

# Course of Aerospace Structures

Written test, January 23<sup>th</sup>, 2024

Name \_\_\_\_\_

Surname \_\_\_\_\_

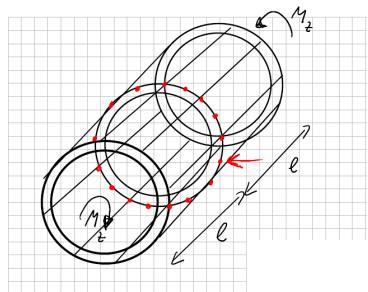
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## Exercise 1

The figure represents a semi-monocoque model of a fuselage trunk of length  $2l$ . It has three circular frames, each with outer radius  $r_1$  and inner radius  $r_2$ , and eight uniformly spaced stringers, each with concentrated area  $A$ . The outer cylindrical thin panel thickness is equal to  $t$ . The panel is connected to the central frame by means of sixteen uniformly spaced rivets, each with shank diameter  $d$ , and represented by the red dots in the figure. The outer cylindrical thin panel is continuous across the central rib (there is not a junction between a “forward” and “rear” panel), thus the rivets do only connect the rib to the continuous panel. The fuselage is transmitting a constant torsional moment  $M_z$ . Compute the shear stress in the rivet shank highlighted by the red arrow.

(Unit for result: MPa)



### Data

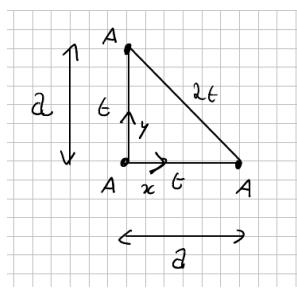
$r_1 = 1.5 \text{ m}$   
 $r_2 = 1.45 \text{ m}$   
 $l = 1 \text{ m}$   
 $d = 3 \text{ mm}$   
 $A = 10 \text{ cm}^2$   
 $t = 1.5 \text{ mm}$   
 $M_z = 15000 \text{ N m}$

Answer \_\_\_\_\_

## Exercise 2

The semi-monocoque cross section sketched in the figure has three concentrated areas  $A$ , two panels with thickness  $t$  and one panel with thickness  $2t$ . Compute, with respect to the reference system sketched in the figure, the  $x$  coordinate of the shear center.

(Unit for result: mm)



### Data

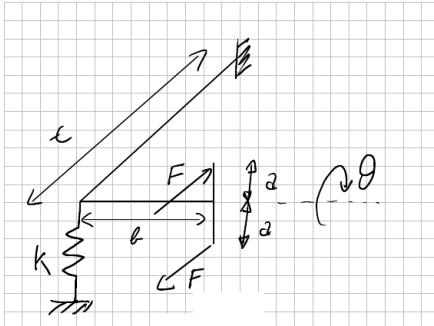
$a = 1 \text{ m}$   
 $A = 4 \text{ cm}^2$   
 $E = 7 \times 10^4 \text{ MPa}$   
 $\nu = 0.3$

Answer \_\_\_\_\_

**Exercise 3**

Consider the thin beam model sketched in the figure, and loaded by the two forces  $F$ . All the beams have the same cross-section. Compute the rotation  $\theta$  of the point where the beam of length  $b$  is joined to the two beams of length  $a$ . Neglect shear deformability.

(Unit for result: rad)



Answer \_\_\_\_\_

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*Data*

$$a = 1 \text{ m}$$

$$b = 2 \text{ m}$$

$$c = 3 \text{ m}$$

$$EI_{xx} = EI_{yy} = 12 \times 10^{14} \text{ N mm}^2$$

$$EA = 6 \times 10^{10} \text{ N}$$

$$GJ = 7 \times 10^{14} \text{ N mm}^2$$

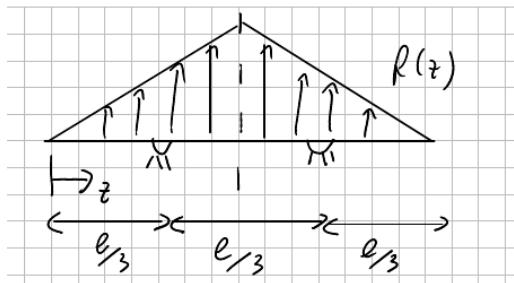
$$K = 1 \times 10^6 \text{ N/mm}$$

$$F = 10000 \text{ N}$$

**Exercise 4**

Consider the simply supported thin beam model sketched in the figure, with overall length  $l$ , and loaded by the linearly varying force per unit of length  $f(z)$ , with maximum value equal to  $a$ . Compute the exact vertical displacement  $v(l/2)$  in the middle of the beam. Neglect shear deformability.

(Unit for result: mm)



Answer \_\_\_\_\_

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*Data*

$$a = 1000 \text{ N/mm}$$

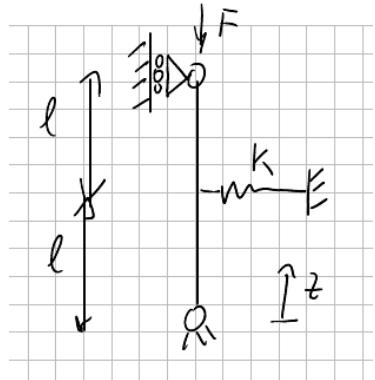
$$l = 2000 \text{ mm}$$

$$EI = 12 \times 10^{12} \text{ N mm}^2$$

**Exercise 5**

The thin beam sketched in the figure, of length  $2l$ , is loaded by the compressive force  $F$ . A spring with stiffness  $K$  is connected in the middle of the beam, and helps increasing the beam buckling load. Compute the approximated value of critical buckling load by resorting to a suitable polynomial approximation of the transverse displacement truncated to the first non-null term.

