

# Ben-Jose SAT Solving Software Library

## Tool Paper\*

Jose Luis Quiroga Beltran

Independent Researcher  
joseluisquirolga@yahoo.com  
March 2016

### Abstract

The software library Ben-Jose (<https://github.com/joseluisquirolga/ben-jose>) for solving instances (formulas) of the satisfiability problem (SAT) in CNF form (DIMACS format) is presented. Ben-Jose implements a trainable strategy that extends the traditional DPLL+BCP+CDCL resolution based approach, first introduced by Joao Marques da Silva [8] and latter refined by others [15] [10]. Ben-Jose has an original technique (BDUST) to check during search if, for a given partial assignment of the solving formula variables, the resulting current sub-formula has been previously found unsatisfiable. It does that by finding the current sub-formula permutation to its "BDUST canonical form formula" (BCFF) and checking the BCFF existence in a database of unsatisfiable BCFFs. That in order to entirely skip the search on the current sub-formula. The calculation of a BCFF introduces an original stabilization procedure (as in [2]) for the structure of CNF formulas. The calculation has linear complexity and is tightly coupled with the work done by BCP.

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\*Especial thanks to our heavenly Father, his anointed King, Magda Beltran de Quiroga and Federman Quiroga.

## 1 Introduction

The satisfiability problem (SAT) is the canonical decision problem by excellence [3] [13] [14]. It lays at the heart of the P vs NP question and its importance cannot be overstated [5]. People have proved both that " $NP \neq P$ " and that " $NP = P$ " [19] [16], and filed patent applications for optimal SAT solvers based on resolution [17].

The practical limitations of human verification of long and complex proofs, even under the peer-review system, highlights the importance of automated proof checking. This and the practical applications of automated theorem proving highlights the importance of SAT.

Exponential lower bounds of resolution (RES) proof size for the pigeon hole principle (PHP) have been proven [11] [4], and polynomial size proofs for extended resolution (ER) have also been proven for the PHP [6] [7] [12] instances of the SAT problem. That work suggests that solvers based on RES [8] [15] [10] need "something else" in order to be "faster" [9] [1].

Based on the notion that theorems are proved with lemmas and the observation that the structure of  $PHP(n+1, n)$  can be matched with several substructures of  $PHP(n+2, n+1)$ , the software library presented in this work (Ben-Jose) extends RES by learning the structure of unsatisfiable sub-formulas (proved unsatisfiable during its execution) and matching them against future structures of sub-formulas found during its execution, in order to skip the search, and directly backtrack on them, when ever a match (subsumed isomorphism) is found.

This technique is here after called Backtrack Driven by Unsatisfiable Sub-formula Training (BDUST). BDUST introduces an original stabilization procedure (as in [2]) for the unsatisfiable sub-formulas found, uses the work done by BCP (each BCP step groups some variables), and has linear complexity with respect to the size of the sub-formulas. The structures learned with BDUST have the advantage that can be used also with different instances than the one they were found on. That is why BDUST is "training" and not "learning".

This form of extending RES is not ER, as the system presented by Tseitin [18], because the subsumed isomorphism detection technique is not RES based, and the power and complexity of the resulting proof system has not been formally studied. The empirical results on the classical theoretical problem of PHP are presented here.

## 2 Objectives

Ben-jose is designed to be used as a support library for applications or libraries that need to solve both theoretical and practical instances of SAT. The expected user is a C/C++ programmer. In order to achieve that it has the following sub-objectives:

User objectives:

1. To be easy to use for the C/C++ programmer.
2. To isolate the user from all difficulties of SAT solving.
3. To do be the world most used trainable SAT solving programming library. ;)

Formal objectives:

1. To present an original, general, and practical alternative strategy to SAT solving.
2. To use other known SAT solving techniques as much as possible.
3. To have a solid empirically checked algorithmic soundness and correctness.

Technical objectives:

1. To do the less possible number of steps assuming unsatisfiability.
2. To do about the same number of steps for any permutation of the given instance.
3. To reuse as much information as possible during solving.
4. To use visualization techniques to debug target theoretical cases.
5. To optionally write proofs for unsatisfiable cases.

