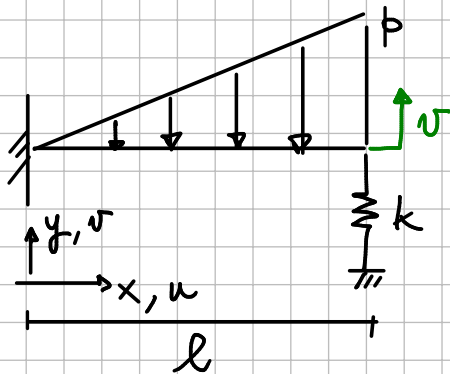


# EXERCISE SESSION 12

Ex 1 (EXAM  
25/01/2023)



$$p = 14 \text{ N/mm}$$

$$l = 2000 \text{ mm}$$

$$EI = 10^{10} \text{ Nmm}^2$$

$$k = 100 \text{ N/mm}$$

FIND  $v$

USING 1 TERM  
POLY APPROX

SOL  $v(x) = a_0 + a_1 x + a_2 x^2$  BC

$$v(0) = 0 \quad a_0 = 0$$

$$v'(0) = 0 \quad a_1 = 0$$

$$\rightarrow v(x) = a x^2$$

$$\delta W_e = \int_0^l -\delta v q(x) dx - \delta v(l) \cdot k v(l)$$

$$\delta W_i = \int_0^l \delta v_{,xx} EI v_{,xx} dx$$

WITH  $\delta v = \delta a \cdot x^2$

$$v_{,xx} = a \cdot 2 \quad \delta v_{,xx} = \delta a \cdot 2$$

$$q(x) = p \cdot \frac{x}{l}$$

PVW  $\delta W_i = \delta W_e$

$$\delta a \int_0^l 2EI 2a dx = -\delta a \left( \int_0^l x^2 \cdot p \cdot \frac{x}{l} dx + l^2 \cdot k \cdot a \cdot l^2 \right)$$

$$a \cdot 4EI \cdot l = -\frac{1}{4} \frac{pl^4}{l} - a \cdot kl^4$$

$$a = -\frac{pl^2}{16EI + 4kl^3}$$

$$v(l) = a \cdot l^2 = -60.67 \text{ mm}$$

## Contents

---

- [Data](#)
- [Solution](#)

```
clear variables
close all
home
```

## Data

---

```
f = 14; % [N/mm]
EJ = 1E+10; % [Nmm^2]
l = 2000; % [mm]
k = 100; % [N/mm]
```

## Solution

---

```
syms c x

q = f*x/l;

Phi = x^2;
w = c*Phi;

LHS = int(diff(Phi, x, 2)^2*EJ*c, x, 0, l);
RHS = int(-Phi*q, x, 0, l) - subs(Phi, x, l)^2*c*k;

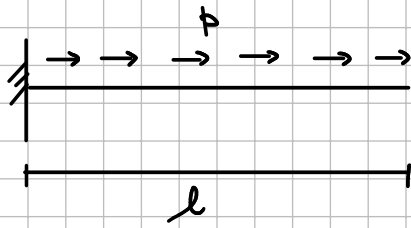
c_d = double(solve(LHS == RHS, c));

w_a = double(subs(w, [c x], [c_d l]))
```

```
w_a =

-66.666666666666671
```

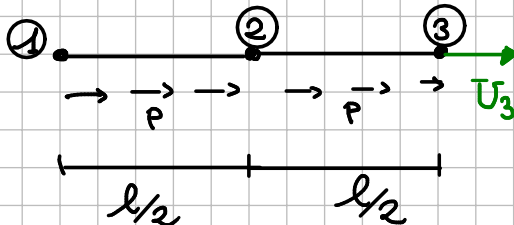
# Ex 2 (EXAM 05/07/2023)



$$l = 3000 \text{ mm}$$

$$EA = 7 \cdot 10^5 \text{ N}$$

$$p(x) = 10 \text{ N/mm}$$

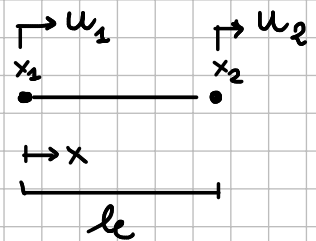


LINEAR FE ELEMENTS

FIND  $U_3$

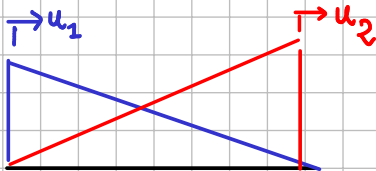
SOL ELEMENT LENGTH  $l_e = \frac{l}{2}$

LOCAL REF. SYST. FOR EACH ELEMENT



LOCAL

$$u_e(x) = N_1(x) \cdot u_1 + N_2(x) \cdot u_2 = \underline{N}_e \cdot \underline{q}_e = \begin{bmatrix} N_1 & N_2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



