

DCS Framework



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	Initials	Date	Signature
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1. Purpose

The DCS Framework provides an overview on the entities of the Physical Model (Unit Classes, Equipment Module Classes) and the entities of the Procedural Model (Phase Classes) to be implemented in the DeltaV DCS Software for the stainless steel media and buffer systems.

A separate DCS Framework will be provided for the single-use Process Units.

The Automation Framework will be a living document, which will be updated and extended as required during the specification and implementation of the DCS Software.

2. Method

The Automation Framework is an Excel spread sheet that is subdivided in two sections for the Physical Model and the Procedural Model.

The section for the Physical Model identifies all Unit Classes with Unit Instances and all Equipment Module Classes and the location of the Equipment Module Classes.

The spread sheet identifies by **X** all Equipment Modules that belong to one particular Unit.

The spread sheet identifies by **S** all Equipment Modules that are shared Equipment Modules, which do not belong to one particular Unit but can be acquired from Phases that run on particular Units.

The section for the Procedural Model is a Phase Map that identifies all required Phases.

The spread sheet identifies by **X** all Units at which the Phase can be executed .

The spread sheet identifies by **X** or by **S** all Equipment Modules that will be acquired from the Phase.

The following information is provided in the individual columns of the Spread Sheet:

Index	Numerical index for further reference	
Phase Name	Phase Name per Naming Conventions	
Phase Descriptions	Short description of functionality of the Phase	
Ref. PFD	Reference to Page of marked up PFD's, that show SIP, CIP, XFER flow paths	
Phase is executed at Unit	Identification of Units at which an instance of the Phase will be executed	
Phase acquires Equipment Modules	Identification of all Equipment Modules that will be acquired by the Phase per following keys	
	X	Equipment Module from own Unit is acquired
	S	Equipment Module from another Unit or from no Unit (Shared EM) is acquired

3. Naming Conventions

Entity	Naming Convention	Example
Phase	max. 16 characters, capital letters, _ for delimiter	SIP_TANK_EMPTY
Unit	Free text	Buffer Hold Tank 1
EM	max. 16 characters, capital letters, _ for delimiter, EM_.....	EM_Bottom_Group

4. Change Log

The Automation Framework is a living document, that will be updated as required.

Changes to last version will be identified with text in **red letters**.

Major revisions will be done only if structural elements (Units, Equipment Modules, Phases) are added or deleted, and for milestones in project execution. All intermediate versions are indicated by the major revision and subsequent number, e.g. 02-2

Rev.	Date	Name	Description
0	2020-10-28	张予婧	draft
0.1a	2020-11-06	张予婧	add UF phase
0.1b	2020-11-18	张予婧	更新部分描述增加层析排气phase
0.1c	2020-11-20	张予婧	BP_BH launch unit 更新
0.1d	2020-11-25	张予婧	launch unit 更新 add abbreviation list
0.1e	2020-12-10	张予婧	add alarm phase
1.0	2021-03-03	杜林茂	新增PH_S_PUR_PA, PH_X_PT_DF, PH_X_PT_VF, PH_PRES_CONT
2.0	2021-04-26	杜林茂	新增PH_BUF_VD_TM, PH_PUR_VD_TM; 删除PH_SET_STATE

5 Acronyms and Abbreviations

Abbreviation	
S	SIP
C	CIP
LT	Leak test
DR	Drain
X	Transfer
P	Preparation
TC	Temperature control
VAL	Validation
BP	Buffer preparation tank
BH	Buffer holding tank
PUR	Purification tank
CHT	Chromatography
DF	Depth filter
VF	Virus filter
UF	Ultra filter
POU	Point of use
ALW	Alkali and WFI
DIS	Distribution pipe
GEL	Gel tank
PU	Pump
HV	Harvest tank
VT	Vent
Sample	Sample
INST	Install
STOR	Storage
MSG	Message
AG	Agitator
TK	Tank
ALK	Alkali
RTN	Return
WT	Wash tank
RT	Rinse tank
AT	Alkali tank
DSF	Drug substance filling

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