

Course of Aerospace Structures

Written test, January 20th, 2025

Name _____

Surname _____

Person code:

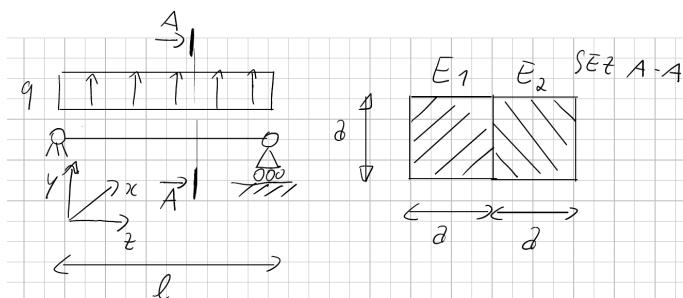
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Exercise 1

The simply supported beam in the figure cross section is made with two different materials, as sketched in Sez A-A. The beam is loaded with a distributed force per unit of length q . Compute the maximum value, over the whole structure, of the axial stress σ_{zz} .

Neglect shear deformability.

(Unit for result: MPa)



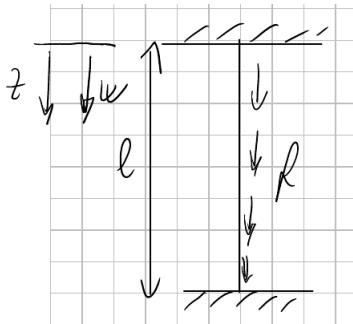
Data
 $l = 1500 \text{ mm}$
 $a = 30 \text{ mm}$
 $E_1 = 70000 \text{ MPa}$
 $E_2 = 210000 \text{ MPa}$
 $\nu = 0.3$
 $q = 1 \text{ N/mm}$

Answer _____

Exercise 2

The beam in the figure is clamped at both ends, and is loaded with an distributed axial force per unit of length f . Compute the displacement of the point at $z = l/2$.

(Unit for result: mm)



Data
 $l = 1000 \text{ mm}$
 $EA = 6 \times 10^9 \text{ N}$
 $f = 300 \text{ N/mm}$

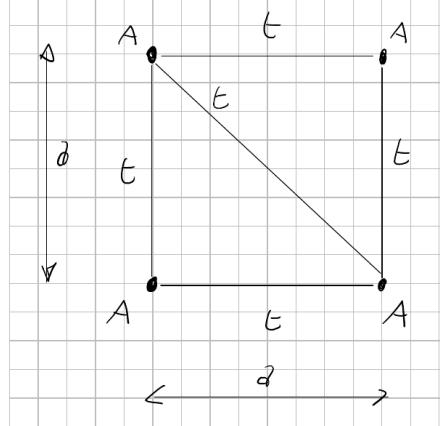
Answer _____

Exercise 3

Consider the semi-monocoque cross section sketched in the figure, with four concentrated areas, each with area A , five panels of thickness t and two cells.

Compute the torsional stiffness GJ of the cross section.

(Unit for result: N mm²)



Data

$$a = 500 \text{ mm}$$

$$t = 2 \text{ mm}$$

$$E = 70000 \text{ MPa}$$

$$\nu = 0.3$$

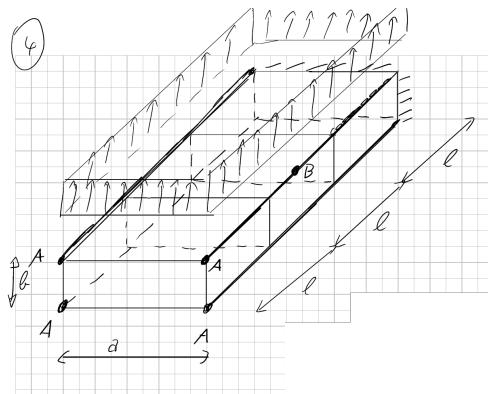
$$A = 200 \text{ mm}^2$$

Answer

Exercise 4

The semi-monocoque beam sketched in the figure, with overall length $3l$, has four panels, each with thickness t , and four concentrated areas, each with area A . It is loaded on the upper panel, by force per unit of surface q . The load is introduced into the structure by four different ribs, with pitch equal to l (the first rib is at the clamp, the last one at the beam free extremity).