$$N_1(x) = \frac{x - x_2}{x_1 - x_2} = \frac{x_2 - x}{l_e}$$

$$N_2(x) = \frac{x - x_1}{x_2 - x_1} = \frac{x - x_1}{l_e}$$

$$\varepsilon_e(x) = u_{e/x}(x) = \sum_i N_{i/x} \cdot u_i$$

$$= -\frac{1}{l_e} \cdot u_1 + \frac{1}{l_e} u_2 = \begin{bmatrix} -1/l_e & 1/l_e \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$= \underline{B}_e \cdot \underline{q}_e$$

$$\begin{aligned}
 \delta W_{ie} &= \int_{x_1}^{x_2} \delta \underline{\epsilon}_e^T \cdot EA \underline{\epsilon}_e dx \\
 &= \int_{x_1}^{x_2} \delta [q_e]^T [B_e]^T EA [B_e] [q_e] dx \\
 &= \delta \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}^T \cdot \int_{x_1}^{x_2} \begin{bmatrix} -1/l_e & 1/l_e \end{bmatrix}^T EA \cdot \begin{bmatrix} -1/l_e & 1/l_e \end{bmatrix} dx \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}
 \end{aligned}$$

$$\begin{aligned}
 &\frac{1}{l_e^2} \cdot EA \cdot \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \cdot [x_2 - x_1] \\
 &\frac{EA}{l_e} \cdot \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \underline{\underline{K_e}}
 \end{aligned}$$

$$= \delta \underline{q}_e^T \cdot \underline{\underline{K_e}} \cdot \underline{q}_e$$

$\begin{matrix} 1 \times 2 & 2 \times 2 & 2 \times 1 \end{matrix}$

$$\begin{aligned}
 \delta W_{ee} &= \int_{x_1}^{x_2} \delta \underline{u}_e^T \cdot p(x) dx \\
 &= \delta \underline{q}_e^T \cdot \int_{x_1}^{x_2} \begin{bmatrix} N_1 & N_2 \end{bmatrix}^T \cdot p(x) dx \\
 &= \delta \underline{q}_e^T \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} \frac{p \cdot l_e}{2} = \delta \underline{q}_e^T \cdot \underline{f}_e
 \end{aligned}$$

$$\begin{aligned}
 &\int_{x_1}^{x_2} \begin{bmatrix} N_1 & N_2 \end{bmatrix}^T \cdot p dx \\
 &\int_{x_1}^{x_2} \begin{bmatrix} \frac{x_2 - x}{x_2 - x_1} & \frac{x - x_1}{x_2 - x_1} \end{bmatrix}^T \cdot p \cdot dx \\
 &\begin{bmatrix} \frac{x_2 x - x^2}{x_2 - x_1} \cdot \frac{1}{2} & \frac{x^2 - x_1 x}{x_2 - x_1} \cdot \frac{1}{2} \end{bmatrix} \cdot p \\
 &\begin{bmatrix} \frac{x_2^2 - \frac{1}{2}x_2^2 - x_1 x_2 + \frac{1}{2}x_1^2}{2} & \frac{\frac{1}{2}x_2^2 - x_1 x_2 - \frac{1}{2}x_1^2 + x_1^2}{2} \end{bmatrix} \cdot \frac{p}{l_e} \\
 &\begin{bmatrix} \frac{(x_2 - x_1)^2}{2} & \frac{(x_2 - x_1)^2}{2} \end{bmatrix} \cdot \frac{p}{l_e} \\
 &\begin{bmatrix} 1 & 1 \end{bmatrix} \frac{p \cdot l_e}{2}
 \end{aligned}$$

ASSEMBLE :

