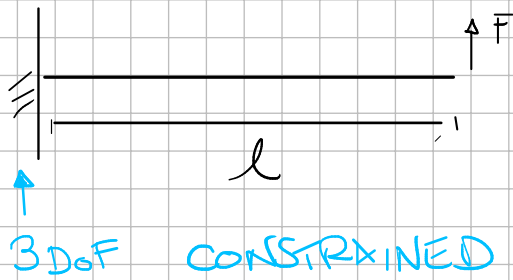


EXERCISE SESSION 1 - 16/09/2022

Isostatic beam systems

Ex 1



FIND VALUES OF

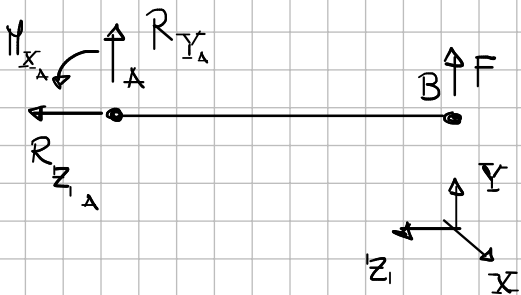
- CONSTRAINT REACTION FORCES
- INTERNAL ACTIONS

3 DoF
3 EQ EQS

HORIZONTAL
VERTICAL
ROTATION

} TRANSLATIONS

1) REACTION FORCES



3 UNKNOWN :

R_{Y_A} R_{Z_A} M_{X_A}

Z : $R_{Z_A} = 0$

Y : $R_{Y_A} + F = 0$

X : $M_{X_A} + F \cdot l = 0$

$\sum F_{z_i} = 0$

$\sum F_Y = 0$

$\sum M_x = 0$ IN POINT A

$$\begin{cases} R_{Z_A} = 0 \\ R_{Y_A} = -F \\ M_{X_A} = -F \cdot l \end{cases}$$

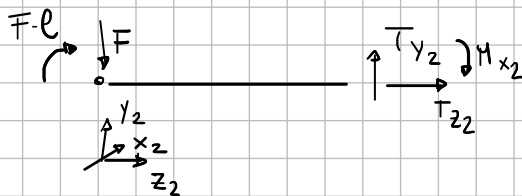
2) INTERNAL ACTIONS



$$\begin{cases} T_{y_1}(z_1) = F \\ T_{z_1}(z_1) = 0 \\ H_{x_1}(z_1) = F \cdot z_1 \end{cases}$$

THESE IN GENERAL TERMS ARE FUNCTIONS OF z_1

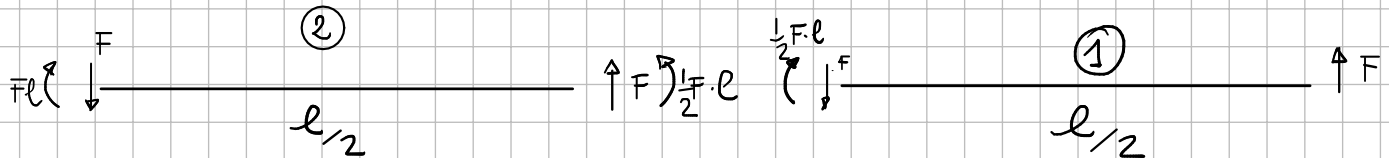
FROM CONSTRAINED SIDE:



EQ EQS

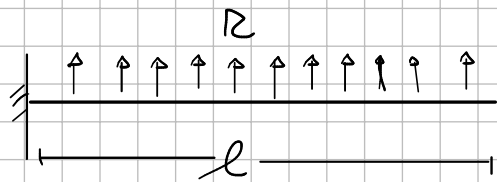
$$\begin{aligned} z_2: & \begin{cases} T_{z_2} = 0 \\ T_{y_2} = F \\ H_{x_2} + F \cdot l - F \cdot z_2 = 0 \end{cases} \\ \text{or } x_2: & \begin{cases} H_{x_2} = F \cdot z_2 - F \cdot l \end{cases} \end{aligned}$$

