

# Adaptive Runge-Kutta methods

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Advance two exact solutions from  $t$  to  $t + \Delta t$ . Advance one by taking one time step of magnitude  $\Delta t$  (called  $\mathbf{x}_1$ ) and the other by taking two time steps of  $\Delta t$  (called  $\mathbf{x}_2$ ), such that:

$$\begin{aligned}\mathbf{x}(t + \Delta t) &= \mathbf{x}_1 + \mathbf{c}(\Delta t)^{p+1} + \mathcal{O}(\Delta t^{p+2}) \\ \mathbf{x}(t + \Delta t) &= \mathbf{x}_2 + \mathbf{c}2(\Delta t/2)^{p+1} + \mathcal{O}(\Delta t^{p+2})\end{aligned}$$

where the value  $\mathbf{c}$  remains constant over the step and  $\mathcal{O}(\Delta t^{p+2})$  represents the sixth and higher order terms. The difference between the two equations is an indicator of the truncation error:

$$\begin{aligned}0 &= \mathbf{x}_1 + \mathbf{c}(\Delta t)^{p+1} - \mathbf{x}_2 - \mathbf{c}2(\Delta t/2)^{p+1} \\ 0 &= \mathbf{x}_1 - \mathbf{x}_2 + \mathbf{c}\Delta t^{p+1}(1 - 2^{-p}) \\ \mathbf{c} &= \frac{\mathbf{x}_1 - \mathbf{x}_2}{\Delta t^{p+1}(2^{-p} - 1)}\end{aligned}$$

Substitute  $\mathbf{c}$  into the second estimate to get:

$$\begin{aligned}\mathbf{x}(t + \Delta t) &= \mathbf{x}_1 + \frac{\mathbf{x}_1 - \mathbf{x}_2}{\Delta t^{p+1}(2^{-p} - 1)} \Delta t^{p+1}(1/2)^p + \mathcal{O}(\Delta t^{p+2}) \\ &= \mathbf{x}_2 + \frac{\mathbf{x}_1 - \mathbf{x}_2}{2^p - 1} + \mathcal{O}(\Delta t^{p+2})\end{aligned}$$

So if we choose a 4th order method,  $p = 4$ , and to 6th order the truncation error is given

$$\varepsilon = \frac{|\mathbf{x}_1 - \mathbf{x}_2|}{2^p - 1} = \frac{|\mathbf{x}_1 - \mathbf{x}_2|}{15}$$

Therefore if we want the truncation error of a given step to be below some value,  $\varepsilon_0$ :

$$\begin{aligned}\mathbf{c}\Delta t_{\text{new}}^{p+1} &= \frac{\mathbf{x}_1 - \mathbf{x}_2}{(2^{-p} - 1)} \frac{\Delta t_{\text{new}}^{p+1}}{\Delta t^{p+1}} \\ &= \varepsilon \frac{\Delta t_{\text{new}}^{p+1}}{\Delta t^{p+1}} \\ &\leq \varepsilon_0\end{aligned}$$