(Unit for result: N)



*Data*

$$\begin{aligned}l &= 2000 \text{ mm} \\EA &= 6 \times 10^{10} \text{ N} \\EI &= 12 \times 10^{10} \text{ N mm}^2 \\K &= 1 \times 10^3 \text{ N/mm}\end{aligned}$$

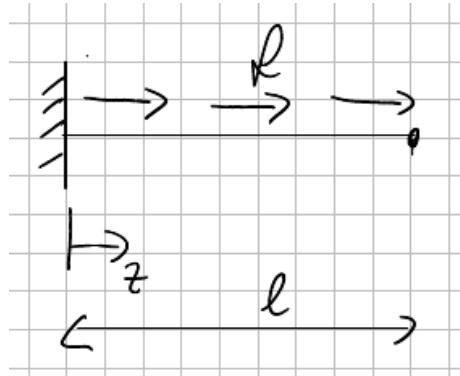
Answer \_\_\_\_\_

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**Exercise 6**

The clamped beam sketched in the figure has a varying axial stiffness  $EA(z) = a + bz$ , and is loaded by the constant force per unit of length  $f$ . By resorting to a polynomial approximation of the axial displacement, truncated to one term, estimate the axial displacement  $w(l)$  at the free extremity of the beam.

(Unit for result: mm)



*Data*

$$\begin{aligned}l &= 4000 \text{ mm} \\f &= 1000 \text{ N/mm} \\a &= 6 \times 10^{10} \text{ N} \\b &= 2.5 \times 10^7 \text{ N/mm}\end{aligned}$$

Answer \_\_\_\_\_

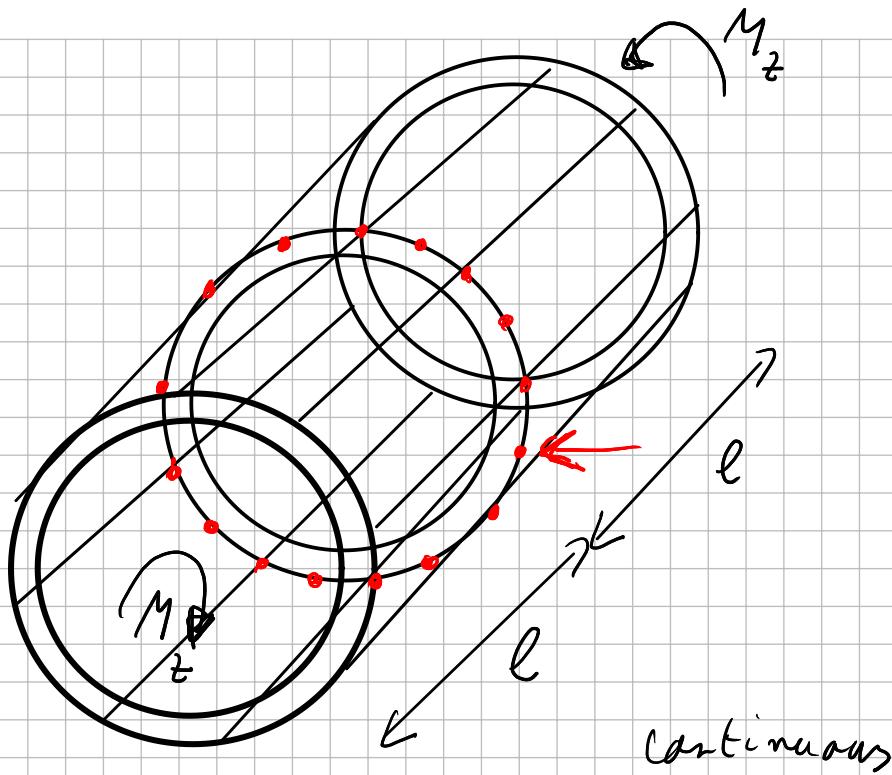
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**True/False Questions***(Put a T (true) or F (false) at the end of the sentence)*

1. The axial stress of beam that is transmitting a constant bending moment  $M_x$  does not depend on the material elastic modulus  $E$
2. The Timoshenko model is used to compute the critical buckling stress of a simply supported compressed plate
3. Hermitian shape functions are  $C^2$  (continuous, and with continuous first and second derivatives)

**Multiple Choice questions***(Circle the correct answer)*

1. “Crippling” is:
  - (a) a failure mode of thin-walled compressed beam
  - (b) a failure mode of compact compressed beam
  - (c) a failure mode affecting the fuselage of Boeing 737 MAX
  - (d) a failure mode of railways
  - (e) a special design technique preventing the buckling of beams
  - (f) none of the above
2. Assume that the solution of a given three dimensional elastic problem has a finite  $H_{10}$  norm; an approximated solution, obtained with quadratic finite elements with average dimension  $h$ :
  - (a) has quadratic convergence of the stress with respect to  $h$
  - (b) has cubic convergence of the stress with respect to  $h$
  - (c) has linear convergence of the displacement with respect to  $h$
  - (d) has quadratic convergence of the displacement with respect to  $h$
  - (e) none of the above
3. A structure is modeled using finite elements. It is unconstrained and subjected to a set of loads in self equilibrium. The solution of the linear static problem:
  - (a) is stress-free because the loads have null resultant and moment resultant
  - (b) can be computed, up to a rigid body motion, after constraining the displacement of the structure all over its boundary
  - (c) can be computed only if the loads are concentrated
  - (d) can be computed, up to a rigid body motion, only if the loads are distributed
  - (e) is defined up to a rigid body motion; thus, not being unique, it is not possible to compute the stress and strain fields
  - (f) none of the above



the torsional moment  $M_z$ . Compute the shear stress in the rivet shanks.

