output thrust should be at a maximum. Lift and drag are produced as soon as the aircraft has speed, and the values of lift and drag depend on the AOA and dynamic pressure.

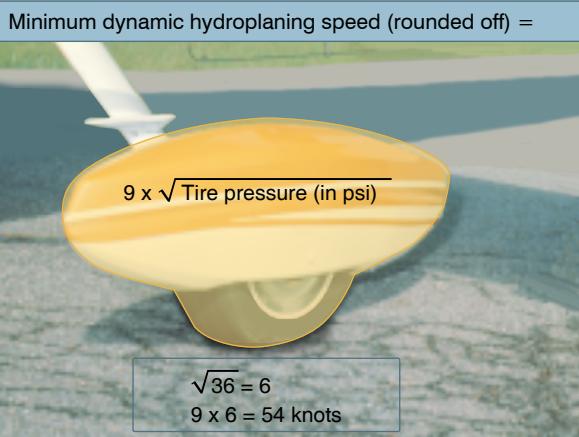


Figure 11-18. Tire pressure.

As discussed in Chapter 6, engine pressure ratio (EPR) is the ratio between exhaust pressure (jet blast) and inlet (static) pressure on a turbo jet or turbo fan engine. An EPR gauge tells the pilot how much power the engines are generating. The higher the EPR, the higher the engine thrust. EPR is used to avoid over-boosting an engine and to set takeoff and go around power if needed. This information is important to know before taking off as it helps determine the performance of the aircraft.

In addition to the important factors of proper procedures, many other variables affect the takeoff performance of an aircraft. Any item that alters the takeoff speed or acceleration rate during the takeoff roll affects the takeoff distance.

For example, the effect of gross weight on takeoff distance is significant, and proper consideration of this item must be made in predicting the aircraft's takeoff distance. Increased gross weight can be considered to produce a threefold effect on takeoff performance:

1. Higher lift-off speed
2. Greater mass to accelerate
3. Increased retarding force (drag and ground friction)

If the gross weight increases, a greater speed is necessary to produce the greater lift necessary to get the aircraft airborne at the takeoff lift coefficient. As an example of the effect of a change in gross weight, a 21 percent increase in takeoff weight requires a 10 percent increase in lift-off speed to support the greater weight.

A change in gross weight changes the net accelerating force and changes the mass that is being accelerated. If the aircraft has a relatively high thrust-to-weight ratio, the change in the net accelerating force is slight and the principal effect on acceleration is due to the change in mass.

For example, a 10 percent increase in takeoff gross weight would cause:

- A 5 percent increase in takeoff velocity
- At least a 9 percent decrease in rate of acceleration
- At least a 21 percent increase in takeoff distance

With ISA conditions, increasing the takeoff weight of the average Cessna 182 from 2,400 pounds to 2,700 pounds (11 percent increase) results in an increased takeoff distance from 440 feet to 575 feet (23 percent increase).

For the aircraft with a high thrust-to-weight ratio, the increase in takeoff distance might be approximately 21 to 22 percent, but for the aircraft with a relatively low thrust-to-weight

ratio, the increase in takeoff distance would be approximately 25 to 30 percent. Such a powerful effect requires proper consideration of gross weight in predicting takeoff distance.

The effect of wind on takeoff distance is large, and proper consideration must also be provided when predicting takeoff distance. The effect of a headwind is to allow the aircraft to reach the lift-off speed at a lower groundspeed, while the effect of a tailwind is to require the aircraft to achieve a greater groundspeed to attain the lift-off speed.

A headwind that is 10 percent of the takeoff airspeed reduces the takeoff distance approximately 19 percent. However, a tailwind that is 10 percent of the takeoff airspeed increases the takeoff distance approximately 21 percent. In the case where the headwind speed is 50 percent of the takeoff speed, the takeoff distance would be approximately 25 percent of the zero wind takeoff distance (75 percent reduction).

The effect of wind on landing distance is identical to its effect on takeoff distance. *Figure 11-19* illustrates the general effect of wind by the percent change in takeoff or landing distance as a function of the ratio of wind velocity to takeoff or landing speed.

The effect of proper takeoff speed is especially important when runway lengths and takeoff distances are critical. The takeoff speeds specified in the AFM/POH are generally the minimum safe speeds at which the aircraft can become airborne. Any attempt to take off below the recommended speed means that the aircraft could stall, be difficult to control, or have a very low initial ROC. In some cases, an

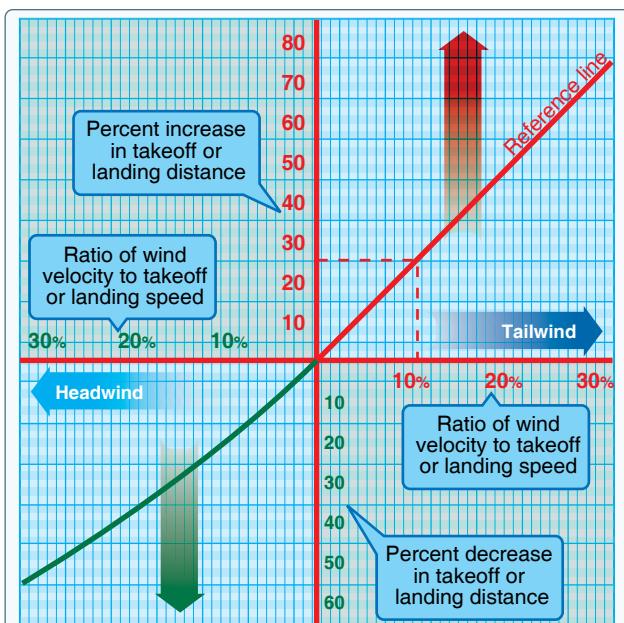


Figure 11-19. Effect of wind on takeoff and landing.

excessive AOA may not allow the aircraft to climb out of ground effect. On the other hand, an excessive airspeed at takeoff may improve the initial ROC and “feel” of the aircraft but produces an undesirable increase in takeoff distance. Assuming that the acceleration is essentially unaffected, the takeoff distance varies with the square of the takeoff velocity.

Thus, ten percent excess airspeed would increase the takeoff distance 21 percent. In most critical takeoff conditions, such an increase in takeoff distance would be prohibitive, and the pilot must adhere to the recommended takeoff speeds.

The effect of pressure altitude and ambient temperature is to define the density altitude and its effect on takeoff performance. While subsequent corrections are appropriate for the effect of temperature on certain items of powerplant performance, density altitude defines specific effects on takeoff performance. An increase in density altitude can produce a twofold effect on takeoff performance:

1. Greater takeoff speed
2. Decreased thrust and reduced net accelerating force

If an aircraft of given weight and configuration is operated at greater heights above standard sea level, the aircraft requires the same dynamic pressure to become airborne at the takeoff lift coefficient. Thus, the aircraft at altitude takes off at the same indicated airspeed (IAS) as at sea level, but because of the reduced air density, the TAS is greater.

The effect of density altitude on powerplant thrust depends much on the type of powerplant. An increase in altitude above standard sea level brings an immediate decrease in power output for the unsupercharged reciprocating engine. However, an increase in altitude above standard sea level does not cause a decrease in power output for the supercharged reciprocating engine until the altitude exceeds the critical operating altitude. For those powerplants that experience a decay in thrust with an increase in altitude, the effect on the net accelerating force and acceleration rate can be approximated by assuming a direct variation with density. Actually, this assumed variation would closely approximate the effect on aircraft with high thrust-to-weight ratios.

Proper accounting of pressure altitude and temperature is mandatory for accurate prediction of takeoff roll distance. The most critical conditions of takeoff performance are the result of some combination of high gross weight, altitude, temperature, and unfavorable wind. In all cases, the pilot must make an accurate prediction of takeoff distance from the performance data of the AFM/POH, regardless of the runway available, and strive for a polished, professional takeoff procedure.

