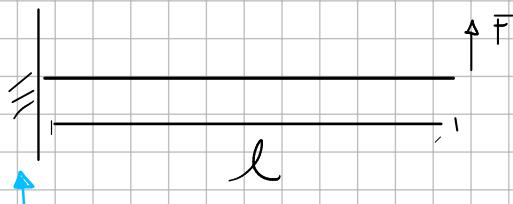


EXERCISE SESSION 1 - 16/09/2022

Bogostatic beam systems

Ex 1

3 DoF CONSTRAINED

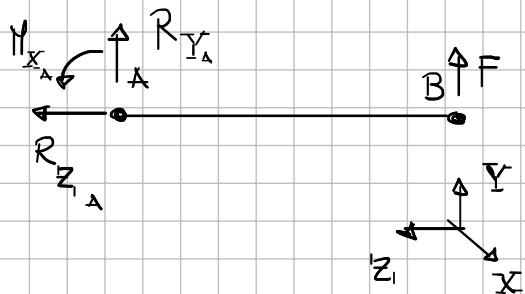
3 DoF
3 EQ EQS

HORIZONTAL
VERTICAL
ROTATION } TRANSLATIONS

FIND VALUES OF

- CONSTRAINT REACTION FORCES
- INTERNAL ACTIONS

1) REACTION FORCES



3 UNKNOWN :

$$R_{z_A}, R_{y_B}, R_{x_A}$$

$$Z : R_{z_A} = 0$$

$$Y : R_{y_B} + F = 0$$

$$X_A : R_{x_A} + F \cdot l = 0$$

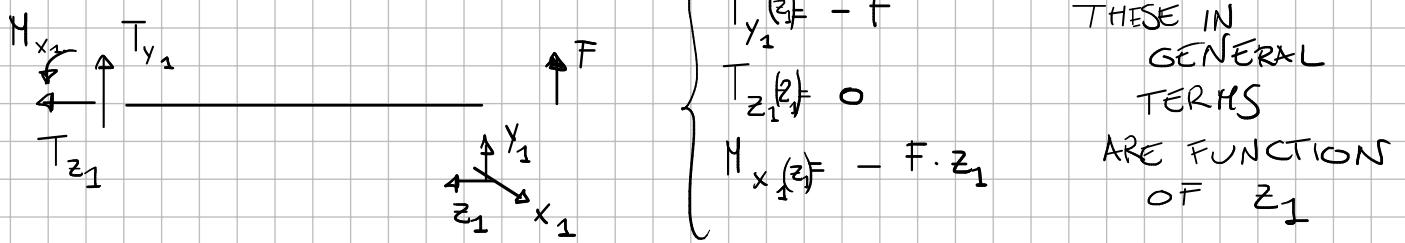
$$\sum F_{z_1} = 0$$

$$\sum F_Y = 0$$

$$\sum M_X = 0 \text{ IN POINT A}$$

$$\left\{ \begin{array}{l} R_{z_A} = 0 \\ R_{y_B} = -F \\ R_{x_A} = -F \cdot l \end{array} \right.$$

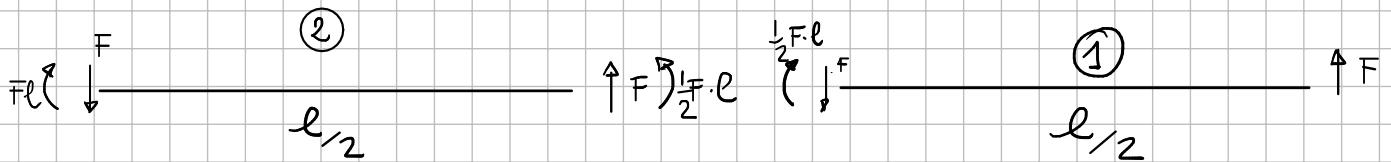
2) INTERNAL ACTIONS



FROM CONSTRAINED SIDE:

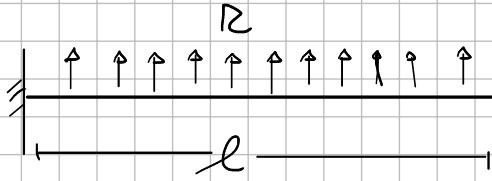
$$\begin{aligned} z_2: & \left\{ \begin{array}{l} T_{z_2} = 0 \\ T_{y_2} = F \\ M_{xz}(z_2) + F \cdot l - F \cdot z_2 = 0 \end{array} \right. \\ \text{at } z_2: & M_{xz}(z_2) = F \cdot z_2 - F \cdot l \end{aligned}$$