Compute the axial stress at the point B, as sketched in the figure, located at $z = 3/2l$ from the clamp.
(Unit for result: MPa)



Data

$$l = 1000 \text{ mm}$$

$$a = 700 \text{ mm}$$

$$b = 100 \text{ mm}$$

$$t = 1 \text{ mm}$$

$$A = 500 \text{ mm}^2$$

$$E = 70000 \text{ MPa}$$

$$\nu = 0.3$$

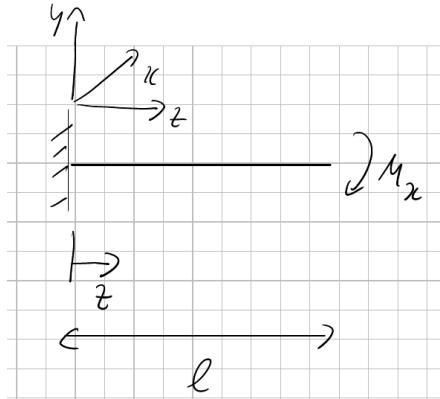
$$q = 0.01 \text{ N/mm}^2$$

Answer

Exercise 5

Consider the slender beam structure sketched in the figure, loaded at the free extremity by the concentrated moment M_x . The bending stiffness varies linearly along the beam, $EI_{xx} = a + bz$. Estimate the transverse displacement v at the extremity by assuming a polynomial approximation of the transverse displacement truncated to the first non null term. Neglect shear deformability.

(Unit for result: mm)



Data

$$\begin{aligned}l &= 3000 \text{ mm} \\a &= 1 \times 10^{13} \text{ N mm}^2 \\b &= 3 \times 10^9 \text{ N mm} \\M_x &= 1 \times 10^5 \text{ N mm}\end{aligned}$$

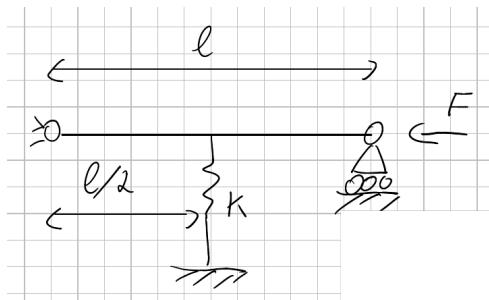
Answer _____

Exercise 6

The single simply supported beam sketched in the figure, with bending stiffness EI_{xx} , has a supporting spring in the middle with stiffness K . The beam is loaded by the compressive force F . Estimate the critical buckling value of F by assuming a trigonometric expansion of the transverse displacement, truncated to one term.

Neglect shear deformability.

(Unit for result: N)



Data

$$\begin{aligned}l &= 3000 \text{ mm} \\EI_{xx} &= 1 \times 10^{10} \text{ N mm}^2 \\K &= 100 \text{ N/mm}\end{aligned}$$

Answer _____

True/False Questions

(Put a T (true) or F (false) at the end of the sentence)

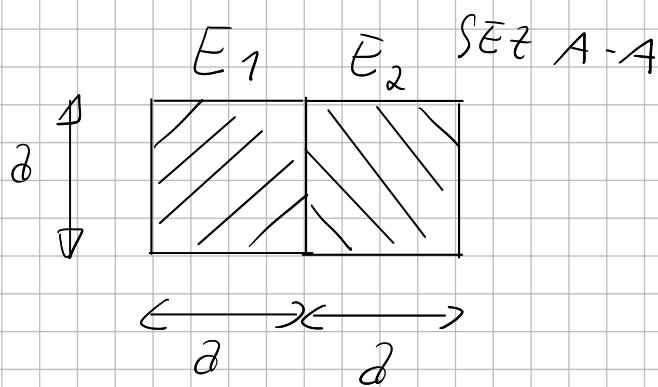
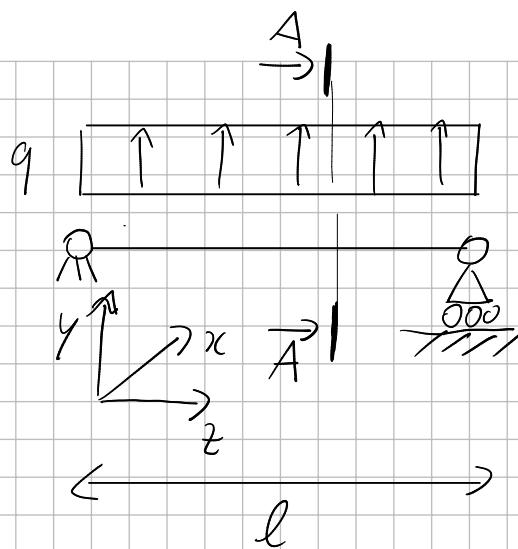
1. The assumption of plane strain implies that a component of strain is null.
2. The Neumann boundary conditions are satisfied in a weak sense by the Principle of Virtual Work.
3. According to the semi-monocoque model, the shear stress in the panels can be computed from the axial derivative of the axial stress σ_{zz} .