In the prediction of takeoff distance from the AFM/POH data, the following primary considerations must be given:

- Pressure altitude and temperature—to define the effect of density altitude on distance
- Gross weight—a large effect on distance
- Wind—a large effect due to the wind or wind component along the runway
- Runway slope and condition—the effect of an incline and retarding effect of factors such as snow or ice

Landing Performance

In many cases, the landing distance of an aircraft defines the runway requirements for flight operations. The minimum landing distance is obtained by landing at some minimum safe speed, that allows sufficient margin above stall and provides satisfactory control and capability for a go-around. Generally, the landing speed is some fixed percentage of the stall speed or minimum control speed for the aircraft in the landing configuration. As such, the landing is accomplished at some particular value of lift coefficient and AOA. The exact values depend on the aircraft characteristics but, once defined, the values are independent of weight, altitude, and wind.

To obtain minimum landing distance at the specified landing speed, the forces that act on the aircraft must provide maximum deceleration during the landing roll. The forces acting on the aircraft during the landing roll may require various procedures to maintain landing deceleration at the peak value.

A distinction should be made between the procedures for minimum landing distance and an ordinary landing roll with considerable excess runway available. Minimum landing distance is obtained by creating a continuous peak deceleration of the aircraft; that is, extensive use of the brakes for maximum deceleration. On the other hand, an ordinary landing roll with considerable excess runway may allow extensive use of aerodynamic drag to minimize wear and tear on the tires and brakes. If aerodynamic drag is sufficient to cause deceleration, it can be used in deference to the brakes in the early stages of the landing roll (i.e., brakes and tires suffer from continuous hard use, but aircraft aerodynamic drag is free and does not wear out with use). The use of aerodynamic drag is applicable only for deceleration to 60 or 70 percent of the touchdown speed. At speeds less than 60 to 70 percent of the touchdown speed, aerodynamic drag is so slight as to be of little use, and braking must be utilized to produce continued deceleration. Since the objective during the landing roll is to decelerate, the powerplant thrust should be the smallest possible positive value (or largest possible negative value in the case of thrust reversers).

In addition to the important factors of proper procedures, many other variables affect the landing performance. Any item that alters the landing speed or deceleration rate during the landing roll affects the landing distance.

The effect of gross weight on landing distance is one of the principal items determining the landing distance. One effect of an increased gross weight is that a greater speed is required to support the aircraft at the landing AOA and lift coefficient. For an example of the effect of a change in gross weight, a 21 percent increase in landing weight requires a ten percent increase in landing speed to support the greater weight.

When minimum landing distances are considered, braking friction forces predominate during the landing roll and, for the majority of aircraft configurations, braking friction is the main source of deceleration.

The minimum landing distance varies in direct proportion to the gross weight. For example, a ten percent increase in gross weight at landing would cause a:

- Five percent increase in landing velocity
- Ten percent increase in landing distance

A contingency of this is the relationship between weight and braking friction force.

The effect of wind on landing distance is large and deserves proper consideration when predicting landing distance. Since the aircraft lands at a particular airspeed independent of the wind, the principal effect of wind on landing distance is the change in the groundspeed at which the aircraft touches down. The effect of wind on deceleration during the landing is identical to the effect on acceleration during the takeoff.

The effect of pressure altitude and ambient temperature is to define density altitude and its effect on landing performance. An increase in density altitude increases the landing speed but does not alter the net retarding force. Thus, the aircraft at altitude lands at the same IAS as at sea level but, because of the reduced density, the TAS is greater. Since the aircraft lands at altitude with the same weight and dynamic pressure, the drag and braking friction throughout the landing roll have the same values as at sea level. As long as the condition is within the capability of the brakes, the net retarding force is unchanged, and the deceleration is the same as with the landing at sea level. Since an increase in altitude does not alter deceleration, the effect of density altitude on landing distance is due to the greater TAS.

The minimum landing distance at 5,000 feet is 16 percent greater than the minimum landing distance at sea level. The approximate increase in landing distance with altitude is

approximately three and one-half percent for each 1,000 feet of altitude. Proper accounting of density altitude is necessary to accurately predict landing distance.

The effect of proper landing speed is important when runway lengths and landing distances are critical. The landing speeds specified in the AFM/POH are generally the minimum safe speeds at which the aircraft can be landed. Any attempt to land at below the specified speed may mean that the aircraft may stall, be difficult to control, or develop high rates of descent. On the other hand, an excessive speed at landing may improve the controllability slightly (especially in crosswinds) but causes an undesirable increase in landing distance.

A ten percent excess landing speed causes at least a 21 percent increase in landing distance. The excess speed places a greater working load on the brakes because of the additional kinetic energy to be dissipated. Also, the additional speed causes increased drag and lift in the normal ground attitude, and the increased lift reduces the normal force on the braking surfaces. The deceleration during this range of speed immediately after touchdown may suffer, and it is more probable for a tire to be blown out from braking at this point.

The most critical conditions of landing performance are combinations of high gross weight, high density altitude, and unfavorable wind. These conditions produce the greatest required landing distances and critical levels of energy dissipation on the brakes. In all cases, it is necessary to make an accurate prediction of minimum landing distance to compare with the available runway. A polished, professional landing procedure is necessary because the landing phase of flight accounts for more pilot-caused aircraft accidents than any other single phase of flight.

In the prediction of minimum landing distance from the AFM/POH data, the following considerations must be given:

- Pressure altitude and temperature—to define the effect of density altitude
- Gross weight—which defines the CAS for landing
- Wind—a large effect due to wind or wind component along the runway
- Runway slope and condition—relatively small correction for ordinary values of runway slope, but a significant effect of snow, ice, or soft ground

A tail wind of ten knots increases the landing distance by about 21 percent. An increase of landing speed by ten percent increases the landing distance by 20 percent. Hydroplaning makes braking ineffective until a decrease of speed that can be determined by using *Figure 11-18*.

For instance, a pilot is downwind for runway 18, and the tower asks if runway 27 could be accepted. There is a light rain and the winds are out of the east at ten knots. The pilot accepts because he or she is approaching the extended centerline of runway 27. The turn is tight and the pilot must descend (dive) to get to runway 27. After becoming aligned with the runway and at 50 feet AGL, the pilot is already 1,000 feet down the 3,500 foot runway. The airspeed is still high by about ten percent (should be at 70 knots and is at about 80 knots). The wind of ten knots is blowing from behind.

First, the airspeed being high by about ten percent (80 knots versus 70 knots), as presented in the performance chapter, results in a 20 percent increase in the landing distance. In performance planning, the pilot determined that at 70 knots the distance would be 1,600 feet. However, now it is increased by 20 percent and the required distance is now 1,920 feet.

The newly revised landing distance of 1,920 feet is also affected by the wind. In looking at *Figure 11-19*, the effect of the wind is an additional 20 percent for every ten miles per hour (mph) in wind. This is computed not on the original estimate but on the estimate based upon the increased airspeed. Now the landing distance is increased by another 320 feet for a total requirement of 2,240 feet to land the airplane after reaching 50 feet AGL.

That is the original estimate of 1,600 under planned conditions plus the additional 640 feet for excess speed and the tailwind. Given the pilot overshot the threshold by 1,000 feet, the total length required is 3,240 on a 3,500 foot runway; 260 feet to spare. But this is in a perfect environment. Most pilots become fearful as the end of the runway is facing them just ahead. A typical pilot reaction is to brake—and brake hard. Because the aircraft does not have antilock braking features like a car, the brakes lock, and the aircraft hydroplanes on the wet surface of the runway until decreasing to a speed of about 54 knots (the square root of the tire pressure ($\sqrt{36}$) \times 9). Braking is ineffective when hydroplaning.

The 260 feet that a pilot might feel is left over has long since evaporated as the aircraft hydroplaned the first 300–500 feet when the brakes locked. This is an example of a true story, but one which only changes from year to year because of new participants and aircraft with different N-numbers.

In this example, the pilot actually made many bad decisions. Bad decisions, when combined, have a synergy greater than the individual errors. Therefore, the corrective actions become larger and larger until correction is almost impossible. Aeronautical decision-making is discussed more fully in Chapter 2, Aeronautical Decision-Making (ADM).

Performance Speeds

True airspeed (TAS)—the speed of the aircraft in relation to the air mass in which it is flying.

Indicated airspeed (IAS)—the speed of the aircraft as observed on the ASI. It is the airspeed without correction for indicator, position (or installation), or compressibility errors.

Calibrated airspeed (CAS)—the ASI reading corrected for position (or installation) and instrument errors. (CAS is equal to TAS at sea level in standard atmosphere.) The color coding for various design speeds marked on ASIs may be IAS or CAS.