If we compute internal actions at $z_1 = \frac{l}{2}$, $z_2 = \frac{l}{2}$



THE FACES ARE IN EQUILIBRIUM WHEN WE OPEN A BEAM,
EACH PART IS IN EQUILIBRIUM

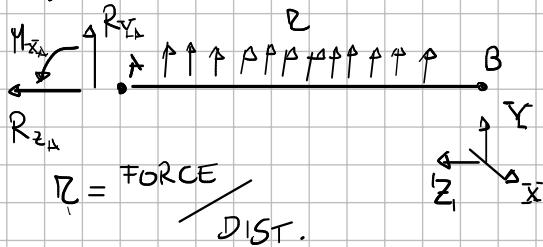
E x 2



FIND :

- REACTION FORCES
- INTERNAL ACTIONS

1) FIND REACTION FORCES



EQ. Eqs

$$\begin{cases} R_{x_A} = 0 \\ R_{y_A} + R \cdot l = 0 \\ M_{x_A} + R \cdot l \cdot \frac{l}{2} \rightarrow \text{ARM} = 0 \end{cases}$$

RESULTANT OF DISTR.
FORCE

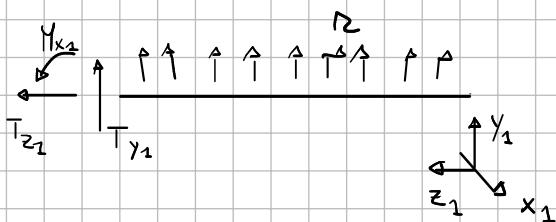
$$M_R = \int_0^l R \cdot z \cdot dz$$

$$R = R \cdot l$$



$$\begin{cases} R_{x_A} = 0 \\ R_{y_A} = - R \cdot l \\ M_{x_A} = - \frac{1}{2} R l^2 \end{cases}$$

2) COMPUTE INTERNAL ACTIONS



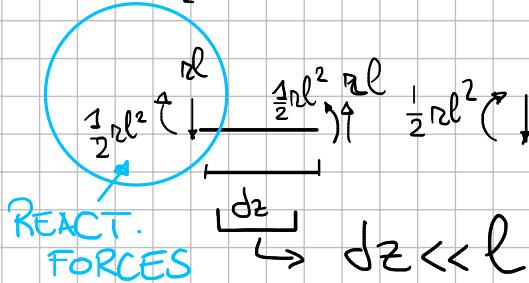
$$\begin{aligned} z_1 : & \left\{ T_{z_1}(z_1) = 0 \right. \\ y_1 : & \left\{ T_{y_1}(z_1) = - R z_1 \right. \\ \text{ROT } x_1 : & M_{x_1}(z_1) = - \frac{1}{2} R z_1^2 \end{aligned}$$

If we substitute inside here $z_1 = l$

$$T_{z_1} = 0$$

$$T_{y_1} = - R l$$

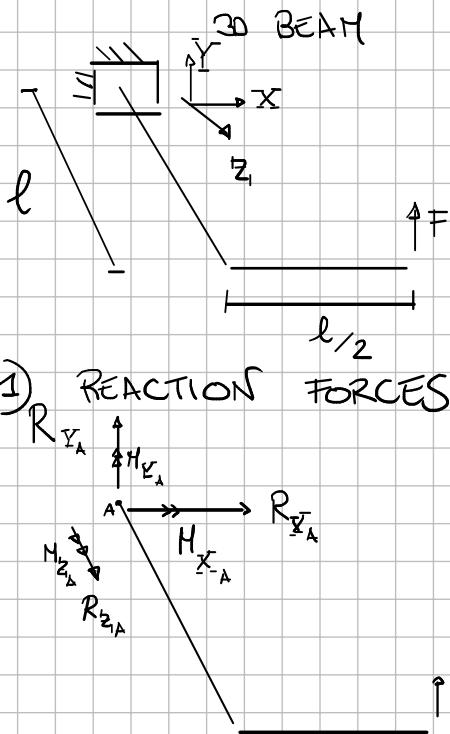
$$M_{x_1} = - \frac{1}{2} R l^2$$



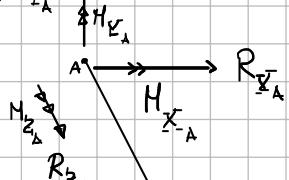
We obtain the reaction forces

(and not something) in eq. with them

Ex 3



1) REACTION FORCES



FIND :