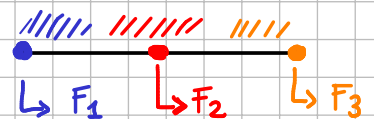
FOR EL #1	$\leadsto u_1 = U_1$	$u_2 = U_2$
EL #2	$\leadsto u_1 = U_2$	$u_2 = U_3$

$$\underline{q} = \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix}$$

$$\underline{\underline{K}} = \begin{bmatrix} \underline{\underline{K_e}} & \mathbf{0} \\ \mathbf{0} & \underline{\underline{K_e}} \end{bmatrix} + \begin{bmatrix} \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \underline{\underline{K_e}} \end{bmatrix} = \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \cdot \frac{EA}{l_e}$$

$\begin{matrix} \text{EL \#1} & & \text{EL \#2} \end{matrix}$

$$\underline{f} = \begin{bmatrix} \frac{p \cdot l_e}{2} \\ \frac{p \cdot l_e}{2} \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{p \cdot l_e}{2} \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \frac{p \cdot l_e}{2}$$



SOLVE  $\underline{\underline{K}} \cdot \underline{q} = \underline{f}$

$$\frac{EA}{l} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \cdot \begin{bmatrix} \bar{U}_1 \\ \bar{U}_2 \\ \bar{U}_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \frac{p \cdot l_e}{2}$$

From BC'  $\bar{U}_1 = 0$

$$\begin{cases} 2\bar{U}_2 - \bar{U}_3 = \frac{pl_e^2}{EA} \\ -\bar{U}_2 + \bar{U}_3 = \frac{pl_e^2}{2EA} \end{cases} \rightarrow \begin{cases} \bar{U}_2 = \frac{3}{2} \frac{pl_e^2}{EA} \\ \bar{U}_3 = 2 \frac{pl_e^2}{EA} = 64.286 \text{ mm} \end{cases}$$

## Contents

---

- [Data](#)
- [Sol](#)

```
close all
clear variables
home
```

## Data

---

```
f = 10;      % N/mm
l = 3000;    % mm
EA = 7E+05; % N
```

## Sol

---

```
syms x_e u_1 u_2 u_3

l_e = l/2;

N_1 = (l_e-x_e)/l_e;
N_2 = (x_e)/l_e;

Ne_1 = [N_1 N_2 0];
Ne_2 = [0 N_1 N_2];

u = [u_1; u_2; u_3];

Be_1 = diff(Ne_1, x_e, 1);
Be_2 = diff(Ne_2, x_e, 1);

K = (int(Be_1.'*EA*Be_1, x_e, 0, l_e) + int(Be_2.'*EA*Be_2, x_e, 0, l_e));

dW_e = (int(Ne_1.', x_e, 0, l_e) + int(Ne_2.', x_e, 0, l_e))*f;

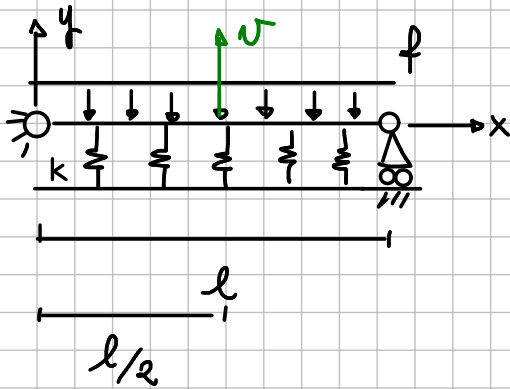
sol = solve(K(2:end, 2:end)*u(2:end) == dW_e(2:end), u(2:end));

double(sol.u_3)
```

ans =

64.285714285714292

Ex 3 (EXAM  
05/09/2023)



DATA

$$l = 1000 \text{ mm}$$

$$EI = 1 \text{E}+12 \text{ Nmm}^2$$

$$k = 8 \text{ MPa} \left( \frac{\text{N}}{\text{mm}} \cdot \frac{1}{\text{mm}} \right)$$

$$f = 100 \text{ N/mm}$$

FIND  $v$  USING TRIG. APPROX

SOL  $v(x) = A \cdot \sin\left(\frac{\pi \cdot x}{l}\right) = A \cdot \phi(x)$  and SATISFY BC

$$v_{/x}(x) = A \frac{\pi}{l} \cdot \cos\left(\frac{\pi x}{l}\right) = A \phi_{/x}(x)$$

$$v_{/xx}(x) = -A \frac{\pi^2}{l^2} \cdot \sin\left(\frac{\pi x}{l}\right) = A \cdot \phi_{/xx}(x)$$