Multiple Choice questions

(Circle the correct answer)

1. The shear flux in a thin panel is equal to:
 - (a) the shear stress in the panel divided by the panel thickness
 - (b) the shear stress in the panel multiplied by the panel thickness
 - (c) the shear stress in the panel
 - (d) the derivative of the axial stress in the panel
 - (e) none of the above
2. The axial stiffness for a thin-walled beam:
 - (a) is null
 - (b) is generally larger than that of a corresponding (same material and cross-section area of the material) compact section
 - (c) is generally smaller than that of a corresponding (same material and cross-section area of the material) compact section
 - (d) is equal to that of a corresponding (same material and cross-section area of the material) compact section
 - (e) can be neglected
 - (f) is infinite
 - (g) none of the above
3. A “simply supported” plate has:
 - (a) vertical (normal to the plate) displacement and bending rotation prevented on one of its boundary sides
 - (b) vertical displacement and bending rotation prevented on all of its boundary sides
 - (c) vertical displacement prevented on two opposite boundary sides, bending rotation left free
 - (d) vertical displacement prevented on all of its boundary sides, bending rotation left free
 - (e) vertical displacement and bending rotation prevented on two opposite boundary sides, vertical displacement prevented and bending rotation left free on the other two
 - (f) none of the above

①



$$\bar{T}_y = -\frac{q l}{2} + q z$$

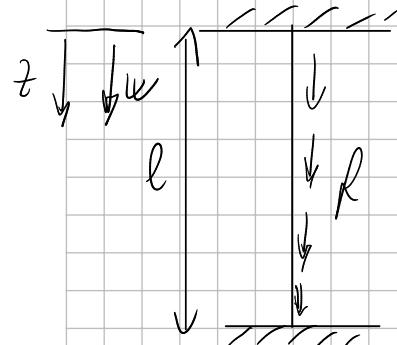
$$\bar{E} \bar{\chi}_{xz} = \frac{1}{12} d^4 (E_1 + E_2)$$

$$\bar{\sigma}_{xz_1} = \frac{M_x(\frac{l}{2}) \cdot \frac{d}{2}}{\bar{E} \bar{\chi}_{xz}} \cdot E_1$$

$$M_x = +\frac{q l}{2} z - \frac{1}{2} q z^2$$

$$\bar{\sigma}_{xz_2} = \frac{M_x(\frac{l}{2}) \cdot \frac{d}{2}}{\bar{E} \bar{\chi}_{xz}} \cdot E_2$$

(2)



$$M = \frac{Rl}{2} - Rz$$

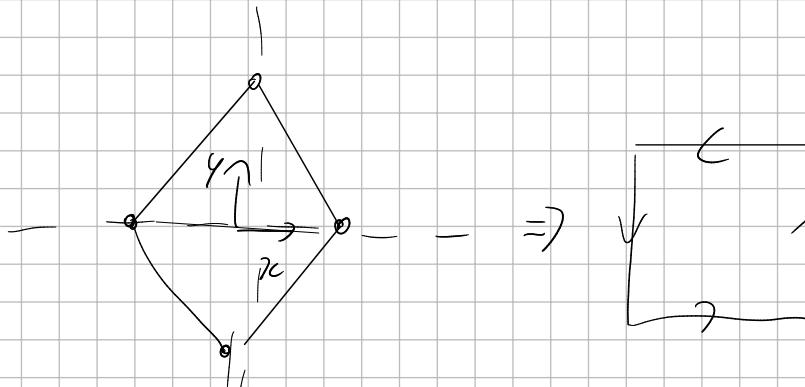
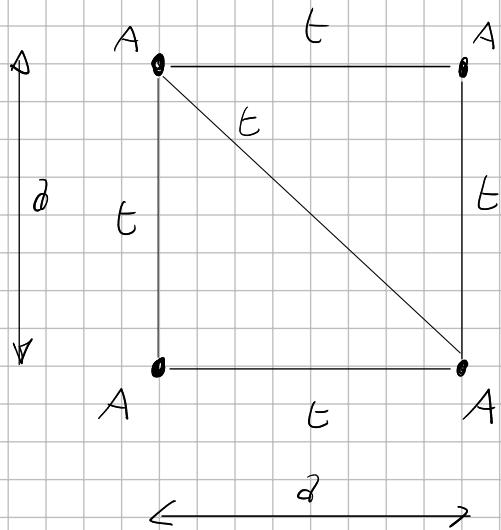
$$\epsilon_{zz} = \frac{M}{EA}$$