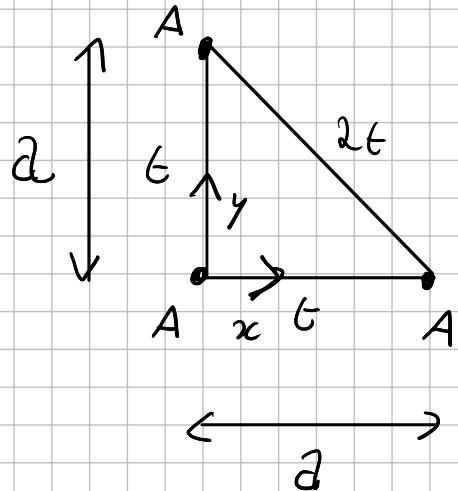
$$R_1 = 1,5 \text{ m} \quad l = 1 \text{ m} \quad d = 3 \text{ mm}$$

$$R_2 = 1,45 \text{ m} \quad A = 10 \text{ cm}^2 \quad t = 1,5 \text{ mm}$$

$$M_z = 15000 \text{ Nm}$$

The figure represents a semi-nanalog model of a fuselage section, with three circular frames, with outer radius  $R_1$  and inner radius  $R_2$ , eight equispaced stringers with concentrated area  $A$  and a thin lateral panel with thickness  $t$ . The panel is connected to the frames by means of sixteen equispaced rivets with shank diameter  $d$ , represented by the red dots in the figure. The fuselage is transmitting the torsional moment  $M_z$ . Compute the shear stress in the rivet shanks.

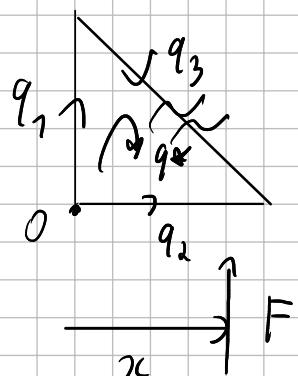
$$\cancel{\sigma_{zz}} = 0 \text{ MPa}$$



The semi-monocyclic cross section sketched in the figure has the concentrated areas  $A$ , two panels with thickness  $t$  and one panel with thickness  $2t$ . Compute, considering the reference system sketched in the figure, the  $x$  coordinate of the shear center.

$$d = 7 \text{ mm} \quad A = 4 \text{ mm}^2 \quad t = 1 \text{ mm}$$

$$E = 70000 \text{ MPa} \quad V = 0,3$$



$$\theta' = \frac{1}{\alpha^2 G} \left( \frac{q_1 \alpha}{t} + \frac{q_3 \alpha \sqrt{2}}{2t} - \frac{q_2 \alpha}{t} \right) = \frac{\alpha}{\alpha^2 E G} \left( \left(1 - \frac{x}{\alpha}\right) - \frac{\sqrt{2} x}{\alpha} - \frac{\sqrt{2} x}{2\alpha} \right) = 0$$

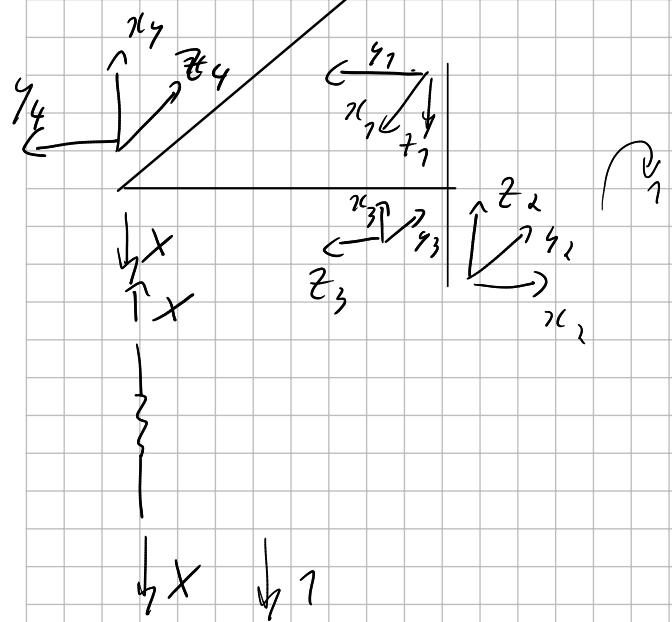
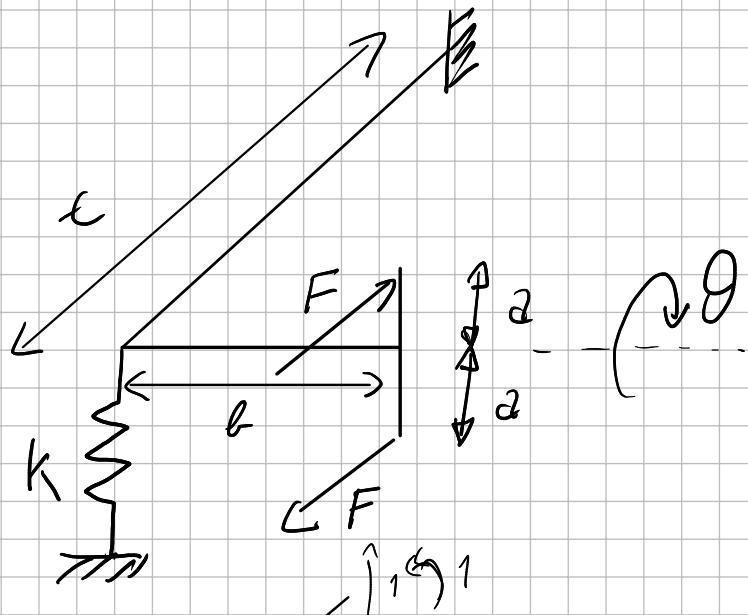
$$q'_1 = \frac{F}{\alpha} \quad q'_2 = 0$$

