

Find the minimum value  
 $EJ/EJ_0$  such that  
the vertical displacement  
at  $x = L/2$  is smaller  
than  $w_{max}$

### Data

$$L = 1200 \left(1 + \frac{B}{10}\right) \text{ mm}$$

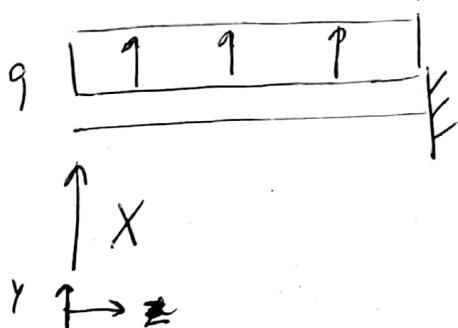
$$EJ_0 = 6 \cdot 10^7 \text{ N mm}^2$$

$$q = 1.0 \cdot \left(1 + \frac{C}{10}\right) \text{ N/mm}$$

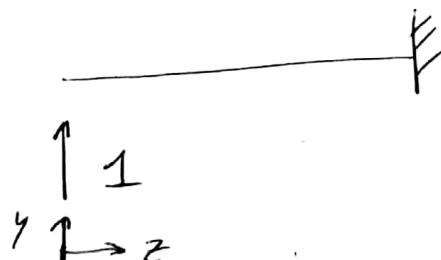
$$w_{max} = 5.0 \text{ mm}$$

### Solution ( $B = C = 0$ )

Find first the unknown reaction force  $X$



Real

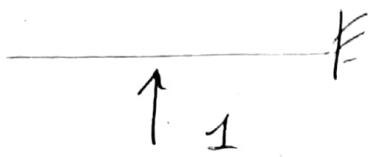
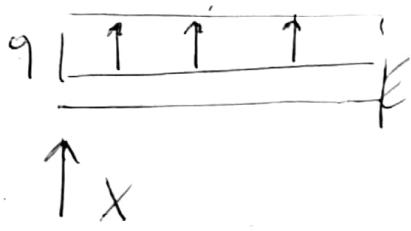


Dummy

$$M_x = -Xz - \frac{qz^2}{2} \quad \delta M_x = -z$$

$$\int_0^L \frac{M_x \delta M_x}{EI} dz = 0 \Rightarrow X = -\frac{3}{8} qL$$

Evaluate now the displacement:



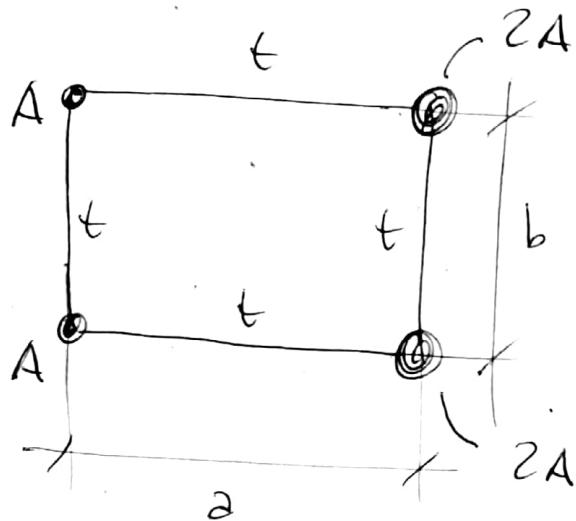
As before

$$\delta M_x = -z + \frac{L}{2}$$

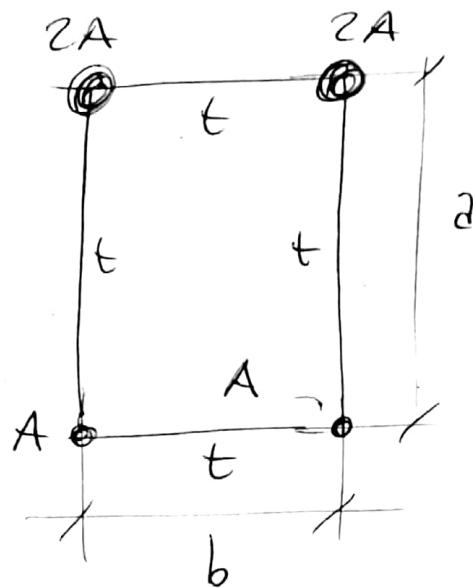
$$\int_{L/2}^L \frac{\delta M_x M_x}{EI} dz = S = W_{max} \quad \text{and so:}$$

$$EI = \frac{1}{W_{max}} \int_{L/2}^L \delta M_x M_x dz \quad \text{from which}$$

$$\frac{EI}{EI_0} = \frac{1}{EI_0} \frac{L^3 (40x + 17qL)}{384 W_{max}}$$



Section #1



Section #2

Calculate the ratio between the rotational stiffness of the two sections  $GJ_2 / GJ_1$