Equivalent airspeed (EAS)—the ASI reading corrected for position (or installation), for instrument error, and for adiabatic compressible flow for the particular altitude. (EAS is equal to CAS at sea level in standard atmosphere.)

V_{S0} —the calibrated power-off stalling speed or the minimum steady flight speed at which the aircraft is controllable in the landing configuration.

V_{S1} —the calibrated power-off stalling speed or the minimum steady flight speed at which the aircraft is controllable in a specified configuration.

V_Y —the speed at which the aircraft obtains the maximum increase in altitude per unit of time. This best ROC speed normally decreases slightly with altitude.

V_X —the speed at which the aircraft obtains the highest altitude in a given horizontal distance. This best AOC speed normally increases slightly with altitude.

V_{LE} —the maximum speed at which the aircraft can be safely flown with the landing gear extended. This is a problem involving stability and controllability.

V_{LO} —the maximum speed at which the landing gear can be safely extended or retracted. This is a problem involving the air loads imposed on the operating mechanism during extension or retraction of the gear.

V_{FE} —the highest speed permissible with the wing flaps in a prescribed extended position. This is because of the air loads imposed on the structure of the flaps.

V_A —the calibrated design maneuvering airspeed. This is the maximum speed at which the limit load can be imposed (either by gusts or full deflection of the control surfaces) without causing structural damage. Operating at or below

maneuvering speed does not provide structural protection against multiple full control inputs in one axis or full control inputs in more than one axis at the same time.

V_{N0} —the maximum speed for normal operation or the maximum structural cruising speed. This is the speed at which exceeding the limit load factor may cause permanent deformation of the aircraft structure.

V_{NE} —the speed that should *never* be exceeded. If flight is attempted above this speed, structural damage or structural failure may result.

Performance Charts

Performance charts allow a pilot to predict the takeoff, climb, cruise, and landing performance of an aircraft. These charts, provided by the manufacturer, are included in the AFM/POH. Information the manufacturer provides on these charts has been gathered from test flights conducted in a new aircraft, under normal operating conditions while using average piloting skills, and with the aircraft and engine in good working order. Engineers record the flight data and create performance charts based on the behavior of the aircraft during the test flights. By using these performance charts, a pilot can determine the runway length needed to take off and land, the amount of fuel to be used during flight, and the time required to arrive at the destination. It is important to remember that the data from the charts will not be accurate if the aircraft is not in good working order or when operating under adverse conditions. Always consider the necessity to compensate for the performance numbers if the aircraft is not in good working order or piloting skills are below average.

Each aircraft performs differently and, therefore, has different performance numbers. Compute the performance of the aircraft prior to every flight, as every flight is different. (See appendix for examples of performance charts for a Cessna Model 172R and Challenger 605.)

Every chart is based on certain conditions and contains notes on how to adapt the information for flight conditions. It is important to read every chart and understand how to use it. Read the instructions provided by the manufacturer. For an explanation on how to use the charts, refer to the example provided by the manufacturer for that specific chart. [Figure 11-20]

The information manufacturers furnish is not standardized. Information may be contained in a table format and other information may be contained in a graph format. Sometimes combined graphs incorporate two or more graphs into one chart to compensate for multiple conditions of flight. Combined graphs allow the pilot to predict aircraft performance for variations in density altitude, weight, and winds all on one chart. Because of the vast amount of information that can be extracted from this type of chart, it is important to be very accurate in reading the chart. A small error in the beginning can lead to a large error at the end.

The remainder of this section covers performance information for aircraft in general and discusses what information the charts contain and how to extract information from the charts by direct reading and interpolation methods. Every chart contains a wealth of information that should be used when flight planning. Examples of the table, graph, and combined graph formats for all aspects of flight are discussed.

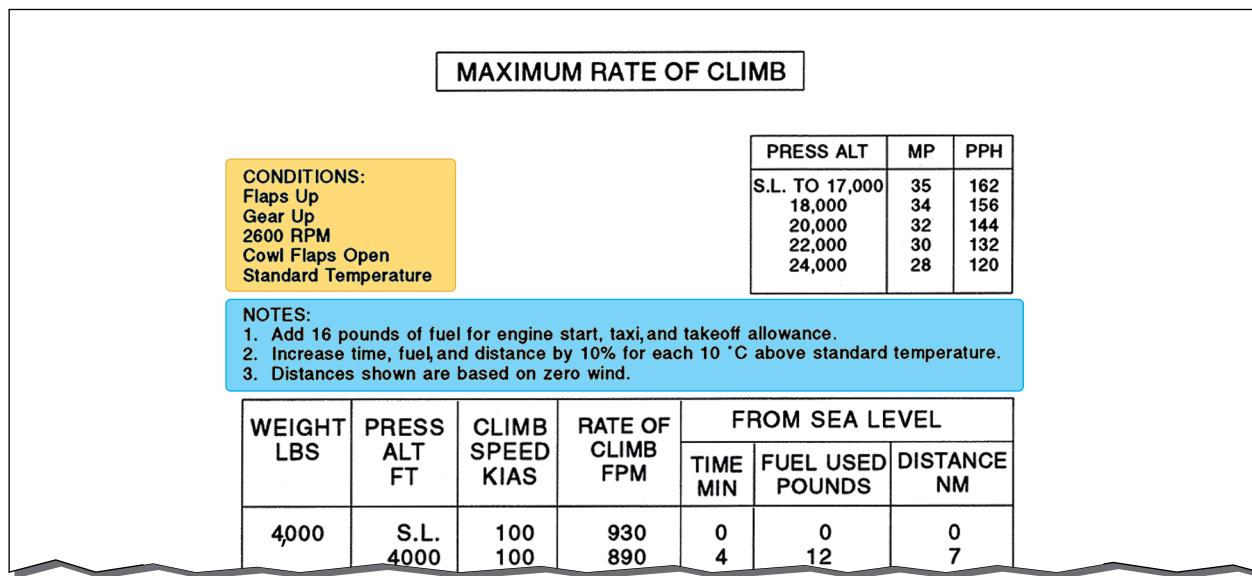


Figure 11-20. Conditions notes chart.

Interpolation

Not all of the information on the charts is easily extracted. Some charts require interpolation to find the information for specific flight conditions. Interpolating information means that by taking the known information, a pilot can compute intermediate information. However, pilots sometimes round off values from charts to a more conservative figure.

Using values that reflect slightly more adverse conditions provides a reasonable estimate of performance information and gives a slight margin of safety. The following illustration is an example of interpolating information from a takeoff distance chart. [Figure 11-21]

Density Altitude Charts

Use a density altitude chart to figure the density altitude at the departing airport. Using Figure 11-22, determine the density altitude based on the given information.

Sample Problem 1

Airport Elevation.....	5,883 feet
OAT.....	70 °F
Altimeter.....	30.10 "Hg

First, compute the pressure altitude conversion. Find 30.10 under the altimeter heading. Read across to the second column. It reads “–165.” Therefore, it is necessary to subtract 165 from the airport elevation giving a pressure altitude of 5,718 feet. Next, locate the outside air temperature on the scale along the bottom of the graph. From 70°, draw a line up to the 5,718 feet pressure altitude line, which is about two-thirds of the way up between the 5,000 and 6,000 foot lines. Draw a line straight across to the far left side of the graph

and read the approximate density altitude. The approximate density altitude in thousands of feet is 7,700 feet.

Takeoff Charts

Takeoff charts are typically provided in several forms and allow a pilot to compute the takeoff distance of the aircraft with no flaps or with a specific flap configuration. A pilot can also compute distances for a no flap takeoff over a 50 foot obstacle scenario, as well as with flaps over a 50 foot obstacle. The takeoff distance chart provides for various aircraft weights, altitudes, temperatures, winds, and obstacle heights.