$$M_{f(0)} = q'' \cdot \alpha^2 = -Fx \quad q'' = -\frac{F x}{\alpha^2}$$

$$q_1 = \frac{F}{\alpha} \left( 1 - \frac{x}{\alpha} \right) \quad q_2 = \frac{F x}{\alpha^2} \quad q_3 = -\frac{F x}{\alpha^2}$$

$$\frac{(-4 - \sqrt{2})x}{2d} = -1$$

$$x = \frac{2d}{(4 + \sqrt{2})} = 369,4 \text{ mm}$$



$$a = 1 \text{ m}$$

$$b = 2 \text{ m}$$

$$\ell = 3 \text{ m}$$

$$k = 1E6 \text{ N/mm}$$

$$F = 10000 \text{ N}$$

$$EI = 12E14 \text{ Nmm}^2$$

$$EA = 6E20 \text{ N}$$

$$GJ = 7E14 \text{ Nmm}^2$$

$\theta_1$

$$M_{y_1} = -F z_1$$

$$M_{x_2} = +F z_2$$

$$M_{z_3} = -2Fa$$

$$M_{y_4} = X z_4 - 2Fa$$

$$M'_{y_1} = \emptyset$$

$$M'_{x_2} = \emptyset$$

$$M'_{z_3} = -1$$

$$M'_{y_4} = -1$$

$$X' = \emptyset$$

$$M''_{y_1} = \emptyset$$

$$M''_{x_2} = \emptyset$$

$$M''_{z_3} = \emptyset$$

$$M''_{y_4} = z_4$$

Compute  $X$

$$\int_0^L \frac{M_{44} \cdot M''_{44}}{EI_{yy}} dz + \frac{X}{K} = 0$$

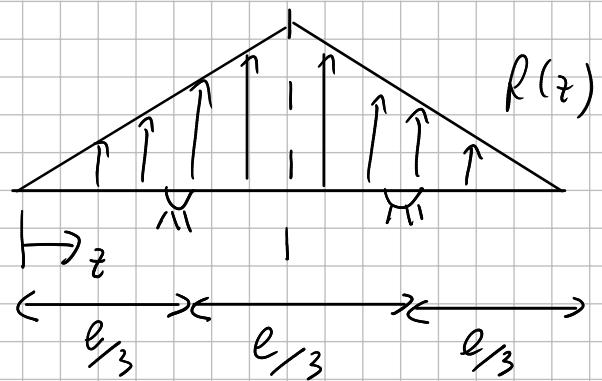
$$\int_0^L \frac{X z_4^2 - 2 F_d z_4}{EI} dz + \frac{X}{K} = \frac{1}{3} \frac{X \epsilon^3}{EI} - \frac{F_d \epsilon^2}{EI} + \frac{X}{K} = 0$$

$$X \left( \frac{\epsilon^3}{3 EI} + \frac{1}{K} \right) = \frac{F_d \epsilon^2}{EI} \quad X = 8823,5 \text{ N}$$

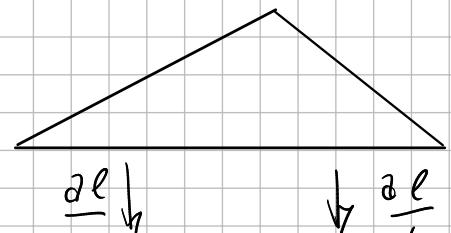
Compute  $\delta$

$$\int_0^L \frac{M_{44} M'_{44}}{GJ} dz + \int_0^L \frac{M_{44} M'_{44}}{EI} dz = 1.9$$

$$\frac{2 F_d}{GJ} L - \frac{X \epsilon^2}{2 EI} + \frac{2 F_d \epsilon}{EI} = \delta = 7,4 E - 5 \text{ rad}$$



$$\int_0^l R(z) = \frac{a\ell}{2}$$



$$R(z) = a \frac{2z}{\ell} \quad \forall z \in [0, \frac{\ell}{2}]$$

$$a \left(1 - \frac{2z}{\ell}\right) \quad \forall z \in [\frac{\ell}{2}, \ell]$$

$$a = 1000 \text{ N/mm}$$

$$\ell = 2000 \text{ mm}$$

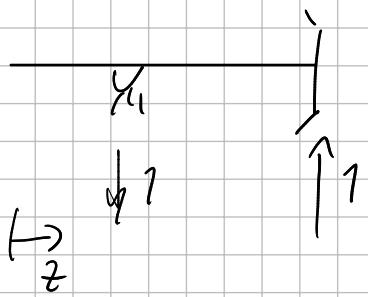
$$EI = 12E 12 \text{ N mm}^2$$

$$T = \frac{a z^2}{\ell}$$

$$\int_0^z T dz = \int_0^z \frac{2a z^2}{\ell} dz = \frac{2}{3} \frac{a z^3}{\ell} \quad \forall z \in [0, \frac{\ell}{2}]$$

$$M_x = -\frac{2}{3} \frac{a z^3}{\ell} + \frac{a z^3}{\ell} = \frac{a z^3}{3 \ell} \quad \forall z \in [0, \frac{\ell}{3}]$$

$$-\frac{2}{3} \frac{a z^3}{\ell} - \frac{a \ell}{4} \left(z - \frac{\ell}{3}\right) + \frac{a z^3}{\ell} = \frac{a z^3}{3 \ell} - \frac{a \ell}{4} \left(z - \frac{\ell}{3}\right) \quad \forall z \in [\frac{\ell}{3}, \frac{\ell}{2}]$$

