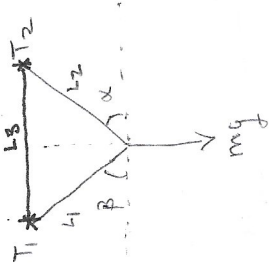
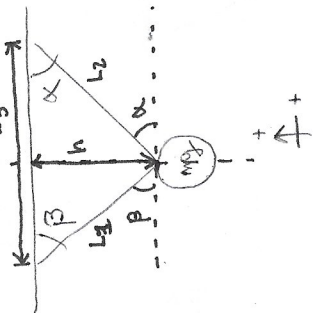


$$\alpha = \sin^{-1}\left(\frac{h}{L_2}\right)$$

$$\beta = \sin^{-1}\left(\frac{h}{L_1}\right)$$



$$\Sigma F_x = 0 = T_2 \cos \alpha - T_1 \cos \beta$$

$$\Sigma F_y = 0 = T_1 \sin \beta + T_2 \sin \alpha - mg$$

$$T_2 \cos \alpha = T_1 \cos \beta$$

$$T_2 = T_1 \frac{\cos \beta}{\cos \alpha}$$

#####

$$T_1 \cos \beta + T_2 \cos \alpha - mg = 0$$

$$T_1 \sin \beta + \left(T_1 \frac{\cos \beta}{\cos \alpha}\right) \sin \alpha - mg = 0$$

$$T_1 \sin \beta + T_1 \cos \beta \tan \alpha - mg = 0$$

$$T_1 (\sin \beta + \cos \beta \tan \alpha) - mg = 0$$

$$T_1 = \frac{mg}{\sin \beta + \cos \beta \tan \alpha}$$

$$T_2 = \left( \frac{mg}{\sin \beta + \cos \beta \tan \alpha} \right) \left( \frac{\cos \beta}{\cos \alpha} \right)$$

on program:

$T_1$  = tension 1  
 $T_2$  = tension 2

$m$  = mass  
 $g$  = ACCEL-DUE-TO-GR.  
 $L_1$  = length 1  
 $L_2$  = length 2  
 $L_3$  = length 3

$\alpha$  = angle 2  
 $\beta$  = angle 1