Sample Problem 2

Pressure Altitude.....	2,000 feet
OAT.....	22 °C
Takeoff Weight.....	2,600 pounds
Headwind.....	6 knots
Obstacle Height.....	50 foot obstacle

Refer to Figure 11-23. This chart is an example of a combined takeoff distance graph. It takes into consideration pressure altitude, temperature, weight, wind, and obstacles all on one chart. First, find the correct temperature on the bottom left side of the graph. Follow the line from 22 °C straight up until it intersects the 2,000 foot altitude line. From that point, draw a line straight across to the first dark reference line. Continue to draw the line from the reference point in a diagonal direction following the surrounding lines until it intersects the corresponding weight line. From the intersection of 2,600 pounds, draw a line straight across until it reaches the second reference line. Once again, follow the lines in a diagonal manner until it reaches the six knot headwind mark. Follow

Conditions	Flaps 10° Full throttle prior to brake release Paved level runway Zero wind			TAKEOFF DISTANCE MAXIMUM WEIGHT 2,400 LB										
	Weight (lb)	Takeoff speed KIAS		Press ALT (ft)	0 °C		10 °C		20 °C		30 °C		40 °C	
		Lift off	AT 50 ft		Grnd roll (ft)	Total feet to clear 50 ft OBS								
	2,400	51	56	S.L.	795	1,460	860	1,570	925	1,685	995	1,810	1,065	1,945
				1,000	875	1,605	940	1,725	1,015	1,860	1,090	2,000	1,170	2,155
				2,000	960	1,770	1,035	1,910	1,115	2,060	1,200	2,220	1,290	2,395
				3,000	1,055	1,960	1,140	2,120	1,230	2,295	1,325	2,480	1,425	2,685
				4,000	1,165	2,185	1,260	2,365	1,355	2,570	1,465	2,790	1,575	3,030
				5,000	1,285	2,445	1,390	2,660	1,500	2,895	1,620	3,160	1,745	3,455
				6,000	1,425	2,755	1,540	3,015	1,665	3,300	1,800	3,620	1,940	3,990
				7,000	1,580	3,140	1,710	3,450	1,850	3,805	2,000	4,220	---	---
				8,000	1,755	3,615	1,905	4,015	2,060	4,480	---	---	---	---

To find the takeoff distance for a pressure altitude of 2,500 feet at 20 °C, average the ground roll for 2,000 feet and 3,000 feet.

$$\frac{1,115 + 1,230}{2} = 1,173 \text{ feet}$$

Figure 11-21. Interpolating charts.

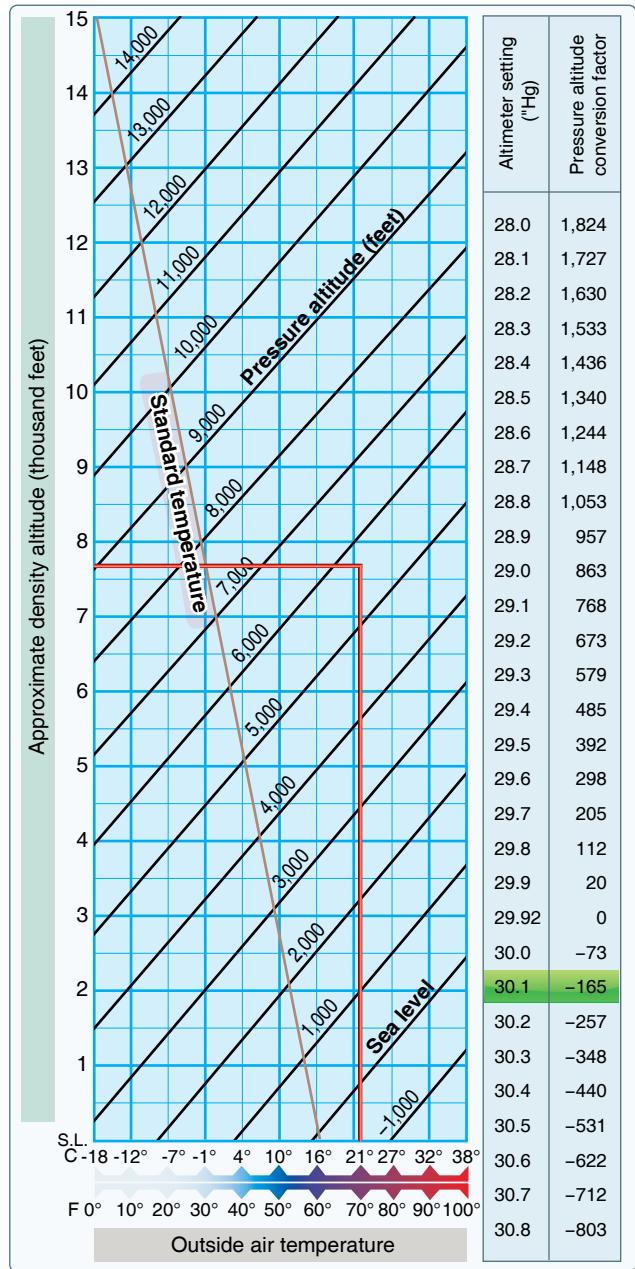


Figure 11-22. Density altitude chart.

straight across to the third reference line and from here, draw a line in two directions. First, draw a line straight across to figure the ground roll distance. Next, follow the diagonal lines again until they reach the corresponding obstacle height. In this case, it is a 50 foot obstacle. Therefore, draw the diagonal line to the far edge of the chart. This results in a 700 foot ground roll distance and a total distance of 1,400 feet over a 50 foot obstacle. To find the corresponding takeoff speeds at lift-off and over the 50 foot obstacle, refer to the table on the top of the chart. In this case, the lift-off speed at 2,600 pounds would be 63 knots and over the 50 foot obstacle would be 68 knots.

Sample Problem 3

Pressure Altitude.....	3,000 feet
OAT.....	30 °C
Takeoff Weight.....	2,400 pounds
Headwind.....	18 knots

Refer to *Figure 11-24*. This chart is an example of a takeoff distance table for short-field takeoffs. For this table, first find the takeoff weight. Once at 2,400 pounds, begin reading from left to right across the table. The takeoff speed is in the second column and, in the third column under pressure altitude, find the pressure altitude of 3,000 feet. Carefully follow that line to the right until it is under the correct temperature column of 30 °C. The ground roll total reads 1,325 feet and the total required to clear a 50 foot obstacle is 2,480 feet. At this point, there is an 18 knot headwind. According to the notes section under point number two, decrease the distances by ten percent for each 9 knots of headwind. With an 18 knot headwind, it is necessary to decrease the distance by 20 percent. Multiply 1,325 feet by 20 percent ($1,325 \times .20 = 265$), subtract the product from the total distance ($1,325 - 265 = 1,060$). Repeat this process for the total distance over a 50 foot obstacle. The ground roll distance is 1,060 feet and the total distance over a 50 foot obstacle is 1,984 feet.

Climb and Cruise Charts

Climb and cruise chart information is based on actual flight tests conducted in an aircraft of the same type. This information is extremely useful when planning a cross-country flight to predict the performance and fuel consumption of the aircraft. Manufacturers produce several different charts for climb and cruise performance. These charts include everything from fuel, time, and distance to climb to best power setting during cruise to cruise range performance.

The first chart to check for climb performance is a fuel, time, and distance-to-climb chart. This chart gives the fuel amount used during the climb, the time it takes to accomplish the climb, and the ground distance that is covered during the climb. To use this chart, obtain the information for the departing airport and for the cruise altitude. Using *Figure 11-25*, calculate the fuel, time, and distance to climb based on the information provided.