PW  $\delta W_i = \int_0^l \delta v_{/xx} EI v_{/xx} dx$

$$\delta W_e = - \int_0^l \delta v \cdot f(x) dx - \int_0^l \delta v k \cdot v dx$$

$$\delta W_i = \delta A \cdot \int_0^l - \frac{\pi^2}{l^2} \sin\left(\frac{\pi x}{l}\right) EI \cdot - \frac{\pi^2}{l^2} \cdot A \cdot \sin\left(\frac{\pi x}{l}\right) dx$$

KNOWN  $\int_0^l \sin^2\left(\frac{\pi x}{l}\right) dx = \frac{l}{2}$

$$\delta W_e = \delta A \cdot \left( - \int_0^l \sin\left(\frac{\pi x}{l}\right) \cdot f dx - \int_0^l \sin^2\left(\frac{\pi x}{l}\right) \cdot k \cdot A dx \right)$$

KNOWN  $\int_0^l \sin\left(\frac{\pi x}{l}\right) dx = \frac{2l}{\pi}$

PW  $\leadsto \delta W_i = \delta W_e \Rightarrow \underbrace{EI \cdot A \cdot \frac{\pi^4}{l^4} \cdot \frac{l}{2}}_{\text{}} = - f \cdot \frac{2l}{\pi} - kA \cdot \frac{l}{2}$

$$v\left(\frac{l}{2}\right) = A \cdot \sin\left(\frac{\pi \cdot l/2}{l}\right) = A = - \frac{f \frac{2l}{\pi}}{\frac{1}{2} EI \frac{\pi^4}{l^3} + k \frac{l}{2}} = -1.208 \text{ mm}$$

## Contents

---

- [Data](#)
- [Sol](#)

```
close all
clear variables
home
```

## Data

---

```
l = 1000;    % mm
EJ = 1E+12;  % Nmm^2
k = 8;       % MPa
f = 100;     % N/mm
```

## Sol

---

```
syms z A

phi = sin(pi*z/l);

LHS = int(diff(phi, 2, z)^2*EJ*A, z, 0, l) + ...
      int(phi*f, z, 0, l) + ...
      int(phi*k*A*phi, z, 0, l);

sol = solve(LHS == 0, A);

v = double(sol*subs(phi, z, l/2))
```

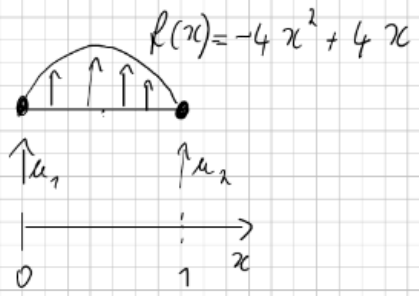
v =

-1.207902973306587



## Ex 4 (EXAM 13/06/2023)

The two-node finite element sketched in the figure is loaded by the distributed force  $f(x)$ . Compute the virtual work of the force for the virtual displacement of node #2. The overall length of the finite element is equal to 1 mm  
(Unit for result: N mm)



Data  
 $f(x) = -4x^2 + 4x \text{ N/mm}$

FIND

$$\delta W_e = \delta u_1 \cdot [\dots] + \delta u_2 \cdot \overbrace{[\dots]}^{\text{THIS}}$$

SOL

$$N_1(x) = (1-x)$$
$$N_2(x) = x$$
$$u(x) = N_1 \cdot u_1 + N_2 \cdot u_2$$

$$\begin{aligned} \delta W_e &= \int_0^l \delta u \cdot f(x) dx \\ &= \delta u_1 \cdot \int_0^l N_1 \cdot f(x) dx + \delta u_2 \cdot \int_0^l N_2 \cdot f(x) dx \end{aligned}$$

$$\begin{aligned} \bullet \int_0^l N_2 \cdot f(x) dx &= \int_0^l x \cdot (-4x^2 + 4x) dx \\ &= \int_0^l -4x^3 + 4x^2 dx \\ &= \left[ -x^4 + \frac{4}{3}x^3 \right]_0^l = -1 + \frac{4}{3} = \frac{1}{3} \end{aligned}$$