Data

$$a = 200 \left(1 + F_{10}\right) \text{ mm}$$

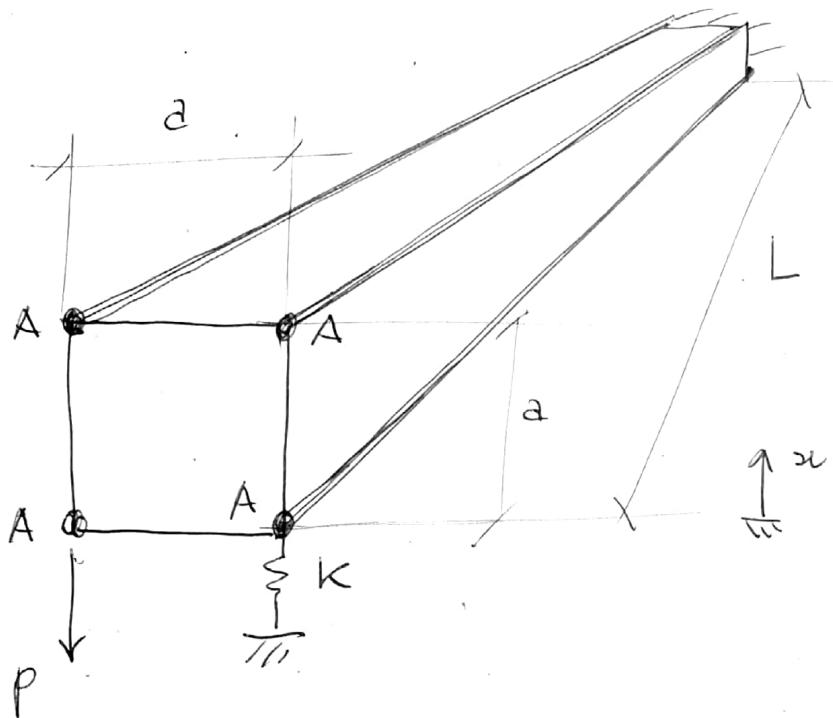
$$b = 100 \text{ mm}$$

$$A = 500 \left(1 + A_{10}\right) \text{ mm}^2$$

$$t = 1 \text{ mm}$$

Solution

$$GJ_2 / GJ_1 = 1.0$$



Determine the vertical displacement in correspondence of the spring. (refer to the  $x$  axis in the figure)

### Data

$$A = 250 \text{ mm}^2$$

$$E = 72000 \text{ MPa}$$

$$a = 150 \text{ mm}$$

$$\varphi = 0.3$$

$$t = 0.6 (1 + \beta/10) \text{ mm}$$

$$P = 1700 \text{ N}$$

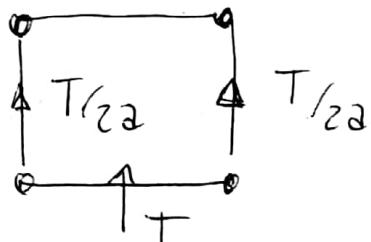
$$L = 1200 (1 + F/10) \text{ mm}$$

$$K = 100 \text{ N/mm}$$

Solution ( $B = F = 0$ )

Section properties can be evaluated straightforwardly by exploiting the section symmetries