Sample Problem 4

Departing Airport Pressure Altitude.....	6,000 feet
Departing Airport OAT.....	25 °C
Cruise Pressure Altitude.....	10,000 feet
Cruise OAT.....	10 °C

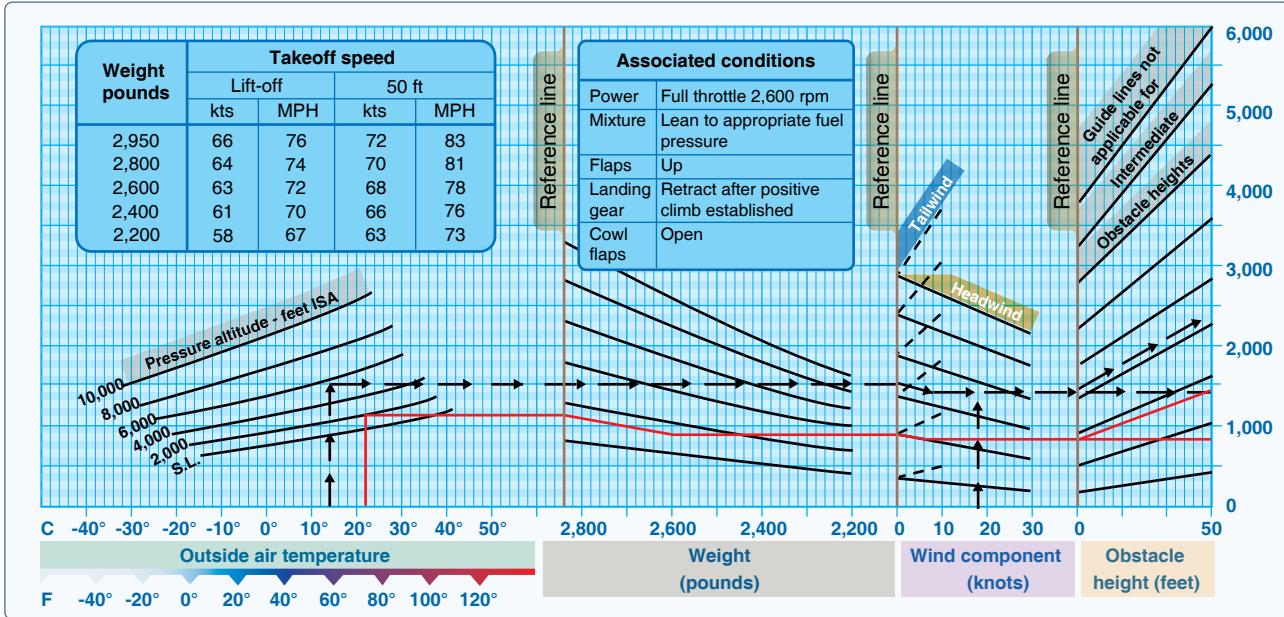


Figure 11-23. Takeoff distance graph.

Conditions	Flaps 10° Full throttle prior to brake release Paved level runway Zero wind			TAKEOFF DISTANCE MAXIMUM WEIGHT 2,400 LB SHORT FIELD									
				0 °C		10 °C		20 °C		30 °C		40 °C	
Weight (lb)	Takeoff speed KIAS		Press ALT (ft)	Grnd roll (ft)	Total feet to clear 50 ft OBS	Grnd roll (ft)	Total feet to clear 50 ft OBS	Grnd roll (ft)	Total feet to clear 50 ft OBS	Grnd roll (ft)	Total feet to clear 50 ft OBS	Grnd roll (ft)	Total feet to clear 50 ft OBS
	Lift off	AT 50 ft											
2,400	51	56	S.L.	795	1,460	860	1,570	925	1,685	995	1,810	1,065	1,945
			1,000	875	1,605	940	1,725	1,015	1,860	1,090	2,000	1,170	2,155
			2,000	960	1,770	1,035	1,910	1,115	2,060	1,200	2,220	1,290	2,395
			3,000	1,055	1,960	1,140	2,120	1,230	2,295	1,325	2,480	1,425	2,685
			4,000	1,165	2,185	1,260	2,365	1,355	2,570	1,465	2,790	1,575	3,030
			5,000	1,285	2,445	1,390	2,660	1,500	2,895	1,620	3,160	1,745	3,455
			6,000	1,425	2,755	1,540	3,015	1,665	3,300	1,800	3,620	1,940	3,990
			7,000	1,580	3,140	1,710	3,450	1,850	3,805	2,000	4,220	---	---
			8,000	1,755	3,615	1,905	4,015	2,060	4,480	---	---	---	---
2,200	49	54	S.L.	650	1,195	700	1,280	750	1,375	805	1,470	865	1,575
			1,000	710	1,310	765	1,405	825	1,510	885	1,615	950	1,735
			2,000	780	1,440	840	1,545	905	1,660	975	1,785	1,045	1,915
			3,000	855	1,585	925	1,705	995	1,835	1,070	1,975	1,150	2,130
			4,000	945	1,750	1,020	1,890	1,100	2,040	1,180	2,200	1,270	2,375
			5,000	1,040	1,945	1,125	2,105	1,210	2,275	1,305	2,465	1,405	2,665
			6,000	1,150	2,170	1,240	2,355	1,340	2,555	1,445	2,775	1,555	3,020
			7,000	1,270	2,440	1,375	2,655	1,485	2,890	1,605	3,155	1,730	3,450
			8,000	1,410	2,760	1,525	3,015	1,650	3,305	1,785	3,630	1,925	4,005
2,000	46	51	S.L.	525	970	565	1,035	605	1,110	650	1,185	695	1,265
			1,000	570	1,060	615	1,135	665	1,215	710	1,295	765	1,385
			2,000	625	1,160	675	1,240	725	1,330	780	1,425	840	1,525
			3,000	690	1,270	740	1,365	800	1,465	860	1,570	920	1,685
			4,000	755	1,400	815	1,500	880	1,615	945	1,735	1,015	1,865
			5,000	830	1,545	900	1,660	970	1,790	2,145	1,925	1,120	2,070
			6,000	920	1,710	990	1,845	1,070	1,990	2,405	2,145	1,235	2,315
			7,000	1,015	1,900	1,095	2,055	1,180	2,225	2,715	2,405	1,370	2,605
			8,000	1,125	2,125	1,215	2,305	1,310	2,500	1,410	2,715	1,520	2,950

Figure 11-24. Takeoff distance short field charts.

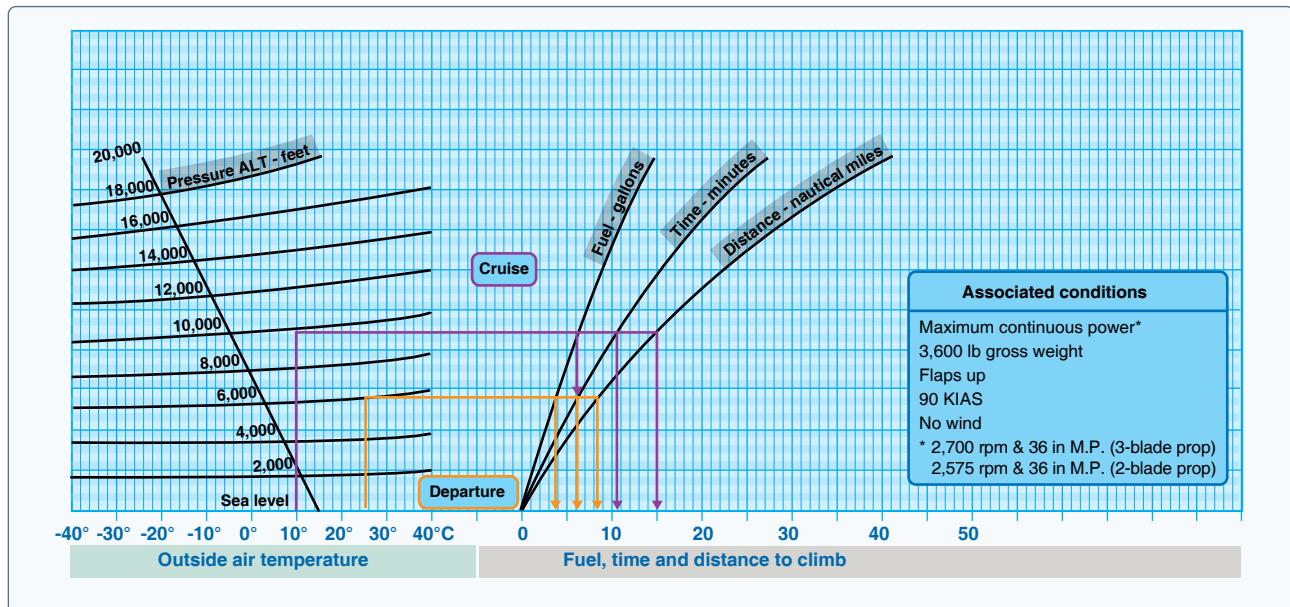


Figure 11-25. Fuel, time, and distance climb chart.