- REACTION FORCES
- INTERNAL ACTIONS

6 DOF

6 EQ. Eqs

TRANSL.

$$X : \begin{cases} R_{x_A} = 0 \\ R_{y_A} = -F \\ R_{z_A} = 0 \end{cases}$$

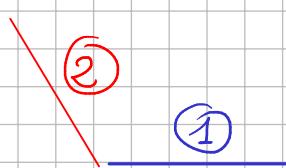
ROT IN A

$$X : M_{x_A} - F \cdot \ell = 0 \rightarrow M_{x_A} = F \cdot \ell$$

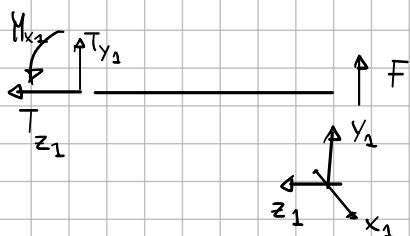
$$Y : M_{y_A} = 0$$

$$Z : M_{z_A} + F \cdot \frac{\ell}{2} = 0 \rightarrow M_{z_A} = -\frac{1}{2}F\ell$$

2) INTERNAL ACTIONS



PART (1) :



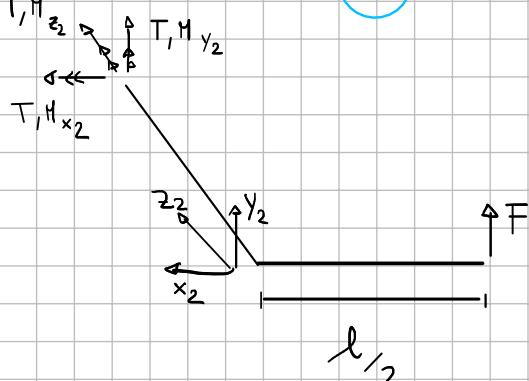
$$T_{z_1}(z_1) = 0$$

$$T_{y_1}(z_1) = -F$$

$$M_{x_1}(z_1) = -F \cdot z_1$$

PART (2)

APPROACH (1)



6 EQ. Eqs

$$\begin{cases} T_{z_2} = 0 \\ T_{y_2} = -F \\ T_{x_2} = 0 \end{cases}$$

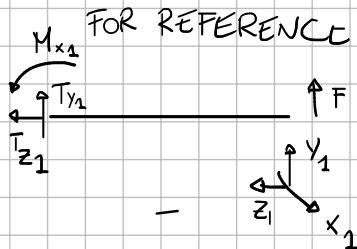
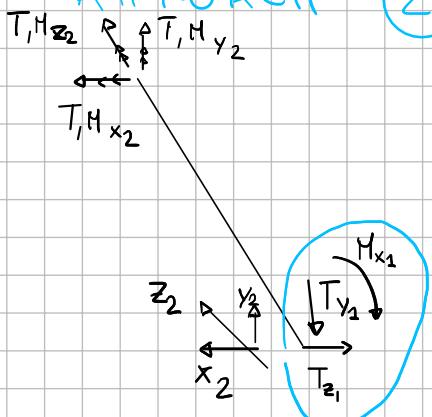
3 EQ FOR TRANSL.

$$\begin{cases} M_{z_2} = F \cdot \ell/2 \\ M_{y_2} = 0 \\ M_{x_2} = -F \cdot z_2 \end{cases}$$

3 EQ FOR ROT.

APPROACH

(2)



MUST BE EVALUATED IN $z_1 = \frac{l}{2}$

$$\begin{cases} T_{y_2}(z_2) = T_{y_1}\left(\frac{l}{2}\right) \\ T_{z_2}(z_2) = 0 \\ T_{x_2}(z_2) = 0 \end{cases}$$