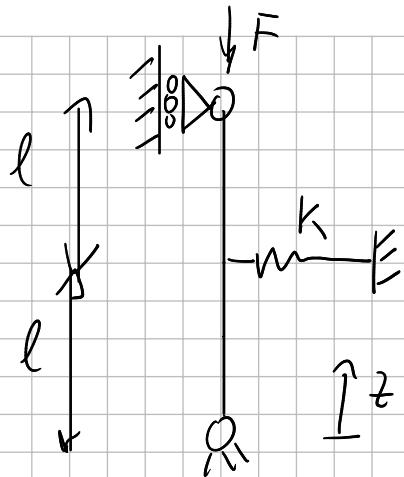


$$M_x' = -\left(z - \frac{l}{3}\right)$$

$$\forall z \in \left[\frac{l}{3}, \frac{l}{2}\right]$$

$$\frac{\int_{\frac{l}{3}}^{\frac{l}{2}} \left[ \frac{1}{3} \frac{z^3}{l} - \frac{z^2 l}{4} + \frac{z l^2}{12} \right] \left( \frac{l}{3} - z \right) dz}{EI} = v = \frac{-72 l^4}{233280} \frac{1}{EI}$$

$$= -0,04$$



$$l = 2000 \text{ mm}$$

$$EI = 12 \times 10^3 \text{ N mm}^2$$

$$EA = 6 \times 10^3 \text{ N}$$

$$k = 1 \times 10^3 \text{ N/mm}$$

$$w = \alpha z + b z^2 \quad 2\alpha l + 4b l^2 = 0 \quad \alpha = -2b l$$

$$\Rightarrow w = -2b l z + b z^2 \quad w' = -2b l + 2b z$$

$$w'' = 2b$$

$$\int w'' EI w'' - f w' F w' dz + \delta b l^4 k b = 0$$

$$\begin{aligned} w(l) &= -2b l^2 + b l^2 \\ &= -b l^2 \\ f w(l) &= -\delta b l^2 \end{aligned}$$

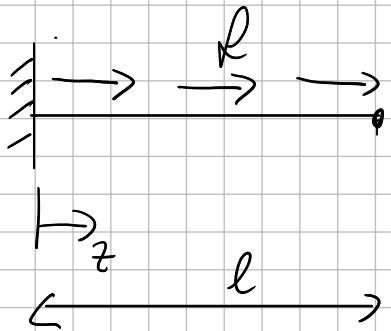
$$\int_0^{2l} \left( 4 \delta b b EI - (-2\delta b l + 2\delta b z) \right) (-2b l + 2b z) dz + \delta b l^4 k b = 0$$

$$\delta b \int_0^{2l} \left( 4EI - 4l^2 F + 8l^2 F - 4z^2 F \right) dz + \delta b l^4 k b = 0$$

$$(8EI\ell - 8\ell^3F + \frac{8}{2}Fl^4\ell^2 - \frac{4}{3}8\ell^3F + Kl^4) b = 0$$

$$F \left( -8 + 4 - \frac{32}{3} \right) \ell^3 = -8EI\ell - Kl^4$$

$$F = \frac{8EI\ell + Kl^4}{\left( -8 + 4 - \frac{32}{3} \right) \ell^3} = 8,4 E^{-5}$$



$$EA = a + b z$$

$$F = 1000 \text{ N/mm}$$

$$a = 6 \times 10^{-10} \text{ N}$$

$$b = 2,5 \times 10^{-7} \text{ N/mm}$$

$$l = 4000 \text{ mm}$$

1 term polynomial approx

$$w(l) = ?$$

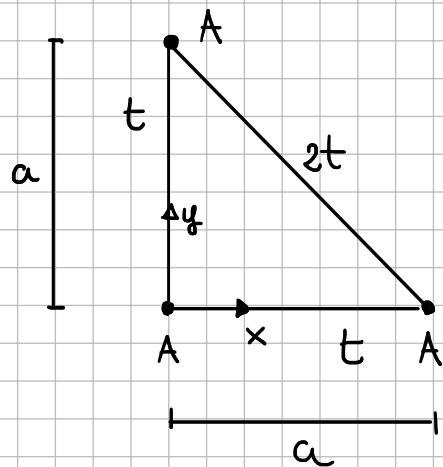
$$w = \epsilon z \quad w' = \epsilon \quad \delta w' = \delta \epsilon$$

$$\int_0^l \delta \epsilon (a + bz) \epsilon dz = \int_0^l \delta \epsilon Fz dz$$

$$\left( a\ell + \frac{1}{2} b\ell^2 \right) \epsilon = \frac{1}{2} \rho \ell^2 \quad \epsilon = \frac{1}{2} \rho \ell^2 / \left( a\ell + \frac{1}{2} b\ell^2 \right)$$

$$w(l) = \epsilon l = 0,07272 \text{ mm}$$

## Ex 2



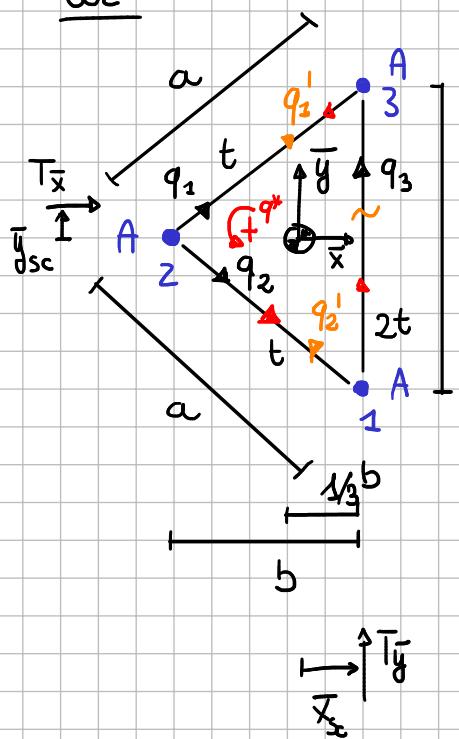
$$a = 1000 \text{ mm}$$

$$A = 400 \text{ mm}^2$$

$$E = 10^4 \text{ MPa}$$

$$\nu = 0.3$$

SOL



$$b = \frac{\sqrt{2}}{2} a$$

DUE TO SYMM.