First, find the information for the departing airport. Find the OAT for the departing airport along the bottom, left side of the graph. Follow the line from 25 °C straight up until it intersects the line corresponding to the pressure altitude of 6,000 feet. Continue this line straight across until it intersects all three lines for fuel, time, and distance. Draw a line straight down from the intersection of altitude and fuel, altitude and time, and a third line at altitude and distance. It should read three and one-half gallons of fuel, 6 minutes of time, and nine NM. Next, repeat the steps to find the information for the cruise altitude. It should read six gallons of fuel, 10.5 minutes of time, and 15 NM. Take each set of numbers for fuel, time, and distance and subtract them from one another ($6.0 - 3.5 = 2.5$ gallons of fuel). It takes two and one-half gallons of fuel and 4 minutes of time to climb to 10,000 feet. During that climb, the distance covered is six NM. Remember, according to the notes at the top of the chart, these numbers do not take into account wind, and it is assumed maximum continuous power is being used.

The next example is a fuel, time, and distance-to-climb table. For this table, use the same basic criteria as for the previous chart. However, it is necessary to figure the information in a different manner. Refer to *Figure 11-26* to work the following sample problem.

Sample Problem 5

Departing Airport Pressure Altitude.....Sea level

Departing Airport OAT.....22 °C

Cruise Pressure Altitude.....8,000 feet

Takeoff Weight.....3,400 pounds

To begin, find the given weight of 3,400 in the first column of the chart. Move across to the pressure altitude column to find the sea level altitude numbers. At sea level, the numbers read zero. Next, read the line that corresponds with the cruising altitude of 8,000 feet. Normally, a pilot would subtract these

Conditions	Flaps up Gear up 2,500 rpm 30 "Hg 120 PPH fuel flow Cowl flaps open Standard temperature	NORMAL CLIMB 110 KIAS			
Notes	1. Add 16 pounds of fuel for engine start, taxi, and takeoff allowance. 2. Increase time, fuel, and distance by 10% for each 7 °C above standard temperature. 3. Distances shown are based on zero wind.				
Weight (pounds)	Press ALT (feet)	Rate of climb fpm	From sea level		
			Time (minutes)	Fuel used (pounds)	Distance (nautical miles)
4,000	S.L. 4,000 8,000 12,000 16,000 20,000	605 570 530 485 430 365	0 7 14 22 31 41	0 14 28 44 62 82	0 13 27 43 63 87
3,700	S.L. 4,000 8,000 12,000 16,000 20,000	700 665 625 580 525 460	0 6 12 19 26 34	0 12 24 37 52 68	0 11 23 37 53 72
3,400	S.L. 4,000 8,000 12,000 16,000 20,000	810 775 735 690 635 565	0 5 10 16 22 29	0 10 21 32 44 57	0 9 20 31 45 61

Figure 11-26. Fuel time distance climb.

two sets of numbers from one another, but given the fact that the numbers read zero at sea level, it is known that the time to climb from sea level to 8,000 feet is 10 minutes. It is also known that 21 pounds of fuel is used and 20 NM is covered during the climb. However, the temperature is 22 °C, which is 7° above the standard temperature of 15 °C. The notes section of this chart indicate that the findings must be increased by ten percent for each 7° above standard. Multiply the findings by ten percent or .10 ($10 \times .10 = 1$, $1 + 10 = 11$ minutes). After accounting for the additional ten percent, the findings should read 11 minutes, 23.1 pounds of fuel, and 22 NM. Notice that the fuel is reported in pounds of fuel, not gallons. Aviation fuel weighs six pounds per gallon, so 23.1 pounds of fuel is equal to 3.85 gallons of fuel ($23.1 \div 6 = 3.85$).

The next example is a cruise and range performance chart. This type of table is designed to give TAS, fuel consumption, endurance in hours, and range in miles at specific cruise configurations. Use *Figure 11-27* to determine the cruise and range performance under the given conditions.

Sample Problem 6

Pressure Altitude.....5,000 feet
 RPM.....2,400 rpm
 Fuel Carrying Capacity.....38 gallons, no reserve

Find 5,000 feet pressure altitude in the first column on the left side of the table. Next, find the correct rpm of 2,400 in the second column. Follow that line straight across and read the TAS of 116 mph and a fuel burn rate of 6.9 gallons per hour. As per the example, the aircraft is equipped with a fuel carrying capacity of 38 gallons. Under this column, read that the endurance in hours is 5.5 hours and the range in miles is 635 miles.

Cruise power setting tables are useful when planning cross-country flights. The table gives the correct cruise power settings, as well as the fuel flow and airspeed performance numbers at that altitude and airspeed.

Sample Problem 7

Pressure Altitude at Cruise.....6,000 feet
 OAT.....36 °F above standard

Refer to *Figure 11-28* for this sample problem. First, locate the pressure altitude of 6,000 feet on the far left side of the table. Follow that line across to the far right side of the table under the 20 °C (or 36 °F) column. At 6,000 feet, the rpm setting of 2,450 will maintain 65 percent continuous power at 21.0 "Hg with a fuel flow rate of 11.5 gallons per hour and airspeed of 161 knots.

Conditions	Gross weight—2,300 lb. Standard conditions Zero wind Lean mixture							
	Notes Maximum cruise is normally limited to 75% power.							
ALT	RPM	% BHP	TAS MPH	GAL/Hour	38 gal (no reserve)		48 gal (no reserve)	
					Endr. hours	Range miles	Endr. hours	Range miles
2,500	2,700	86	134	9.7	3.9	525	4.9	660
	2,600	79	129	8.6	4.4	570	5.6	720
	2,500	72	123	7.8	4.9	600	6.2	760
	2,400	65	117	7.2	5.3	620	6.7	780
	2,300	58	111	6.7	5.7	630	7.2	795
	2,200	52	103	6.3	6.1	625	7.7	790
5,000	2,700	82	134	9.0	4.2	565	5.3	710
	2,600	75	128	8.1	4.7	600	5.9	760
	2,500	68	122	7.4	5.1	625	6.4	790
	2,400	61	116	6.9	5.5	635	6.9	805
	2,300	55	108	6.5	5.9	635	7.4	805
	2,200	49	100	6.0	6.3	630	7.9	795
7,500	2,700	78	133	8.4	4.5	600	5.7	755
	2,600	71	127	7.7	4.9	625	6.2	790
	2,500	64	121	7.1	5.3	645	6.7	810
	2,400	58	113	6.7	5.7	645	7.2	820
	2,300	52	105	6.2	6.1	640	7.7	810
10,000	2,650	70	129	7.6	5.0	640	6.3	810
	2,600	67	125	7.3	5.2	650	6.5	820
	2,500	61	118	6.9	5.5	655	7.0	830
	2,400	55	110	6.4	5.9	650	7.5	825
	2,300	49	100	6.0	6.3	635	8.0	800

Figure 11-27. Cruise and range performance.

Another type of cruise chart is a best power mixture range graph. This graph gives the best range based on power setting and altitude. Using *Figure 11-29*, find the range at 65 percent power with and without a reserve based on the provided conditions.

Sample Problem 8

OAT.....Standard
 Pressure Altitude.....5,000 feet

First, move up the left side of the graph to 5,000 feet and standard temperature. Follow the line straight across the graph until it intersects the 65 percent line under both the reserve and no reserve categories. Draw a line straight down from both intersections to the bottom of the graph. At 65 percent power with a reserve, the range is approximately 522 miles. At 65 percent power with no reserve, the range should be 581 miles.

The last cruise chart referenced is a cruise performance graph. This graph is designed to tell the TAS performance of the airplane depending on the altitude, temperature, and power setting. Using *Figure 11-30*, find the TAS performance based on the given information.