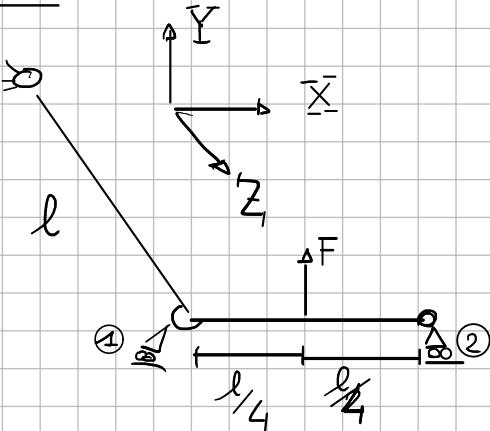
$$\begin{cases} M_{y_2}(z_2) = 0 \\ M_{z_2}(z_2) = -M_{x_1}\left(\frac{l}{2}\right) \\ M_{x_2}(z_2) = T_{y_1}\left(\frac{l}{2}\right) \cdot z_2 \end{cases}$$

PART (1)

$$\begin{cases} T_{z_1}(z_1) = 0 \\ T_{y_1}(z_1) = -F \\ M_{x_1}(z_1) = -F \cdot z_1 \end{cases}$$

$$\rightarrow \begin{cases} T_{y_2}(z_2) = -F \\ M_{z_2}(z_2) = F \cdot \frac{l}{2} \\ M_{x_2}(z_2) = -F \cdot z_2 \end{cases}$$

Ex 4



- ① LOCKS \bar{X}, \bar{Y}
② LOCKS \bar{Y}

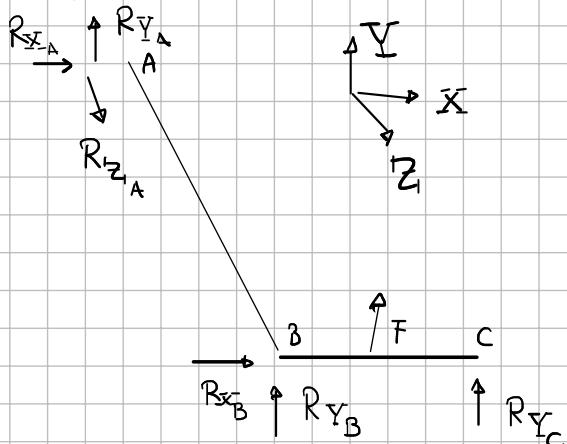
THE BEAM IS CONTINUOUS

SLIDE ① DOES NOT BREAK
THE BEAM!

FIND:

- REACTION FORCES
- INTERNAL ACTIONS

① REACTION FORCES



EQ Eqs)

$$\begin{aligned} 1 \bar{X} : & \left\{ \begin{array}{l} R_{X_A} + R_{X_B} = 0 \\ R_{Y_A} + R_{Y_B} + R_{Y_C} + F = 0 \\ R_{Z_A} = 0 \end{array} \right. \\ 2 \bar{Y} : & \left\{ \begin{array}{l} R_{Y_A} + R_{Y_B} + R_{Y_C} + F = 0 \\ R_{Z_A} = 0 \end{array} \right. \\ 3 \bar{Z} : & \left\{ \begin{array}{l} R_{Z_A} = 0 \end{array} \right. \end{aligned}$$

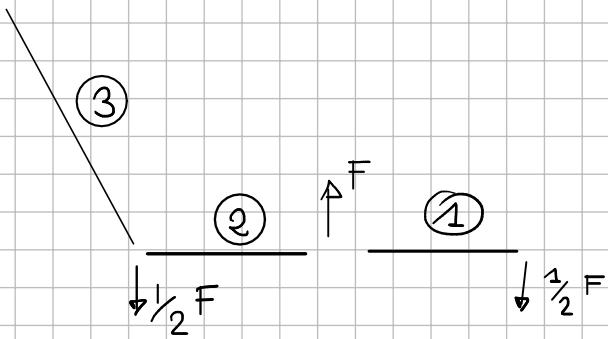
TRANS.