$$w\left(\frac{l}{2}\right) = \int_0^{\frac{l}{2}} \epsilon_{zz} dz = \frac{1}{EA} \int_0^{\frac{l}{2}} \left(\frac{Rl}{2} - Rz \right) dz$$

$$= \frac{1}{EA} \left(\frac{Rl}{2} z - \frac{1}{2} R z^2 \right) \Big|_0^{\frac{l}{2}}$$

$$= \frac{1}{EA} \left(\frac{Rl^2}{4} - \frac{1}{8} Rl^2 \right) = \frac{1}{EA} \frac{Rl^2}{8}$$

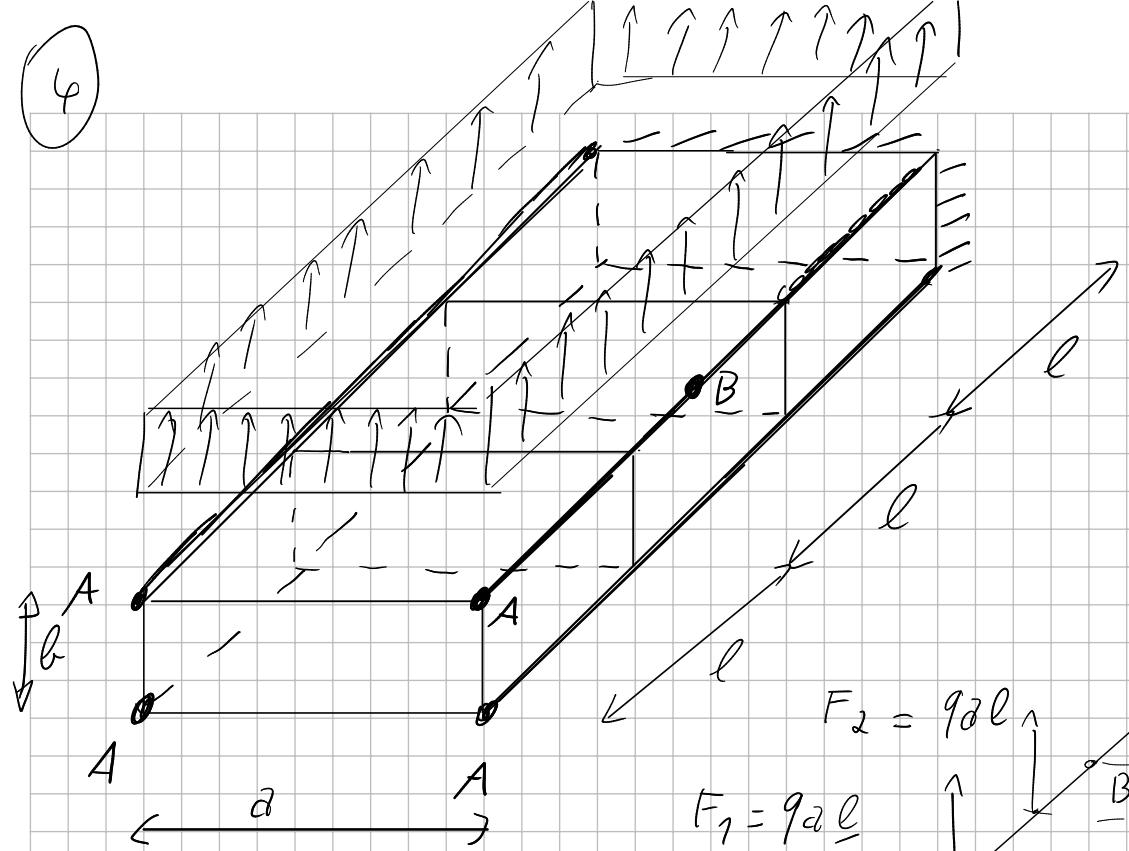
3



$$q = \frac{M_e}{2a^2}$$

$$\theta' = \frac{1}{2a^2 G} \frac{q/4a^2}{t} = \frac{M_e X}{2a^2 a G t} = \frac{M_e}{a^3 G t}$$