		CRUISE POWER SETTING																						
		65% MAXIMUM CONTINUOUS POWER (OR FULL THROTTLE)																						
		2,800 POUNDS																						
Press ALT		ISA -20° (-36 °F)						Standard day (ISA)																
		IOAT	Engine speed	Man. press	Fuel flow per engine	TAS		IOAT	Engine speed	Man. press	Fuel flow per engine	TAS												
		°F	°C	RPM	"HG	PSI	GPH	kts	MPH	°F	°C	RPM	"HG	PSI	GPH	kts	MPH							
S.L.	27	-3	2,450	20.7	6.6	11.5	147	169	63	17	2,450	21.2	6.6	11.5	150	173	99	37	2,450	21.8	6.6	11.5	153	176
2,000	19	-7	2,450	20.4	6.6	11.5	149	171	55	13	2,450	21.0	6.6	11.5	153	176	91	33	2,450	21.5	6.6	11.5	156	180
4,000	12	-11	2,450	20.1	6.6	11.5	152	175	48	9	2,450	20.7	6.6	11.5	156	180	84	29	2,450	21.3	6.6	11.5	159	183
6,000	5	-15	2,450	19.8	6.6	11.5	155	178	41	5	2,450	20.4	6.6	11.5	158	182	79	26	2,450	21.0	6.6	11.5	161	185
8,000	-2	-19	2,450	19.5	6.6	11.5	157	181	36	2	2,450	20.2	6.6	11.5	161	185	72	22	2,450	20.8	6.6	11.5	164	189
10,000	-8	-22	2,450	19.2	6.6	11.5	160	184	28	-2	2,450	19.9	6.6	11.5	163	188	64	18	2,450	20.3	6.5	11.4	166	191
12,000	-15	-26	2,450	18.8	6.4	11.3	162	186	21	-6	2,450	18.8	6.1	10.9	163	188	57	14	2,450	18.8	5.9	10.6	163	188
14,000	-22	-30	2,450	17.4	5.8	10.5	159	183	14	-10	2,450	17.4	5.6	10.1	160	184	50	10	2,450	17.4	5.4	9.8	160	184
16,000	-29	-34	2,450	16.1	5.3	9.7	156	180	7	-14	2,450	16.1	5.1	9.4	156	180	43	6	2,450	16.1	4.9	9.1	155	178

Figure 11-28. Cruise power setting.

Sample Problem 9

OAT.....16 °C
 Pressure Altitude.....6,000 feet
 Power Setting.....65 percent, best power
 Wheel Fairings.....Not installed

Begin by finding the correct OAT on the bottom left side of the graph. Move up that line until it intersects the pressure altitude of 6,000 feet. Draw a line straight across to the

65 percent, best power line. This is the solid line, that represents best economy. Draw a line straight down from this intersection to the bottom of the graph. The TAS at 65 percent best power is 140 knots. However, it is necessary to subtract 8 knots from the speed since there are no wheel fairings. This note is listed under the title and conditions. The TAS is 132 knots.

Crosswind and Headwind Component Chart

Every aircraft is tested according to Federal Aviation Administration (FAA) regulations prior to certification. The aircraft is tested by a pilot with average piloting skills in 90° crosswinds with a velocity up to 0.2 V_{s0} or two-tenths of the aircraft's stalling speed with power off, gear down, and flaps down. This means that if the stalling speed of the aircraft is 45 knots, it must be capable of landing in a 9-knot, 90° crosswind. The maximum demonstrated crosswind component is published in the AFM/POH. The crosswind and headwind component chart allows for figuring the headwind and crosswind component for any given wind direction and velocity.

Sample Problem 10

Runway.....17
 Wind.....140° at 25 knots

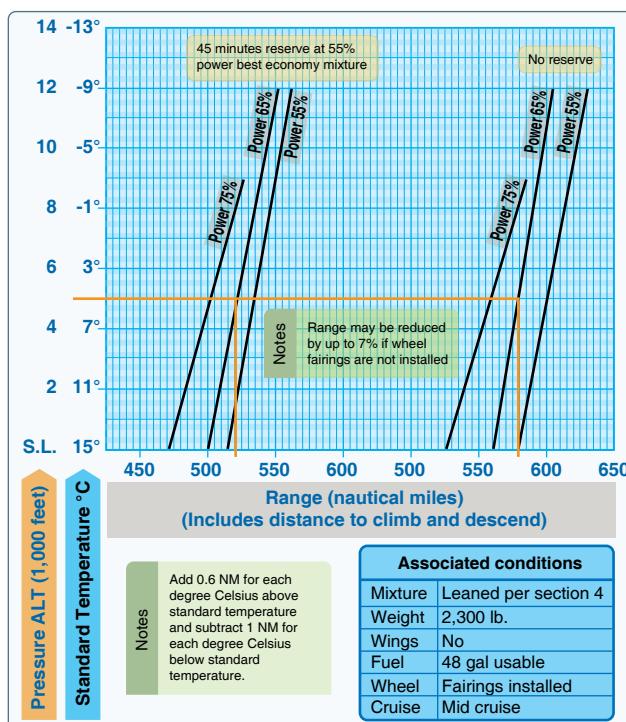


Figure 11-29. Best power mixture range.

Refer to Figure 11-31 to solve this problem. First, determine how many degrees difference there is between the runway and the wind direction. It is known that runway 17 means a direction of 170°; from that subtract the wind direction of 140°. This gives a 30° angular difference or wind angle. Next, locate the 30° mark and draw a line from there until it intersects the correct wind velocity of 25 knots. From

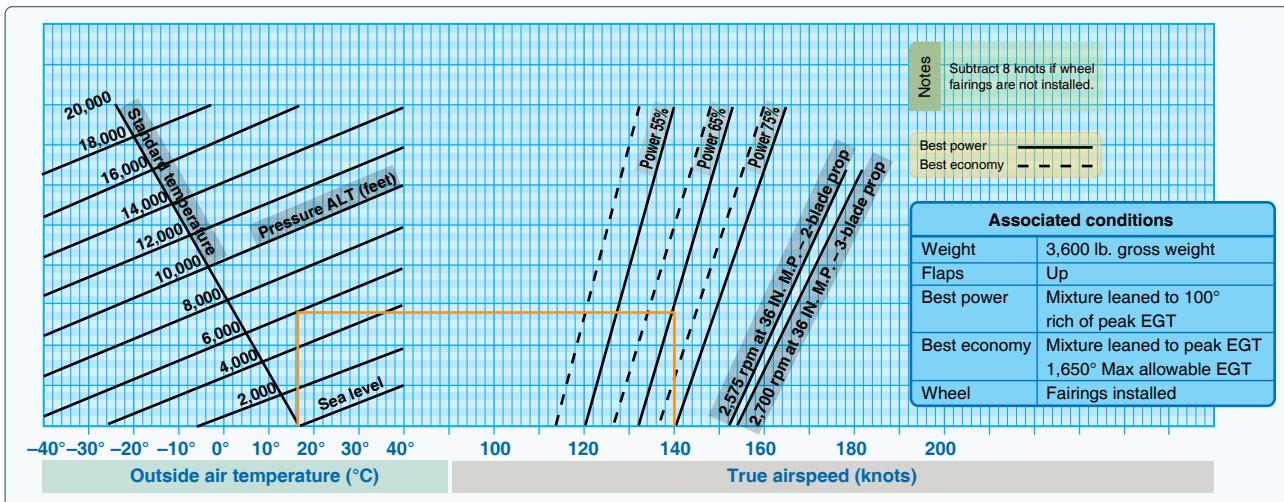


Figure 11-30. Cruise performance graph.

there, draw a line straight down and a line straight across. The headwind component is 22 knots and the crosswind component is 13 knots. This information is important when taking off and landing so that, first of all, the appropriate runway can be picked if more than one exists at a particular airport, but also so that the aircraft is not pushed beyond its tested limits.

Landing Charts

Landing performance is affected by variables similar to those affecting takeoff performance. It is necessary to compensate for differences in density altitude, weight of the airplane, and headwinds. Like takeoff performance charts, landing distance information is available as normal landing information, as well as landing distance over a 50 foot obstacle. As

usual, read the associated conditions and notes in order to ascertain the basis of the chart information. Remember, when calculating landing distance that the landing weight is not the same as the takeoff weight. The weight must be recalculated to compensate for the fuel that was used during the flight.

Sample Problem 11

Pressure Altitude.....1,250 feet

Temperature.....Standard

Refer to *Figure 10-32*. This example makes use of a landing distance table. Notice that the altitude of 1,250 feet is not on this table. It is, therefore, necessary to interpolate to find the correct landing distance. The pressure altitude of 1,250 is halfway between sea level and 2,500 feet. First, find the column for sea level and the column for 2,500 feet. Take the total distance of 1,075 for sea level and the total distance of 1,135 for 2,500 and add them together. Divide the total by two to obtain the distance for 1,250 feet. The distance is 1,105 feet total landing distance to clear a 50 foot obstacle. Repeat this process to obtain the ground roll distance for the pressure altitude. The ground roll should be 457.5 feet.