ROT. IN A

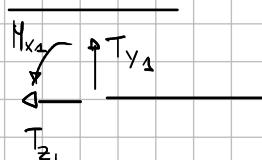
$$\begin{aligned} 4 \bar{X} : & \left\{ R_{Y_B} \cdot l + R_{Y_C} \cdot l + F \cdot l = 0 \right. \\ 5 \bar{Y} : & \left\{ R_{X_B} \cdot l = 0 \right. \\ 6 \bar{Z} : & \left\{ F \cdot \frac{l}{4} + R_{Y_C} \cdot \frac{l}{2} = 0 \right. \end{aligned}$$

$$\begin{aligned} 6. & \left\{ R_{Y_C} = -\frac{1}{2}F \right. \\ 5 & \left. R_{X_B} = 0 \right. \\ 3 & \left. R_{Z_A} = 0 \right. \\ 4 & \left. R_{Y_B} = -\frac{1}{2}F \right. \\ 1 & \left. R_{X_A} = 0 \right. \\ 2 & \left. R_{Y_A} = 0 \right. \end{aligned}$$

2) COMPUTE INT. ACTIONS

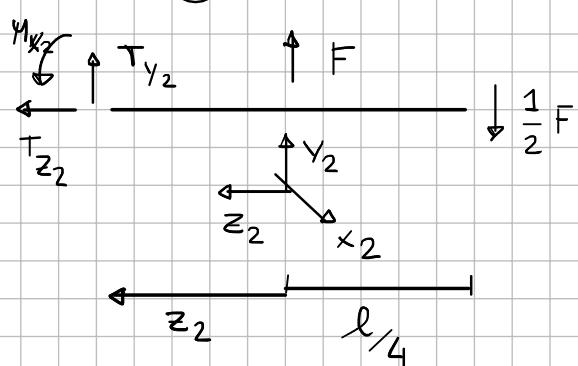


PART 1



$$\begin{cases} T_{z_1} = 0 \\ T_{y_1}(z_1) = \frac{1}{2} F \\ M_{x_1}(z_1) = \frac{1}{2} F \cdot z_1 \end{cases}$$

PART 2



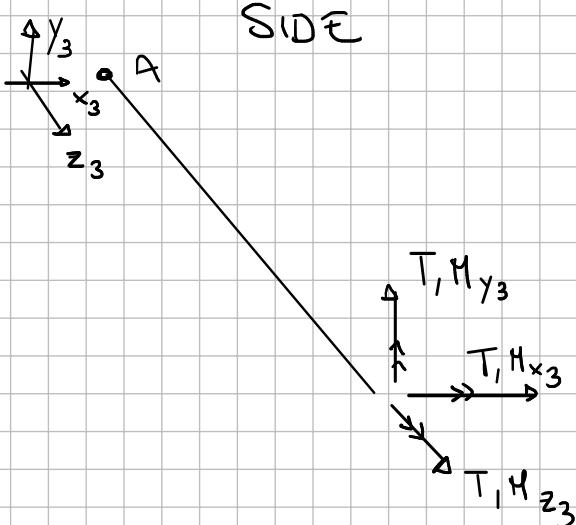
$$\begin{cases} T_{z_2}(z_2) = 0 \\ T_{y_2}(z_2) = -\frac{1}{2} F \\ M_{x_2}(z_2) = \frac{1}{2} F \left(\frac{l}{4} + z_2 \right) - F z_2 \end{cases}$$

PART 3

UNLOADED :

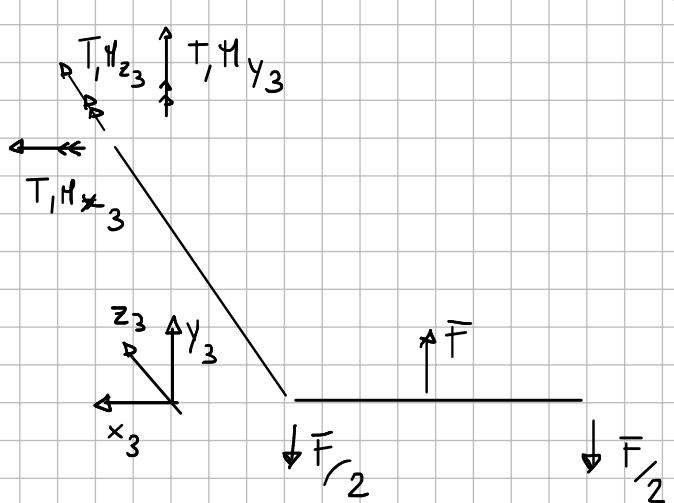
COMING FROM CONSTR.

SIDE



NO LOADS TO BE
EQUILIBRATED

COMING FROM PART 2



THE SYSTEM OF FORCE IS
ALREADY EQUILIBRATED