RX12 Changelog

# Firmware

Version 1.0 – First tested and flown version.

Version 1.01

* If receiver is powered on before transmitter the log will no longer show a Failsafe alert.

Version 1.2

* Added PPM output option on Ch. 12 pins.

Version 1.3

* Added sBus output option on Ch. 12 pins.
* Changed blink codes to make them easier to distinguish.

Version 1.4

* Changed PPM output order to AETR to maintain compatibility with PPM encoders.
* Fixed sBus bug – Throttle channel was incorrect.
* sBus failsafe bit was in wrong position.

Version 1.5

* PWM outputs 1-11 are now active even in sBus mode. Output 12 is used for sBus so channel 12 is not available in PWM format.

Version 1.6

* Outputs 11 and 12 are disabled whenever rx is powered up in bind mode. This prevents these outputs from becoming active with a bind plug attached and shorting the pin to ground. Power cycling will enable outputs.

Version 1.7

* If sBus mode is selected you can now select 11ms or 22ms for the servo frame rate. Previous versions only allowed 22ms when using sBus. Added blink code for sBus 11ms.

# Client

Version 1.00 – Initial version

Version 1.1 – Added PPM option

Version 1.2 – Added S.Bus option

Version 1.3 – Changed connection behavior. Now only reports “Connected” after successful read. Now Save button is only enabled after successful read.

Version 1.4 – UI changes to accommodate firmware version 1.7 Should still work with older versions.

# Schematic and PCB

Version 1.0 – Initial production version