

# CHEAT SHEET FOR IMAGE PROCESSING

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<code>cv2.imread()</code>	loads an image from the specified file
<code>cv2.namedWindow()</code>	used to create an empty window with a suitable name and size to display images
<code>cv2.imshow()</code>	used to create a window and set the image with a given window name
<code>cv2.waitKey()</code>	for blocking the script ( wait for a key press )
<code>cv2.destroyAllWindows()</code>	for destroying the displayed image
<code>IMAGE_WRITE_JPEG_QUALITY</code>	used to set the quality of the image (compression size)
<code>cv2.cvtColor()</code>	To convert the image to a different color space
<code>cv2.calcHist()</code>	calculate the histogram of the image as a 1D array
<code>cv2.equalizeHist()</code>	equalize the histogram of the image to increase the contrast
<code>costume func : MSE(image1, image2)</code>	<pre># Calculate the squared difference between the two images squared_diff = (image1 - image2) ** 2 # Calculate the mean of the squared differences mse = np.mean(squared_diff)</pre>
<code>gaussianNoise</code>	<code>np.random.randn(image.shape[0], image.shape[1]) * 2</code>
<code>saltPepperNoise</code>	<code>np.random.choice([0, 255], size=image.shape, p=[0.95, 0.05])</code>
<code>cv2.add(img1,img2)</code>	this function is used to combine two images ( ex : noise + original image )

```
meanFilter(image,kernel_size)
```

```
# Create a kernel with ones and divide each element by the kernelsize  
kernel = np.ones((kernel_size, kernel_size), np.float32) /  
(kernel_size ** 2)  
# Apply the kernel to the image using convolution  
filtered_image = cv2.filter2D(image, -1, kernel)
```

```
medianFilter(image, kernel_size)
```

```
# Apply the median filter to the image  
filtered_image = cv2.medianBlur(image, kernel_size)
```

```
gaussianFilter(image, kernel_size,  
sigma)
```

```
# Apply the Gaussian filter to the image  
filtered_image = cv2.GaussianBlur(image, (kernel_size, kernel_size), sigma)
```