$$c = 2b = \sqrt{2}a$$

$$|\bar{U}_{sc} = 0|$$

$$J_{\bar{x}\bar{x}} = 2\left(\frac{c}{2}\right)^2 A = 2Ab^2$$

$$S_{\bar{x}_1} = -S_{\bar{x}_3} = -Ab$$

$$|\bar{T}_x = 0|$$

$$S_{\bar{x}_2} = 0$$

$$\bar{T}_{\bar{y}} = 1$$

OPEN CELL FLOW.

$$q'_2 = -\bar{T}_{\bar{y}} \frac{S_{x_1}}{J_{xx}} \rightarrow = \frac{1}{2} \frac{T_y}{b} = q'$$

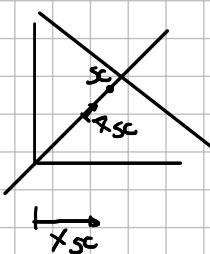
$$q'_1 = \bar{T}_{\bar{y}} \frac{S_{x_3}}{J_{xx}}$$

NON. EQ. WRT 2)

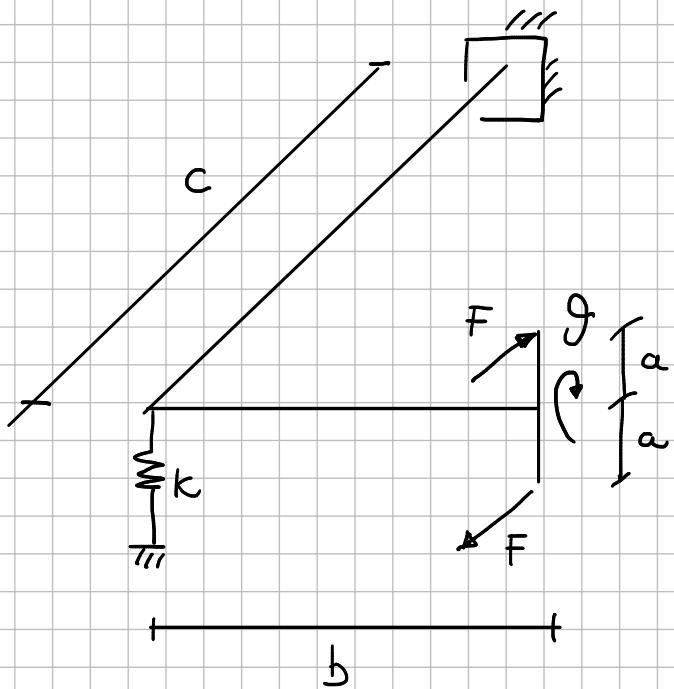
$$\bar{T}_{\bar{y}} \cdot \left( \frac{2}{3}b + \bar{x}_{sc} \right) = 2 \oint_{cell} q^* \text{ WRT } \oint_{cell} = \frac{1}{2}cb$$

$$\underline{\text{ROT}} \quad q' = \frac{1}{G2\Omega_{cell}} \cdot \left( \frac{q^* \cdot 2a}{k} + \frac{q^* \cdot c}{2t} - \frac{2q' \cdot a}{k} \right) = 0 \rightarrow \bar{x}_{sc}$$

$$\underline{| x_{sc} = \frac{2}{3} \frac{\sqrt{2}}{2} b + \frac{\sqrt{2}}{2} \bar{x}_{sc} = 369.398 \text{ mm} |}$$



