



	PROJECT
	Implement a Planning Search
	A part of the Artificial Intelligence Nanodegree Program
	PROJECT REVIEW
	CODE REVIEW
	ANNOTATIONS 1
	NOTES
IARE VOUR ACCO	MADI CHMENTI NE
leets Specifi	Cations
	ission. You have a very good understanding of underlying concepts. Congratulations on successfully completing the project.
is a periode sasin	issues to the figure and the second of the control of the control of the figure of the
lanning Proble	m Representation
	√
The problems and o	class methods in the my_air_cargo_problems.py module are correctly represented.
Correct!	
An ontimal seguena	ce of actions is identified for each problem in the written report.
Awesome: Good wo	rk! You have identified the optimal no. of steps for each of the 3 problems.
utomated Heu	ristics
A	
Automated neuristi	ics "ignore-preconditions" and "level-sum" (planning graph) are correctly implemented.
Correct!	
- wf- www	
erformance Co	mparison
	✓
	ormed planning algorithms (including breadth- and depth-first search) are compared on all three problems, and at least two automatic heuristics are n for planning on all three problems including "ignore-preconditions" and "level-sum" from the Planning Graph.
Good job! You have	implemented the atleast two automatic heuristics along with the uninformed planning search algorithms.
	✓

Very neat comparison of all the different search results on problems 1, 2 and 3.



The report explains the reason for the observed results using at least one appropriate justification from the video lessons or from outside resources (e.g., Norvig and Russell's textbook).

Great analysis! However please site your outside resources (e.g., Norvig and Russell's textbook). Since this is academic paper, students are encouraged to add references to their claims. All sources that are used in producing this report (video lecture, text book) should be included at the end in a Reference section, similar to how you did it in research summary.

Research Review



The report includes a summary of at least three key developments in the field of AI planning and search.

Well written

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Student FAQ

Reviewer Agreement