If we compute internal actions at $z_1 = \frac{l}{2}$ $z_2 = \frac{l}{2}$



THE FACES ARE IN EQUILIBRIUM WHEN WE OPEN A BEAM,
EACH PART IS IN EQUILIBRIUM

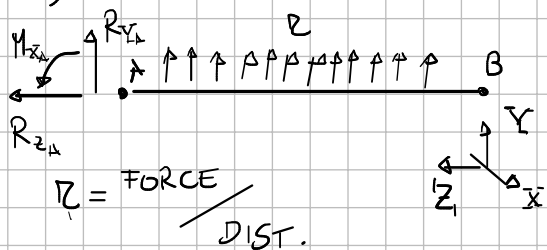
Ex 2



FIND:

- REACTION FORCES
- INTERNAL ACTIONS

1) FIND REACTION FORCES



EQ. EQS

$$\begin{cases} R_{z_A} = 0 \\ R_{y_A} + R \cdot l = 0 \\ M_{x_A} + R \cdot l \cdot \frac{l}{2} \rightarrow \text{ARM} = 0 \end{cases}$$

RESULTANT OF DISTR. FORCE

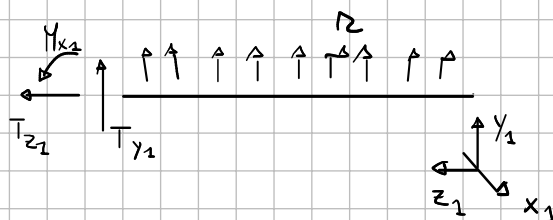
$$M_R = \int_0^l R \cdot z \cdot dz$$

$$R = R \cdot l$$



$$\begin{cases} R_{z_A} = 0 \\ R_{y_A} = -R \cdot l \\ M_{x_A} = -\frac{1}{2} R l^2 \end{cases}$$

2) COMPUTE INTERNAL ACTIONS



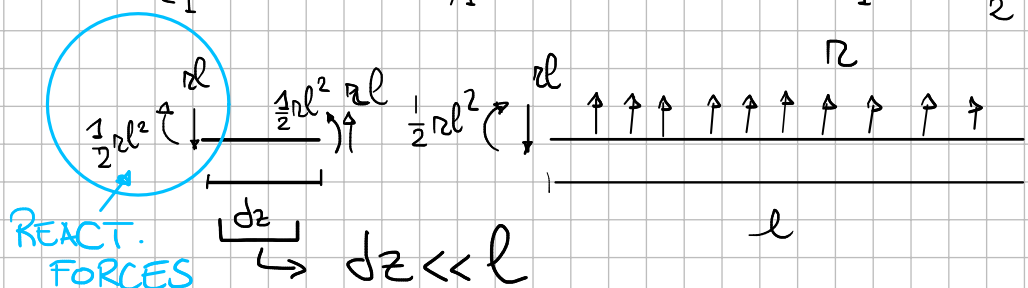
$$\begin{aligned} z_1: & \begin{cases} T_{z_1}(z_1) = 0 \\ T_{y_1}(z_1) = -R z_1 \\ M_{x_1}(z_1) = -\frac{1}{2} R z_1^2 \end{cases} \end{aligned}$$

If we substitute inside here $z_1 = l$

$$T_{z_1} = 0$$

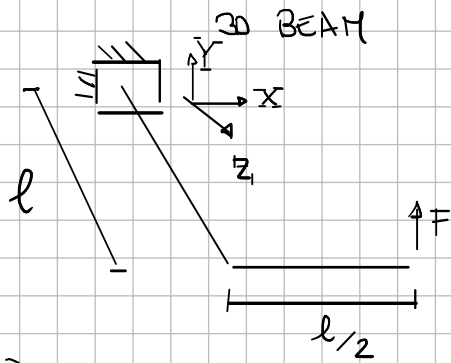
$$T_{y_1} = -Rl$$

$$M_{x_1} = -\frac{1}{2} R l^2$$



We obtain the reaction forces (and not something) in eq. with them

Ex 3



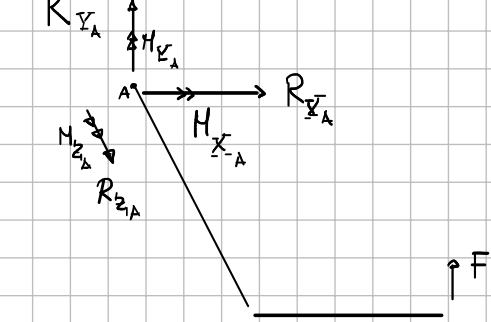
FIND :