### Ex 3



$$a = 1000 \text{ mm}$$

$$b = 2000 \text{ mm}$$

$$c = 3000 \text{ mm}$$

$$EI_{xx} = EI_{yy} = 12 \cdot 10^{14} \text{ Nmm}^2$$

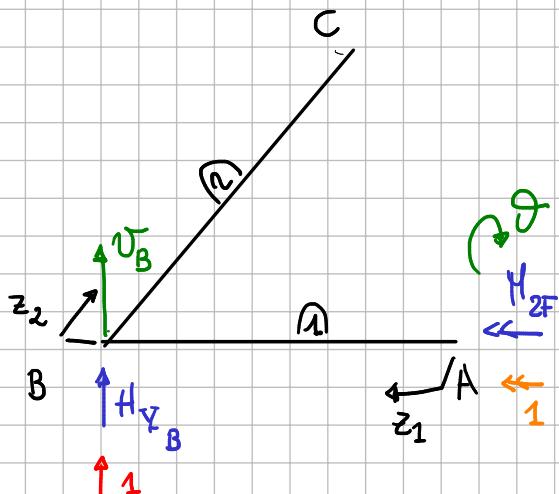
$$EA = 6 \cdot 10^{10} \text{ N}$$

$$GJ = 7 \cdot 10^9 \text{ Nmm}^2$$

$$k = 1 \cdot 10^6 \text{ N/mm}$$

$$F = 10^4 \text{ N}$$

### Sol



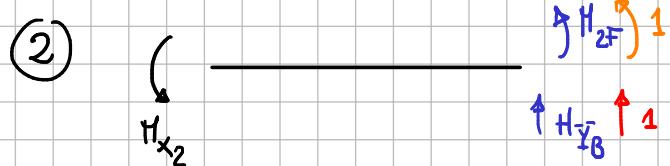
$$M_{2F} = 2 \cdot F \cdot a$$

①



$$M_{z_1} = -M_{2F}$$

$$M_{z_1}^{-1} = -1$$



$$kN_B = -H_{Y_B} \rightarrow N_B = -\frac{H_{Y_B}}{k}$$

$$M_{x_2}(z) = -M_{2F} - H_{Y_B} \cdot z_2$$

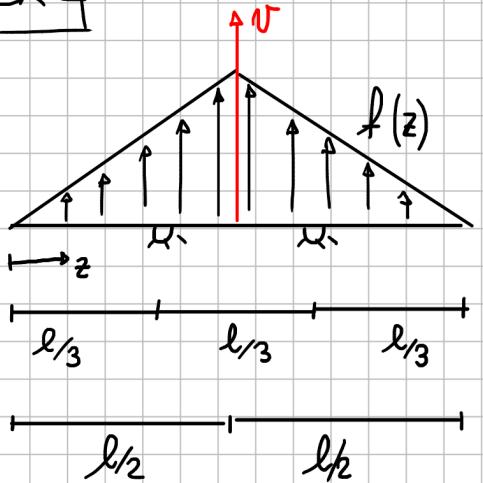
$$M_{x_2}^{-1}(z_2) = -1$$

$$M_{x_2}''(z_2) = -1 \cdot z_2$$

Pcvw

$$\bullet \bullet \quad \left\{ \begin{array}{l} 1. \vartheta = \int_0^b M_{z_1}^{-1} \cdot \frac{H_{z_1}}{GJ} dz_1 + \int_0^c M_{x_2}^{-1} \cdot \frac{H_{x_2}}{EJ} dx_2 \\ 1. \eta_B = \int_0^c M_{x_2}^{-1} \cdot \frac{H_{x_2}}{EJ} dx_2 \end{array} \right.$$

Ex 4



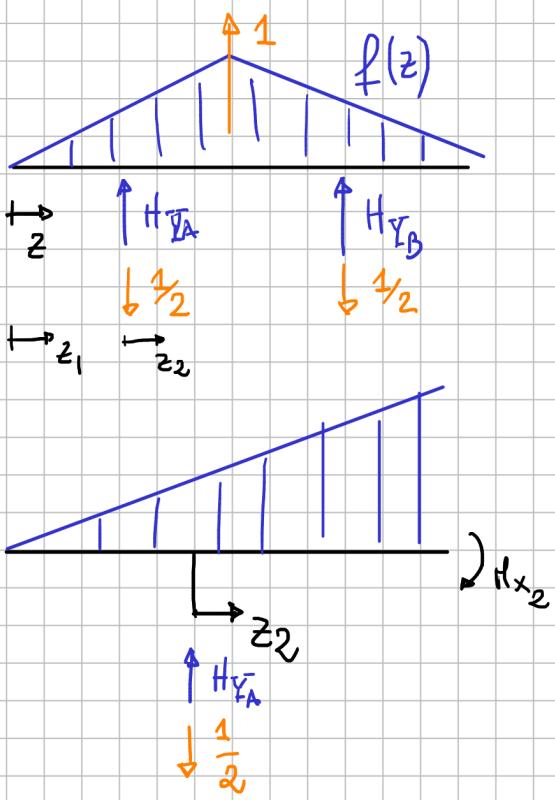
$$a = 1000 \text{ N/mm}$$

$$l = 2000 \text{ mm}$$

$$EI = 12 \cdot 10^{12} \text{ Nmm}^2$$

SOL  $f(z) = \frac{2a}{l} \cdot z$

EQUILIBRIUM EQ.



DUE TO SYMMETRY

$$H_{Y_A} = - \int_0^{l/2} f(z) dz = H_{Y_B}$$

WHERE  $f(z) = \frac{2a}{l} z$

IN  $z_1$  DUMMY SYST UNLOADED

IN  $z_2$ :

$$H_{X_2}(z_2) = -H_{Y_A} \cdot z_2 +$$

$$- \frac{2a}{l} \left( z_2 + \frac{l}{3} \right) \cdot \frac{\left( z_2 + \frac{l}{3} \right)}{3} \cdot \left( z_2 + \frac{l}{3} \right) \cdot \frac{1}{2}$$

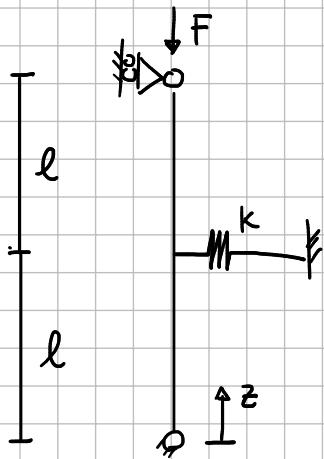
$$H_{X_2}'(z_2) = + \frac{1}{2} z_2$$

Pcvw

$$\boxed{N = 2 \int_0^{l/6} H_{X_2} \cdot \frac{H_{X_2}}{EI} dz_2 = -0.04 \text{ mm}}$$