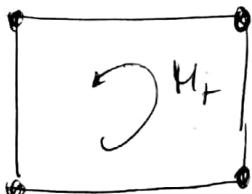
Shear



$$A^* = 2at$$

$$GA^* = 2atG$$

Torsional

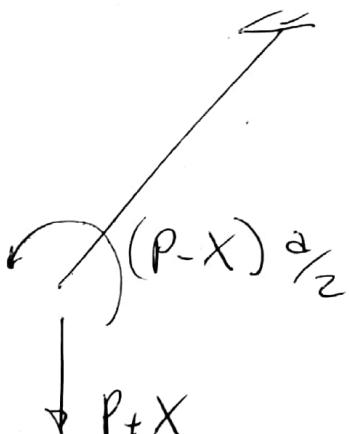


$$GJ = G a^3 t$$

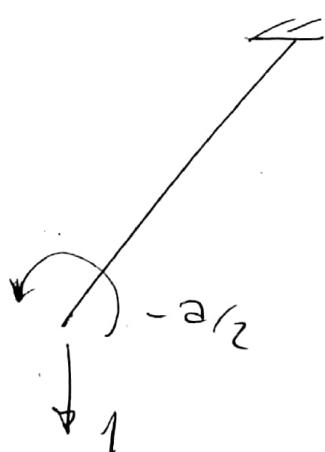
Bending

$$EI = EAa^2$$

Evaluate how the unknown reaction force  $X$  is  
correspondence of the spring



Real



Dummy

$$T = P + X$$

$$\delta T = 1$$

$$M = (P + X) z$$

$$\delta M = z$$

$$M_t = (P - X) \frac{d}{z}$$

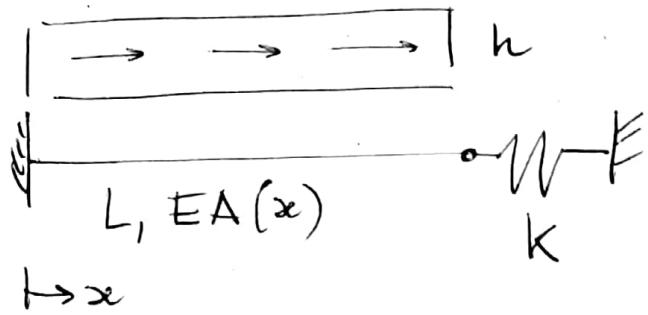
$$\delta M_t = - \frac{d}{z}$$

$$\int_0^L \left( \frac{\delta T T}{GA^*} + \frac{\delta M M}{EI} + \frac{\delta M_t M_t}{GJ} \right) dz + \frac{X}{k} = 0$$

From which:

$$X = P \frac{\frac{z^2}{4GJ} - \frac{L^2}{3EI} - \frac{1}{6A^*}}{\frac{1}{6A^*} + \frac{L^2}{3EI} + \frac{z^2}{4GJ} + \frac{1}{KL}} = -222.55 N$$

$$S = \frac{X}{k} = -2.23 \text{ mm}$$



Using the Ritz method and a 2-dof polynomial approximation determine the strain energy

Defo

$$L = 2700 \text{ mm}$$

$$h = 2(1 + F_{10}) \text{ N/mm}$$

$$EA_0 = 2.8 \cdot 10^5 \text{ N}$$

$$EA_1 = 6.5 \cdot 10^5 \text{ N}$$

$$k = 300(1 + B_{10}) \text{ N/mm}$$

Solution ( $B = F = 0$ )

$$u(x) = q_1 x + q_2 x^2, \text{ so:}$$

$$\int_0^L \delta u_{xx} EA(x) u_{xx} dx + \delta u(L) k u(L) =$$

$$= \int_0^L \delta u h dx$$

$$\text{with } EA(x) = \alpha + \beta x$$

$$\text{and } \alpha = EA_0; \beta = \frac{EA_1 - EA_0}{L}$$

Upon substitution:

$$k_{11} = \alpha L + \beta L^2/2 + kL^2$$

$$k_{12} = k_{21} = \alpha L^2 + 2\beta L^3/3 + kL^3$$

$$k_{22} = 4\beta L^3/3 + \beta L^4 + kL^4$$

$$f_1 = L^2/2 h$$

$$f_2 = L^3/3 h$$

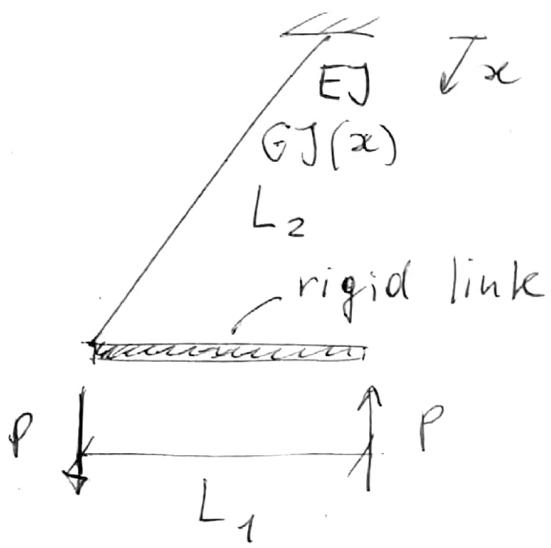
The problem is then:  $\underline{k} \underline{q} = \underline{f}$ , from which:

$$q_1 = 9.23 \cdot 10^{-3}$$

$$q_2 = -2.51 \cdot 10^{-6}$$

The strain energy is:

$$U = \frac{1}{2} \underline{q}^T \underline{k} \underline{q} = 17151 \text{ Nmm}$$



Using the Ritz method  
and a 1-dof polynomial  
approximation, determine  
the strain energy.