## 3 Functionality

### 3.1 Hello World example

The basic functionality of the library is best shown by the `bj-hello-world.c` program:

Listing 1: `bj-hello-world.c` program

---

```
1 #include <stdio.h>
2 #include "ben_jose.h"
3
4 int main(int argc, char** argv)
5 {
6     if(argc < 2){
7         printf("args: <cnf_file_path>\n");
8         return 1;
9     }
10    char* ff = argv[1];
11
12    bj_solver_t ss = bj_solver_create("");
13
14    bj_satisf_val_t vv = bj_solve_file(ss, ff);
15    switch(vv){
16        case bjr_yes_satisf:
17            printf("%s is SAT instance\n", ff);
18            break;
19        case bjr_no_satisf:
20            printf("%s is UNS instance\n", ff);
21            break;
22        case bjr_error:
23            printf("ERROR! in %s\n", ff);
24            break;
25        default:
26            printf("FATAL_ERROR! in %s\n", ff);
27            break;
28    }
29
30    // more info with this functions
31    //bj_output_t oo = bj_get_output(ss);
32    //const long* aa = bj_get_assig(ss);
33
34    bj_solver_release(ss);
35    return 0;
36 }
```

---

This program finds the solution to the SAT instance defined by the file "ff". The file must be in the simplified DIMACS format as described in <http://www.satcompetition.org/2009/format-benchmarks2009.html>.

Three functions are minimally needed to use the library `bj_solver_create`, `bj_solve_file`, and `bj_solver_release`.

## 3.2 Compiling

Once the library has been installed (see Section 6), a user program can be compiled using standard `c++` compilation.

Assuming that the file `libben-jose.a` is in the directory `BJ_LIB.PTH`, the program in Listing 1 is build and compiled as in Listing 2:

Listing 2: compiling the `bj-hello-world.c` program

---

```
1 BJ_LIB.PTH=../.././build/gnu_make/bin
2
3 cc -o bj-hello-world.o -c -MD -Wall -std=c99 -I../../library/api bj-
  hello-world.c
4 cc -o bj-hello-world -rdynamic -L${BJ_LIB.PTH} bj-hello-world.o -lben-
  jose -lstdc++ -lgmpxx -lgmp
```

---

## 3.3 Input format

The input format of a file called with `bj_solve_file` must be the simplified DIMACS format.

The simplified DIMACS format is just that:

Listing 3: Simplified DIMACS CNF format example

---

```
1 c
2 c start with comments
3 c
4 c
5 p cnf 5 3
6 1 -5 4 0
7 -1 5 3 4 0
8 -3 -4 0
```

---

1. The file can start with comments, that is lines beginning with the character `c`.
2. Right after the comments, there is the line `p cnf nbvar nbclauses` indicating that the instance is in CNF format; `nbvar` is the exact number of variables appearing in the file; `nbclauses` is the exact number of clauses contained in the file.
3. Then the clauses follow. Each clause is a sequence of distinct non-null numbers between `-nbvar` and `nbvar` ending with 0 on the same line; it cannot contain the opposite literals `i` and `-i` simultaneously. Positive numbers denote the corresponding variables. Negative numbers denote the negations of the corresponding variables.

## 4 Architecture

(Describe here the architecture)

## 4.1 The Library

The following classes and names for attributes are the most important to explain how the solver works. They are explained in terms used in [8], [15] and [2].

### 4.1.1 DPLL+BCP+CDCL classes

To explain the most important parts of DPLL+BCP+CDCL, the following classes will be used.

**neuron**: class for CNF clause behavior. So there is one **neuron** per clause.

**quanton**: class for CNF variables (each variable has a positon and a negaton). There are two **quantons** per variable. **neurons** hold references to **quantons** called fibres. They are used for BCP.

**prop\_signal**: class for representing BCP propagation data: which **quanton** fired by which **neuron** (which clause forced a given variable). BCP is done with the two watched literals technique (two watched fibres in the library's terminology).

**deduction**: class for holds the result of analyzing (doing resolution) of a conflict. It has the data for learning new **neurons** (clauses).

**brain**: class that holds all data used to solve a particular CNF instance. So there is one **brain** per CNF instance. It is created to solve an instance, and destroyed after solving that particular instance.

**deducer**: class that holds the data used to analyze a conflict.

**leveldat**: A level is all that happens between choices during BCP. So there is one level per choice. This class holds level relevant data.

### 4.1.2 Stabilization classes

The process of calculating a BDUST canonical form formula (BCFF) is called stabilization. The following classes will be used to explain the most important aspects of CNF stabilization:

**sort\_glb**: It holds all global data used to stabilize a group of items (**neurons** and **quantons** representing a sub-formula of a CNF). It does not handle **neurons** and **quantons**, instead it handles **sortees**.