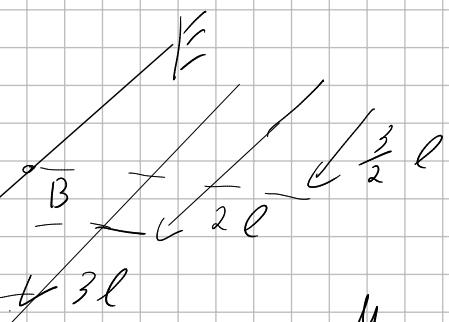
(4)



$$F_1 = q_0 \frac{l}{2}$$

$$F_2 = q_0 l$$

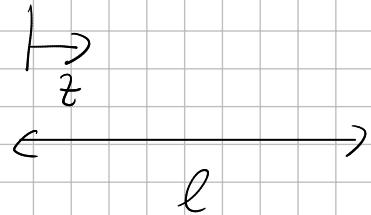
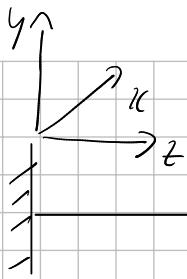
$$I_{xx} = 4A \cdot \left(\frac{a}{2}\right)^2$$



$$M_{xx} = F_1 \frac{3}{2}l + F_2 \frac{l}{2}$$

$$\tau_{z_7} = - \frac{M_{xx}}{I_{xx}} \cdot \frac{a}{2}$$

(5)



$$\bar{E}I_{x_0} = a + b z$$

$$v = c z^2$$

$$\delta v'' = 2 \delta c$$

$$\delta v' = 2 c z$$

$$\int_0^l \delta c \cdot 4 \bar{E} I_{x_0} z \, dz = - \delta c \cdot 2 l \cdot M_x$$

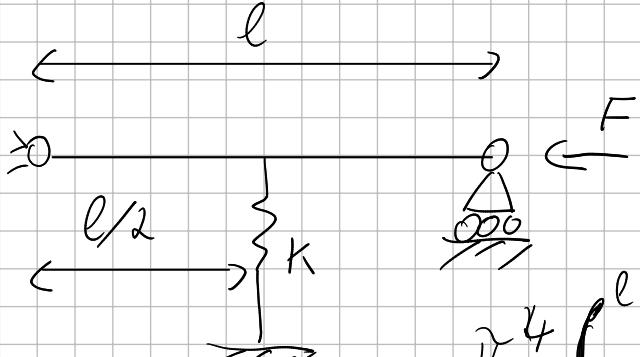
$$\delta c \int_0^l : (4a + 4bz) dz \cdot c = - \delta c \cdot 2l \cdot M_x$$

$$= \delta c \left(4al + 2bl^2 \right) c = - \delta c \cdot 2l \cdot M_x$$

$$c = \frac{-2l M_x}{4al + 2bl^2}$$

$$v(l) = c l^2$$

(6)



$$\delta_d \left(\frac{\pi^4}{l^4} E I_{xx} \frac{l}{2} - \frac{\pi^2}{l^2} \frac{l}{2} F + K \right) = 0$$

$$+ \delta_d \sin^2 \left(\frac{\pi}{2} \right) K = 0$$

$$v = a \sin \left(\frac{\pi z}{l} \right)$$

$$v'' = -\frac{\pi^2}{l^2} a \sin \left(\frac{\pi z}{l} \right)$$

$$\delta_d \left(\frac{\pi^4}{l^4} E I_{xx} \frac{l}{2} - \frac{\pi^2}{l^2} \frac{l}{2} F + K \right) = 0$$

$$\delta_d \left(\frac{\pi^4 E I_{xx}}{2 l^3} + K - \frac{\pi^2}{2 l} F \right) = 0$$

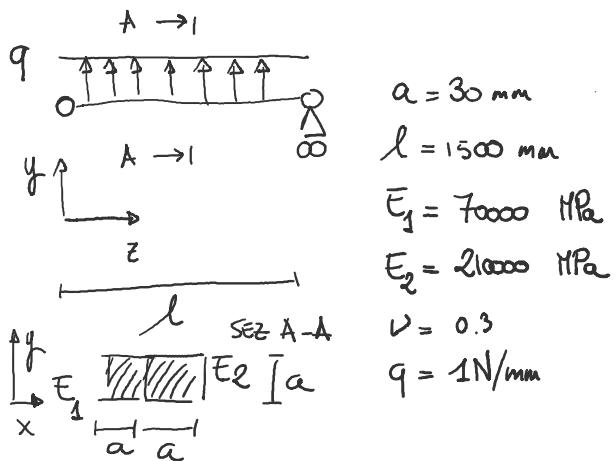
$$F = \frac{\frac{\pi^4 E I_{xx}}{2 l^3} + K}{\frac{\pi^2}{2 l}}$$