Sample Problem 12

OAT.....57 °F

Pressure Altitude.....4,000 feet

Landing Weight.....2,400 pounds

Headwind.....6 knots

Obstacle Height.....50 feet

Using the given conditions and *Figure 11-33*, determine the landing distance for the aircraft. This graph is an example of

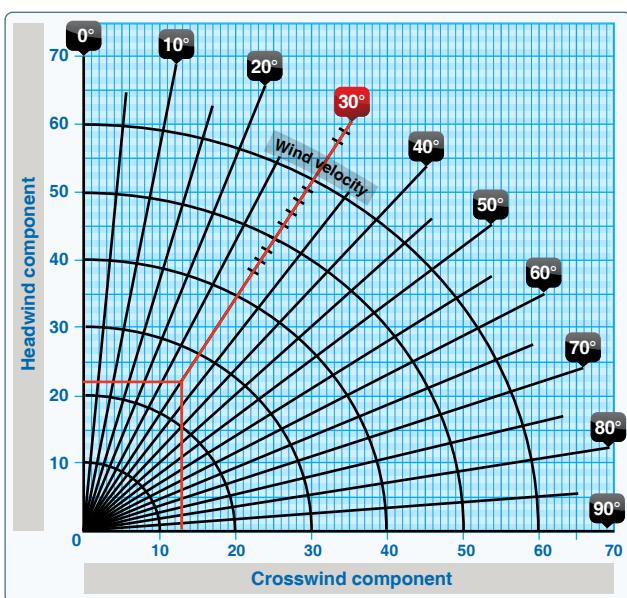


Figure 10-31. Crosswind component chart.

Conditions		LANDING DISTANCE							
Gross weight lb	Approach speed IAS, MPH	At sea level & 59 °F		At 2,500 ft & 50 °F		At 5,000 ft & 41 °F		At 7,500 ft & 32 °F	
		Ground roll	Total to clear 50 ft OBS	Ground roll	Total to clear 50 ft OBS	Ground roll	Total to clear 50 ft OBS	Ground roll	Total to clear 50 ft OBS
1,600	60	445	1,075	470	1,135	495	1,195	520	1,255

Note 1. Decrease the distances shown by 10% for each 4 knots of headwind.
2. Increase the distance by 10% for each 60 °F temperature increase above standard.
3. For operation on a dry, grass runway, increase distances (both "ground roll" and "total to clear 50 ft obstacle") by 20% of the "total to clear 50 ft obstacle" figure.

Figure 11-32. Landing distance table.

a combined landing distance graph and allows compensation for temperature, weight, headwinds, tailwinds, and varying obstacle height. Begin by finding the correct OAT on the scale on the left side of the chart. Move up in a straight line to the correct pressure altitude of 4,000 feet. From this intersection, move straight across to the first dark reference line. Follow the lines in the same diagonal fashion until the correct landing weight is reached. At 2,400 pounds, continue in a straight line across to the second dark reference line. Once again, draw a line in a diagonal manner to the correct wind component and then straight across to the third dark reference line. From this point, draw a line in two separate directions: one straight across to figure the ground roll and one in a diagonal manner to the correct obstacle height. This should be 975 feet for the total ground roll and 1,500 feet for the total distance over a 50 foot obstacle.

Stall Speed Performance Charts

Stall speed performance charts are designed to give an understanding of the speed at which the aircraft stalls in a given configuration. This type of chart typically takes into account the angle of bank, the position of the gear and flaps, and the throttle position. Use Figure 11-34 and the accompanying conditions to find the speed at which the airplane stalls.

Sample Problem 13

Power..... OFF
Flaps..... Down
Gear..... Down
Angle of Bank..... 45°

First, locate the correct flap and gear configuration. The bottom half of the chart should be used since the gear and

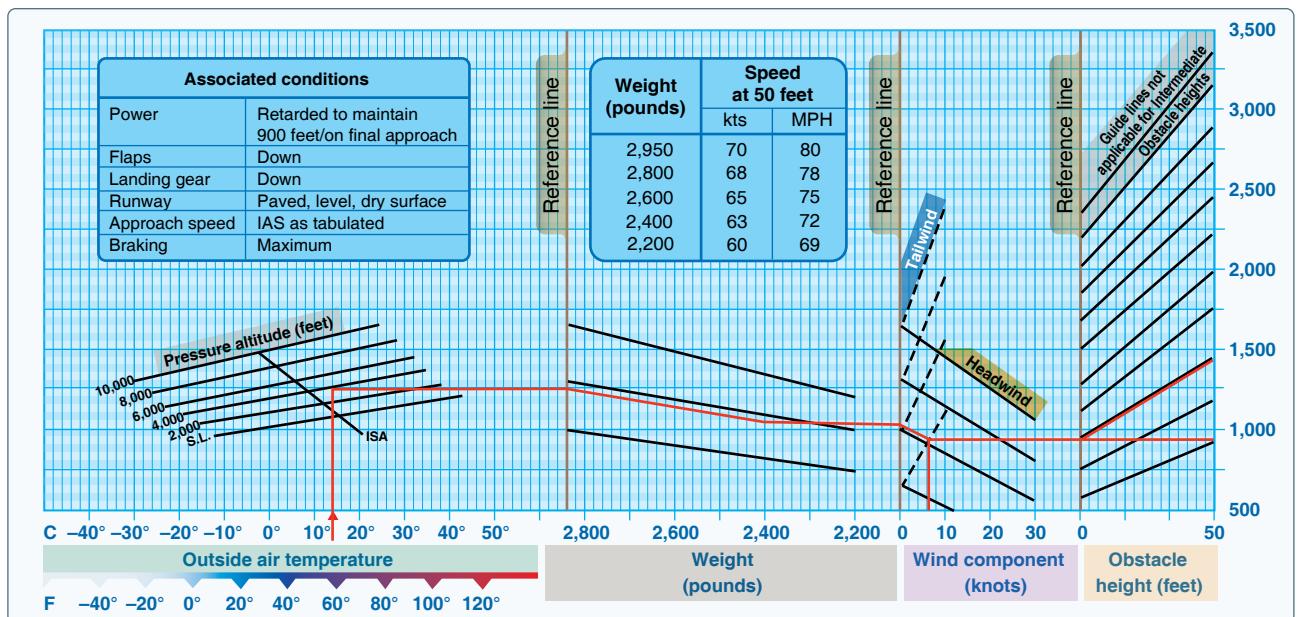


Figure 11-33. Landing distance graph.

Gross weight 2,750 lb		Angle of bank			
		Level	30°	45°	60°
		Gear and flaps up			
Power	On	MPH	62	67	74
		knots	54	58	64
	Off	MPH	75	81	89
		knots	65	70	77
Gear and flaps down					
Power	On	MPH	54	58	64
		knots	47	50	56
	Off	MPH	66	71	78
		knots	57	62	68

Figure 11-34. Stall speed table.

flaps are down. Next, choose the row corresponding to a power-off situation. Now, find the correct angle of bank column, which is 45°. The stall speed is 78 mph, and the stall speed in knots would be 68 knots.

Performance charts provide valuable information to the pilot. By using these charts, a pilot can predict the performance of the aircraft under most flying conditions, providing a better plan for every flight. The Code of Federal Regulations (CFR) requires that a pilot be familiar with all information available prior to any flight. Pilots should use the information to their advantage as it can only contribute to safety in flight.

Transport Category Aircraft Performance

Transport category aircraft are certificated under Title 14 of the CFR (14 CFR) part 25. For additional information concerning transport category airplanes, consult the Airplane Flying Handbook, FAA-H-8083-3 (as revised).

Transport category helicopters are certificated under 14 CFR part 29.

Air Carrier Obstacle Clearance Requirements

For information on air carrier obstacle clearance requirements consult the Instrument Procedures Handbook, FAA-H-8083-16 (as revised).

Chapter Summary

Performance characteristics and capabilities vary greatly among aircraft. As transport aircraft become more capable and more complex, most operators find themselves having to rely increasingly on computerized flight mission planning systems. These systems may be on board or used during the planning phase of the flight. Moreover, aircraft weight, atmospheric conditions, and external environmental factors can significantly affect aircraft performance. It is essential that a pilot become intimately familiar with the mission planning programs, performance characteristics, and capabilities of the aircraft being flown, as well as all of the onboard computerized systems in today's complex aircraft. The primary source of this information is the AFM/POH.