- REACTION FORCES
- INTERNAL ACTIONS

6 DOF

6 EQ. EQS

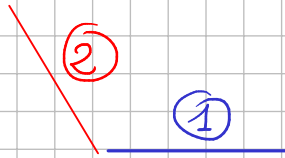
1) REACTION FORCES



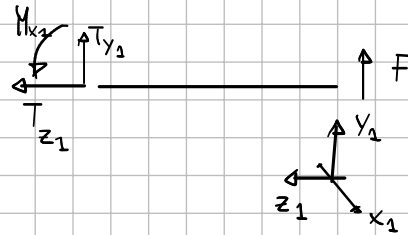
TRANSL. $\begin{cases} X : R_{x_A} = 0 \\ Y : R_{y_A} = -F \\ Z : R_{z_A} = 0 \end{cases}$

ROT IN A $\begin{cases} X : M_{x_A} - F \cdot l = 0 \rightarrow M_{x_A} = F \cdot l \\ Y : M_{y_A} = 0 \\ Z : M_{z_A} + F \cdot \frac{l}{2} = 0 \rightarrow M_{z_A} = -\frac{1}{2} F l \end{cases}$

2) INTERNAL ACTIONS

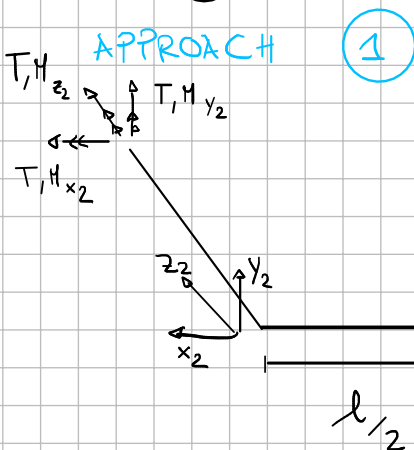


PART ① :



$$\begin{aligned} T_{z_1}(z_1) &= 0 \\ T_{y_1}(z_1) &= -F \\ M_{x_1}(z_1) &= -F \cdot z_1 \end{aligned}$$

PART ②



6 EQ. EQS

$$\begin{cases} T_{z_2} = 0 \\ T_{y_2} = -F \\ T_{x_2} = 0 \end{cases}$$

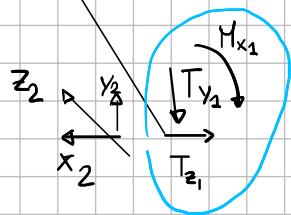
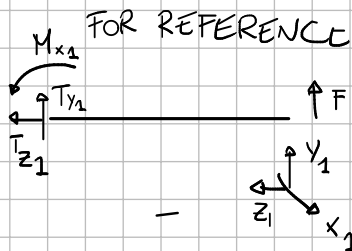
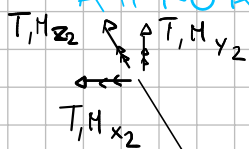
3 EQ FOR TRANSL.

$$\begin{cases} M_{z_2} = F \cdot \frac{l}{2} \\ M_{y_2} = 0 \\ M_{x_2} = -F \cdot z_2 \end{cases}$$

3 EQ FOR ROT.

APPROACH

2



MUST BE EVALUATED IN $z_1 = \frac{l}{2}$

$$\begin{cases} T_{y_2}(z_2) = T_{y_1}\left(\frac{l}{2}\right) \\ T_{z_2}(z_2) = 0 \\ T_{x_2}(z_2) = 0 \end{cases}$$