- The assumption of plane strain implies that a component of strain is null
 - True
 - The Newmann boundary conditions are satisfied in a weak sense by the Principle of Virtual Work
 - True
 - According to the semi-monocoque model, the shear stress in the panels can be computed from the axial derivative of the axial stress σ_{zz} :
 - False
1. The shear flux in a thin panel is equal to
 - (a) the shear stress in the panel divided by the panel thickness
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 - (c) the shear stress
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- (e) vertical displacement and bending rotation prevented on two opposite boundary sides, vertical displacement prevented and bending rotation left free on the other two
- (f) none of the above

2025-01-20 Ex 1

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SOL

$$\begin{array}{c} \uparrow \uparrow \uparrow \uparrow \uparrow \uparrow \\ \downarrow \frac{1}{2}ql \\ \end{array} \quad \begin{array}{c} \uparrow \uparrow \uparrow \uparrow \uparrow \\ \downarrow \frac{1}{2}ql \\ \end{array} \quad \begin{array}{c} \uparrow \uparrow \uparrow \uparrow \uparrow \\ \downarrow \frac{1}{2}ql \\ \end{array}$$

$\hookrightarrow z$

$$M_x(z) = \frac{1}{2}qlz - qz \cdot \frac{z}{2}$$

$$M'_x(z) = \frac{1}{2}ql - qz \rightsquigarrow M'_x(z) = 0$$

$$z = \frac{1}{2}l$$

$$\begin{aligned} M_{x_{\max}} &= \frac{1}{2}ql \cdot \frac{1}{2}l - q \cdot \frac{1}{2}l \cdot \frac{\frac{1}{2}l}{2} \\ &= \frac{1}{4}ql^2 - \frac{1}{8}ql^2 = \frac{1}{8}ql^2 \end{aligned}$$

$$\epsilon_{xz} = \frac{M_{x_{\max}}}{E J_{xx}} \cdot \frac{a}{2} \quad E = \frac{E_1 + E_2}{2}$$

$$J_{xx} = \int_{-a/2}^{a/2} \int_{-a/2}^{a/2} y^2 dx dy$$

$$= \int_{-a/2}^{a/2} y^2 dy \cdot \int_{-a/2}^{a/2} dx$$

$$= \frac{1}{3} \left(\frac{a^3}{8} + \frac{a^3}{8} \right) \cdot \left(\frac{a}{2} + \frac{a}{2} \right)$$

$$= \frac{1}{12} a^4$$

$$\tau_{\text{max}} = \frac{M_{x_{\max}}}{I_{xx}} \cdot \frac{a}{2}$$

$$= \frac{1}{12} a^4$$

$$J_{xx_2} = \frac{1}{12} a^4 = J_{xx_1}$$

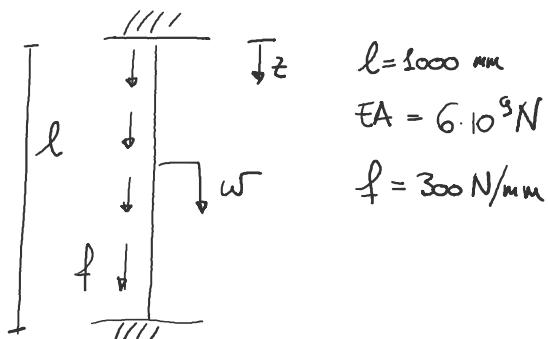
$$J_{xx} = \frac{1}{6} a^4 = J_{xx_1} + J_{xx_2} = 2 J_{xx_1}$$

$$\epsilon_{zz_{max}} = \frac{3x_0 h_{xx}}{E a^4} \cdot \frac{\cancel{a}}{2} = \frac{3}{8 E a^3} q l^2$$

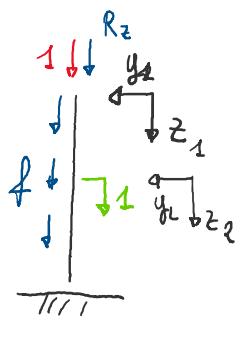
$$\sigma_{xx_{max}} = E_2 \cdot \epsilon_{zz_{max}} = \frac{3}{8 E a^3} q l^2 \cdot E_2$$

2025-01-20 Ex 2

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SOL



$$\begin{aligned} T_{z_1} &= -f \cdot z_1 - R_z \\ T_{z_1}' &= -1 \\ T_{z_2} &= -f \cdot z_2 - f \cdot \frac{l}{2} - R_z \\ T_{z_2}' &= -1 \\ T_{z_2}'' &= -1 \end{aligned}$$