WE HAVE TO CONSIDER THE WHOLE STRUCTURE

## Ex 5



DATA

$$l = 2000 \text{ mm}$$

$$EA = 6 \cdot 10^6 \text{ N}$$

$$EJ = 12 \cdot 10^6 \text{ N mm}^2$$

$$k = 1 \cdot 10^3 \text{ N/mm}$$

SOL WITH EB BEAM & NON LINEAR GL STRAIN TENSOR FOR  
INFINITEITAL DISPL. IN Z & SMALL IN Y

$$\varepsilon_{zz} = \omega_z - y \nabla_{zz} + \frac{1}{2} \nabla_z^2$$

$$\delta w_i = \int_V \delta \varepsilon_{zz} G_{zz} dV$$

$$\begin{aligned} \text{WHERE } \delta \varepsilon_{zz} &= \delta \omega_z - y \delta \nabla_{zz} + \delta \nabla_z \cdot \nabla_z \\ &= \delta \varepsilon_0 - y \delta \nabla_{zz} \end{aligned}$$

$$\begin{aligned} \delta W_i &= \int_V \delta \varepsilon_0 G_{zz} dV - \int_V \delta \nabla_{zz} y G_{zz} dV \\ &= \int_{2l} \delta \varepsilon_0 N \cdot \delta z + \int_{2l} \delta \nabla_{zz} EJ N \nabla_{zz} dz \quad \left( \int_V y G_{zz} dV = \int_{2l} M_x dz - EJ \nabla_{zz} \right) \end{aligned}$$

$$\begin{aligned} \delta W_e &= -F \delta w(2l) - k \cdot v(l) \cdot \delta v(l) \\ &= - \int_0^{2l} \delta w_z F dz - \delta v(l) k \cdot N(l) \end{aligned}$$

$$\text{Pvw } \delta w: \int_0^{2l} \delta w_z \cdot N dz = - \int_0^{2l} \delta w_z \cdot F dz \rightarrow N = -F$$

$$\delta v: \int_0^{2l} \delta v_z EJ N_{zz} + \delta N_z N_{zz} dz = -\delta v(l) k \cdot N(l) - F$$

$$N = Az^2 + Bz + C$$

$$BC_1 : N(0) = 0 \rightarrow C = 0$$

$$N(2\ell) = 0 \rightarrow B = -A \cdot 2\ell$$

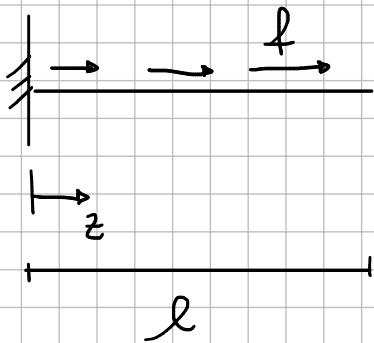
$$N = C \phi(z) \rightarrow C = [A \quad -A \cdot 2\ell]$$
$$\phi = [z^2 \quad z]^T$$

$$\delta A \int_0^{2\ell} \frac{\partial C}{\partial A} \phi_{zz} \delta C \phi_{zz} - \frac{\partial C}{\partial A} \phi_z F \cdot C \phi_z dz = -\delta A \cdot \frac{\partial C}{\partial A} \phi(\ell) \delta C \phi(\ell)$$

TWO SOLUTIONS  $A = 0$

$$F = 840000 \text{ N}$$

## Ex 6



DATA

$$l = 4000 \text{ mm}$$

$$f = 1000 \text{ N/mm}$$

$$a = 6 \cdot 10^6 \text{ N}$$

$$b = 2.5 \cdot 10^7 \text{ N/mm}$$

SOL  $\omega = Az + B$

B.C.:  $\omega(0) = 0 \rightarrow B = 0$

$$\delta W_i = \int_0^l \delta \omega_z \cdot N dz \quad \text{WHERE } N = EA \cdot \omega_z \quad \text{WITH } EA = a + bz$$

$$\delta W_e = \int_0^l \delta \omega \cdot f dz$$

P.W.  $EA \cdot \int_0^l EA \cdot A dz = \int_0^l EA \cdot z \cdot f dz$   
 $\rightarrow \int_0^l (Aa + Abz - zf) dz = 0$

$$\rightarrow Aa\ell + \frac{1}{2}Ab\ell^2 - \frac{1}{2}f\ell^2 = 0$$

$$A = \frac{1}{2} \frac{f\ell^2}{a\ell + \frac{1}{2}b\ell^2} = \frac{1}{2} \frac{f\ell}{a + \frac{1}{2}b\ell}$$

$$\omega(l) = A \cdot \ell = \frac{1}{2} \frac{f\ell^2}{a + \frac{1}{2}b\ell} = 0.0727 \text{ mm}$$

### **True/False Questions**

(Put a T (true) or F (false) at the end of the sentence)

1. The axial stress of beam transmitting a constant bending moment  $M_x$  does not depend on the material elastic modulus  $E$ 
  - True
2. The Timoshenko model is used to compute the critical buckling stress of a simply supported compressed plate
  - False
3. Hermitian shape functions are  $C^2$  (continuous, and with continuous first and second derivatives)
  - False

### **Multiple Choice questions**

(Circle the correct answer)

1. “Crippling” is:
  - (a) a failure mode of thin-walled compressed beam
  - (b) a failure mode of compact compressed beam
  - (c) a failure mode affecting the fuselage of Boing 737 MAX
  - (d) a failure mode of railways
  - (e) a special design technique preventing the buckling of beams
  - (f) none of the above
2. Assume that the solution of a given three dimensional elastic problem has a finite  $H_{10}$  norm; an approximated solution, obtained with quadratic finite elements with average dimension  $h$ :
  - (a) has quadratic convergence of the stress with respect to  $h$
  - (b) has cubic convergence of the stress with respect to  $h$
  - (c) has linear convergence of the displacements with respect to  $h$
  - (d) has quadratic convergence of the displacements with respect to  $h$
  - (e) none of the above

3. A structure is modeled using finite elements. It is unconstrained and subjected to a set of loads in self equilibrium. The solution of the linear static problem:
- (a) is stress-free because the loads have null resultant and moment resultant
  - (b) can be computed, up to a rigid body motion, after preventing the displacement of the structure all over its boundary
  - (c) can be computed only if the loads are concentrated
  - (d) can be computed, up to a rigid body motion, only if the loads are distributed
  - (e) is defined up to a rigid body motion; thus, not being unique, it is not possible to compute the stress and strain fields
  - (f) **none of the above**