Component	2	1	0
Color Sensor	-Reads Colour - Heads in right direction - Displays colour on screen	-Reads Colour - Heads in right direction	-No colour sensor used
Gyro Sensor	-Gyro is accurate and arrives at final destination appropriately	-Gyro is used, but arrives slightly off its final destinations	-No gyro used
Ultrasonic Sensor	-Sensor gets within appropriate distance of pickup item	-Sensor is used, but runs over the item, or comes up short	-No ultrasonic used
Push Sensor	-Push button sensor used to release the item in drop zone & signals next round	-Push button sensor used only to release item in drop zone	-No push button sensor used
Line Following	-Robot is guided back to drop zone using line detection from colour sensor	-Robot is guided back to drop zone with gyro sensor or base programming	-Robot does not make it back to drop zone successfully
Pickups	-All items are collected and appropriately dropped off	-Some items (1-3) are collected and dropped off	-No items successfully picked up
Speed	-Fastest in the class	-Completes the task	-Does not complete total task
BONUS	Python coded + 2		