Ex 5

(EXAM

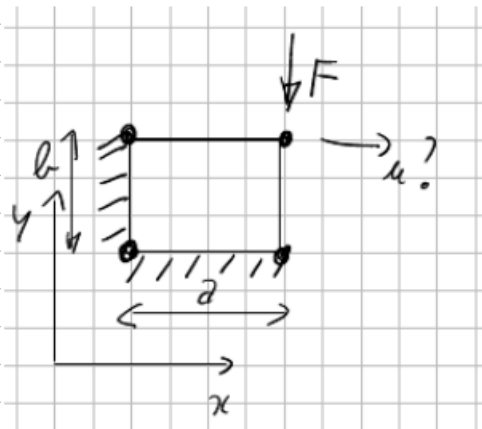
09/09/2024)

The single bilinear finite element sketched in the figure has the displacement of the top left, bottom left and bottom right nodes completely constrained. The element has unit thickness, and the material works in a state of plane stress, so that

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \tau_{xy} \end{Bmatrix} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & (1-\nu)/2 \end{bmatrix} \begin{Bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \gamma_{xy} \end{Bmatrix} \quad (1)$$

The top right node is loaded by the vertical force  $F$ , as sketched. Compute the horizontal displacement  $u$  of the top right node.

(Unit for result: mm)



Data

$$t = 1 \text{ mm}$$

$$a = 4 \text{ mm}$$

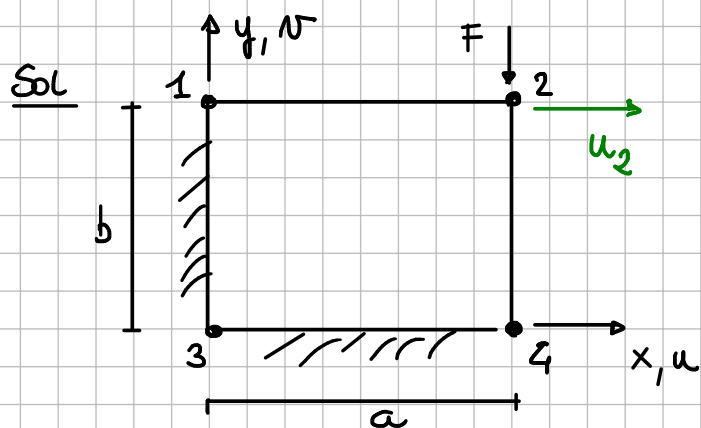
$$b = 3 \text{ mm}$$

$$E = 72000 \text{ MPa}$$

$$\nu = 0.3$$

$$F = 100 \text{ N}$$

BILINEAR MEANS THAT  $u(x)$  &  $v(x)$  ARE LINEAR



FROM BC

$$\begin{cases} u_1, u_3, u_4 = 0 \\ v_1, v_3, v_4 = 0 \end{cases}$$

PVW

$$\int_V \delta \underline{\varepsilon}^T \cdot \underline{\sigma} dV = \delta \underline{u}^T(a, b) \cdot \underline{F}$$

KNOW FROM PLANE STRESS EVERYTHING IS CONSTANT IN  $z$

$$\int_V \delta \underline{\varepsilon}^T \cdot \underline{\sigma} dV = \int_A \delta \underline{\varepsilon}^T \cdot \underline{\sigma} dA \cdot t \quad \text{WHERE } t = 1$$

KNOW  $\underline{u} = \begin{Bmatrix} u(x, y) \\ v(x, y) \end{Bmatrix}$  &  $\underline{F} = \begin{Bmatrix} 0 \\ -F \end{Bmatrix}$

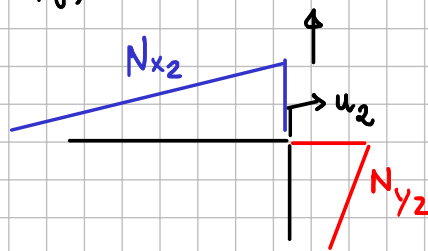
IF FULLY UNCONSTRAINED

$$\underline{u}(x,y) = \underline{N} \cdot \underline{q}$$

$$\begin{matrix} \left[ \underline{N} \right] & \cdot & \left\{ \underline{q} \right\} \\ 2 \times 8 & & 8 \times 1 \\ & & \uparrow \\ & & \left\{ \begin{matrix} \{u_i\} \\ \{N_i\} \end{matrix} \right\} \end{matrix}$$