( $GJ$  varies linearly  
from  $GJ_0$  at  $x=0$   
to  $GJ_1$  at  $x=L_2$ )

$$L_1 = 180 \text{ mm}$$

$$L_2 = 1800 \text{ mm}$$

$$GJ_0 = 1.1 \cdot 10^8 \text{ N mm}^2$$

$$GJ_1 = 3.3 \cdot 10^8 \text{ N mm}^2$$

$$P = 50(1 + D/10) \text{ N}$$

Solution ( $D=0$ )

$$\theta = q_1 x$$

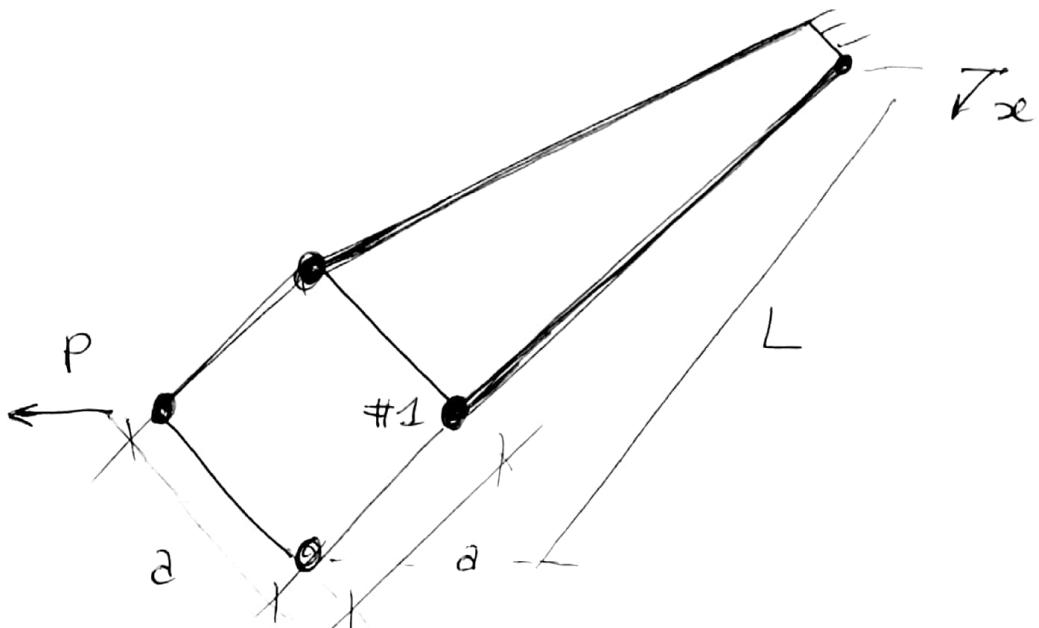
$$GJ(x) = \alpha + \beta x; \quad \alpha = GJ_0; \quad \beta = \frac{GJ_1 - GJ_0}{L_2}$$

$$\int_0^{L_2} \delta \theta' GJ(x) \theta' dx = \delta \theta(L_2) PL_1, \quad \text{so:}$$

$$\left( \alpha L_2 + \beta L_2^2 / 2 \right) q_1 = PL_1 L_2$$

$$q_1 = 4.091 \cdot 10^{-5}, \text{ and}$$

$$U = \frac{1}{2} (\alpha L_2 + \beta L_2^2 / \zeta) q_1^2 = 331.36 \text{ Nmm}$$



Evaluate the axial stress in stringer #1 at  $x=0$ .

Dots

$$a = 180 \text{ mm} \quad L = 1600 (1+A/10) \text{ mm}$$

$$A = 350 \text{ mm}^2 \quad P = 1300 (1+F/10) \text{ N}$$

Solution ( $A=F=0$ )

$$J_{xx} = Aa^2$$

The bending moment at  $x=0$  is  $M = PL$ , so:

$$\sigma = \frac{M}{J_{xx}} \frac{2\sqrt{2}}{2} = 23.35 \text{ MPa}$$

- The solution due to De Saint Venant does not account for local effects because local effects are always negligible.

False

- The Hooke's law is a constitutive law for linear elastic materials.

True

- Shear deformability effects are generally more relevant for thin-walled beams than for compact beams.

True

- The elastic problem can be formulated in terms of displacements:

Always

- The shear center of open section thin-walled beam section modeled according to the semi-monocoque scheme

can be determined by imposing the equivalence of torsional moment

- The Timoshenko beam model

accounts for shear deformability