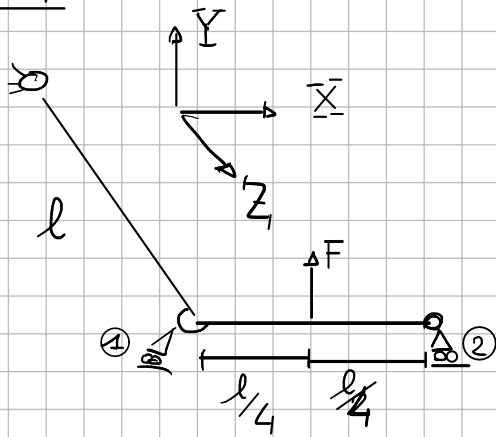
$$\begin{cases} M_{y_2}(z_2) = 0 \\ M_{z_2}(z_2) = -M_{x_1}\left(\frac{l}{2}\right) \\ M_{x_2}(z_2) = T_{y_1}\left(\frac{l}{2}\right) \cdot z_2 \end{cases}$$

PART ①

$$\begin{cases} T_{z_1}(z_1) = 0 \\ T_{y_1}(z_1) = -F \\ M_{x_1}(z_1) = -F \cdot z_1 \end{cases}$$

$$\rightarrow \begin{cases} T_{y_2}(z_2) = -F \\ M_{z_2}(z_2) = F \cdot \frac{l}{2} \\ M_{x_2}(z_2) = -F \cdot z_2 \end{cases}$$

Ex 4



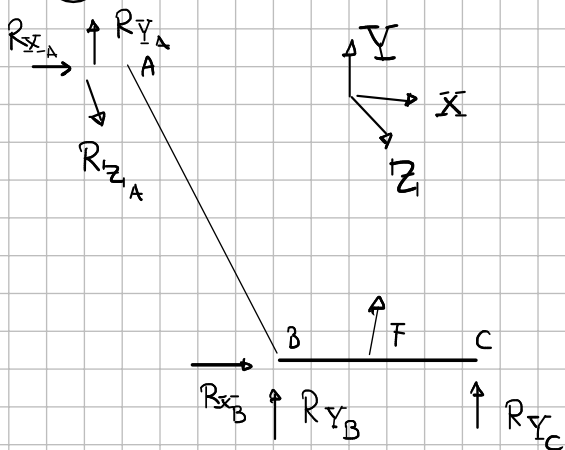
THE BEAM IS CONTINUOUS
SLIDE ① DOES NOT BREAK
THE BEAM!

FIND:

- REACTION FORCES
- INTERNAL ACTIONS

- ① LOCKS \bar{X}, \bar{Y}
② LOCKS \bar{Y}

① REACTION FORCES



EQ EQS

$$\begin{aligned} 1 \bar{X} &: R_{\bar{X}_A} + R_{\bar{X}_B} = 0 \\ 2 \bar{Y} &: R_{\bar{Y}_A} + R_{\bar{Y}_B} + R_{\bar{Y}_C} + F = 0 \\ 3 \bar{Z} &: R_{\bar{Z}_A} = 0 \end{aligned}$$

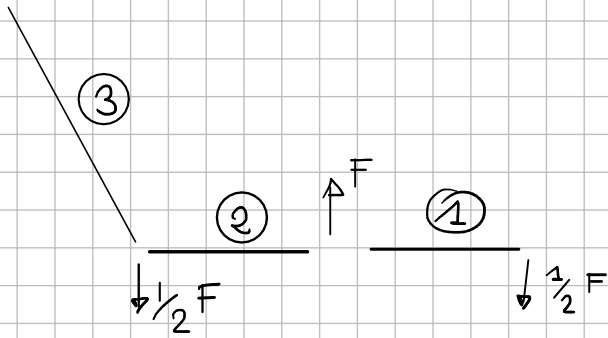
TRANS.

ROT. IN Δ

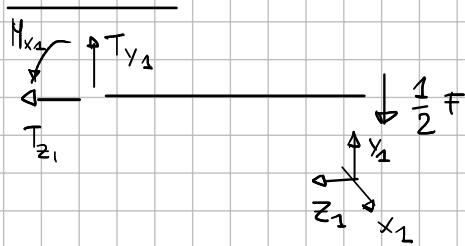
$$\begin{aligned} 4 \bar{X} &: R_{\bar{Y}_B} \cdot l + R_{\bar{Y}_C} \cdot l + F \cdot l = 0 \\ 5 \bar{Y} &: R_{\bar{X}_B} \cdot l = 0 \\ 6 \bar{Z} &: F \cdot \frac{l}{4} + R_{\bar{Y}_C} \cdot \frac{l}{2} = 0 \end{aligned}$$

$$\begin{aligned} 6 &: R_{\bar{Y}_C} = -\frac{1}{2} F \\ 5 &: R_{\bar{X}_B} = 0 \\ 3 &: R_{\bar{Z}_A} = 0 \\ 4 &: R_{\bar{Y}_B} = -\frac{1}{2} F \\ 1 &: R_{\bar{X}_A} = 0 \\ 2 &: R_{\bar{Y}_A} = 0 \end{aligned}$$