**sortee**: It is an item to be stabilized. Each **neurons** contains one **sortee** and each **quantons** contains one **sortee**. Each **sortee** "knows" (void pointer) which **neuron** or **quanton** contains it. It is a one-to-one relation that is used to stabilize CNF sub-formulas. During stabilization, the **sort\_glb** handles the **sortees** not the **neurons** and **quantons** containing them.

**sorset**: It is a group of **sortees**. In order to stabilize a group of **sortees** the **sort\_glb** class (or **sortor**) groups **sortees** (representing **neurons** and **quantons** in our case) into **sorsets**. A sub-formula is represented within stabilization by a group of **sorsets**. Each step of stabilization refines the group of **sorsets** that represent the stabilizing sub-formula, so that every step there are more **sorsets**, each one having less **sortees**, until the process cannot refine each **sorset** anymore. The ideal stabilization ends with each **sorset** containing only one **sortee**. Since stabilization handles only **sortees**. This class is used for such iterated sub-grouping.

**sortrel**: It represents a relation between two **sortees**. In our case every **sortee** representing a **neuron** holds one **sortrel** per fiber (literal), and each **sortee** representing a **quanton** holds one **sortrel** per **neuron** in wick the **quanton** is found. They must be properly initiated before each stabilization. They define the stabilizing sub-formula's relations between it's **neurons** and **quantons** by relating their respective **sortees**. They represent relations between a particular sub group (sub-formula) of **neuron**'s **sortees** and **quanton**'s **sortees**.

### 4.1.3 Matching classes

Matching consists basically of two steps. Stabilization and finding the resulting BCFF in the database of BCFFs. The following classes will be used to explain the most important aspects of CNF matching:

**coloring:** The initial and final state for an stabilization is a **coloring**. A color is just an integer. A **coloring** of a sub-formula is an assignation of an integer (**neuron-color**) to each **neuron** and an integer (**quanton-color**) to each **quanton** of the sub-formula. An stabilization may start with all **neurons** having the same **neuron-color** and all **quantons** having the same **quanton-color** and finalize with each **neuron** having a unique **neuron-color** and each **quanton** having a unique **quanton-color**, called a complete **coloring**.

**colorings** are "loaded" into the **sort\_glb** class in order to start stabilization. After stabilization the final **coloring** may be "saved". Each color in a **coloring** will correspond to one **sorset** during stabilization.

This class is used to specify only the input to the stabilization process (the initial state). The class **canon\_cnf** is used for the output (it is the result of applying the output **coloring** (stabilized **coloring**) to the sub-formula it defines: **neurons** and **quantons** in the **coloring**. To initialize the sorter, it "loads" the initial **coloring** into the **sort\_glb** instance that will stabilize the CNF sub-formula.

**canon\_cnf:** It is a BCFF. It represents the output of an stabilization process: the stabilized CNF sub-formula. It is the interface class to the database class that handles all disk operations (the **skeleton** class). This class contains some disk handling related information (paths and sha info). A **canon\_cnf** basically is a set of **canon\_clauses** (which are basically arrays of numbers).

**neuomap:** This class represents a CNF sub-formula. It is the pivot class to do all stabilization. It is maintained during BCP and used during backtracking in order to know what CNF sub-formulas are to be stabilized and searched for in the database (**skeleton** class). There is one **neuomap** per **leveldat** and they are either active or inactive. Active when they are candidates for stabilization, matching and search in database (or saving), at backtrack time. When a CNF sub-formula, during search, is found to be unsatisfiable, is not trivial (BCP could not figure it out), and both search branches had the same variables (so that it can latter be searched only with one of them), it is saved, stored in the database (**skeleton** class). Every time an still active **neuomap** has done its first branch of BCP, it is stabilized and searched for in the database (**skeleton** class). Trivial sub-formulas are called anchors in the code because they serve as a start point for stabilizing not trivial ones.

### 4.1.4 Database classes

The **skeleton** class handles all disk related functions and management. The database is basically a directory and all its sub-directories in disk. The directory (**skeleton**) is seen as a group of ("key", "value") pairs. Just like a common database "index", a "dictionary" class, or a "map" class. A path within the **skeleton** is a "key" and the files in the path are the "value". To see if a "key" exists is to see if a path exists within the **skeleton**. Unsatisfiable **canon\_cnf**s are saved and searched by the SHA function of their content. They are saved in a path ("key") that is constructed with the SHA and other relevant search info.