PCW

$$\bullet \bullet \quad \delta \omega_e^1 = 1.0$$

$$\delta \omega_e^1 = \int_0^{l/2} \frac{f z_1 + R_z}{E A} dz_1 + \int_0^{l/2} \frac{f z_2 + f l/2 + R_z}{E A} dz_2$$

$$\rightarrow \frac{1}{2} f \cdot \frac{l^2}{4} + R_z \frac{l}{2} + \frac{1}{2} f \frac{l^2}{4} + \frac{1}{4} f l^2 + R_z \frac{l}{2} = 0$$

$$R_z = - \left(\frac{1}{8} + \frac{1}{8} + \frac{1}{4} \right) f l = -\frac{1}{2} f l$$

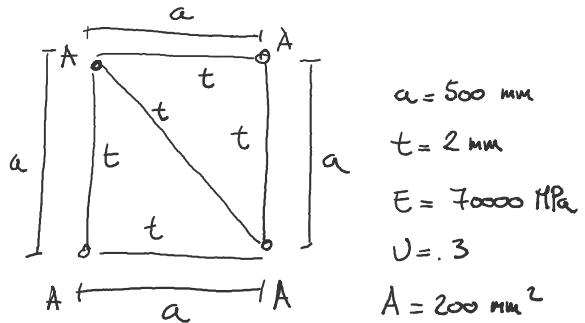
$$\bullet \bullet \quad \delta \omega_e^1 = \omega \cdot 1$$

$$\delta \omega_e^1 = \int_0^{l/2} \frac{f z_2 + \frac{1}{2} f l - \frac{1}{2} f l}{E A} dz_2 = \frac{1}{2} \frac{f l^2}{E A} = \frac{f l^2}{8 E A}$$

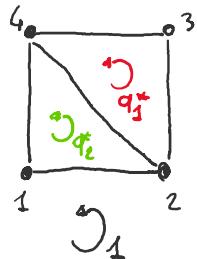
$$\omega = \frac{f l^2}{8 E A}$$

2025-01-20 Ex 3

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SOL OPEN CELL FLUXS = 0



MOM EQ. WRT. 2 \Rightarrow

$$1 = 2q_1^* \cdot \frac{1}{2}a^2 + 2q_2^* \cdot \frac{1}{2}a^2$$

ROT.

$$\theta_1' = \frac{1}{2 \cdot \frac{1}{2}a^2 \cdot G \cdot t} \left(2q_1^* \cdot a + q_1^* \cdot \sqrt{2}a - q_2^* \cdot \sqrt{2}a \right)$$

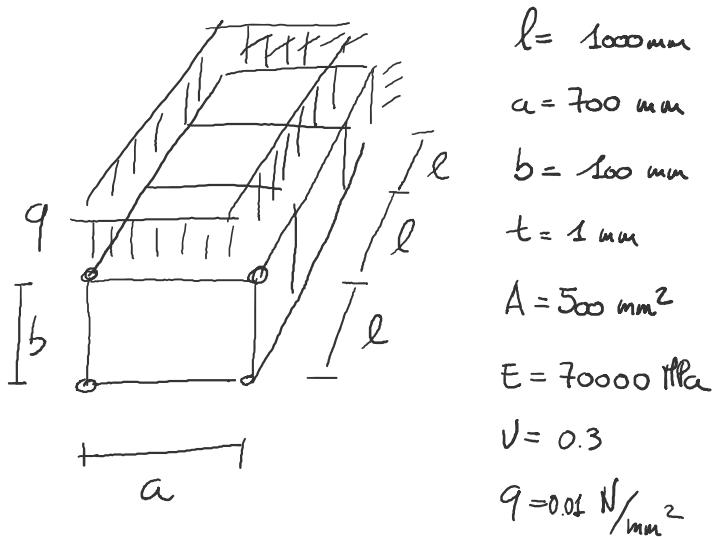
$$\theta_2' = \frac{1}{2 \cdot \frac{1}{2}a^2 G t} \cdot \left(+2q_2^* \cdot a + q_2^* \cdot \sqrt{2}a - q_1^* \cdot \sqrt{2}a \right)$$

$$\begin{cases} \theta_1' = \theta_2' \\ LHS_{MOM} = R + S_{-MOM} \end{cases} \rightarrow q_1^*, q_2^*$$