2) COMPUTE INT. ACTIONS

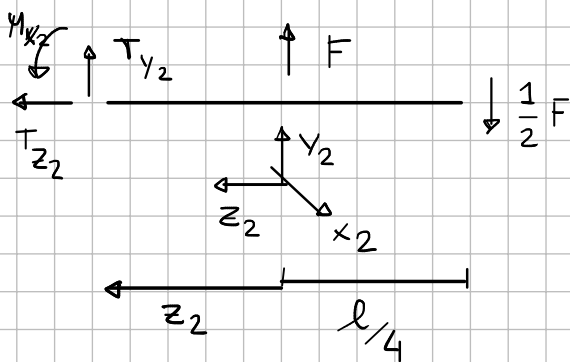


PART 1



$$\begin{cases} T_{z1} = 0 \\ T_{y1}(z_1) = \frac{1}{2} F \\ H_{x1}(z_1) = \frac{1}{2} F \cdot z_1 \end{cases}$$

PART 2

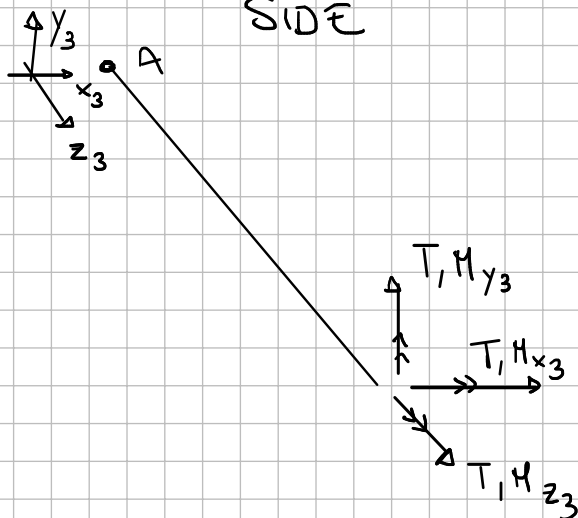


$$\begin{cases} T_{z2}(z_2) = 0 \\ T_{y2}(z_2) = -\frac{1}{2} F \\ H_{x2}(z_2) = \frac{1}{2} F \left(\frac{l}{4} + z_2 \right) - F z_2 \end{cases}$$

PART 3

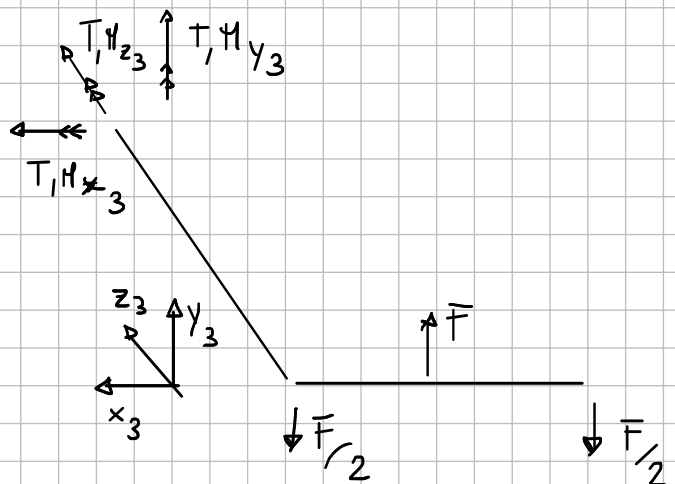
UNLOADED:

COMING FROM CONSTR. SIDE



NO LOADS TO BE
EQUILIBRATED

COMING FROM PART 2



THE SYSTEM OF FORCE IS
ALREADY EQUILIBRATED