SINCE 1, 3, 4 ARE CONSTRAINED  $q$  is  $2 \times 1$   $N$  is  $2 \times 2$

$$\underline{u}(x,y) = \begin{Bmatrix} u(x,y) \\ v(x,y) \end{Bmatrix} = \begin{bmatrix} x y / ab & 0 \\ 0 & x y / ab \end{bmatrix} \begin{Bmatrix} u_2 \\ v_2 \end{Bmatrix} = \underline{N} \cdot \underline{q}$$



$$\underline{u} = \begin{Bmatrix} (u_2 \cdot x/a) \cdot y/b \\ (v_2 \cdot y/b) \cdot x/a \end{Bmatrix}$$

HOW TO INTERPOLATE DISPLACEMENT:

FROM  $u_2$  FIX  $y = b$  GET  $u(x)$

USE INTERPOLATION  $N_{x2} = x/a$

$u(x) = u_2 \cdot x/a$ , THEN INTERP.

$u(x)$  IN  $y$  USING  $N_{y2} = y/b$

$\rightarrow u(x,y) = (u_2 \cdot x/a) \cdot y/b$

COMPUTE THE STRAIN

$$\underline{\varepsilon} = \begin{Bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \gamma_{12} \end{Bmatrix} = \begin{bmatrix} \partial/\partial x & 0 \\ 0 & \partial/\partial y \\ \partial/\partial y & \partial/\partial x \end{bmatrix} \underline{u}$$

$3 \times 2 \qquad 2 \times 1$

$$= \underbrace{\begin{bmatrix} \partial/\partial x & 0 \\ 0 & \partial/\partial y \\ \partial/\partial y & \partial/\partial x \end{bmatrix} \begin{bmatrix} x y / ab & 0 \\ 0 & x y / ab \end{bmatrix}}_{\underline{B}} \cdot \underbrace{\begin{Bmatrix} u_2 \\ v_2 \end{Bmatrix}}_{\underline{q}}$$

$3 \times 2 \qquad 2 \times 2 \qquad 2 \times 1$

$$\underline{\varepsilon} = \begin{bmatrix} y/ab & 0 \\ 0 & x/ab \\ x/ab & y/ab \end{bmatrix} \cdot \begin{Bmatrix} u_2 \\ v_2 \end{Bmatrix} = \underline{B} \cdot \underline{q}$$

STRESS AS FUNCTION OF STRAIN  $\underline{\sigma} = \underline{D} \cdot \underline{\varepsilon}$

$3 \times 1 \qquad 3 \times 3 \quad 3 \times 1$

$$\delta W_i = \int_A \delta \underline{q}^T \cdot \underline{\underline{B}}^T \cdot \underline{\underline{D}} \cdot \underline{\underline{B}} \cdot \underline{q} \, dA$$

$1 \times 2 \quad 2 \times 3 \quad 3 \times 3 \quad 3 \times 2 \quad 2 \times 1$

$$\delta W_e = \delta \underline{q}^T \cdot \underbrace{\underline{\underline{N}}^T(a, b)}_{\underline{\underline{I}}} \cdot \underline{F} = \delta \underline{q}^T \cdot \underline{F} = -\delta N_2 \cdot F$$

$1 \times 2 \quad 2 \times 1$

$$\underline{\underline{K}} \underline{q} = \underline{f}$$

$\underline{\underline{K}} \quad \underline{q} \quad \underline{f}$

Solve  $\underline{\underline{K}} \underline{q} = \underline{f}$  for  $\underline{q} = \begin{Bmatrix} u_2 \\ N_2 \end{Bmatrix} \rightarrow u_2 = 1.08 \cdot 10^{-3} \text{ mm}$

## Contents

---

- [Sol](#)
- [Data](#)

```
close all
clear variables
home
```

## Sol

---

```
syms x y z u_2 v_2 t a b E nu F

q = [u_2; v_2];
B = [
    y/a/b 0;
    0 x/a/b;
    x/a/b y/a/b
];
D = E/(1-nu^2)*[
    1 nu 0;
    nu 1 0;
    0 0 (1-nu)/2
];
F_v = [
    0;
    -F
];

RHS = F_v;
K = int(...
    int( ...
    int( ...
    transpose(B)*D*B, x, 0, a ...
    ), y, 0, b ...
    ), z, 0, t);

LHS = K*q;
```

## Data

---

```
t = 1;
a = 4;
b = 3;
E = 72000;
nu = .3;
F = 100;

sol = solve(subs(LHS) == subs(RHS), q);

u_2_d = double(sol.u_2)
```

```
u_2_d =

    0.001084801369375
```