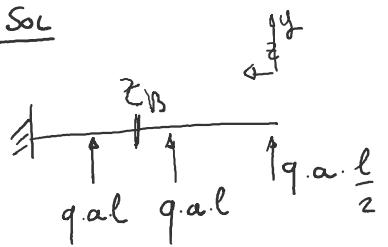
$$GJ = \frac{M_t}{\theta_1'} = \frac{1}{\theta_1'}$$

2025-01-20 Ex 4

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Sol



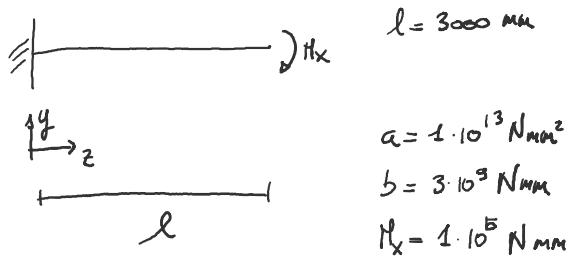
$$M_x(z_B) = -q \cdot a \cdot l \cdot \frac{l}{2} - q \cdot a \cdot l \cdot \frac{3l}{2}$$

$$J_{xx} = 4 \cdot A \left(\frac{b}{2} \right)^2 = A b^2$$

$$G_{z_B} = \frac{M_x(z_B)}{J_{xx}} \cdot \frac{b}{2}$$

2025-01-20 Ex 5

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$$a = 1 \cdot 10^{13} \text{ N mm}^2$$

$$b = 3 \cdot 10^9 \text{ N mm}$$

$$M_x = 1 \cdot 10^5 \text{ N mm}$$

SOL

$$N(z) = Az^2$$

$$\text{Pw} \quad \delta w_e = -\delta N'(l) \cdot M_x$$

$$\delta w_e = \int_0^l \delta N''(z) M_x dz$$

$$\rightarrow \delta K \int_0^l 2EJ(z) 2A dz = -\delta K \cdot 2l \cdot M_x$$

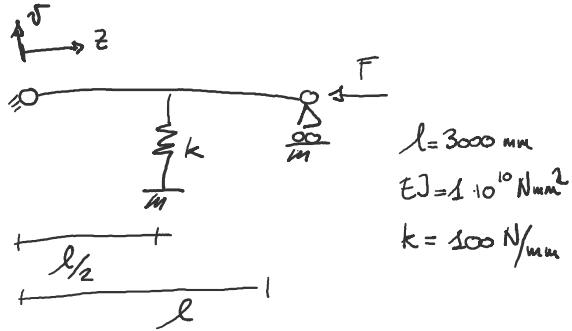
$$A = -\frac{2l \cdot M_x}{2K \int_0^l EJ(z) dz} = -\frac{M_x}{2a + bl}$$

$$\int_0^l a + bz dz = al + \frac{1}{2}bl^2$$

$$N(l) = -\frac{M_x}{2a + bl} \cdot l^2$$

2025-01-20 Ex 6

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SOL FROM AXIAL EQUILIBRIUM $N = -F$

$$N(z) = A \sin\left(\frac{\pi z}{l}\right)$$

$$N'(z) = A \frac{\pi}{l} \cos\left(\frac{\pi z}{l}\right)$$

$$N''(z) = -A \frac{\pi^2}{l^2} \sin\left(\frac{\pi z}{l}\right)$$

$$\begin{aligned} \delta W_i &= \int_0^l \delta N''(z) N'' + \delta N' N' dz \\ &= \delta A \int_0^l \frac{\pi^4}{l^4} EJ \sin^2\left(\frac{\pi z}{l}\right) A + \dots \\ &\quad - \frac{\pi^2}{l^2} F \cos^2\left(\frac{\pi z}{l}\right) A dz \\ &= \delta A \left[\frac{\pi^4}{l^4} EJ \cdot \frac{l}{2} A - \frac{\pi^2}{l^2} F \cdot \frac{l}{2} A \right] \end{aligned}$$

$$\delta W_b = -\delta N\left(\frac{l}{2}\right) \cdot k \cdot N\left(\frac{l}{2}\right)$$

$$= -\delta A \cdot k \cdot A \underbrace{\sin\left(\frac{\pi}{2}\right)}_1$$

$$= -\delta A \cdot k \cdot A$$

FOR $A \neq 0$

$$\rightarrow F = \left(\frac{\pi^4}{l^4} EJ \cdot \frac{l}{2} + k \right) \cdot \left(\frac{\pi^2}{l^2} \cdot \frac{l}{2} \right)^{-1}$$

$$\bar{F} = \frac{\pi^2}{l^2} \cdot EJ + \frac{2k \cdot l}{\pi^2}$$