Since an unsatisfiable sub-formula might not be minimal (have some unnecessary clauses for unsatisfiability), each unsatisfiable CNF sub-formula has three relevant **canon\_cnf**:

1. The guide. It is the **canon\_cnf** resulting of stabilizing the CNF sub-formula covered by first search branch variables. So it is a satisfiable part of the unsatisfiable CNF sub-formula that is a "guide" for the search.

2. The tauto. It is the full unsatisfiable CNF sub-formula. It is the `canon_cnf` resulting of stabilizing the CNF sub-formula covered by both search branches charged `quantons` (used variables).
3. The diff. This `canon_cnf` contains all `canon_clauses` in tauto but not in guide. Each diff is saved in a path called 'variant' in the `skeleton`. So one guide can have several variants.

A search of a target CNF sub-formula is conducted in two phases: the search for the guide of the target and the search for the variant that is a sub-formula of the target diff. Once the guide is stabilized the search for it is a simple: "see if its path exists" (remember that its path contains the SHA of its content). If the target `canon_cnf` is not equal to a variant (the path does not exist), the second phase is more time consuming because it involves reading each variant and comparing it to the target diff to see if the the variant is a sub-formula of the target diff (which would mean that the target is unsatisfiable and therefore can be backtracked).

## 5 Use case

(Describe here the use case)

## 6 Installation

Since there is no current release version of the library, it has to be installed from source. To do so:

1. Download the library from <https://github.com/joseluisquiroga/ben-jose>.
2. Build and install the library following the instructions in the README.txt file.

The README.txt file refers you to the installation alternatives:

1. To build and install with autotools follow:  
`./build/gnu_autotools/README.to_install_with_autotools`
2. To build with gnu\_make follow:  
`./build/gnu_make/README.to_install_with_gnu_make`

It is very probable that when installing with autotools you will need to first follow the file:  
`./build/gnu_autotools/README.when_clean_all_non_human_made`  
because the source tree is usually cleaned from all non human made files.

### 6.1 Required Packages

There are minimal requirements for building and compiling ben-jose:

- A linux system.
- GNU c++ (g++) installed.
- GMP Library (gmpxx) installed.

Almost every linux system comes with the second two in the basic installation, so there is basically one requirement: a linux system.

## 7 Comparison with other tools

### 7.1 Trainable

The most important difference of ben-jose with any other solver available today is the fact that it matches sub-formulas to already known to be unsatisfiable formulas (BCFFs) in order to skip the search on sub-formulas that match.

That technique allows this solver to be trainable. It holds a database of BCFFs that can be reused in later instances of SAT.

In order to achieve this behavior some important modifications had to be done to the standard way of doing DPLL+BCP+CDCL. Learned clauses (**neurons**) are kept only until they are backtracked. That imposes a performance penalty when that clause can actually prune the search after it has been backtracked since it has to be deduced again by RES.

### 7.2 Monos

They are variables (**quantons**) that occur either only in positive form, or only in negative form after a BCP step, that is a level has been processed (**level** data hold the data for levels). In the code they are called "monos". So:

- When it is detected that there are only positons of a variable in the current sub-formula, the variable can safely be assumed to be set "true".
- When it is detected that there are only negatons of a variable in the current sub-formula, the variable can safely be assumed to be set "false".

This difference is crucial for to ease the matching of BCFFs.

### 7.3 Longest BCP

The solver uses a kind of "look up technique" that always chooses the "longest" path for BCP.

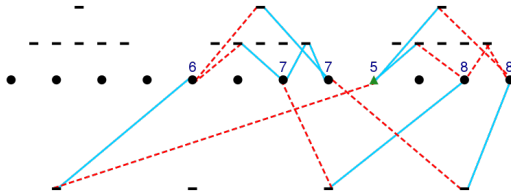
When ever a choice is been made it tries both values in orther to see wich value propagates more variables.

This difference is also crucial for to ease the matching of BCFFs.

In the code it can bee seen in the function "start\_propagation" when it calls "select\_propag\_side".



## 8 Future Work



(Describe here future work)

## 9 Acknowledgments

1. Our heavenly Father YHWH (Yahweh).
2. Our Lord Yashua (Jesus Christ).
3. Magda Beltran de Quiroga (my mother).
4. Federman Quiroga Rios (my father).
5. Joao Marquez da Silva for his work on the SAT problem.
6. All the authors in the bibliography.

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